# SAILOR 



TECHNICAL MANUAL FOR
SAILOR COMPACT HF SSB T2130
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## 1 GENERAL INFORMATION

### 1.1 INTRODUCTION

The SAILOR Compact HF SSB T2130 is a 250W PEP SSB transmitter for the SAILOR Compact HF SSB Programme 2000.

SAILOR Compact HF SSB Programme 2000 is a powerful, advanced, high technology short wave communication system, which is extremely easy to operate.

Is has been developed on the basis of S. P. Radio's many years of experience with short wave communication equipment.

Is has the same high reliability as all SAILOR equipment is known for.

## SAILOR HF SSB PROGRAMME 2000 CONSISTS OF THE FOLLOWING UNITS:

RE2100: Control unit with integral receiver and exciter.
T2130: 250W PEP SSB transmitter with integral power supply for RE2100. Supply voltage 24 V .

AT2110: 250W PEP aerial coupler for use outdoors.
N2160: $\quad$ 12V DC power supply for T2130.

N2161: 110/220/240V AC, 50 Hz power supply for T2130.

### 1.2 GENERAL DESCRIPTION

SAILOR HF SSB T2130 is an all solid state constructed microcomputer controlled SSB shortwave transmitter.

SAILOR HF SSB T2130 covers the frequency range from 1.6 MHz to 30 MHz .
SAILOR HF SSB T2130 has an output power of 250 W PEP.
SAILOR HF SSB T2130 is constructed for continuous operation.
SAILOR HF SSB T2130 has 50 ohm output impedance.
SAILOR HF SSB T2130 is able to control the automatic aerial coupler AT2110.
SAILOR HF SSB T2130 has built-in power supply for 24V DC.
SAILOR HF SSB T2130 is able to supply the transceiver RE2100.
SAILOR HF SSB T2130 has built-in protection system, so that it will not be damaged if the aerial is open circuited or short-circuited.

### 1.3 TECHNICAL DATA (complies with SOLAS, ITU, CEPT, MPT, DOC, FTZ, KSR, FCC)

## GENERAL

| Frequency Range: | Receiver: 100 kHz to 30 MHz <br> Transmitter: 1.6 MHz to 30 MHz |
| :--- | :--- |
| Modes: | J3E (USB/LSB), R3E and H3E (AM) |
| Channel Capacity: | 100 user defined quick-select channels and ITU defined channels <br> in the maritime bands. Each channel contains both RX and TX frequency <br> and mode settings. |
| Scanning Facilities: | 10 scanning prograammes, each able to contain <br> 128 pairs of frequencies. |
| Distress Call: | Quick selection of 2182 kHz <br> Built-in two tone alarm: 1300 Hz and 2200 Hz <br> with a duration of $45 \mathrm{secs}$. |

Operating Temperature Range: $-15^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$

| Frequency Stability: | Better than 0.34 ppm |  |
| :--- | :--- | ---: |
| Primary Voltage: | 24 V DC $-10 \%+30 \%$ |  |
|  |  |  |
| Current Drain: | Receiver (standby) | 0.9 A |
|  | Transmit voice | 7 A |
|  | Transmit two-tone | 13 A |

## Aerials:

from 7-15m

TRANSMITTER T2130

| Power Output: | 250 W PEP $\pm 1.4 \mathrm{~dB}$ (T2130/I 240W PEP max.) |
| :--- | :--- |
| Intermodulation: | better than 32 dB below PEP |
| Spurious Emission: | better than 67 dB below PEP |
| Harmonics: | better than 43 dB below PEP or <br> better than 67 dB below PEP with aerial coupler AT2110 <br> Carrier Suppression: |
| better than 46 dB below PEP |  |
| Audio Response: | 350 Hz to 2700 Hz at -6 dB |

## RECEIVER RE2100

| Receive System: | Double conversion super heterodyne <br> 1st IF 70 MHz .2 nd 10.73 MHz |
| :--- | :--- |
| Selectivity: | J3E (SSB) 350 Hz to 2700 Hz at -6 dB |
|  | H3E (AM) $\pm 3.3 \mathrm{kHz}$ at -6 dB |

Sensitivity:

Spurious and IF Rejection:
Cross Modulaton:
Desensitization:
AGC:

Intermodulation:
Spurious Emission:
Clarifier:
Squelch:
Audio Power:

J3E (SSB) <10 dB/uV for 20 dB SINAD H3E (AM) <24 dB/uV for 20 dB SINAD
better than -70 dB
better than $90 \mathrm{~dB} / \mathrm{uV}$ (CEPT method of test)
better than $100 \mathrm{~dB} / \mathrm{uV}$ (CEPT method of test)
less than 2 dB audio level change from $10 \mathrm{~dB} / \mathrm{uV}$ to $80 \mathrm{~dB} / \mathrm{uV}$.
Fast attack, slow release time.
better than $90 \mathrm{~dB} / \mathrm{uV}$ (CEPT method of test)
better than 1 nW into dummy aerial
$\pm 150 \mathrm{~Hz}$ in steps of 10 Hz
Voice activated, opens for SINAD $>6 \mathrm{~dB}$
5 Watt, 8 ohm, less than $10 \%$ distortion
10 Watt, 4 ohm, less than $10 \%$ distortion

## AERIAL COUPLER AT2110

Power:
Aerials:
Temperature Range:
Tuning Time:

## ACCESSORIES

Loudspeaker:

## Power Supplies:

Weight:

H2054 see special brochure H2074 see special brochure

## N2160

Input supply: $12 \mathrm{~V}+30 \%-10 \%$
For more information see the manual for N 2160
N2161
Input supply: 110V-127V-220V-240VAC
Input frequency: $50-60 \mathrm{~Hz}$
For more information see the manual for N 2161
RE2100: 4.5 kg
T2130: $\quad 14 \mathrm{~kg}$
AT2110: $\quad 4.5 \mathrm{~kg}$

### 1.4 PRINCIPLE OF OPERATION AND BLOCK DIAGRAM

SAILOR Compact HF SSB T2130 is a 250W PEP transmitter in SAILOR Compact HF SSB Programme 2000. It contains following circuits.

## POWER AMPLIFIER

The power amplifier is a push-pull amplifier.
The input signal from RE2100 is fed through a TX/RX switch on the output filter unit to the input of the power amplifier. The signal is amplified to approx. 280W PEP. The bias to the pre-driver, driver, and PA can be switched off from the TX microprocessor. When this is done, the output power will be attenuated more than 60 dB .

## OUTPUT FILTER

The output filter consists of six lowpass filters, a directional coupler, a tune/transmit switch, and a TX/RX switch.
From the power amplifier the signal is fed to a lowpass filter, which attenuates all harmonics. Then the signal passes a directional coupler, which gives information about the standing wave ratio to the TXprocessor unit.
After the directional coupler the signal is fed to a drive/transmit switch. In position drive the output power is fed to a 50 ohm load. This load is used to set the output power to the correct value.
After this switch the signal is fed to the TX/RX switch.
In position RX the signal from the aerial coupler AT2110 or the aerial is fed directly to RE2100. In position TX the signal from RE2100 is fed to the input of the power amplifier and the output power is fed to the aerial coupler AT2110 or the aerial

## TX PROCESSOR

The processor takes care of controlling the power amplifier, output filters, aerial coupler AT2110, and communication with RE2100
From RE2100 the TX-processor receives information about frequency and receive/transmit mode. The TX-processor gives information to RE2100 about tuning/tune ready and attenuator setting.
During tune-up the TX-processor is controlling the aerial coupler. It tunes for best standing wave ratio measured with the directional coupler on the output filter module.
During transmit the TX-processor is checking the temperature of the PA-transistors, supply voltage, and stating wave ratio. From these data the TX processor calculates the max. permissible power, and then sends this information to the RE2100, where the processor unit sets the attenuator in the exciter unit to the correct value.

## POWER SUPPLY

This unit consists of two power supplies and the AF-amplifier.
The 24 V DC is first fed to a relay which switches off/on the supply to the power supplies.
One switch mode power supply is used to generate $\pm 18 \mathrm{~V}$ and 9 V for all small signal circuits in T 2130 and RE2100. The supply for the power amplifier and the AF-amplifier passes through a serial regulator, which limits the voltage to max. 28 V .

## CONNECTION BOARD

The connection board is the interface to the aerial coupler AT2110, HF SSB RE2100, 24V mains, and other units e.g. loudspeaker, muting of ext. receivers etc.
All input and output from ext. equipment are made through an optocoupler, a relay, or a transformer.

## BLOCK DIAGRAM T2130



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2 INSTALLATION MECHANICAL HF SSB TRANSMITTER T2130
2.1 MOUNTING POSSIBILITIES/DIMENSIONS AND DRILLING PLAN


25889B


25891A


Free space for air circulation.
Ambient temperature:
Max. $40^{\circ} \mathrm{C}$.
Weight: T2130: 14 kg

Free space for air circulation and cable entry.


25890A


26197A

### 2.1.1 INSTALLATION HINTS

The HF SSB Transmitter T2130 has to be installed vertically because it is convection cooled.
To ensure free airflow inside the transmitter, at least 100 mm free space is necessary at the top of the cover. At the bottom of the transmitter, 100 mm free space is necessary for cable lead-in.
In order to facilitate the installation, dismantle the turnable inner chassis (see the section 4.0. MECHANICAL DISASSEMBLING). Then install the back plate with the connection board PCB as described in section 2.1. MOUNTING POSSIBILITIES/DIMENSIONS AND DRILLING PLAN.

When all cables have been connected according to the cable plans in question, reinstall the turnable inner chassis and complete the installation by executing the function check (see the section 3.8. FUNCTION CHECK).


25958D

### 2.2.2 BATTERY REQUIREMENTS FOR GMDSS

## 6 HOURS REQUIREMENT:

The radio batteries must have sufficient capacity to supply the radio station for 6 hours ( 3 hours transmit and 3 hours standby).
When the battery is drained in 6 hours, instead of the normal 20 hours, you have add $20 \%$ to the capacity given be the manufacture.
The three hours transmit has to be in telex mode ARQ.

| Equipment | Mode | Current | Battery capacity |
| :---: | :---: | :---: | :---: |
| T2130/DSC | transmit | 15 A | 45 Ah |
| T2130/DSC | standby | 1 A | 3 Ah |
| VHF/DSC | transmit | 7 A | 21 Ah |
| VHF/DSC | standby | .33 A | 1 Ah |
| EMERGENCY LIGHT | on | 1 A | 6 Ah |
| GPS RECEIVER | on | 1 A | 6 Ah |
| TOTAL6 HOURS |  |  | $82,0 \mathrm{Ah}$ |
| $+20 \%$ |  |  | 98.4 Ah |

If you chose to make a installation without AC power supply N2161. Then you must have a battery charger large enough to ensure, that you not will drain your batteries during transmission. That gives a charger requirement of 25 amp . The maximum allowable charge current is $10 \%$ of the battery capacity. When the charger can give 25 amps the battery capacity must be 250Ah.

## We recommend 250Ah battery capacity.

If you chose to make a installation with AC and DC power supply N2161. Then you must have a battery charger large enough to ensure, that you can charge your batteries, within 10 hours. That gives a charger requirement of 10 amp .
The maximum allowable charge current is $10 \%$ of the battery capacity.
We recommend 100Ah battery capacity.

## 1 HOUR REQUIREMENT:

The radio batteries must have sufficient capacity to supply the radio station for 1 hour ( 0.5 hours transmit and 0.5 hours standby).
When the battery is drained in 1 hour, instead of the 24 hours, you have add $50 \%$ to the capacity given be the manufacture.
The half hour transmit has to be in telex mode ARQ.

| Equipment | Mode | Current | Battery capacity |
| :---: | :---: | :---: | :---: |
| T2130/DSC | transmit | 15 A | 7.5 Ah |
| T2130/DSC | standby | 1 A | 0.5 Ah |
| VHF/DSC | transmit | 7 A | 3.5 Ah |
| VHF/DSC | standby | .33 A | .17 Ah |
| EMERGENCY LIGHT | on | 1 A | 1 Ah |
| GPS RECEIVER | on | 1 A | 1 Ah |
| TOTAL 1 HOURS |  |  | 13.7 Ah |
| $+50 \%$ |  |  | 20.6 Ah |

If you chose to make a installation without AC power supply N2161. Then you must have a battery charger large enough to ensure, that you not will drain your batteries during transmission. That gives a charger requirement of 25 amp .
The maximum allowable charge current is $10 \%$ of the battery capacity. When the charger can give 25 amps the battery capacity must be 250Ah.

## We recommend 250Ah battery capacity.

If you chose to make a installation with AC and DC power supply N2161. Then you must have a battery charger large enough to ensure, that you can charge your batteries within 10 hours. That gives a charger requirement of 3 amp .
The maximum allowable charge current is $10 \%$ of the battery capacity.
We recommend 60Ah battery capacity.

### 2.2.3 AERIAL AND RF GROUNDING REQUIREMENTS

## AERIAL

Most important for good communication is the aerial. The best efficiency of the aerial will be with the aerial coupler AT2110 mounted outdoors close to the footpoint of the aerial and the aerial placed as high and free as possible. The aerial coupler AT2110 has to be grounded carefully.

## AERIAL LENGTH

Max. length 15 metres, min. length 7 metres. Aerial length measured from insulator on AT2110 to the top of the aerial.

If the transmitter has to work mainly on frequencies below 4 MHz a total aerial length of 12-14 metres is recommended.

If the transmitter has to work mainly on frequencies higher than 4 MHz an 8.5 m whip aerial is recommended.

## GROUND

AT2110 has to be grounded at the footpoint of the aerial.
If a metal wheel house, weld up a pillar for AT2110 and bolt it to the pillar. This is the best way of getting a good ground for the aerial system.

If a wooden or fibre glass boat, connect all accessible metal parts together and connect them to the aerial coupler with a copper strip ( $100 \times 0.5 \mathrm{~m}$ ) making the copper strip as short as possible. You can also make an artificial ground under the aerial as shown in example 5.

Example 1. AT2110 mounted on top of a wheel house with a whip aerial.


AT2110 has to be grounded through the two lower mounting holes.

Example 2. AT2110 mounted on top of a wheel house with wire aerial.


Example 3. AT2110 mounted on top or a mast.

AT2110 has to be grounded to the mast if a metal mast.

If $h>8 m$ then the coax cable works as ground and an acceptable performance will be obtained.

If $\mathrm{h}<8 \mathrm{~m}$ then a copper strip $(10 \times 0.5 \mathrm{~mm})$ has to be connected from AT2110 to ground. (See chapter GROUND).


## Example 4. AT2110 mounted on a sailing ship.



4-0-25237

AT2110 has to be grounded to the metal handrail or other metal parts.

## Example 5. AT2110 mounted on top of building.



### 2.2.4 MAIN CABLE PLANE WHEN SUPPLIED FROM 24V BATTERY.



### 2.2.5 MAIN CABLE PLANE WHEN SUPPLIED FROM 12V DC BATTERY, USING N2160 12V DC TO 24 V DC CONVERTER.



### 2.2.6 MAIN CABLE PLAN WHEN SUPPLIED FROM AC, USING N2161 AC TO 24V DC POWER SUPPLY. <br> MAIN CABLE PLAN WHEN SUPPLIED BOTH FROM AC AND DC (N2161).






1-2 Mute Out
Relay contact closed when
transmitting
transmitting.
3-4 TX-key
Optocoupler:
$12 \mathrm{~V} \leq$ Vin $H$ igh $\leq 22 \mathrm{~V}$
$10 \mathrm{~mA} \leq$ lin High $\leq 20 \mathrm{~m}$
$-1 \mathrm{~V} \leq$ Vin Low $\leq 2 \mathrm{~V}$
$5-6 \mathrm{RF}$ On/Off
Optocoupler:
$12 \mathrm{~V} \leq \mathrm{Vin} H$ igh $\leq 15 \mathrm{~V}$
$12 \mathrm{~V} \leq \mathrm{Vin} H i g h \leq 15 \mathrm{~V}$
$25 \mathrm{~mA} \leq$ lin $\operatorname{ligh} \leq 35 \mathrm{~mA}$
$-1 \mathrm{~V} \leq$ Vin Low $\leq 2 \mathrm{~V}$
$7-80 \mathrm{dBm}$ out
Transformer:
$600 \mathrm{ohm}, 0 \mathrm{dBm}$

9-10 Aux AF in Tx
Transformer:
600 ohm, leve
level 0 to 10 dBm

11-12 Mute RX In Relay Coil
Max. voltage: $35 \mathrm{~V}, 20^{\circ} \mathrm{C}$
Min. voltage: $9 \mathrm{~V}, 20^{\circ} \mathrm{C}$
Coil resistance: 2250 ohm $\pm 300$ ohm

13-14 Loudspeaker
8 ohm, max. power 10W
14-16 Ext. Loudspeaker
8 ohm, max. power 10W

Note 1,2 and 3

| Distance in meters | 1.3 | 2 | 3.2 | 5 | 8 | 10 | 13 | 16 | 24 | 34 | Mains fuse |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Copper cable dimensions in $\mathrm{mm}^{2}$ |  |  |  |  |  |  |  |  |  |  |  |
| Note 1 <br>  <br>  | 1.5 | 2.5 | 4 | 6 | 10 | 10 | 16 | 16 | 25 | 35 |  |
| Note 2 <br> N2161 AC supply cables 220 AC approx 3 | 1.5 | 1.5 | 1.5 | 1.5 | 1.5 | 1.5 | 1.5 | 1.5 | 1.5 |  | 108 |
| 110 V Ac approx 6 A | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 |  | 10a |
| Note 3 N2160 DC supply cables 12 DC approx 50A | 4 | 6 | 10 | 16 | 25 | 35 | 50 | 70 | 95 | 120 |  |


| Cable between T2130 and re2100 |  |  |  |
| :---: | :---: | :---: | :---: |
| Cable specifikations: Factory supplied, 10 metres $21 \times 0,25 \mathrm{~mm}^{2}$ Up to 15 metres cable lenght use $21 \times 0,25 \mathrm{~mm}^{2}$ cable.Up to 30 metres cable lenght use $21 \times 0,5 \mathrm{~mm}^{2}$ cable. ngt use $210,5 \mathrm{~mm}^{2}$ cable. |  |  |  |
| T2130 | RE2100 |  |  |
| sT2 | J3 | colour | signal |
| 1 | 1 | Black | mute Rx |
| 2 | 15 | Yellow/brown | VF/AE-CURRENT |
| 3 | 11 | violet | +9v |
| 4 | 12 | Grey | ${ }_{+18 \mathrm{~V}}$ |
| 5 | 13 | White | Suppiy on/orf |
| 6 | 14 | Pink/brown | mic key |
| 7 | 2 | Brown | af to amp common |
| 8 | 16 | Brown/green | $\mathrm{AF}^{\text {a }}$ то AMP |
| 9 | 17 | Brown/grey | oabm our common |
| 10 | 20 | White/green | AUX AF |
| 11 | 19 | White/yellow | rf-Gain control |
| 12 | 18 | White/pink | Oавm |
| 13 | 21 | white/blue | tX-KEX |
| 14 | 10 | в1ue | -18V |
| 15 | 25 | Red/blue | -batr. |
| 16 | 6 | Red | SP--buS interrupr |
| Chassis | 5 | screen |  |


| Cable between T2130 and AT2110 |  |  |
| :---: | :---: | :---: |
|  |  |  |
| T2130 | AT2100 | Signal |
| ST1 | ST01 |  |
| 1 | 1 | +21v |
| 2 | 2 | +21v |
| 3 | 3 | AE-CURRENT/180 PULSE |
| 4 | 4 | GND |
| 5 | 5 | clock |
| 6 | 6 | Data |
| 7 | 7 | MOTOR+ |
| 8 | 8 | ova |
| 9 | 9 | ova |
| 10 | 10 | ova |


| Cable between T2130 and C2140 |  |  |
| :---: | :---: | :---: |
| For cable specifications: see manual for C2140 (2.3) |  |  |
| T2130 | C2140 |  |
| ST7 | ST1 | Signal |
| 1 | 1 | aUX af to tx |
| 2 | 2 | AUX AF To tx |
| 3 | 3 | OdBm |
| 4 | 4 | OdBm |
| 5 | 5 | gain control |
| 6 | 6 | aE CURRENT/STGNAL |
| 7 | 7 | SP-BuS interrupt |
| 8 | 8 | -24V DC |
| 9 | 9 | +24V DC |
| 10 | 10 | GND |

### 2.2.11 CONNECTIONS TO RE2100



25816

J03-5
Pin no. 1
Pin no. 2 AF to AMP common
Pin no. 3
Pin no. 4
Pin no. 5 GND
Pin no. 6 SP BUS interrupt
Pin no. 7
Pin no. 8
Pin no. 9 AUX AF to TX common
Pin no. $10-18 \mathrm{~V}$
Pin no. $11+9 \mathrm{~V}$
Pin no. $12+18 \mathrm{~V}$
Pin no. 13 Supply on/off
Pin no. 14 Mic key
Pin no. 15 VF/AE-current
Pin no. $16 \quad \mathrm{AF}$ to AMP
Pin no. 170 dBm out common
Pin no. 180 dBm out
Pin no. 19 Ext. RF control
Pin no. 20 AUX AF to TX
Pin no. 21 RF on/off
Pin no. 22 GND
Pin no. $23+9 \mathrm{~V}$
Pin no. $24+18 \mathrm{~V}$
Pin no. 25 -battery

J03-2

| Pin no. 1 | Telephone | Red |
| :--- | :--- | :--- |
| Pin no. 2 | GND | Yellow |
| Pin no. 3 | Signal GND | White |
| Pin no. 4 | Mic | Blue |
| Pin no. 5 | Mic key | Brown |
| Pin no. 6 | Ext. SQ on/off |  |
| Pin no. 7 | Distress |  |
| Pin no. 8 | Ser.+ |  |
| Pin no. 9 | $+18 V$ |  |

### 2.2.12 CONNECTIONS TO AT2110



## WIRE STRIPPING FOR TRIAXIALCABLE H1213



MULTICABLE: Max. diameter ø 14.5mm
Length:
0-50m
Type:
50-100m
$10 \times 0.5 \mathrm{~mm}^{2}$
$10 \times 1 \mathrm{~mm}^{2}$

### 2.2.13 CONNECTIONS TO N2161



26199

MAINS TO N2171:
220V MAINS:Current: approx 6 Amp
Mains fuse min. 10 Amp
$3 \times 1.5 \mathrm{~mm}^{2}$ max. length 12 metres
110V MAINS-Current: approx 12 Amp
Mains fuse min. 16 Amp
$3 \times 2.5 \mathrm{~mm}^{2}$ max. length 10 metres

| CONNECTION BOARD (5) | SIGNAL |
| :---: | :---: |
| ST1 and ST2 | GND |
| 1 | GIVE |
| 2 | NEUTRAL |
| 3 |  |

CABLE 12
BATTERY TO T2131:
When N2170 is in a separate cabinet. Use following cable: $2.5 \mathrm{~mm}^{2}$ max. length 10 metres.

When N 2170 is in the same cabinet as T2131.
Use cable as shown in the table bellow:
Current consumption: 50 Amp.


## CABLE 18

MAINS TO N2174:
220V MAINS:Current: approx 8 Amp Mains fuses 16 Amp
$3 \times 1.5 \mathrm{~mm}^{2}$ max. length 12 metres 110V MAIS:Current: approx Mains fuses 25 Amp
$3 \times 2.5 \mathrm{~mm}^{2}$ max. length 10 metres

| N2174 | SIGNAL |
| :---: | :---: |
| ST2 |  |
| 1 | GND |
| 2 | LINE |
| 3 | NEUTRAL |

## CABLE 19

## N2174 TO H2180

Multicable: $6 \times 0.75 \mathrm{~mm}^{2}$ max. length 15 metres Multicable: $6 \times 1.5 \mathrm{~mm}^{2}$ max. length 30 metres

| N21744 | H2180 | SIGNAL |
| :---: | :---: | :---: |
| ST7 |  |  |
| 1 | 1 | - SHUUT |
| 2 | 2 | + SHUNT |
| 3 | 3 | -VS |
| 4 | 4 | MAN |
| 5 | 5 | 26V |
| 6 | 6 | AUTO |

## CABLE 20

N2174 TO H2182/H2183 (SHUNT)
$4 \times 1.0 \mathrm{~mm}^{2}$ max. length 10 metres
$4 \times 2.5 \mathrm{~mm}^{2}$ max. length 25 metres

| N2174 |  |  |  |
| :---: | :---: | :---: | :---: |
| ST6 | ST4 | ST10 |  |
| 1 | 1 | 1 | vs |
| 2 | 2 | 2 | + vs |
| 3 | 3 | 3 | T |

## CABLE 21

N2174 TO H2182/ (BATTERY):

+ BATT. and - BATT. cable dimensions in $\mathrm{mm}^{2}$ Current 30A

| LENGTHIN <br> MTRES | 8 | 13 | 22 | 30 | 40 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CABEE |  |  |  |  |  |
| DIMENSION | 10 | 16 | 25 | 35 | 50 |

## CABLE 22

H2182 to battery:

+ BATT. and - BATT. Cable dimensions in $\mathrm{mm}^{2}$ Current approx. 70A

| LENGTHIN <br> METRES | 2.5 | 4 | 6 | 8 | 12 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CABLE <br> DIMENSION | 16 | 25 | 35 | 50 | 70 |

## CABLE 26

N2174 TO H2182/H2183
(Temperature sensor)
Multicable: $2 \times 0.5 \mathrm{~mm}^{2}$ max. length 50 metres

| N2174 |  |  | SIGN |
| :---: | :---: | :---: | :---: |
|  | ST2 | ST8 |  |
| 1 | 1 | 1 |  |



## CONNECTIONS TO BATTERY CHARGER N2174



### 2.3 SYSTEM DESCRIPTION AND TROUBLE SHOOTING

## ERROR MESSAGES

The error messages are displayed in the upper part of the display in the RE2100.
Table 1 indicates the possibly faulty units. An asterisk in parenthesis indicates the alternative unit where the error also may be found.

Table 1

| ERROR | RE2100 | T2130 | AT2110 |
| :---: | :---: | :---: | :---: |
| 70 |  | ${ }^{*}$ | ${ }^{*}$ |
| 71 | $*$ | ${ }^{*}$ |  |
| 72 | $*$ | $\left({ }^{*}\right)$ |  |
| 73 |  | $\left({ }^{*}\right)$ | ${ }^{*}$ |
| 74 |  | ${ }^{*}$ |  |
| 75 |  | $\left({ }^{*}\right)$ | ${ }^{*}$ |
| 76 |  | ${ }^{*}$ |  |
| 77 |  | ${ }^{*}$ |  |
| 78 |  | ${ }^{*}$ |  |

The error messages numbered from 70 to 78 are generated by the TX-processor and mainly related to the T2130 and the AT2110. For the detailed error description please refer to the section 3.4.1. REPLACEMENT OF COMPONENT.

### 2.3.3 SYSTEM FUNCTIONAL DESCRIPTION

This section describes mainly the overall functions of the software in the T2130.
The main functions are described in sections, where section 2.3.3.1. SP-BUS COMMUNICATION TO 2130 is a common section to be read in conjunction with the others.
In order to have the full understanding of the mode of operation of the T2130, section 2.3.3. SYSTEM
FUNCTIONAL DESCRIPTION has to be read together with section 5. CIRCUIT DESCRIPTION.
This section describes the following functions:

- 2.3.3.1 SP-BUS COMMUNICATION TO T2130
- 2.3.3.2 AUTOMATIC POWER SETTING
- 2.3.3.3 TUNING THE AT2110
- 2.3.3.4 TRANSMIT SUPERVISING
- 2.3.3.5 CALIBRATION OF THE T2130


### 2.3.3.1 SP BUS COMMUNICATION TO T2130

The SP-Bus is a time-multiplexed serial data bus. The RE2100 is the master and the T2130 is one of several slaves. The T2130 is assigned a given slave address. RE2100 initiates and controls all communication to the T2130. This means that all activities performed in T2130 is controlled by the RE2100.

The T2130 may receive a number of commands according to the expected action in the T2130. When the T2130 has received a message it must replay immediately. The T2130 has four different options to answer the RE2100:

A: The received command is understood and is executed.
B: The received command is understood and T2130 is busy executing the command.

C: The received command is understood and is executed. The T2130 has information for the RE2100.

D: A communication error is detected. The command is not executed. The error can be a parity error or a message length error.

The answer options A, B, and C may be followed by information related to the specific command. If the T2130 does not answer the RE2100, the RE2100 is repeating the command a number of times. If the T2130 does still not answer, an error (Error 20) will occur in the display in the RE2100.

## COMMANDS AND ANSWERS.

In the following the commands to the T2130 and the answers from T2130 are described.

SYNCRONIZE/STATUS AND ERROR CODE
This command/answer is used in two situations:

- When the power has been switched on at the RE2100, the RE2100 detects the existence of possible slaves.
- When the T2130 has detected an error the T2130 has answered the previous message with the answer option (C). This results in a synchronized message from the RE2100.


## RECEIVER FREQUENCY

Whenever the received frequency has been changed at the RE2100, the frequency is sent to the T2130. The T2130 ensures that a transformer is switched in at receiver frequencies below 4000 kHz and switched out at frequencies above 4000 kHz .

## KEY

This command is sent continuously to the T2130 when the handset key is activated at the RE2100. The first time it is sent the command is followed by the actual transmitter frequency and the selected mode (telex etc.) at the RE2100. The answer is option (A). The following commands are sent without associated data. There are two different answers depending on the state of the T2130. In both states the T2130 has the full control of the step attenuator placed in the Exciter Unit (4) in the RE2100.

- State one. Indicates that the T2130 and the AT2110 are NOT ready to transmit.

The answers consist of the answer option (B) associated with an absolute step.
The duration of this state is given by the duration of the automatic power setting and the tuning of the AT2110.

- State two. The T2130 and the AT2110 are ready to transmit.

The answers consist of the answer option (A) associated with an absolute step.
This state continues until the key is released and the 'Stop' command is sent from the RE2100.

## TUNE

This command is a subset of the 'Key' command. Only state one is performed followed by the 'Stop' command. The command is only sent from the RE2100 when the 'TX' and 'Tune' keys are activated.

## DUMMY LOAD KEY

This command is equal to the 'Key' command except for the RF output power.
The RF output power is delivered to the AT2110 built-in dummy load instead of the connected aerial.

## DUMMY LOAD TUNE

This command is equal to the 'Tune' command except for the RF output power. The RF output power is delivered to the AT2110 built-in dummy load instead of the connected aerial.

## STOP TUNE/KEY

This command always terminates the above mentioned 4 variants of the 'Tune' and 'Key' commands. The answer is option (A). The command is sent from the RE2100 at one of the following events:

- When the handset key is released after a transmit period.
- When the T2130 is ready to transmit after the 'TX' and 'Tune' keys have been activated.
- When the 'Enter/Stop' key is pressed while the Automatic Power setting or the tuning of the AT2110 takes place.


## OPEN AERIAL

This command sets the relays in the AT2110 so that the aerial is disconnected from the HF SSB radiotelephone.

## SERVICE

This command is always given associated with a service subcommand. There are several service subcommands, each corresponding to a given Service Programme. The answer consists of option (A) or (B) followed by 5 ASCII characters which are displayed in the lower part of the display in the RE2100.

### 2.3.3.2 AUTOMATIC POWER SETTING

## MOTIVE FOR THE AUTOMATIC POWER SETTING

The automatic setting of the power level is done to ensure the maximum RF-level out of the transmitter T2130, regardless of

- variations in the RF-level out of the RE2100 exciter,
- RF-loss due to long cables between RE2100 and T2130,
- variations in the gain in the Power Amplifier from one to another,
- variations in the gain in the Power Amplifier due to the frequency,
- variations in the loss in the Output Filter module from one to another,
- variations in the loss in the Output Filter module due to the frequency,
- battery voltage supplying the Power Amplifier.
(variations in the DC loss in the Power Supply).


## PRINCIPLES FOR THE AUTOMATIC POWER SETTING

The RF-level out of the RE2100 exciter is increased in steps until a predetermined maximum allowable Vforward level out of the Output Filter (2) is reached.

## EVENTS FOR STARTING THE AUTOMATIC POWER SETTING

The automatic power setting is done because of one of the following events:

- The TX-frequency is changed and the key on the handset has been activated.
- The TX-Tune key on the keyboard is pushed.
- The time elapsed since latest automatic power setting is more than approx. 4 minutes.


## NECESSARY SIGNALS AND PARAMETERS

- Vforward.

The RF-level is measured by SWR-detector circuitry on the Output Filter (2) and is mentioned as 'Vforward'. Vforward is measured by the TX-processor (3) by means of an analog to digital converter.

- Vforward maximum.

The predetermined maximum allowable Vforward level is composed of a number of parameters. This composition of the maximum allowable Vforward is described in a section below. In the following it is assumed that the maximum allowable Vforward has already been calculated.
The predetermined maximum allowable Vforward level will in the following sections be mentioned as Vf_ max (Vforward maximum).

- RF level control.

A digitally controlled step attenuator with 64 steps, each step is approx. 0.3 dB , is placed in the Exciter Unit (4) in the RE2100. During the automatic power setting the TX-processor (3) in the T2130 has the full control of the step attenuator via the SP-Bus and the Processor Module (5) in the RE2100.

## FUNCTIONAL DESCRIPTION OF THE AUTOMATIC POWER SETTING

When the automatic power setting is about to start the step attenuator in the Exciter Unit (4) is preset to step 43 by the answer to the first 'Tune' command.
The automatic power setting may now take place in 2 or 3 states, depending on the initial measured Vforward (step 31) related to the Vf_max.

- State 1 is always run as the first state.
- State 2 is run when the RF-level has to be increased one or several steps.
- State 3 is always run as the last state in the automatic power setting.


## STATE 1

The Vforward level (step 43) is measured by the TX-processor and compared to 4 different levels:

- A minimum level.

If Vforward is lower, then an error is generated. The Vforward level is too low.

- Vf_max-0.6dB.

If Vforward is lower, then a number of steps is calculated for increasing the RF-level out of the Exciter. The calculation is described below. The automatic power setting continues at state 2.

- Vf_max.

If Vforward is lower or equal to, then the step is increased with one, The automatic power setting continues at state 2.

- Vf_max +0.3 dB .

If $\overline{\text { Vforward }}$ is lower, then the automatic power setting
continues at state 3 . Else an error is generated. The Vforward level is too high.

## STEP CALCULATION

In order to reduce the time used for the automatic power setting the RFlevel is increased a number of steps initially. The number of steps ' $n$ ' is calculated in the following way:

Vf_max $=10((\mathrm{~A} / 20))$ * $n$
Vforward
Where A is the resolution of the step attenuator in dB . Theoretically A should $\mathrm{be}=0.3 \mathrm{~dB} /$ step. However, there is some compression in the amplifiers, etc. involved. Iterations have shown that $A=0.43 \mathrm{~dB} /$ step is suitable in order to reach the correct power level in an acceptable time without overshooting.

## STATE 2

In this state the RF-level is increased one step at a time and compared to 2 different levels:

- Vf_max.

If Vforward is higher then the automatic power setting continues at state 3.

- The previous measured Vforward +0.12 dB .

If Vforward is lower then the automatic power setting continues at state 3.
Else state 2 is repeated.
This specification compared to the previous Vforward +0.12 dB is performed to ensure that the increasing of the Vforward is stopped if there has been an increase less than 0.12 dB . This may occur when the Power Amplifier (1) has begun cumpressing the signal. The compressing of the signal gives distortion and reduces the intermodulation.

STATE 3
This state is run when the Vforward was measured to be one step too high. RF-level is reduced one step because the previous level was too high.
Depending on which event has started the automatic power setting the RFlevel is reduced further. If an AT2110 is in the system, (jumper 5 is not inserted) Vforward is further reduced 20 steps (approx. 6 dB ) in order to protect the Power Amplifier (1) while tuning the AT2110.

## CALCULATING VFORWARD MAXIMUM

Vf_max is compounded of 4 parameters:

- A value (Vf_max1) calculated from the Vforward - Vbattery equation (the graph in fig. 1).
- An addition (Vf_max2) as a result of the calibration. The calibration procedure is described in section 2.3.3.5 CALIBRATION OF THE T2130
- An addition (Vf_max3) related to the frequency.
- A reduction (Vf_max4) because of reduced power.

Vf_max is found in the following way:

- Vfmax5 = Vf_max1 + Vf_max2 + Vf_max3
- Vf_max $=$ the lowest of Vf_max4 and Vf_max5

In the following the parameters are described separately.

## Vf_max1 (VFORWARD - VBATTERY EQUATION)

The Vforward maximum is depending on the present Vbattery. The graph in fig. 1 shows the coherence of the Vbattery and the maximum allowable Vforward.


26190

Fig. 1. Nominal values of Vbattery, Vforward maximum.

The graph consists of two linear parts. Part 1 is valid for a Vbattery < 26.5 Volt and has the following equation:

$$
\text { Vf_max1 }=0.33 \text { * Vbattery }+0.20 \text { (Volt) }
$$

Part 2 is valid for a Vbattery >= 26.5 Volt and has the following equation:

$$
\text { Vf_max1 = } 9.00 \text { (Volt) }
$$

Vbattery is measured by the TX-processor. This is described in section 2.3.3.5. CALIBRATION OF THE T2130.

## Vf_max2

The addition due to the result of the calibration may be either positive or negative. The principles for the calibration of the T2130 are described in section 2.3.3.5. CALIBRATION OF THE T2130.

## Vf_max3

This addition is made in order to reduce the variations in the gain in the Power Amplifier (1) and the variations in the loss in the Output Filter (2).
The addition may either be positive or negative. There are 6 different additions which may be added. One for each frequency range covered by the lowpass filters in the Output Filter Module (2). The addition for the frequency range $1.6-2.599 \mathrm{MHz}$ is always 0 as 1.6 MHz is used as a reference.

## Vf_max4

This is in fact not an addition. It is possible to reduce the RF PEP power out of the transmitter in a few steps by means of the Service Programmes.
When the power is not reduced the Vf_max4 has a value which is always higher than Vf_max5.
When the power is reduced the Vf_max4 has a fixed value corresponding to the selected PEP power level.

### 2.3.3.3 TUNING THE AT2110

The tuning may take place in 3 different procedures:

- Uptune, where a tuning is done from basic data.
- Retune, where the tuning is done from data saved at the latest Uptune.
- $\quad$ No tune, which is done when there is no AT2110 in the system (jumper 5 is inserted).


## UPTUNE PROCEDURE

This is the basic tune procedure for tuning the AT2110. The conditions for an uptune procedure are the following:

- 'TX TUNE' is entered on the keyboard on the RE2100.
- The frequency has not been tuned before. This means that there is no valid data in the EEPROM's for the specific 200 kHz band in which the frequency is.
- The retune procedure did not work out. The retuning could not be done with the data saved in the EEPROM's. The measured Standing Wave Ratio (SWR) was too high. The aerial conditions may have been changed since the latest uptune of a frequency in the 200 kHz band concerned, or the data saved in the EEPROM's are deleted by use of the Service Programmes.

The uptuning may take place in up to 6 states. The states are sequently executed until the uptuning is accepted.

1. The relays in the AT2110 are set so the RF-signal is fed straight through the coupler. This means that no resonance (inductance, (L)) or load (capacitance, (C)) is active.If the SWR (Standing Wave Ratio) is better than or equal to 2.0 the tuning of the aerial is accepted. A possible previously saved combination is deleted from the EEPROM's.
If jumper 4 on the TX-processor (3) is inserted this 'signal straight through' combination will NOT be tested.
2. A sequence of shifting the resonance and the load in a certain pattern is run through. For each frequency band ( 200 kHz ) a number of combinations of fixed resonance values (L) and fixed load values (C) are switched in.
For every combination of a fixed resonance and a fixed load the variable capacitor is run through the working range.
Within the working range of the variable capacitor the SWR is measured and compared continuously to certain limits.

The first combination always contains the highest value of the resonance (most L is in) and the lowest value of the load (least $C$ is in).
The next combinations contain each a decreasing value of the resonance and the lowest value of the load.

When the lowest value of resonance has been tested the next higher value of load is switched in and all the resonance values are tested again.

The variable capacitor is activated by the tune motor MO1. The motor may run at high speed or al low speed. In the following mentioned as 'high tune speed' and 'low tune speed'.
With the tune speed high the SWR is measured and compared continuously to the following limits and different actions may take place:
$1.0<$ SWR < $=1.5$.
The actual combination of resonance and load is kept and the tune speed is changed to low. The variable capacitor is run through its variation range again. When the SWR limit is passed again, the tune motor is stopped immediately and the tuning is accepted. The found combination of resonance and load and the SWR limit are saved in the EEPROM's for a later retune procedure.

$$
1.5<\text { SWR }<=2.0
$$

The actual combination of resonance and load is remembered by the processor in order to tune with the low speed later.
$2.0<$ SWR < = 2.5.
The actual combination of resonance and load is remembered together with a flag indicating that the SWR is in the range $2.0<S W R<=2.5$ by the processor in order to tune with the low speed later.
3. If no combination could give an $\mathrm{SWR}<=1.5$ the remembered combinations giving an $\mathrm{SWR}<=2.0$ are tested at low tune speed.
The SWR is measured and compared to the following limits and different actions take place:
$1.5<$ SWR < $=1.7$.
The tune motor is stopped immediately and the tuning is accepted.
The found combination of resonance and load and the SWR limit are saved in the EEPROM's for a later retune procedure.
4. If no combination could give an $\mathrm{SWR}<=1.7$ the remembered combinations giving an $\mathrm{SWR}<=2.0$ are tested again at low tune speed.
The SWR is measured and is now compared to the following limit:
1.7 < SWR <= 2.0

The tune motor is stopped immediately and the tuning is accepted.
The found combination of resonance and load and the SWR limit are saved in the EEPROM's for a later retune procedure.
5. If no combination could give an $S W R<=2.0$ the remembered combinations giving an $S W R$ in the range $2.0<$ SWR <= 2.5 are tested at low tune speed.
The SWR is measured and is compared to the following limit:
SWR <= 2.5.
The tune motor is stopped immediately and the tuning is accepted.
6. If no combination could give an SWR $<=2.5$ the AT2110 relays are set to feed the RF-signal straight through the coupler and this is then accepted as an uptune. When the transmitter is keyed the RFpower is reduced accordingly to the actual SWR.

## RETUNE PROCEDURE

This is the tune procedure normally used. The conditions for a retune procedure are the following:

- A frequency within the same 200 kHz band has been tuned previously to an SWR <= 2.0. This means that valid data are read out of the EEPROM's and the aerial conditions have not changed essentially.

The data saved in the EEPROM's for a retune are divided into 142 elements. Each element equals a frequency band covering 200 kHz . For each 200 kHz band a relay combination and a code for the tuned SWR are saved.

The principles for a retune procedure are described in the following.
Data concerning the actual 200 kHz are read out of the EEPROM's and validated.
If the code for the SWR is not acceptable an uptune procedure is started immediately.
If the code for the SWR is valid then the codes for the SWR and the relays are converted. The specific relays are activated.

With the tune speed low the SWR is measured and compared continuously to the limit which is read out from the EEPROM's.
The SWR limit is 1.5 or 1.7 or 2.0 . The retune procedure will then always try to tune to the same SWR limit as the untune procedure. If however, this is not possible the retune will try to tune to the next higher limit. If it is not possible to tune to an SWR $<=2.0$ the uptune procedure is started immediately.

## NO TUNE PROCEDURE

This procedure is run only when there is no AT2110 connected to the T2130. In fact the jumper 5 on the TX-processor (3) must be inserted.

The only purpose for this routine is to measure the SWR and if the SWR <= 2.0 inform the RE2100 and the user.

### 2.3.3.4 TRANSMIT SUPERVISING

The motives for the supervising are as follows:

- Protection of the Transmitter T2130 against high SWR (bad aerial conditions).
- Protection of the power transistors in Power Amplifier (1) against damage caused by high temperature.
- Ensuring that the transmitter T2130 does always deliver maximum RF-power with a minimum of intermodulation regardless of variations in the battery voltage supplying the Power Amplifier (1).

When the Transmitter T2130 is keyed, certain parameters are watched by the TX-processor (3) and action is taken if the change of the parameters is essential. The following parameters are watched:

- SWR, Standing Wave Ratio
- Supply voltage to the Power Amplifier (1)
- Temperature in the Power Amplifier (1).

In general a change of any of the watched parameters causes a control of the RF-level input to the Power Amplifier.
While the transmitter is keyed the TX-processor has the full control of the digitally controlled step attenuator in the Exciter Unit (4) in the RE2100 via the SP-Bus and the Processor Unit (5) in the RE2100.

Each of the watched parameters results in a number of steps. The steps are simply added to the step found when the Automatic Power Setting was performed.

Where: act_step = actual step for the attenuator
APS_step = the step found at the Automatic Power Setting
n1 = deviation step related to SWR
n2 = deviation step related to Temperature
n3 = deviation step related to Battery Voltage
The subsections below describe each of the parameters watched.

## SWR WATCHING

When the T2130 is transmitting, the SWR is continuously watched. This means in terms that the TXprocessor (3) measures the Rho approx. 2500 times per second.

Note: Rho and SWR are two expressions describing the same physics.

The measured Rho is compared to two limits.
If $S W R>2.0$ (Rho $>0.333$ ) then a calculation takes place. The result of the calculation gives a number of 0.3 dB steps with which the RF-signal has to be reduced. The number of steps n 1 is given by:

If SWR $>5.0$ then the error message 'Bad SWR' is generated. The operator is informed when the key is released.

## TEMPERATURE WATCHING

The temperature at the power transistors in the Power Amplifier (1) is measured 4 times per second. The measured temperature is compared to two limits. If the temperature is above 980 Celcius a calculation takes place.
The result of the calculation gives a number of 0.3 dB steps with which the RF-signal has to be reduced. The number of steps n 2 is given by:
n2 $=$
Measured temperature $-98^{\circ} \mathrm{C}$
2
This means that a temperature increase of $20^{\circ} \mathrm{C}$ to $118^{\circ} \mathrm{C}$ reduces the RF power approx. 3 dB .
If the temperature is above $118^{\circ}$ Celcius the Power Amplifier (1) is blocked and the RF-power is reduced further approx. 60 dB . An error message is generated and when the key is released the operator is informed.
When the temperature has fallen to $100^{\circ}$ Celcius the Power Amplifier (1) is opened again.

## SUPPLY VOLTAGE WATCHING

The battery voltage is measured 4 times per second. The battery voltage is measured as described in section 2.3.3.5. CALIBRATION OF THE T2130.
A Vforward maximum (Vf_max) is found as described in section 2.3.3.2. AUTOMATIC POWER SETTING. The Vf_max is compared to the maximal Vforward (Vf_max_tun) found when the Automatic Power Setting was performed. When there is a certain difference (in dB ) the step attenuator is controlled accordingly.
As there is a certain compressing of the RF-signal in the Power Amplifier (1) a certain change (in dB) of the Vf_max (due to a change in the battery voltage) will give a small change of the input RF-signal to the Power Amplifier. This means that if the supply voltage has increased so much that the Vf_max is 0.6 dB higher than the Vf_max found at the Automatic Power Setting, the RF-input level must be increased by 0.3 dB .

The number of steps ( n 3 ) the step attenuator has to be changed due to change in the supply voltage is calculated in the following way:

$$
\begin{array}{ll}
\text { (Vf_---------------------------------------------1 } & \text { (n3 can be negative, } \\
\text { 10(0.6/20) }-1 & \text { zero, or positive). }
\end{array}
$$

In order to prevent fast oscillating in the automatic control of the step attenuator a decrease of the step due to higher battery voltage is delayed a few seconds.

### 2.3.3.5 CALIBRATION OF THE T2130

In practice the calibration is done by means of a Service Programme. Please refer to the Service Programmes. In the following the calibration is described functional.

## MOTIVE FOR THE CALIBRATION

The calibration is done in order to eliminate tolerances in specific components related to the measuring of the battery voltage and the Vforward voltage.

## PRINCIPLES FOR THE CALIBRATION

The principle for the calibration is as follows. With a given battery supply voltage the RF-output is increased until a specific distortion is reached. The battery voltage and the corresponding Vforward are measured and the differences between the measured and the nominal values are calculated.

## NECESSARY SIGNALS AND PARAMETERS

- Vbattery. This is measured by the TX-processor (3). The technique used by the TX-processor to measure the 24 Volt battery is discussed in a separate subsection below.
- Vforward. This is measured by the TX-processor (3).
- Nominal values. This covers the coherence between the battery supply voltage and the maximum allowable Vforward. For the description of the graph please refer to the subsection 'Calculating Vforward maximum' in section 2.3.3.2. AUTOMATIC POWER SETTING.


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Fig. 2. Nominal values of the Vbattery, Vforward maximum.

## FUNCTIONAL DESCRIPTION OF THE CALIBRATION

A Vbattery $=24,000$ Volt must be present at the '+' and the '-' 24 Volt battery terminals on the Connection Board (6).
The Service Programme for calibrating ensures that the two tone RF-signal is present at the internal dummy load in the T2130. The level of the two RF-signal is now increased by use of the keyboard on the RE2100 until specific requirements for the intermodulation is just fulfilled.
At this point the TX-processor is ordered to measure the actual battery voltage and the actual Vforward voltage. When this is done some calculations take place.
Concerning the Vbattery an offset is calculated. This offset is the difference between the nominal Vbattery and the meaured Vbattery.
Concerning the Vforward an offset is calculated. The offset is mentioned in the subsection above as Vf_max2.
Vf_max2 is the difference between the nominal value of Vf_max1 at Vbatt $=24,000$ Volt and the measured Vforward.

## MEASURING THE BATTERY VOLTAGE

As the battery is galvanic isolated from the ground it is not possible for the TX-processor to measure the battery voltage direct.
The TX-processor (3) is measuring the voltage ' +24 V Sense' and an offset is added. The offset added is a result of the calibration described in section 2.3.3.5. CALIBRATION OF THE T2130.
In the Power Supply (4) the ' +24 V Sense' is generated.
The DC to DC converter in the Power Supply is working after the 'Pulse Width Modulation' principle. The peak voltage on the secondary turn of the isolation transformer is then proportional to the voltage switched on the primary turn. The ' +24 V Sense' is then proportional to the battery voltage.

In the Service Programmes the measured ' +24 V Sense' is converted to voltage and read out to the display on the RE2100.
The relation between the battery voltage and the ' +24 V Sense' is determined empirical and is given by the following equation:
'+24V Sense' + Cal_offset = Vbattery * 1.31-0.95 (Volt)
giving:
Vbattery $=\begin{gathered}\text { '24V Sense' }+ \text { Cal_----------------------------------- } \\ 1.31\end{gathered}$ (Volt)

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## 3 SERVICE

### 3.1 MAINTENANCE

## PREVENTIVE MAINTANANCE

If SAILOR T2130 has been installed in a proper way the maintenance can be reduced to an overhaul at each visit of the service staff.
Then inspect the set, the antenna, cables, and plugs for mechanical damages, salt deposits, corrosion, and any foreign material.
Owing to its traditional structure, the SAILOR T2130 has a long lifetime, but it must always be carefully checked at intervals not exceeding 12 months - dependent on the conditions under which the set is working.

Along with each set a TEST-SHEET is delivered in which all the measurements, made in the test department of the factory, are listed. If the control measurings made in the service workshop should not show the same values as those listed in the test-sheet, the set must be adjusted as specified in chapter 3.6. ADJUSTMENT PROCEDURE.

### 3.2 ALIGNMENT INSTRUCTIONS

## INTRODUCTION

The measuring values indicated in chapter 5. CIRCUIT DESCRIPTION AND SCHEMATIC DIAGRAMS are typical values and as indicated it will be necessary to use instruments in absolute conformity with the below list:

### 3.3 PROPOSAL FOR NECESSARY MEASURING INSTRUMENTS

Tone Generator type PM5107
Electronic Multimeter type PM2505
RF Directional Wattmeter Model 43
250W Load with type
Oscilloscope type PM3216
Dummy load 50 ohm/250W
Power Supply 21-32V, 20A

PHILIPS
PHILIPS
BIRD
BIRD
PHILIPS

### 3.4 TROUBLE SHOOTING

SAILOR Compact HF SSB system has built-in self-diagnostic service system, which is a great help in locating a fault.

When a fault is detected an error message will be displayed in the RE2100 display.
The following description will help you to find the defective unit or module.
Trouble-shooting should only be performed by persons with sufficient technical knowledge, who have the necessary measuring instruments at their disposal, and who have carefully studied the operation principles and structure of SAILOR T2130.

The first thing to check is whether the fault is somewhere in the antenna circuit or power source.
When measuring in the units, short-circuits must be avoided as the transistors would then be spoiled.

## LOCATING THE FAULTY MODULE

## ERROR MESSAGES, DESCRIPTION

The error messages displayed in the RE2100 display are technically described in the following.

## 70. MOTOR CIRCUIT ERROR (AT2110)

An error is detected in the circuitry controlling the tune motor MO1 in the AT2110. The TX-processor has not detected the '180o pulse' from the AT2110.

The error may be one of several possibilities:
If the tune motor MO1 starts running immediately after the power is switched on at the RE2100:

- Check the level of the ' $180^{\circ}$ PULSE/AE-CURRENT' at ST01 pin 3, on the Connection Board (6) in T2130.

If the level is high (approx. 15 Volt):
The error is probably in the AT2110:

- Check the ' $180^{\circ}$ PULSE/AE-CURRENT' connection between T2130 and AT2110.
- Check the ' $180^{\circ}$ PULSE/AE-CURRENT' connection in the AT2110.
- Check the light in the optocoupler OC01 on the Main Board (1) in the AT2110. This may be done by measuring the voltage drop across the resistor R26 in the Connection and Interface module (3) in the AT2110.

If the level is low:
The error is probably in the T2130:

- Check the ' $180^{\circ}$ PULSE/AE-CURRENT' connection between the Connection Board (6) and the TX-processor (3) in the T2130.

If the tune motor MO1 does NOT start running immediately after the power is switched on at the RE2100:

- Check the voltage at ST01 pin 7 when the power is tuned on at RE2100. The voltage should be approx. 16 Volt.

If the 16 Volt is ok:
The error is probably in the AT2110:

- Check the connection to the tune motor MO1 in AT2110.
- Check the 'Motor +' connection between the T2130 and the AT2110.

If the 16 Volt is NOT present:
The error is probably in the T2130:

- Check the connection between the TX-processor (3) and the Connection Board (6) in T2130.


## 71. VFORWARD LOW

The level of the Vforward voltage is low ( $<0.7$ Volt) measured at the output of the SWR detector on the Output Filter (2).
SP-22-0 displays the latest measured Vforward.
The RF-signal is probably

## 72. VFORWARD HIGH

The level of the Vforward voltage is high.
SP 22-0 displays the latest measured Vforward.
Check the output level of the Exciter Unit (4) in the RE2100.
The error may also occur if the T2130 has been improperly calibrated.

## 73. HIGH SWR IN THE TUNING OF THE AT2110

It is not possible to tune the AT2110 to an SWR better than 2.5.

- Check the aerial.
- Check the RF-signal path from the Power Amplifier (1) in the T2130 to the aerial.
- Check the SWR detector on the Output Filter (2). Please refer to section 3.4.2. in the instruction manual for T2130.


## 74. TRANSMITTER TEMPERATURE HIGH

Ensure a free air flow at the bottom and at the top of the T2130 chassis.
SP 21-0 displays the state of the temperature protection function. Please refer to the Service Programmes.

- Check the idle current in the Power Amplifier (1). Please refer to section 3.4.1. in the instruction manual for T2130.
- Check the temperature measuring circuit. Please refer to section 3.5.3.1. A/D CONVERTER in the instruction manual for T2130.


## 75. HIGH SWR WHEN TRANSMITTING

This error may occur if the aerial has become bad since the latest uptune on the frequency or has become bad during a transmit period.
SP-23-0 displays the latest measured SWR.

## 76. BATTERY VOLTAGE LOW

The Power Amplifier (1) has been blocked due to low battery voltage.
During the period of the automatic power setting or when the transmitter has been keyed, the battery voltage has been measured to be lower than approx. 18 Volt.

- Check the battery, specially the charging state.
- Check the cable installation from the battery to the Connection Board (6) in the T2130.

If the error has appeared because of an error in the measuring circuit, please refer to section 3.5.3.1. $\mathrm{A} /$ D CONVERTER, +24 Volt Sense Measuring, in the instruction manual for T2130.

## 77. TEMPERATURE SENSOR ERROR

The temperature is measured to be very high or very low, indicating an error in the temperature measuring circuit. Please refer to section 3.5.3.1. A/D CONVERTER, Temperature Measuring in the instruction manual for T2130.

## 78. INTERNAL SWR TOO HIGH

The SWR in the internal dummy load used for the automatic power setting is higher than certain limits.
For frequencies lower than 20 MHz the SWR is 1.2.
For frequencies above 20 MHz the SWR limit is 1.6.
Please refer to the circuit description for the Output Filter (2) section 3.4.2. in the instruction manual for T2130.

### 3.4.1 POWER AMPLIFIER (MODULE 1)

Connect a 50 ohm load to RF in/out (ST04) on the Connection Board (6).

### 3.4.1.1 ERROR 71. VFORWARD LOW

This means that there is no output from the PA-module.
Select service programme SP-29, see section 3.9.1.

### 3.4.1.2

Check the RF-input level on the PA-module (1).
Approx. 1.2 Vpp.

### 3.4.1.3

Check the RF-output level on the PA-module (1).
Approx. 200 Vpp.

### 3.4.1.4

Check of bias. Note only when the output is zero. See chapter 3.6. ADJUSTMENT PROCEDURE, sections 3.6.1.1 to 3.6.1.4.

### 3.4.1.5

If the measurement above is ok, then the fault is probably to be found in the Output Filter (2).

### 3.4.1.6 ERROR 74. TRANSMITTER TEMPERATURE HIGH

The temperature on the output transistors is too high.

### 3.4.1.7

Check that there are free air circulation around the transmitter and the ambient temperature is not more than $40^{\circ} \mathrm{C}$. If the temperature is higher the performance will be reduced.

### 3.4.1.8

Check R45 (temperature sensor) located on one of the screws holding Q10 (see component location for Power Amplifier (1) in chapter 5.1). When it is $25^{\circ} \mathrm{C}$ the resistance is 2.00 Kohm.

### 3.4.1.9

Check if the output transistors have a good thermal contact to the heatsink.

IMPORTANT! Always use thermal compound for the power transistors. (e.g. Wakefield part No. $120-8$ or equivalent).

### 3.4.2 OUTPUT FILTER (MODULE 2)

### 3.4.2.1 ERROR 71. VFORWARD LOW

### 3.4.2.2

Check if the error comes up on all frequencies (one in each filter). Fault is probably in relay RE14-2 or in the cabling from module 2 to the Connection Board (6).
If the error only comes up in one filter, check the input/output relays (eg. RE01-2, RE07-2), and then the filter capacitors.

### 3.4.2.3

Check of the Vforward detector.
Select service programme SP-29, see chapter 3.9.

### 3.4.2.4

Measure the RF-output voltage on the Connection Board (6) with an oscilloscope approx. 200 Vp-p. Then check the DC voltage on U01/1 pin 1 approx. 6.5 V .

### 3.4.2.5 ERROR 78. INTERNAL SWR TOO HIGH

### 3.4.2.6

Check R27 and R28 (the power resistors to the left of module 6) with an ohmmeter value 50 ohm $\pm 10 \%$.

### 3.4.2.7

Check relay RE14.

### 3.4.2.8 ERROR 73 AND 75

Connect a 50 ohm load to the output terminal on the Connection Board (6).
Select service mode SP-29, see chapter 3.9.

### 3.4.2.9

Check Vforward U1 pin 1 approx. 6.5 V
Vreverse U1 pin 7 approx. 10.5 mV .

### 3.4.2.10

IF Vforward and Vreverse are ok. Then the fault is in TX-Processor (3)

### 3.4.3 TX-PROCESSOR (MODULE 3)

Check all incoming and outgoing voltages.
A. Supply voltages. Measured with voltmeter.

| Incoming: | Pin | Plug | Meas. ref. |
| :---: | :---: | :---: | :---: |
| GND | 1,2,3 | 6 |  |
| +5 Volt A | 6 | 6 | GND |
| +5 Volt B | 7 | 6 | GND |
| -5 Volt | 5 | 6 | GND |
| +15 Volt | 10 | 6 | GND |
| -15 Volt | 9 | 6 | GND |
| +18 Volt | 11 | 6 | GND |
| OVA | 9 | 5 | Battery minus |
| +21 Volt | 1 | 5 | OVA |
| Outgoing: | Pin | Plug | Meas. ref |
| GND | 10,11,12 | 4 |  |
| +15 Volt | 9 | 4 | GND |

B. Signal voltages

| Incoming | Pin | Plug | Please see section |
| :---: | :---: | :---: | :---: |
| Vforward | 7 | 4 | 3.5.3.1. A/D CONVERTER |
| Vreverse | 8 | 4 | 3.5.3.1. A/D CONVERTER |
| AE-current | 3 | 5 | 3.5.3.5. AE-CURRENT, Vf.cond. |
| 180o pulse | 3 | 5 | 3.4. ERROR MESSAGES (70) |
| Man. Tune | 10 | 5 | 3.5.3.10.MANUAL TUNE |
| +24V sense | 4 | 6 | 3.5.3.1. A/D CONVERTER |
| Temperature | 13,14 | 6 | 3.5.3.1. A/D CONVERTER |


| Outgoing: | Pin | Plug | Please see section |
| :---: | :---: | :---: | :---: |
| Control 1-6 | 1-6 | 4 | 3.5.3.2. OUTPUT FILTER DRIVER |
| RX/TX | 13 | 4 | 3.5.3.2. OUTPUT FILTER DRIVER |
| RX-TX/drive | 14 | 4 | 3.5.3.2. OUTPUT FILTER DRIVER |
| TLX on/off | 2 | 5 | 3.5.3.4. TELEX OPEN |
| Mute | 4 | 5 | 3.5.3.2. OUTPUT FILTER DRIVER |
| Clock | 5 | 5 | 3.5.3.6. AT2110 DRIVER |
| Data | 6 | 5 | 3.5.3.6. AT2110 DRIVER |
| Vf/AE-current | 8 | 5 | 3.5.3.3. AE-CURRENT, Vf.Cond. |
| RF on/off | 8 | 6 | 3.5.3.3. RF ON/OFF |

### 3.4.4 POWER SUPPLY (MODULE 4)

### 3.4.4.1

If all output supplies are missing, check the main fuses F02 and F03 (20A) located on the Connection Board (6).

### 3.4.4.2

If only the $+18 \mathrm{~V},-18 \mathrm{~V},+9 \mathrm{~V}$ are missing the fault is in the switch mode power supply.

### 3.4.4.3

Check the voltage on U01 pin 13, 12V (heatsink as common).

### 3.4.4.4

If zero voltage, check fuse F01 (3.15A) on the Connection Board (6).

### 3.4.4.5

If it is ok, disconnect the gate and source on switching Fet's on Q02 and Q03.

### 3.4.4.6

Then check the waveforms on U01 pin 11 and 12, see below.


### 3.4.4.7

If not ok, then the fault is in U01.

### 3.4.4.8

If ok, then reconnect the gate and source and check the waveforms on U01 pin 11/12, see below.


### 3.4.4.9

If the waveforms look like that, the drain/source current is too high, Check for a defect rectifier diode or a defect regulator (U02 to U06).

### 3.4.4.10

If the waveforms look like under point 3.4.4.6, then Q2 or Q3 is defect, It might also be a fault in the feedback circuit (D23, OC01)

### 3.4.5 NOT USED

### 3.4.6 CONNECTION BOARD (MODULE 6)

No hints.

### 3.4.7 REPLACEMENT OF COMPONENTS

When replacing transistors, diodes, resistors, capacitors and similar components you must use a small „pencil" soldering iron of 30 to 75 Watt rating. The soldering must be performed rapidly to avoid overheating, and the use of a tin sucker is recommended, as otherwise there is a risk that both the components and the printed circuit will be spoiled.

After replacement of components look-up the chapter 3.7.2 COMPONENTS REPLACED.

### 3.4.8 REPLACEMENT OF MODULES

If a fault has been found in a module, it may often be worthwhile to replace it and then repair it later on. After replacement of a module look-up the chapter 3.7.1 MODULES REPLACED.

### 3.5 PERFORMANCE CHECK

All tests are done with an RE2100 connected, and a supply voltage of exactly 24.00 V .
In the subsections in this section is referred to the following test setup modes:

Mode 1: Standby. Receive mode, with aerial connected.
Mode 2: 50 ohm dummy load connected to the output of T2130. Jumper 5 is inserted into plug PO2-5 in the TX-processor (3) in the T2130.

Mode 3: 50 ohm dummy load connected to the output of the AT2110.

### 3.5.1 POWER AMPLIFIER (MODULE 1)

Presettings. Note 2.

### 3.5.1.1 BIAS CURRENT

Select service programme SP-33, see section 3.9.1.

### 3.5.1.2

Connect an ammeter (F.S. 100 mA ) in series with P1, and check that the current is 80 mA $\pm 30 \mathrm{~mA}$.

### 3.5.1.3

Select normal receive mode. Check that the current is zero.

### 3.5.1.4

Connect an ammeter (F.S. 1A) in series with P2, and check that the current is 450 mA $\pm 100 \mathrm{~mA}$.

### 3.5.1.5

Select normal receive mode. Check that the current is zero.

### 3.5.1.6 POWER GAIN.

Select service programme SP-29, see section 3.9.1.

### 3.5.1.7

Connect an oscilloscope with $1: 10$ probe ( $0.2 \mathrm{~V} / \mathrm{div}$ ) across J01. Adjust the level to 1 Vpp by means of the buttons 'up' and 'down'.

### 3.5.1.8

Connect the oscilloscope with $1: 10$ probe ( $20 \mathrm{~V} / \mathrm{div}$ ) to J02. Check that the level is $170 \mathrm{Vpp} \pm 50 \mathrm{~V}$.

### 3.5.1.9 CHECK OF FULL POWER OUTPUT

Select normal transmit mode, frequency approx. 1.6 MHz. Connect the handset to RE2100.

### 3.5.1.10

Connect an oscilloscope with 1:10 probe (50V/div) to J02.

### 3.5.1.11

Key the transmitter and whistle into the microtelephone- Check that the level is more than 245 Vpp.

### 3.5.1.12

Select a transmitter frequency near to 25 MHz .

### 3.5.1.13

Key the transmitter and whistle into the microtelephone. Check that the level is more than 228 Vpp.

### 3.5.2 OUTPUT FILTER (MODULE 2)

Presettings. Note 2.

### 3.5.2.1 SWR-DETECTOR

Select service programme SP-29, see section 3.9.1.

### 3.5.2.2

Adjust the output to 200 Vpp across the external 50 ohm load by means of the buttons 'up' and 'down'.

### 3.5.2.3

Check that the voltage on pin 7, U01 is less than 400 mV .

### 3.5.2.4

Check that the voltage on pin $1, \mathrm{U} 01$ is $6.3 \mathrm{~V} \pm 0.5 \mathrm{~V}$.

### 3.5.2.5 FILTER SECTION

Select service programme SP-11, see section 3.9, and note the last digit. Then press $1<E N T>$. The display will now show 'SP-11-1'.

Select service programme SP-12 and note the last digit. Then press $3<E N T>$. The display will now show 'SP-12-3'.

Press <TUNE> and select H3E mode.

### 3.5.2.6

Check the output power for each filter in the low and high end in accordance with the table below. Key the transmitter by means of the handset key.

| Low | High | Max. |
| :--- | :--- | :--- |
| Frequency | Frequency |  |
| kHz | kHz | Power Difference <br> dB |
| 1605 | 2599 |  |
| 2600 | 4199 | 1 |
| 4200 | 6799 | 1 |
| 6800 | 11099 | 1 |
| 11100 | 18099 | 1.4 |
| 18100 | 29999 | 1.7 |

### 3.5.2.7

When the test is finished do the following.
Select service programme SP-11. Then key-in the noted digit and press <ENT>.
Select SP-12 and key-in the noted digit and press <ENT>. Then press <TUNE>.

### 3.5.3 TX-PROCESSOR (MODULE 3)

### 3.5.3.1 A/D CONVERTER

## REFERENCE VOLTAGE

Test set-up: Mode 1.
A. Connect a Voltmeter to pin 13 on U15, (4053).

Voltage is +2.5 Volt $+/-1.5 \%$.
B. Connect a Voltmeter to pin 7 on U16/2, (TLO72).

Voltage is +5.0 Volt $+/-1.7 \%$.

## VFORWARD MEASURING

Test set-up: Mode 2.
A. Select a frequency near 1650 kHz .

Connect a voltmeter to the upper end of R56, (3K92). Key the microphone and whistle into the microphone. Note the voltmeter reading (approx. 10V) Release the key while whistling.
B. Enter SP-22-0.

Compare the displayed Vforward to the measured voltage. Maximum deviation from the measured voltage is $+/-4 \%$.

## SWR MEASURING

Test set-up: Mode 2.
A. Enter SP-29.

Connect a Voltmeter to the upper end of R56, (3K92). Vforward voltage should be approx. 7.3 Volt DC.

B: Connect a Voltmeter to the upper end of R65, (3K92). Vreverse voltage should be approx. 0.12 Volt DC. Leave SP-29 by entering the 'ENT' key.
C: Calculate the SWR.

$$
\text { SWR }=\frac{\text { Vforward }+ \text { Vreverse }}{\text { Vfo------------------- }}
$$

D. Enter SP-23-0 >ENT<.

Compare the displayed SWR to the calculated voltage. Maximum deviation from the calculated is $+12 \% /-5 \%$.

## +24 VOLT SENSE MEASURING

Test set-up: Mode 2.
A. Connect a Voltmeter to the upper end of R63, (15K4).

B: Enter SP-29. Read the voltmeter. Leave SP-29 by entering 'ENT'. Calculate the battery voltage:


Enter SP-20-0 >ENT<.
C: Compare the displayed battery voltage to the calculated voltage. Maximum deviation from the calculated is $+/-5 \%$.

NOTE: This is just checking the measuring circuit - NOT the absolute battery voltage present at the Connection Board (6).
The special sequence of SP-29 followed by SP-20-0 may give a different battery voltage compared to a normal read of SP-20-0 caused by an offset added by the calibration of the T2130.

## TEMPERATURE MEASURING

Test set-up: Mode 1.
A: Disconnect the PO1 on the Power Supply (4). This is the cable to the temperature sensor R45 on the Power Amplifier (1).
Connect a resistor of 2 Kohm on the PO1 on the Power Supply (4).
B: Connect a Voltmeter to the lower end of R60, (8K2). Voltage is 2.5 Volt $+/-1.7 \%+/$ - tolerances on the 2 Kohm resistor.
C: Calculate an adctemp:
adctemp $=\frac{\text { Measured voltage * } 255}{\text {---------------------------- }}$
D: Enter SP-21-1 >ENT<.
Multiply the displayed result by 10. Compare to the calculated acdtemp. Maximum deviation is $+/-2 \%$.
E: Reconnect temperature sensor to P.S. module P01

### 3.5.3.2 OUTPUT FILTER MODULE DRIVERS

## RX/TX RELAY DRIVER

Test set-up: Mode 1.
A: Enter SP-29. Connect the voltmeter to U09 pin 16. Voltage is <1.1 Volt. Leave SP-29 by entering 'ENT'.

## TX/DRIVE RELAY DRIVER

Test set-up: Mode 1.
A: Enter SP-29. Connect the voltmeter to U08 pin 16. Voltage is $<1.1$ Volt. Leave SP-29 by entering 'ENT'.

## OUTPUT FILTER RELAY DRIVERS

Test set-up: Mode 2.
Each of the six drivers controls two relays for switching in the lowpass filters.
A: Key in a TX-frequency in the frequency range for the specific filter.
FREQUENCY RANGE PIN ON U08

| $1.6-2.599 \mathrm{MHz}$ | 14 |
| ---: | ---: |
| $2.6-4.199 \mathrm{MHz}$ | 12 |
| $4.2-6.799 \mathrm{MHz}$ | 10 |
| $6.8-11.099 \mathrm{MHz}$ | 11 |
| $11.1-18.099 \mathrm{MHz}$ | 13 |
| $18.1-30.000 \mathrm{MHz}$ | 15 |

B: Connect the voltmeter to the specific pin on U08.
C: Key the transmitter. Voltage is $<1.1$ Volt.

### 3.5.3.3 RF ON/OFF

Test set-up: Mode 1
A: Connect a voltmeter to the collector of Q11 or at P06 pin 8.
B: Key the transmitter. Voltage is $<0.8$ Volt.

### 3.5.3.4 TELEX OPEN

Test set-up: Mode 1
A: Connect pin 6 ST03 on the Connection Board (6) to ST02 pin 16 SP-BUS INTERRUPT, and connect pin 5 ST03 to ST02 pin $4+18 \mathrm{~V}$.
B: Connect a voltmeter to the collector of Q10.
C: Select „TLX" mode on the RE2100 and key the transmitter.
Check that Q10 is on (low).
D: Select „J3E" mode on the RE2100.
Check that Q10 is off (high).

### 3.5.3.3 AE-CURRENT/VFORWARD CONDITIONING

## AE-CURRENT

Test set-up: Mode 1. Turn „RF" fully clockwise.
A: Connect a voltmeter to ST02 pin 2 on the Connection Board (6).
B Disconnect the wire at pin 3 at ST01 on the Connection Board (6) and connect a variable power supply to pin 3 at ST01 with a 1 Kohm in series (negative terminal to chassis).
C: Vary the power supply and check the voltmeter according to the table below:

| Vin (ST01, pin 3): | Vout (ST02, pin 2): |
| :---: | :--- |
| 0.0 V | $0.87 \mathrm{~V} \pm 10 \%$ |
| 5.0 V | $4.27 \mathrm{~V} \pm 10 \%$ |
| 10.0 V | $7.77 \mathrm{~V} \pm 10 \%$ |
| 15.0 V | $8.00 \mathrm{~V} \pm \pm 0 \%$ |
| 18.5 V | $9.80 \mathrm{~V} \pm 10 \%$ |

## VFORWARD

Test set-up: Mode 1.
A: Insert jumper 5 in the TX-processor.
B: Switch off/on the RE2100.
C: Connect a voltmeter to U06 pin 7 or at ST02 pin 2 on the Connection Board (6).
D: Key the transmitter and modulate. Read the voltmeter. Voltage follows the modulation.
E : Remove the jumper.

### 3.5.3.6 AT2110 DRIVER

## CLOCK DRIVER

Test set-up: Mode 2.
A: Connect an oscilloscope ( $0.5 \mathrm{msec} / \mathrm{div}$, 5 Volt/div) to ST01, pin 5 on the Connection Board (6), ground to ST01, pin 10.
Voltage is low, < approx. 1 Volt.
B: Set the RE2100 to scan two frequencies, one below 3900 kHz , and the other above 4100 kHz .
24 clock pulses appear. The high level is approx. +21 Volt.

## DATA DRIVER

Test set-to: Mode 2.
A: Connect an oscilloscope, ( $0.5 \mathrm{msec} / \mathrm{div}, 5 \mathrm{Volt} / \mathrm{div}$ ) to ST01, pin 6 on the Connection Board (6), ground to ST01, pin 10.
B: Set the RE2100 to scan two frequencies, one below 3900 kHz , and the other above 4100 kHz .
One data pulse appears. The high level is approx. +21 Volt.

### 3.5.3.7 EEPROM'S

A: See Service Programme SP-24-0.

### 3.5.3.8 SP-BUS

Test set-up: Mode 1.
A: Ensure that exactly two termination jumpers are inserted in two of the units connected to the SP-Bus.
B: Switch on the power on the RE2100.
If 'Error 20' is NOT displayed, the SP-Bus is working.
If 'Error 20' appears on the RE2100, the RE2100 cannot establish the communication link to the T2130.
C: Check the cable connection between the RE2100 and the TX-processor (3) in the T2130.
D: Ensure that jumper 1 (the leftmost) is removed on TX-processor (3).

## RECEIVER

## Test set:up: Mode 1.

A: Remove the SP-Bus cable from J01 on the TX-processor (3).
B: Connect an oscilloscope.
Ch 1 to the left end of L01. (2 Volt/div), ground to chassis.
Ch 2 at pin 3 on U05 (74HC08). (2 Volt/div), ground to chassis.
C: Connect a variable power supply to J01 instead of the SP-Bus, chassis as reference.
D: Vary the voltage from +5 Volt to -5 Volt and reverse. Check the trigger voltage $=+/-3$ Volt $+/-10 \%$.

## DRIVER

Test set-up: Mode 1.
It is assumed that the receiver is checked and found ok.
A: Connect an oscilloscope. $0.5 \mathrm{msec} / \mathrm{div}$.
Ch 1 to U04 pin 5 as trigger+ (Driver Enable). (2 Volt/div), ground to chassis.
Ch 2 to or with a 'T' on the SP-Bus. (2 Volt/div), ground to chassis.
B: Let the RE2100 scan two frequencies, one below 3900 kHz , the other above 4100 kHz . Remove the aerial from RE2100.
C: Check the output levels for the driver when the TX-processor 'answers' the RE2100.
Levels: Positive: +4.0 up to 4.8 Volt.
Negative: $\quad-4.0$ down to -4.8 Volt.

### 3.5.3.9 TUNE MOTOR CONTROL

## HIGH SPEED

Test set-up: Mode 1.
A: Connect a voltmeter (positive) at pin 7 at ST01, negative at pin 10 at ST01 on the Connection Board (6).

B: Switch off and on the RE2100.
The tune motor is then being reset at high speed. The motor runs approx. 1.5 sec . Voltage is approx. 16 Volt.

## LOW SPEED

Test set-up: Mode 1.
A: Enter SP-32-3 >ENT<.
Connect a voltmeter to pin 7 motor + and to pin 10, 0 VA.
Check that the voltage is approx. 8 Volt.

### 3.5.3.10 MANUAL TUNE

Test set-up: Mode 1.
A: Connect a voltmeter at pin 23 on U02 (HD63BO3Y).
B: Toggle the 'Manual Tune' switch on the Connection Board (6). High level voltage = approx. 5 Volt. Low level voltage < 0.5 Volt.

### 3.5.3.11 MICROPROCESSOR

## RESET

Test set-up: Mode 1.
A: Check the +5 Volt B supply at pin 1 and 2 on U03 (MAX690). Voltage $=5$ Volt $+/-0.25$ Volt.
B: Check the value at pin 6 on U02 (HD63B03Y). Voltage is above the +5 Volt B minus 0.5 Volt.

## BATTERY LOW DETECTOR

Test set-up: Mode 1.
A: Check the +18 Volt supply at the upper end of R01 (22K1). Voltage $>17.3$ Volt.
B: Check the 'Power fail output' at pin 5 on U03 (MAX690). Voltage $>4.5$ Volt.

## WATCH DOG

Test set-up: Mode 1.
A: Connect an oscilloscope to the 'watch dog input' at pin 6 on U03 (MAX690). ( $0.2 \mathrm{sec} / \mathrm{div}$ and 2 Volt/ div). Check that the level is shifted for every 0.8 sec . If it is not, then the microprocessor does not execute the programme properly.

### 3.5.4 POWER SUPPLY (MODULE 4)

### 3.5.4.1

Check of supply voltages to RE2100.
Check the voltages on the Connection Board (6) in accordance with the table below.

| Pin No. | Name | Lower | Upper |
| :---: | :---: | :---: | :---: |
| ST2 |  | limit | limit |
| 3 | +9V | 8 V | 10V |
| 4 | +18V | 18 V | 20 V |
| 14 | -18V | -18V | -20V |
| 16 | GND |  |  |

### 3.5.4.2

Check of supply voltages to TX-Processor (3).
All voltages are with GND as reference. Note the heatsink is connected to -battery (OVA) and is not grounded.

$$
\begin{aligned}
& \text { U02, Vout }=+5 \mathrm{~V} \pm 5 \% \\
& \text { U03, Vout }=+5 \mathrm{~V} \pm 5 \% \\
& \text { U04, Vout }=+15 \mathrm{~V} \pm 5 \% \\
& \text { Co5, Vout }=-15 \mathrm{~V} \pm 5 \% \\
& \text { C06, Vout }=-5 \mathrm{~V} \pm 5 \%
\end{aligned}
$$

### 3.5.4.3

Check of supply voltage to the AT2110 aerial coupler.
The voltage is measured on the Connection Board (6).
ST1 pin 1 to pin $1022 \mathrm{~V} \pm 2 \mathrm{~V}$.

### 3.5.4.4

Check of supply voltage to PA-amplifier (1) with input (battery) voltage $=24.0 \mathrm{~V}$.
Check that the collector supply to the output transistors at PO2 on module 1 is $23.7 \mathrm{~V} \pm 0.2 \mathrm{~V}$. (Heatsink as negative reference).

### 3.5.4.5

Key the transmitter and whistle in the microphone. The collector voltage must not drop more than max. 0.5 V .

### 3.5.4.6

With input (battery) voltage 30V, check that the collector supply to the output transistors at PO2 on module 1 is $27.25 \mathrm{~V} \pm 0.75 \mathrm{~V}$.

### 3.5.4.7

Check of audio amplifier U07.
Connect an 8 ohm load to loudspeaker output on the Connection Board (6) ST3 No. 15 and 16.
Connect an audio generator $1700 \mathrm{~Hz}, 300 \mathrm{mVpp}$ to ST2 No. 7 and 8 (AF to AMP common, AF to AMP).

### 3.5.4.8

Check with an oscilloscope that the output accross the 8 ohm is undistorted and has a peak to peak value of $17 \mathrm{~V} \pm 3 \mathrm{~V}$.

### 3.5.5 NOT USED

### 3.5.6 CONNECTION BOARD (MODULE 6)

### 3.5.6.1 MUTE RX OUT

Key the transmitter with the microtelephone key.

### 3.5.6.2

Check by means of an ohmmeter that there is contact from ST03 pin 1 to 2.

### 3.5.6.3 MUTE RX IN

Connect a power supply +15 V from pin 11 to pin 12 on ST03.

### 3.5.6.4

Check that the receiver is muted.

### 3.5.6.5 TX-KEY AND RF ON/OFF

Only if supplied with telex.

### 3.5.6.6

Select TLX mode on RE2100.

### 3.5.6.7 TX-KEY

Connect pin 3 on ST03 to GND and pin 4 to +18 V on ST02 pin 4.

### 3.5.6.8

Check that the relays on the Output Filter (2) are activated.

### 3.5.6.9 RF ON/OFF

Connect also pin 5 on ST03 to GND and pin 6 to +18 V on ST02 pin 4.
Connect an audio generator ( $1700 \mathrm{~Hz}, 760 \mathrm{mV}$ ) to pin 9 and pin 10 on ST03.

### 3.5.6. 10

Check that the transmitter is now transmitting with full power

### 3.6 ADJUSTMENT PROCEDURE

### 3.6.1 POWER AMPLIFIER (MODULE 1)

### 3.6.1.1 ADJUSTMENT OF ZERO SIGNAL CURRENT

Presettings:
a. Turn R14 and R30 fully counter clockwise.
b. Disconnect P3 (driver supply) and P2 (output transistor supply).
c. Select service programme SP-33, see chapter 3.9.1.

### 3.6.1.2 ADJUSTMENT OF DRIVER ZERO SIGNAL CURRENT

Connect an ammeter (F.S. 100 mA ) in series with J 01 and P01. Adjust R14 to a meter reading of 80 mA .

### 3.6.1.3 ADJUSTMENT OF THE OUTPUT TRANSISTORZERO SIGNAL CURRENT

Connect an ammeter (F.S. 1A) in series with J 02 and P02. Adjust R30 to a meter reading of 450 mA . NOTE! the current will be drifting the first minute or so.

### 3.6.1.4

After adjustment of zero signal currents connect the plugs P3 and P2.

### 3.6.2 ADJUSTMENT OF OUTPUT FILTER (MODULE 2)

### 3.6.2.1 INITIAL SETTINGS:

Select service programme SP-25, see chapter 3.9.1.

### 3.6.2.1 ADJUSTMENT OF SWR DETECTOR

Adjust C31 to minimum voltage on U01 pin 7 (must be less than 0.7 V ).
NOTE! the transmitter is only transmitting for 2 secs, then it is off for 2 secs and so on. You can only adjust C31 when the transmitter is transmitting.

### 3.6.3 ADJUSTMENT OF DRIVE LEVEL

### 3.6.3.1 INITIAL SETTINGS:

a. Connect an oscilloscope with 1:10 probe (50V/div) across R27 module 2.
b. Select service programme SP-25, see chapter 3.9.1.
c. Adjust input voltage to 24.00 V .

### 3.6.3.2


just occurs on the oscilloscope.

IMPORTANT! the input voltage (battery supply) must be 24.00 V for calibration.

Then press
1 to store the drive level setting. See also chapter 3.9.1.

### 3.7 NECESSARY ADJUSTMENTS AFTER REPAIR

### 3.7.1 MODULES REPLACED

### 3.7.1.1 POWER AMPLIFIER (MODULE 1)

Adjust the Power Amplifier (1) as described in section 3.6.1.
Perform a calibration of T2130. Please refer to chapter 3.9. SERVICE PROGRAMMES, SP-25.

### 3.7.1.2 OUTPUT FILTER (MODULE 2)

Adjust the Output Filter (2) as described in section 3.6.2.

### 3.7.1.3 TX-PROCESSOR (MODULE 3)

New module delivered direct from S. P. Radio A/S:
Calibrate the T2130. Please refer to section 3.9. SERVICE PROGRAMMES, SP-25.
An exchanged module:

1. Check the EEPROM's by entering SP-24-0.
2. Initialize the EEPROM's by entering SP-24-2.
3. Calibrate the T2130. Please refer to chapter 3.9. SERVICE PROGRAMMES, SP-25.

### 3.7.1.4 POWER SUPPLY (MODULE 4)

No adjustments.

### 3.7.1.6 CONNECTION BOARD (MODULE 6)

No adjustments.

### 3.7.2 COMPONENTS REPLACED

### 3.7.2.1 POWER AMPLIFIER (MODULE 1)

After replacing the components, perform adjustment procedure section 3.6.1 POWER AMPLIFIER and 3.6.3 ADJUSTMENT OF DRIVE LEVEL.

### 3.7.2.2 OUTPUT FILTER (MODULE 2)

After replacing the components in the filter section, no adjustment is necessary.
After replacing components in the directional coupler, perform adjustment procedure section 3.6.2 ADJUSTMENT OF OUTPUT FILTER (MODULE 2) and 3.6.3 ADJUSTMENT OF DRIVE LEVEL.

### 3.7.2.3 TX-PROCESSOR (MODULE 3)

U11 or U12:

1. Test the replaced EEPROM's for read and write. Please refer to chapter 3.9 SERVICE PROGRAMMES, SP-24-0.
2. Initialize EEPROM's from scratch.

Please refer to chapter 3.9 SERVICE PROGRAMMES, SP-24-1.
3. Calibrate the T2130.

Please refer to chapter 3.9 SERVICE PROGRAMMES, SP-25.
U17:

1. Calibrate the T2130. Please refer to chapter 3.9 SERVICE PROGRAMMES, SP-25.

### 3.7.2.4 POWER SUPPLY (MODULE 4)

No adjustment necessary.

### 3.7.2.6 CONNECTION BOARD (MODULE 6)

No adjustment necessary.

### 3.8 FUNCTION CHECK

The function check is divided into two sections, one for the transmitter installed and one for the transmitter at your workshop.

### 3.8.1 FUNCTION CHECK FOR THE TRANSMITTER INSTALLED

### 3.8.2

Select the lowest transmitting frequency and press $<T X><T U N E>$. When the tune lamp extinguishes, press the handset key and whistle into the microphone. While whisteling release the handset key.

### 3.8.3 BATTERY CHECK

Press <1> and <0> simultaneously. The display will now show 'SP-'.
Then key <200> <ENT>.
The TX display will now show what the battery voltage was when transmitting (must be more than 22 V ).

### 3.8.4 OUTPUT POWER CHECK

Key <222> <ENT>.
The TX display shows the latest measured Vforward (must be more than 9V).

### 3.8.5 SWR CHECK

Key <230> <ENT>.
The TX display shows the SWR (must be better than 2).

### 3.8.6 CHECK OF POWER GAIN IN PA-MODULE (1)

Key <261> <ENT>.
The TX display shows the drive setting (must be more than 12).

### 3.8.7 END OF SERVICE PROGRAMME

Key <TUNE>.

### 3.8.8

Check that it is possible to tune and to transmit in all marine bands.

### 3.8.9

Make a control call to a coast station.

### 3.8.10 FUNCTION CHECK AT WORKSHOP

Connect a 50 ohm load in series with a Bird in line power meter and a power supply 28V, 20A.

### 3.8.11

Perform function check 3.8.2 to 3.8.7.

### 3.8.12 OUTPUT POWER CHECK

Make a power check in each marine band.
Check, by whisteling into the microphone, if the power is within the limits given below.
Low limit High limit

| $1.6-3.8$ | 158 W | 270 W |
| :---: | :---: | :---: |
| 4 MHz band | 158 W | 270 W |
| 6 MHz band | 158 W | 270 W |
| 8 MHz band | 158 W | 270 W |
| 12 MHz band | 158 W | 270 W |
| 16 MHz band | 158 W | 270 W |
| 18 MHz band | 158 W | 270 W |
| 22 MHz band | 158 W | 270 W |
| 25 MHz band | 130 W | 270 W |

### 3.8.13 MODULATION CHECK

Connect an oscilloscope accross the load, modulate the transmitter with speech.

### 3.8.14

Check that the signal looks allright.

### 3.9 SERVICE PROGRAMMES

In the following it is assumed that the Service Programme jumper is inserted in the RE2100. In general, if the RE2100 displays 'Err.0' in a Service Programme, the selected SP does not exist.

Example:

| Operator: | Key: | $20-7$ <ENT> |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-20-7' |
|  |  | ' Err.0' |

Legend: $\quad$ Err. $0=$ The entered service programme does not exist.

### 3.9.1 SERVICE PROGRAMMES IN T2130

## SP-20-0

Displays the latest measured Vbattery voltage.
Example:

| Operator: | Key: | $20-0<E N T>$ <br> RE2100: |
| :--- | :--- | :--- |
|  | Displays: | SP-20-0' |
|  |  | 25.3 ' |
| Legend: | Measured in Volt |  |

## SP-20-1

Measures and displays the present Vbattery voltage.
Example:

| Operator: | Key: | $20-1<E N T>$ <br> RE2100: |
| :--- | :--- | :--- |
|  | Displays: | 'SP-20-1' |
|  |  |  |
|  |  |  |
| Legend: |  | Measured in Volt. |

SP-21-0
Displays the state of the temperature protection.
Example:

| Operator: | Key: | $21-0<E N T>$ |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-21-0' |
|  |  | ' 00.1 ' |

Legend: 00.0 There has been no reduction of Vforward due to high temperature.
00.1 There has been a reduction of Vforward due to high temperature.
00.2 The Power Amplifier has been blocked due to very high temperature.

## SP-22-0

Displays the latest measured Vforward voltage.
The voltage is only valid after the transmitter has been keyed.
Example:

| Operator: | Key: | $22-0<E N T>$ |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-22-0'  <br>   <br>   <br> Legend:  |
|  |  | Measured in Volt |

## SP-22-1

Measures and displays the present Vforward.
Example:
Operator: Key: 22-1<ENT>
RE2100: Displays: 'SP-22-0'

- 10.9'

Legend: Measured in Volt.

## SP-22-2

Displays the latest measured Vforward maximum voltage.
The voltage is only valid after the transmitter has been keyed.
Example:
Operator: $\quad$ Key: $\quad 22-2<E N T>$
RE2100:
Displays: 'SP-22-0'
11.2'

Legend: Measured in Volt.

## SP-23-0

Displays the latest measured SWR.
Example:
Operator: Key: 23-0 <ENT>
RE2100: Displays: 'SP-23-0'

- 1.6'


## SP-23-2

Displays the measured SWR when the tuning has finished.
Example:

| Operator: | Key: | $23-2<E N T>$ |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-23-0' |

## RE2100: <br> $$
\text { Displays: } \quad \text { 'SP-23-0' }
$$

## SP-24-0

Tests the EEPROM's for write and read.
Example:
Operator: Key: 24-0 <ENT>
RE2100: Displays: ‘SP-24-0’
---
RE2100: Displays: ‘SP-24-0’
Legend: $\quad$ A. $=$ No errors found
Err. 1 = Error found in U11
Err. $2=$ Error found in U12.
NOTE! the duration of the test is approx. 8 seconds.

## SP-24-1

Deletes all stored Retune Data from the EEPROM's.
Example:
Operator: Key: 24-1 <ENT>
RE2100: Displays: 'SP-24-1’
---
RE2100: Displays: ‘SP-24-1’
A.

Legend: $\quad$ A. = Deleting finished

SP-24-2
Initializes EEPROM's from scratch. Stores standard data in the EEPROM.
Example:

| Operator: | Key: | $24-2<E N T>$ |
| :--- | :--- | :--- |
| RE2100. | Displays: | 'SP-24-2' |

## ---

RE2100:
Displays:
'SP-24-1’
A.

Legend: $\quad$ A. $=$ Initializing finished.
NOTE! The T2130 must be turned off and on after the execution of this Service Programme. The T2130 MUST be calibrated after this Service Programme.

## SP-25

Calibrates the T2130.
Example:
Operator: Connect an oscilloscope to the internal Dummy Load in the T2130.
Operator: Connect a Voltmeter to the battery supply pins at the Connection Board (6) in the bottom of the T2130.

| Operator: | Key: <br> RE2100: |
| :--- | :--- |
| RE2100: |  |$\quad$| Delisplays: 'SP-25-' |
| :--- |
| TX-frequency: 1600.0 kHz. |

Note! If any 'Err.' comes up the T2130 is NOT calibrated.

## UNINTENTIONAL CALL OF SP-25

If the operator unintentionally has keyed ' 25 ' it is possible to leave Service Programme 25 without calibrating the T2130 in the following way:

Operator: Key: <ENT> or <TUNE>
SP-25 may also be left by switching off the power on the RE2100.

## SP-26-0

Displays the maximum step of the Step Attenuator in the RE2100 Exciter.
Example:

| Operator: | Key: | $26-0<E N T>$ |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-26-0' |

## SP-26-1

Displays the actual step of the Step Attenuator in the RE2100 Exciter.
Example:
Operator: Key: 26-1<ENT>
RE2100: Displays: 'SP-26-1'
18.'

## SP-27

Displays the version and the release of the software in the TX-processor (3) in the T2130.
Example:

| Operator: | Key: | $27-0$ <ENT> |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-27-0' |
|  |  |  |
|  |  | $1083 . A^{\prime}$ |

Legend: '1083' is S. P. Radio's identification of the version of the software. On the label of the EEPROM is written: C1083A.
' " = 1. release
' A ' $=2$ 2. release
' $B$ ' $=3$. release
etc.

## SP-28

Sets RF-power level (reduced power).
Power levels: $\quad 0=$ Normal, 250 W
1 = 150 W
$2=125 \mathrm{~W}$
$3=100 \mathrm{~W}$
Example:

| Operator: | Key: | 28-(0-3)<ENT> <br> 'SP-28-(0-3)' |
| :--- | :--- | :--- |
| --- |  | Displays: |
| RE2100: | 'SP-28-2' <br>  <br> Legend: | 125. $=$ Set to 125 W. |

## SP-29

Trouble shooting service programme.
Example:

| Operator: | Key: | 29 |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-29-0' |

RE2100: Delivers a two-tone RF-signal continuously (same as tune tones). TX-frequency: 1600.0 kHz .
T2130: The corresponding lowpass filter is switched in and the transmitter is keyed. It is advisable to connect a 50 ohm dummy load instead of the aerial coupler.
Operator: May now trouble shoot the transmitter without being disturbed by error messages etc. Adjustment of the RF-level of the two-tones is done by using the keys <FREQ UP> and <FREQ DOWN>. When the trouble shooting is finished:

Operator: Key: <ENT>
RE2100: Displays: ‘SP-29-0’
A.'

## SP-33

Adjustment of the bias current in the power transistors in the Power Amplifier (1).
Example:
Operator: Key: 33
RE2100: Displays: 'SP-33-0'
' SE.
T2130: The transmitter is keyed. There are no RF-signals applied to the Power Amplifier (1).

Operator: May now adjust the bias current in accordance with the adjustment procedure. When the adjustment is finished:

| Operator: | Key: | <ENT> |
| :--- | :--- | :--- |
| RE2100: | Displays: | 'SP-33-0' |
|  |  | A.' |

### 3.9.2 SERVICE PROGRAMMES RELATED TO AT2110

## SP-30

Activates AT2110 relays 1-9 one by one, and releases any relay.
Example:
Operator: Key: $30-(0-9)<E N T>$
RE2100: Displays: 'SP-30-(0-9)'

Legend: $\quad 0=$ No relays activated.
1-9 = Relays 1-9 activated.
A. = Accepted.

The T2130 activates the entered AT2110 relay no., other relays are released.

SP-31
Activates AT2110 relays 10-19 one by one.
Example:
Operator: Key: $31-(0-9)$ <ENT>
RE2100: $\quad$ Displays: 'SP-31-(0-9)'
A.

Legend: $\quad 0-9=$ Relays 10-19 activated.
A. = Accepted.

The T2130 activates the entered AT2110 relay no., other relays are released.
If the AT2110 is in the systen (jumper 5 is inserted in the TX-processor) the following is displayed:
RE2100: Displays: 'SP-25 '
' Err. ${ }^{\prime}$

## SP-32-0

Resets the AT2110 'Clock' line, 'Data' line and the 'Motor +' line to their normal state.
Example:
Operator: Key: $\quad 32-0<E N T>$
RE2100: Displays: 'SP-32-0'
A. '

## SP-32-1

Sets the AT2110 clock line high.
Example:
Operator: Key: $\quad 32-1<E N T>$
RE2100: Displays: 'SP-32-1’

- A.


## SP-32-2

Sets the AT2110 data line high.
Example:
Operator: Key: $32-2$ <ENT> RE2100: Displays: 'SP-32-2'
A.

## SP-32-3

Sets supply on the AT2110 'Motor +' line, (low speed).
Example:
Operator: Key: $32-3$ <ENT>
RE2100: Displays: 'SP-32-3’
A.

## CONTENTS

## 4 MECHANICAL DISASSEMBLING

4.1 MECHANICAL DISASSEMBLING AND MODULE LOCATION 4-1

## 4 MECHANICAL DISASSEMBLING



4-0-25893
After disconnecting all cables on the connection board, remove the inner chassis by dismounting the 2 screws marked *
4.1 MECHANICAL DISASSEMBLING AND MODULE LOCATION



## CONTENTS

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## 5 CIRCUIT DESCRIPTION AND SCHEMATIC DIAGRAMS

### 5.1 POWER AMPLIFIER (MODULE 1) PART NO. 625641

The power amplifier has a gain of $50 \mathrm{~dB} \pm 3 \mathrm{~dB}$.
The power input is approx. 0 dBm and the output is approx. 250 W .
The power amplifier has three stages each working as a class B push-pull amplifier.
The pre-amplifier consists of two 2N3553 (Q03, Q04) transistors working in push-pull. The bias supply for the pre-driver consists of Q01, D01 and R01, R02. R01, R02 divide the 15V down to 9.6V and Q01 is a current amplifier.
Q02 is used to switch off the bias and D01 produces the basis-emitter diode of Q01 from reverse breakdown when Q02 is in saturation.
The signal from the pre-driver is fed through the impedance matching transformer TR02 to the driver. The two driver transistors MRF426 (Q06, Q07) are working as push-pull class B. There is a current feed-back from TR03 through R26 to the basis of Q06, Q07. C10, R21, and C11, R22 form an input impedance matching network.

The bias supply is built around U01/1 OP.Amp.
D02 is a temperature compensating diode and is thermal connected to Q06. When Q06 gets hotter the voltage drop over D02 gets lower and thus the output of U01/1 and Q08 is lowered (Q08 is a current amplifier for U01/1). The result is that the current through Q06, Q07 is stabilized or lowered.
The bias current through Q06, Q07 is adjusted by means of the potentiometer R14.
Q05 is used to switch off the bias of Q06, Q07.
The output from Q06, Q07 is fed through the impedance matching transformer TR04 to the output stage which consists of two TH416 (Q09, Q10) transistors working in class B.
Current feed-back is taken from TR05 through R38, R39 to the basis of Q09, Q10.
C17, R31, R32, R33, and C18, R34, R35, R56 form an input impedance matching network for Q09, Q10. The biasing network is built around U01/2 and is in principle equal to the circuit for the driver. D03 is thermal connected to Q10 and the bias is adjusted by means of the potentiometer R30.
Q11 is used to switch off the bias to Q09, Q10.
TR06 is transforming the low collector impedance of Q09, Q10 up to 50 ohm.
The power output is approx. 250W PEP.
A temperature sensor R45 sensors the temperature of one of the output transistors. The sensor is connected to the TX processor which takes care of reducing the power when the transistors get too hot.

COMPONENT LOCATION POWER AMPLIFIER MODULE 1


Seen from component side with upper side tracks PCB rev. 25641।


Seen from component side with lower side tracks


All vol tages measured with transmitter in
Service mode 5 Sp-29
This diagram is valid for PCB rev. 25641 ।

From the power amplifier the signal is fed to the output filters. There are six seventh order filters.
These filters attunes all harmonics so that they are more than 43 dB below the fundamental frequency. The filters cover the following frequency bands:
filter No. 1 covers $1.6-2.5999 \mathrm{MHz}$
filter No. 2 covers 26-4.1999 MHz
filter No. 3 covers 4.6-6.7999 MHz
filter No. 4 covers 6.8-11.0999 MHz
filter No. 5 covers 11.1-18.0999 MHz
filter No. 6 covers 18.1-29. 9999 MHz

Each filter is a duplex filter. The filters allow the fundamental frequency to pass through and feed the harmonics to the 100 ohm loads. This gives a good load match for the power amplifier.
From the filter the signal is fed through a directional coupler TR01. C31 is used for adjustment of the balance of the directional coupler.
The forward voltage and the reverse voltage is first rectified in a quasi effective value rectifier (VF: D09, R07, R09, and C32. VR: D10, R08, R35, and C33), then in a peak rectifier (VF: U01/3, D11, R15, R13, R11, and C36. VR: U01/4, D12, R16, R14, R12, and C37). Finally they are buffered in a unity gain amplifier (VF: U01/2, VR: U01/2). The signal from the two buffers is then fed to the TX processor.
From the directional coupler the signal is fed to RE13, RE14.
The function of the relays is

1. RE13 and R14 not activated (receive mode)

Connects the RE2100 (RX) J03 to the antenna (AT2110) J04.
2. RE13 activated and RE14 not activated (transmit mode). Connects the RE2100 (TX) J03 to PA input J02.
3. RE13 and R14 activated (output power setting)

Connects the RE2100 (TX) J03 to R27, R28 50 ohm dummy load. This function is used for automatic power setting. See also circuit description for TX processor module 3.


Seen from component side with upper side tracks.
PCB rev. 25642J


Seen from component side with lower side tracks


All volt ages measured with transmitter in
Service mode $5 p-29$
This diagram is valid for PCB rev. 25642 J

### 5.3 TX-PROCESSOR (MODULE 3) PART NO. 625643

## FUNCTIONAL DESCRIPTION

The TX-processor has the following main functions:

- communicates with the RE2100
- switches-in the correct lowpass filter
- sets drive level
- tunes the AT2110 to an acceptable SWR
- remembers the AT2110 relay combination for an acceptable found SWR
- protects the Power Amplifier (1) against high temperatures
- protects the Power Amplifier (1) against bad SWR
- ensures that the RF-output level of the PA-stage is in conjunction with the present battery voltage
- activates the AT2110 RX-relay according to selected RX-frequency

These functions are implemented partially in hardware and partially in software.
The TX-processor hardware is separated in a number of circuits, referring to the diagram:

- SUPPLY VOLTAGES
- MICROCOMPUTER
- WATCH DOG \& BATTERY LOW DETECTOR
- COMMUNICATION BUS DRIVER \& RECEIVER (SP-BUS)
- SERIAL DEVICE BUS DRIVER \& SELECTOR
- EEPROMS
- FILTER MODULE DRIVER
- A/D CONVERTER AND SURROUNDING CIRCUITS
- TELEX OPEN AND RF ON/OFF
- AT2110 BUS DRIVER
- TUNE MOTOR CONTROL
- AE-CURRENT AND Vf CONDITIONING
- OPTION SELECTIONS (JUMPERS)


## SUPPLY VOLTAGES

The board is supplied with the following voltages via P06. These voltages are galvanic isolated from the battery:
+5A General purpose 5 Volt
+5 VB Back-up voltage. This supply is kept stable for a period after there has been a switch off on the RE2100, or the battery voltage has fallen accidentally.
-5V Used for the SP-Bus driver
+15 V Supply for op-amps and for the output filter (module 2).
-15V Supply for op-amps
+18 V This is only used for sensing as the +5 VB is generated from this supply.
+24 V Sense. This voltage is only used for measuring. The +24 V sense is proportional to the Battery Voltage.
GND Common to the above supplies.
The following supply has a direct connection to the battery and is NOT galvanic isolated:
+21V Battery voltage. Supplies the circuits related to the AT2110.
OVA Return for the +21 V .

## MICROCOMPUTER

The purpose of the microcomputer block is to run the programme properly. It consists of the following units:

- an 8 bit Hitachi microprocessor U02
- an EPROM carrying the programme U01
- chip select circuit for the EPROM P01 and U13/2
- a watch dog \& battery low detector U03.

There are several options when configuring the microcomputer. The options are selectable in the jumper block area, ref. P01.

- P01 selects where the microprocessor has to find the programme.

I - Mode: Internal mode, (U02, pin 5 at +5 V )
This means that the programme must be masked and the processor is an HD6301Y type.
The remaining jumpers P01/2, P01/3, and P01/4 have then no sense.
E - Mode: $\quad$ External mode, (U02, pin 5 at 0V).
The programme must reside in an EPROM (PROM) ref. U01. The processor type can either be HD6301Y or HD6303Y.

- P01/2 sets the EPROM size
- P01/3 \&
- P01/4 select in conjunction the address where the EPROM is to be seen for the microprocessor.

27C64 starts address E000 Hex:
Figure 1: P01 connections for 27C64


27C128 starts address C000 Hex:
Figure 2: P01 connections for 27C128
P01


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27C256 starts 8000 Hex:
Figure 3: P01 connections for 27C256.


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## WATCH DOG \& BATTERY LOW DETECTOR

The MAX 690 (U03) has the following purposes:

- ensures a proper reset for the microprocessor when the +5 VB is stable
- $\quad$ senses the +18 V (PFI, pin 4), and gives an early warning when the supply is failing. The limits for the battery low detector are the following:
- $\quad$ The PFO (pin 5 ) must be high $(+5 \mathrm{~V})$ at 17.231 Volt or higher on the +18 V .
- $\quad$ The PFO must be low ( 0 V ) at 14.148 Volt or less on the +18 V supply.
- Watch dog.

During normal operation the microprocessor resets the watch dog at known locations in the programme.
If the microprocessor stays too long in an unintentional loop, without resetting the watch dog, the watch dog will activate the reset pin on the microprocessor.
This may happen if the microprocessor is waiting for an external event which never occurs (failure in hardware), or noise has disturbed the programme execution.

## COMMUNICATION BUS DRIVER \& RECEIVER (SP-BUS)

The communication to the RE2100 is time multiplexed data bus. It is implemented with one 50 ohm coax cable terminated in each end and a driver and a receiver in each connected unit. The RE2100 is the master and a number of slaves may be connected to the SP-Bus.
The driver and the receiver circuits are identical in each unit connected to the SP-Bus.
The driver output is normally in high impedance state except when transmitting on the SP-Bus.
The driver consists of two gates, U04/1 \& U04/2 (74HC132), a transistor Q01 (BC558) for level shifting and two complementary output transistors Q02, Q03.
The driver is connected to the microprocessor U02, pin 13 (Port 2, bit 4, transmit data), and pin 10 (port 2, bit 1, driver enable).

The receiver consists of an op-amp, U06/1 (1458) which is configurated as a Schmitt Trigger and a gate U05/1 ( 74 HC 08 ) for level conditioning.
The receiver is connected to the microprocessor U02, pin 12 (port 2, bit 3, receive data).

As the level on the SP-Bus approximately matches the RS232C standard, it is possible to connect an RS232C to the SP-Bus. The cable terminations (jumper P04) must be removed when the external RD232C is to transmit on the SP-Bus.

## SERIAL DEVICE BUS DRIVER \& SELECTOR

The serial device bus consists of:

```
    - clock
    - Data Out
    - Data In
    - several select lines
    - special select for the A/D converter
```

The serial bus occupies 6 bits of port 6 on the microprocessor. Bit 0 , bit 1 , and bit 2 are connected to the serial device selector, bit 3 is the special select for the A/D converter, bit 6 is the clock, and bit 7 is data.

The serial device selector is a 3 to 8 line decoder 74 HC 237 (U07). The 3 input lines give 8 selects on the output, one selected at a time. The following codes are used:

0 - none is selected
1 - EEPROM U11
2 - EEPROM U12
3 - shift register U10, filter module driver
4 - shift register U14, tune motor control
5 - AT2110 driver
6 - not used
7 - A/D converter, reference voltage switch
The serial device selector is supplied by +5 VB .
The serial device bus driver consists of 3 lines:

- clock, port 6, bit 6
- Data Out, port 6, bit 7
- Data In

In order to have a safe communication, the clock and Data Out are buffered. The buffers are $74 \mathrm{HC08}$ (U08/3 and U08/4) supplied by +5 VB .
The Data In line is connected direct to Port 6, bit 7. R04 ensures a definite impedance on the Data In line.
To inhibit an unknown current sink in the serial device bus when the supply is failing, the buffers are gated with PFO signal from the battery low detector (U03, pin 5).

## EEPROMS

U11 and U12 EEPROMS are supplied by the back-up voltage +5 VB . They are connected to the serial device bus direct to the microprocessor as the serial device bus closes down when the +18 V is failing.

U11 and U12 EEPROMS remember the data for the fast retune of the AT2110.
By use of service programmes it is possible to delete these retune data.

U11 and U12 EEPROMS are from S. P. Radio initialized and programmed with certain constants related to the specific T2130, where the TX-processor is located. The constants are saved in the EEPROMS by means of service programmes.

When any of the EEPROMS are replaced both must be initialized again and the T2130 must be calibrated.
Refer to the service programmes.
When the TX-processor board is replaced or is moved to another T2130, the T2130 must be calibrated again. Refer to the service programme.

## FILTER MODULE DRIVER

The filter module driver activates all relays on the Output Filter (2). It consists of a serial to parallel shift register U10, 74HC595 and 8 open collector Darlington drivers located in U08 and U09 (MC1413/ ULN2003).

The filter module driver is connected to the serial device bus and is supplied from the +5 VA . The +15 V is connected to U 08 and U 09 for protection purposes.

## A/D CONVERTER AND SURROUNDING CIRCUITS

The A/D converter (ADC) converts the following analog signals to digital values:

- forward voltage, (Vforw)
- reverse voltage, (Vrev)
- +24V sense
- temperature in PA (converted to a voltage)

The ADC (U17, ADCO834) is an 8 bit converter and a 4 channel multiplexer (MUX). Data in and out are serial.
The ADC is connected to the serial device bus and to a reference voltage, +5.00 V to the Vref input (pin 9). It is possible to switch the Vforw to the Vref input (pin 9) on the ADC and to make a rathiometric measuring with Vforw and Vref as inputs giving the parameter RHO direct.

Figure 4: Measuring Vforward, +24V Sense and Temperature.


When measuring a voltage, the Vref (pin 9) is at +5.0 Volt. The reference diode D14 (LM385) gives +2.5 Volt. The analog switch U15/3 (MC14053) is controlled by the serial device selector and connects the 2.5 Volt reference to the non-inverting input of the op-amp. U16/2. The op-amp. has a gain of 2 , giving the 5.0 Volt reference to the ADC, pin 9.
-Vforw (P04, pin 7) is connected to channel 0 of the MUX in the ADC via a divider, R56, R55, R54.
-Vrev (P04, pin 8) is connected to channel 1 of the MUX in the ADC via a divider, R65, R64.
-24 V sense (P06, pin 4) is connected to channel 3 of the MUX in the ADC via a divider, R63, R62.
-Temperature. The temperature sensor R25 (KTY11-2B) is placed near the output transistors in the Power Amplifier (1) and is connected to the TX-processor in P06, pin 13 and pin 14.

Figure 5: Temperature Sensor connections.


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The sensor is a nonlinear resistant element having 2.000 Kohm at 1 mA and 250 C . The op-amp. U16/ 1 is a voltage-to-current converter. The input voltage is the 2.5 Volt reference divided by the resistors R57 and R58, giving 0.500 Volt at the noninverting input of the op-amp. The resistor from the inverting input to ground is 449 ohm and gives a constant current flow ( 1 mA ) in the sensor connected from the output to the inverting input of the op-amp.
R60 and C41 inhibits the op-amp. from oscillating.

Figure 6: Measuring RHO


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When measuring RHO the Vforward is connected to reference input of the ADC (U17, pin 9). Vreverse is connected to pin 4. The result of the rathiometric measuring is the parameter RHO, defined by Vreverse divided by Vforward. RHO = Vreverse/Vforward.

## TELEX OPEN AND RF ON/OFF

The transistor Q10 is the telex open function and Q11 is the RF on/off function. Both are controlled direct from the microprocessor (port 6, bit 4 and bit 5).
The RF on/off controls the bias for the power transistors by use of the transistors Q02, Q05 amd Q11 in the power amplifier.

Figure 7: RF and Telex Control


[^0]RF off and telex closed: Q10 is off and Q11 is off. This means that the transistors Q02, Q05, Q11 in power amplifier are at saturation state by a current flow from +15 V through R57 in the Power Supply Unit (4).

RF on: (During tune and „key" from the handset). Q10 is off and Q11 is on. The transistors Q02, Q05, Q11 in the power amplifier are at off state.

Telex open („key" from the telex equipment): Q10 is on and Q11 is off. This allows the optocoupler OC02 in the Connection and Interface Board (6) to control the RF on/off function to the power amplifier.

## AT2110 BUS DRIVER

The serial communication to the AT2110 consists of two identical driver stages. One driving the clock and one driving the data of the serial device bus.
Each driver stage consists of a gate $\mathrm{U} 13 / 3$ \& $\mathrm{U} 13 / 1$ ( 74 HC 10 ), an open collector Darlington driver U09/ 6 \& U09/7 (MC1413/ULN2003) an optocoupler and an output transistor.
The gates perform the select of the driver. The optocouplers insulate between the ground and the battery. The output transistors have their collector resistors placed on the Connection and Interface Board (3) in the AT2110.
When the AT2110 driver is not selected, the output of the gates is high $(+5 \mathrm{~V})$ which gives light in the LED of the optocoupler so that the output transistors are in the saturation state.

Figure 8: Clock and Data to AT2110.


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The clock and data lines between the T2130 and AT2110 are then held at a very low impedance which reduces the possibility for noise introducing unintentional clock and data pulses.

## TUNE MOTOR CONTROL

The main functions of this circuit are to control the motor MO1 in the AT2110 at two speeds, high and low, and detect when the variable capacitor has rotated one half turn.
The speed of the motor is selected from the microprocessor via the serial device bus and the shift register U14 (74HC595).
Two identical circuits are connected to two outputs of U14.
QA, pin 15 controls the low speed as the D07 zener diode is a 9.1 Volt type.
QB, pin 1 controls the high speed as the D08 zener diode is an 18 Volt type.
The selected zener voltage is buffered by the output transistors Q05 and Q06.
When the motor is running as it does when the power is turned on (high speed) or when tuning the AT2110 (high or low speed), a current flows in the emitting light diode in the optocoupler OC01 on the Main Board
(1) in the AT2110. R05 and U10/2 on the Connection and Interface Board (2) and R25 on the Main Board
(1) in the AT2110 ensure this. The detector in the optocoupler OC01 and Q01 on the Main Board (1) are both in saturation state caused by the light from the LED in the OC01.

The transistor Q07 on the TX-processor (3) is on (controlled by the microprocessor). This ensures a current flow in R41 on the TX-processor (3) and in Q01 (and the detector in OC01) on the Main Board (1) in the AT2110.

The collector of the Q01 on the main board in the AT2110 is sensed by the divider R40 and R39 and the Schmitt Trigger U04/4 (74HC132) which is connected to the microprocessor, port 5, bit 7, (U02, pin 24).

The light is broken in the open type optocoupler OC01 on the Main Board (1) when the variable capacitor C01 in AT2110 has maximum capacity and when it has minimum capacity (every $180^{\circ}$ ).
When the light is broken in the optocoupler OC01, the current flow stops in the detector in OC01 and Q01 on the Main Board (1) in AT2110. This gives a level shift which is detected by Schmitt Trigger U04/4 and the microprocessor is informed. The microprocessor turns off the supply voltage to the motor MO1 and the rotation stops.

When the motor MO1 must run at low speed (the AT2110 is tuning) it is always started at high speed and reduced to low speed when the rotation has begun. The high speed time period is the time it takes to rotate the variable capacitor C 01 so far that the light from the light emitter diode in OC01 turns on the detector in OC01 and the transistor Q01 on the Main Board (1). This is detected and the microprocessor will immediately change to low speed.

Figure 9: Motor Control Circuit


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## AE CURRENT AND Vf CONDITIONING

The signal „AE-current" and the signal „ $180^{\circ}$ pulse" share one wire between the AT2110 and the T2130. This means that the AE-current cannot be transferred to the bar-graph in the RE2100 when the AT2110 is tuning. The Vforward is transferred to the bar-graph when the AT2110 is tuning.
When the T2130 is keyed (the tuning has finished) the AE-current is displayed on the bar-graph.
If the jumper 5 is inserted in the P02 and the T2130 is keyed the Vforward is displayed on the bar-graph.

Figure 10: AE current/Vforward - bar-graph.


The analog switch U15/2 which is controlled by the microprocessor via the serial device bus and the shift register U14 and the driver U09/3 switches between the AE-current and the Vforward.
AE-current comes in from the AT2110 to the TX-processor in P05, pin 3 and is divided by the resistors R42 and R44. When the level exceeds approx. 5.7 Volt the diode D20 opens and the dividing ratio is changed. This ensures that the level corresponds to the logarithmic scale on the RE2100.
Vforward comes in from the Output Filter (3) at P04, pin 7 and is divided by the resistors R49 and R44. The selected signal is buffered by $\mathrm{U} 06 / 2$. The output is fed to P 05 , pin 8 and runs to the processor unit (8) in the RE2100 where it is conditioned and lead to the display unit (7) in the RE2100 where it is mixed with the AGC-signal from the Receiver (1). Please refer to the circuit description for the RE2100 modules.

## OPTION SELECTIONS (JUMPERS)

ALL SOFTWARE VERSIONS HIGHER THAN OR EQUAL TO C10830

Figure 11: Jumper Identifications


## Jumper: $1 \quad 2 \quad 3 \quad 4 \quad 5$

## Jumper

1

2

3

4

5

Inserted
The communication on the SP-bus is without parity bit.

New aerial coupler AT2110 No. 430454 or higher.

Do not insert. For future use.
The "Signal Straight through" relay set-up in the AT2110 is NOT tested when tuning the AT2110.

This tells the microprocessor that a T2110 does not exist in the system. All communication to the AT2110 is disabled.

## Out

Normal communication with RE2100.

Old aerial coupler
AT2110 up to No. 430453.
Normal operation.
Normal operation.

Normal operation. The AT2112 is in the system.

## OPTION SELECTIONS (JUMPERS) ALL SOFTWARE VERSIONS UPTO INCL. C1083N

Figure 11: Jumper Identifications


Jumper: 122345

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Jumper
1

2

3

4

5

Inserted
The communication on the SP-bus is without parity bit.

Watch dog reset disabled. of the watch dog.

Do not insert. For future use.
The „Signal Straight through" relay set-up in the AT2110 is NOT tested when tuning the AT2110.

This tells the microprocessor that a T2110 does not exist in the system. All communication to the AT2110 is disabled.

Out
Normal communication with RE2100.

Normal communication

Normal operation.
Normal operation.

Normal operation. The AT2112 is in the system.

## COMPONENT LOCATION TX-PROCESSOR MODULE 3



View from component side with upper side tracks.
PCB rev. 25643M


View from component side with lower side tracks.


### 5.4 POWER SUPPLY I (MODULE 4) PART NO. 625644

This unit contains power supplies for RE2100, AT2110, and T2130. It also contains the audio amplifier for RE2100.

## SWITCH MODE POWER SUPPLY

The power supply is a forward switch mode converter. It converts the 24 V DC battery voltage to $\pm 18 \mathrm{~V}$ DC and $+9 V$ DC $+18 V$ DC and $9 V$ DC are fed to RE2100.

The output voltage of the +18 V DC output is sensed and compared with a reference voltage by an operational amplifier resulting in an error voltage. The current running in the output transistors is sensed over a resistor. The error voltage from the operational amplifier is then compared with the current signal by a comparator.
The oscillator produces a synchronization pulse. This pulse is triggering two flip-flops. One flip-flop is used to alter between the two output MOS transistors working as a push-pull transformer coupled output stage. The other flip-flop turns on the selected output transistors. This flip-flop is turned off by the comparator. So every time the current has reached the level set by the error voltage, the output transistors are turned off. If the output voltage falls, the output supply current is allowed to raise, the pulse width is enlarged, and the output voltage is then reestablished. The regulator is then working in a current mode instead of the usual voltage mode. This is of great advantage for the stability of the control loop, (first order instead of second order loop).
Current limiting is easily done by limiting the error voltage to a fixed maximum voltage. The current is limited to approx. 3.5A
The pulse width regulated voltages from the secondaries of the transformer are then rectified and smoothed by inductors and capacitors.
The sum of the three currents are sensed by a resistor. If this voltage is outside $\pm 0.35 \mathrm{~V} D \mathrm{C}$ approx. (equal to $\pm 1.5 \mathrm{~V}$ DC approx.), the converter is stopped and goes into soft start. This is to protect the rectifier diode against output short-circuit.

All the necessary amplifiers, flip-flops, etc. are contained in the IC U01.
L01, C02-C05 are the input filter
The 12 V DC supply voltage for U 01 is made by R01, D02, C06, and C07. If the supply voltage is lower than approx. 7.5V DC the internal under voltage lock-out is in action.
R02 and C08 determine the oscillator frequency to approx. 50 kHz .
The non-inverting input of the error amplifier is connected to the voltage 12V DC by R03. The inverting input is connected to the reference voltage by R05
D23 and OC01 are the feed-back loop of the error amplifier. R48, C46, and R45, C53 are frequency compensation in the feed-back loop to avoid self oscillations.
R08, R09, and C11 are the feed-back loop of the error amplifier
The output MOS transistor current is sensed by R16-R20, 5 resistors in parallel to minimize the induction. The current signal is then led to current sense amplifier input, pin 4. The R14 and C12 make a lowpass filter to remove noise. The emitter of Q01 follows the ramp voltages on the oscillator capacitor C08. R07 adds some of this ramp signal to the current signal. This is necessary to avoid sub-harmonic oscillations when the duty-cycle is higher than 50 per cent.

The voltage on pin 1 determines the clamp voltage for the error voltage. This voltage is determined by R04 and R06. The capacitor C10 is the soft start capacitor making the duty-cycle and the output voltages raise slowly.
The two pulse width modulated outputs are led to the two output MOS transistors by R10 and R11. These two resistors slow down the rise times of the MOS transistors to prevent spurious oscillations. R12 and R13 secure that the transistors always stay off when the IC U01 is off
R27, C14, R29, C15, R28, and C16 are snuppers, reducing oscillation due to stray capacitors and stray inductions in the transformer.
D06 to D11, L02 to L04, and C17 to C22 are the three output rectifiers and filters.
R30 and R31 limit the voltage in case of no load conditions.
The switch mode power supply is followed by regulators for $\pm 15 \mathrm{~V}$ and $\pm 5 \mathrm{~V}$. These voltages are used to supply the modules in T2130. The +5 VA is used to back-up the microprocessor, when switching off. D12 prevents current to flow from C 23 to other circuits than U03.

## 24VA REGULATOR

The regulator is regulating the battery supply so it is limited to 28 V . It also protects the AF -amplifier and the power amplifier from transients on the battery supply.
The output voltage is sensed by the voltage divider R44, R43 and fed back to the shunt regulator D18. If the output voltage rises above 28V, D18 starts to conduct and the gate of Q06 and Q07 goes lower. When the gate goes lower the drain to source resistance rises and the output voltage is kept on 28 V . If the output is less than 28 V , D18 is not conducting and the gate is high ( +50 V ), thus keeping the drain to source resistance low (voltage drop $\mathrm{D}-\mathrm{S}=0.5 \mathrm{~V}$ )
D17 is protecting D18 from over voltage.
D21 is protecting the gate/source from break-down. The on/off switching is done with RE01 and RE02, controlled from on/off switch in RE2100.

## 21V REGULATOR

The 21 V regulator is stabilizing the supply for the aerial coupler. The regulator is a low drop regulator. D24 is reference voltage for the regulator. R60 and R61 determine the output voltage

## AF AMPLIFIER

The AF amplifier is built-up around U07
The amplifier is supplied from the battery via the 28 V regulator. In the input there is a transformer to obtain insulation between -battery and chassis. It also suppresses common mode noise from the multicable to RE2100.
The input impedance is 600 ohm.
R39 and R38 are setting the voltage gain to 37 dB
At the output, R40, C36, FP01, FP02, and C37 prevent U07 from oscillating
When loaded with 8 ohm, output power will be 5 Watt, when loaded with 4 ohm, output power will be 10 Watt


Seen from component side with upper side tracks.


Seen from component side with lower side tracks.
PCB rev. 25644K



Seen from component side with upper side tracks.


[^1]

This diagram is valid for PCB rev. 25646 I


CABE 1 : TX-PROCESSOR TO POWER SUPPLY I


CHBLE 2:TX-PROCESSOR TO OUTPUT FLITER

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CBELE 4: POWER SUPPLY I TO CONNECTION BOARD

| conection soope (is) |  |
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| do- matrear | ${ }^{1}$ |
| ${ }^{2} 0-\mathrm{Cositgear}$ | $\varepsilon^{2}$ |
| $3^{3} \mathrm{C-C-martery}$ | -30 |
| $40-$ - battery | 40 |
| so- + Batera | $\underline{5}$ |
| ${ }^{6} 0-\mathrm{Cobrtery}$ | ${ }^{6}$ |
|  | - $\mathrm{Z}_{0}$ |
| 80 - -agtery | $\varepsilon_{0}$ |

CABIE 5 : POWER SUPPIY I TO CONNECTION BOARD
$\stackrel{\text { connection bon }}{10}$
$\begin{array}{lll}20 & \text { OVA } \\ 30 & \text { OVA } & 20 \\ 3^{2}\end{array}$
$\begin{array}{lll}30 & \text { OVA } & { }^{3} 0 \\ 40 & \text { GNO } & 40\end{array}$
$50-$ from fuse pul ${ }_{5}^{50}$
${ }^{60}$ GNO ${ }^{10}$
$\begin{array}{lll}10-\quad \text { Eram EUSE FUT } & 10 \\ 10\end{array}$
$120-\quad$ AF то амр 120
$180-+18 \mathrm{~V} \quad 180$
$190-9 v \quad 190$
200 ar ar 200
${ }^{21} 0-\frac{\text { PF ONOF }}{20}$
$240-10$ cuse pui 240
$250-$ To FUSE PuI 250
26 - To FUSE puI

CABLE 6: POWER SUPPLY I TO POWER AMPLIFIER

CABLE 7: POWER SUPPIY I TO POWER AMPIFIER

$$
\begin{aligned}
& \left.\begin{array}{ccc}
10 & T \text { TENP } & 10 \\
2_{0} & \text { TEMP } & 2_{0}
\end{array}\right\} J
\end{aligned}
$$

CABLE 8-9: OUTPUT FILTER TO POWER AMPLIFIER

 CABLE 10-11-12: OUTPUT FILTER TO CONNECTION BOARD



## CONTENTS

$6 \quad$ PARTS LIST

PARTS LIST

| HF SSB T2130 |  | MF/HF TRANSMITTER | ECI A/S | HF SSB T2130 | 802130 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| VARIOUS | COVER WITH STREAMER T2130 |  | ECI A/S | 3-0-25968 | 225968 |
| VARIOUS | COAX CABLE RE2100 (RED) | LENGTH 10m | ECI A/S | 3-0-27081 | 527081 |
| VARIOUS | COAX CABLE RE2100 (BLUE) | LENGHT 10m | ECI A/S | 3-0-27082 | 527082 |
| VARIOUS | STICKER MANUAL TUNE | T2130 | HESTBECH | 9-0-25819 | 53.304 |
| VARIOUS | SPARE FUSES FOR T2130 | T2130 | ECI A/S | 0-0-26121 | 726121 |
| VARIOUS | LASHING KIT FOR T2130 | AND N2160 / N2161 | ECI A/S | 0-0-26141 | 726141 |
| VARIOUS | GLOW DISCHARG.LAMP AT2110 |  | S.P.RADIO A/S | $0-0-27740$ | 727740 |
| VARIOUS | JUMPER KIT 6/1200W 726391 | HF SSB 600/1200W | ECI A/S | 0-0-27767 | 727767 |
| VARIOUS | MANUAL T2130 ENGLISH |  | S.P.RADIO A/S | Ver.: | M2130GB |

## BASE UNIT T2130

T2130
S.P.RADIO A/S

712130

| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| VARIOUS | INTERCONNECTION CABLE | 8-8 POLES L=100mm | ECI A/S | 3-0-26012A | 526012 |
| VARIOUS | INTERCONNECTION CABLE | 8-4+2+2 POLES L=120mm | ECI A/S | 3-0-26013 | 526013 |
| VARIOUS | COAX CABLE $3 \times 37,5 \mathrm{~cm} /$ RED |  | ECI A/S | 3-0-26075 | 526075 |
| VARIOUS | COAX CABLE $3 \times 37,5 \mathrm{~cm} / \mathrm{YELL}$ |  | ECI A/S | 3-0-26076 | 526076 |
| VARIOUS | COAX CABLE $3 \times 23 \mathrm{~cm} / \mathrm{BLUE}$ |  | ECI A/S | 3-0-26077 | 526077 |
| VARIOUS | COAX CABLE $3 \times 59,5 \mathrm{~cm} / \mathrm{BLAC}$ |  | ECI A/S | 3-0-26078 | 526078 |
| VARIOUS | COAX CABLE $3 \times 52,3 \mathrm{~cm}$ |  | ECI A/S | 3-0-26079 | 526079 |
| VARIOUS | INTERCONNECTION CABLE | 2 POLES L= 50 mm | ECI A/S | 3-0-26092A | 526092 |
| VARIOUS | INTERCONNECTION CABLE | 26 POLES L=95mm | 3M | 3-0-26080A | 56.018 |
| VARIOUS | INTERCONNECTION CABLE | 14 POLES L= 120 mm | 3M | 3-0-26081A | 56.019 |
| VARIOUS | INTERCONNECTION CABLE | 14 POLES L=45mm | 3M | 3-0-26082A | 56.020 |
| VAROIUS | INTERCONNECTION CABLE | 10 POLES L=305mm | 3M | 3-0-26083 | 56.021 |
| -1 | PA MODULE 1 | T2130 | ECI A/S | 4-6-25641J / 4-0-25641H | 625641 |
| -2 | OUT-PUT FILTER MODULE 2 | T2130 | ECI A/S | $5-0-25642 \mathrm{~J} / 4.0-25642 \mathrm{M}$ | 625642 |
| -3 | TX-PROCESSOR MODULE 3 | T2130 | ECI A/S | $5-0-25643 \mathrm{M} / 4-0-256430$ | 625643 |
| -4 | POWER SUPPLY I MODULE 4 | T2130 | ECI A/S | $5-0-25644 \mathrm{~K} / 4-0-25644 \mathrm{~J}$ | 625644 |
| -6 | CONNECTION BOARD MODULE 6 | T2130 | ECI A/S | 5-0-25646\| / 4-0-25646L | 625646 |


| PA MODULE 1 |  | T2130 | ECI A/S | 4-6-25641J / 4-0-25641H | 625641 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART No. |
| C1-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C2-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C3-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C4-1 | CAPACITOR CERAMIC | 10nF -20/80\% CL2 50VDC | KCK | RT-HE70 SK YF 103 Z | 15.170 |
| C5-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C6-1 | CAPACITOR POLYSTYRENE | 620PF 1\% 630V | \#PHILIPS | 222243186201 | 10.435 |
| C7-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C8-1 | CAPACITOR ELECTROLYTIC | 10uF -10/+50\% 63VDC | PHILIPS | 222203038109 | 14.546 |
| C9-1 | CAPACITOR CERAMIC | 10nF -20/80\% CL2 50VDC | KCK | RT-HE70 SK YF 103 Z | 15.170 |
| C12-1 | CAPACITOR CERAMIC | 10nF -20/80\% CL2 50VDC | KCK | RT-HE70 SK YF 103 Z | 15.170 |
| C13-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C14-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C15-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C16-1 | CAPACITOR ELECTROLYTIC | 100uF -10/50\% 25VDC | ERO | EKM 00 CC 310 E G5 | 14.610 |
| C17-1 | CAPACITOR MKP | 10n 10\% 400V | ERO | MRP 1841-310/40 5 G | 13.425 |
| C18-1 | CAPACITOR MKP | 10n 10\% 400V | ERO | MRP 1841-310/40 5 G | 13.425 |
| C19-1 | CAPACITOR CERAMIC | 10nF -20/80\% CL2 50VDC | KCK | RT-HE70 SK YF 103 Z | 15.170 |
| C20-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C21-1 | CAPACITOR MKT | 470nF 5\% 63VDC | ERO | MKT 1826-447/06 4-G | 11.187 |
| C22-1 | CAPACITOR ELECTROLYTIC | 10uF -10/+50\% 63VDC | PHILIPS | 222203038109 | 14.546 |
| C23-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C24-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C25-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C26-1 | CAPACITOR ELECTROLYTIC | 10uF -10/+50\% 63VDC | PHILIPS | 222203038109 | 14.546 |
| C27-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |
| C28-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C29-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C30-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410001 5-G | 11.180 |


| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C31-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C32-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C33-1 | CAPACITOR ELECTROLYTIC | 470uF -20/+50\% 10VDC | ELNA | RJ2-10-V-471-M-F | 14.633 |
| C34-1 | CAPACITOR ELECTROLYTIC | 10uF 20\% 35VDC | ELNA | RJ2-35-V-100-M-T58 | 14.512 |
| C37-1 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C38-1 | CAPACITOR CERAMIC | 160pF 5\% N150 50VDC | KCK | RT-HE90-SK PH 161 J | 15.842 |
| C40-1 | CAPACITOR MKT | 47nF 10\% 250VDC | ERO | MKT 1818-347/25 5G | 11.166 |
| C41-1 | CAPACITOR MKT | 47nF 10\% 250VDC | ERO | MKT 1818-347/25 5G | 11.166 |
| C42-1 | CAPACITOR MKT | 47nF 10\% 250VDC | ERO | MKT 1818-347/25 5G | 11.166 |
| C43-1 | CAPACITOR MKT | 47nF 10\% 250VDC | ERO | MKT 1818-347/25 5G | 11.166 |
| C44-1 | CAPACITOR MKT | 4.7NF 100V 10\% | ERO | MKT1818-247/01-5G | 11.145 |
| C45-1 | CAPACITOR MKT | 4.7NF 100V 10\% | ERO | MKT1818-247/01-5G | 11.145 |
| C46-1 | CAPACITOR MICA | 82pF 5\% 500VDC | N-T-D | DM20 C 820 J 5 | 16.593 |
| C49-1 | CAPACITOR MICA | 750pF 5\% 500VDC | N-T-D | DM20 C 751 J 5 | 16.616 |
| D1-1 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D2-1 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D3-1 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1 N4448 | 25.147 |
| FP4-1 | FERRITE BEAD INDUCTOR |  | MURATA | BLO1RN1-A62T5 | 35.188 |
| J1-1 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| J2-1 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| L1-1 | CHOKE FIXED | 180nH 10\% | SIEMENS | B78108-T3181-K | 20.338 |
| L2-1 | COIL | TL067 | ECI A/S | 6-0-20854A | 400067 |
| L3-1 | COIL | TL067 | ECI A/S | 6-0-20854A | 400067 |
| L4-1 | COIL | TL067 | ECI A/S | 6-0-20854A | 400067 |
| L5-1 | COIL | TL067 | ECI A/S | 6-0-20854A | 400067 |
| L6-1 | CHOKE FIXED | 180nH 10\% | SIEMENS | B78108-T3181-K | 20.338 |
| L7-1 | COIL | TL067 | ECI A/S | 6-0-20854A | 400067 |
| P1-1 | PLUG 2POLES |  | MOLEX | 39-28-1023 | 78.215 |
| P2-1 | PLUG 2POLES |  | MOLEX | 39-28-1023 | 78.215 |
| P3-1 | PLUG | 2 POLES | AMP | 0-826375-2 | 78.102 |
| P4-1 | PLUG 4 POLES |  | MOLEX | 39-28-1043 | 78.216 |
| Q1-1 | TRANSISTOR AF | PNP TO-92 BC328 | MOTOROLA | BC328 | 28.050 |
| Q2-1 | TRANSISTOR AF | BC547B NPN TO-92 | PHILIPS | BC547B-126 | 28.067 |
| Q3-1 | TRANSISTOR RF MED.POWER | NPN TO-39 2N3553 | PHILIPS | 2N3553 | 29.315 |
| Q4-1 | TRANSISTOR RF MED.POWER | NPN TO-39 2N3553 | PHILIPS | 2N3553 | 29.315 |
| Q5-1 | TRANSISTOR AF | BC548 NPN TO-92 | PHILIPS | BC548 (-A/-B/-C)126 | 28.070 |
| Q6-1 | TRANSISTOR RF POWER | MRF426 MATCHED PAIR (hFE) | MOTOROLA | MRF 426 hFE SORTED | 29.266 |
| Q7-1 | TRANSISTOR RF POWER | MRF426 MATCHED PAIR (hFE) | MOTOROLA | MRF 426 hFE SORTED | 29.266 |
| Q8-1 | TRANSISTOR AF POWER NPN | DARLINGTON BD645/BDX53 | MOTOROLA | BDX53 | 29.122 |
| Q9-1 | TRANSISTOR RF POWER | MATCHED PAIR (HFE) | THOMSON | SD1729-12 PAR | 29.267 |
| Q10-1 | TRANSISTOR RF POWER | MATCHED PAIR (HFE) | THOMSON | SD1729-12 PAR | 29.267 |
| Q11-1 | TRANSISTOR AF | BC548 NPN TO-92 | PHILIPS | BC548 (-A/-B/-C)126 | 28.070 |
| Q12-1 | TRANSISTOR AF POWER NPN | DARLINGTON BD645/BDX53 | MOTOROLA | BDX53 | 29.122 |
| R1-1 | RESISTOR MF | 68 OHM 5\% 0.4W | PHILIPS | 232218153689 | 01.170 |
| R2-1 | RESISTOR MF | 680 OHM 5\% 0.4W | PHILIPS | 232218153681 | 01.195 |
| R3-1 | RESISTOR MF | 1k8 OHM 5\% 0.4W | PHILIPS | 232218153182 | 01.206 |
| R4-1 | RESISTOR MF | 10 OHM 5\% 0.4W | PHILIPS | 232218153109 | 01.150 |
| R5-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R6-1 | RESISTOR MF | 470 OHM 5\% 0.4W | PHILIPS | 232218153471 | 01.191 |
| R7-1 | RESISTOR MF | 470 OHM 5\% 0.4W | PHILIPS | 232218153471 | 01.191 |
| R8-1 | RESISTOR MF | 820 OHM 5\% 0.4W | PHILIPS | 232218153821 | 01.197 |
| R9-1 | RESISTOR PMF | 120 OHM 5\% 2W | PHILIPS | 232219131201 | 04.178 |
| R10-1 | RESISTOR PMF | 120 OHM 5\% 2W | PHILIPS | 232219131201 | 04.178 |
| R11-1 | RESISTOR MF | 820 OHM 5\% 0.4W | PHILIPS | 232218153821 | 01.197 |
| R12-1 | RESISTOR MF | 15 OHM 5\% 0.4W | PHILIPS | 232218153159 | 01.154 |
| R13-1 | RESISTOR MF | 9k1 OHM 5\% 0.4W | PHILIPS | 232218153912 | 01.224 |
| R14-1 | PRESET CERMET | 200 OHM 10\% 0.5W | BOURNS | 3386P-Y91-201 | 07.884 |
| R15-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R16-1 | RESISTOR MF | 3 k 3 OHM 5\% 0.4W | PHILIPS | 232218153332 | 01.212 |
| R17-1 | RESISTOR MF | 4k7 OHM 5\% 0.4W | PHILIPS | 232218153472 | 01.216 |
| R18-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R19-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R20-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R23-1 | RESISTOR MF | 4k7 OHM 5\% 0.4W | PHILIPS | 232218153472 | 01.216 |
| R24-1 | RESISTOR MF | 470k OHM 5\% 0.4W | PHILIPS | 232218153474 | 01.266 |
| R25-1 | RESISTOR MF | 3 k 3 OHM 5\% 0.4W | PHILIPS | 232218153332 | 01.212 |
| R26-1 | RESISTOR MF | 47 OHM 5\% 0.4W | PHILIPS | 232218153479 | 01.166 |
| R27-1 | RESISTOR MF | 12 k OHM 5\% 0.4W | PHILIPS | 232218153123 | 01.227 |
| R28-1 | RESISTOR MF | 22 OHM 5\% 0.4W | PHILIPS | 232218153229 | 01.158 |
| R29-1 | RESISTOR MF | 9k1 OHM 5\% 0.4W | PHILIPS | 232218153912 | 01.224 |
| R30-1 | PRESET CERMET | 200 OHM 10\% 0.5W | BOURNS | 3386P-Y91-201 | 07.884 |
| R31-1 | RESISTOR PMF | 3R3 OHM 5\% 2W | PHILIPS | 232219413338 | 04.124 |
| R32-1 | RESISTOR PMF | 3R3 OHM 5\% 2W | PHILIPS | 232219413338 | 04.124 |
| R35-1 | RESISTOR PMF | 3R3 OHM 5\% 2W | PHILIPS | 232219413338 | 04.124 |


| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R36-1 | RESISTOR PMF | 3R3 OHM 5\% 2W | PHILIPS | 232219413338 | 04.124 |
| R37-1 | RESISTOR MF | 10 k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R38-1 | RESISTOR PMF | 22 OHM 5\% 2W | PHILIPS | 232219413229 | 04.141 |
| R39-1 | RESISTOR PMF | 22 OHM 5\% 2W | PHILIPS | 232219413229 | 04.141 |
| R40-1 | RESISTOR MF | 3 k 3 OHM 5\% 0.4W | PHILIPS | 232218153332 | 01.212 |
| R41-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R42-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R43-1 | RESISTOR MF | 10k OHM 5\% 0.4W | PHILIPS | 232218153103 | 01.225 |
| R44-1 | RESISTOR MF | 4k7 OHM 5\% 0.4W | PHILIPS | 232218153472 | 01.216 |
| R45-1 | RESISTOR TEMP.SENSOR | 2k0 2.5\% AT 25 CENTIGRADE | SIEMENS | Q62705-K245, -K247 | 07.151 |
| R46-1 | RESISTOR MF | 470k OHM 5\% 0.4W | PHILIPS | 232218153474 | 01.266 |
| R47-1 | RESISTOR MF | 3 k 3 OHM 5\% 0.4W | PHILIPS | 232218153332 | 01.212 |
| R48-1 | RESISTOR MF | 2R2 OHM 5\% 0.4W | PHILIPS | 232218153228 | 01.133 |
| R49-1 | RESISTOR MF | 12 k OHM 5\% 0.4W | PHILIPS | 232218153123 | 01.227 |
| R50-1 | RESISTOR MF | 22 OHM 5\% 0.4W | PHILIPS | 232218153229 | 01.158 |
| R51-1 | RESISTOR MF | 8R2 OHM 5\% 0.4W | PHILIPS | 232218153828 | 01.147 |
| R52-1 | RESISTOR MF | 150 OHM 5\% 0.4W | PHILIPS | 232218153151 | 01.179 |
| R53-1 | RESISTOR MF | 33 OHM 5\% 0.4W | PHILIPS | 232218153339 | 01.162 |
| R54-1 | RESISTOR MF | 150 OHM 5\% 0.4W | PHILIPS | 232218153151 | 01.179 |
| R55-1 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| R56-1 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| TR1-1 | TRANSFORMER | TL514 | ECI A/S | 6-0-25770B | 400514 |
| TR2-1 | TRANSFORMER | TL514 | ECI A/S | 6-0-25770B | 400514 |
| TR3-1 | TRANSFORMER | TL497 | ECI A/S | 6-0-25782A | 400497 |
| TR4-1 | TRANSFORMER | TL498 | ECI A/S | 6-0-25783A | 400498 |
| TR5-1 | TRANSFORMER | TL499 | ECI A/S | 6-0-25784A | 400499 |
| TR6-1 | COIL | TL299 | ECI A/S | 6-0-23121A | 400299 |
| TR7-1 | TRAFO | TL528 | S.P.RADIO | 6-0-25896B | 400528 |
| U1-1 | DUAL OP AMP | LM358N | MOTOTOLA | LM 358N | 31.100 |


| COIL | TL299 |  | ECI A/S | 6-0-23121A | 400299 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| C2 | CAPACITOR MICA | 15nF 10\% 100VDC | N-T-D | SDM20 C 153 K 1 | 18.145 |
| C3 | CAPACITOR MICA | 15nF 10\% 100VDC | N-T-D | SDM20 C 153 K 1 | 18.145 |
| TR1 | COAX CABLES FOR TL299 |  | ECI A/S | 500299 CABLES FOR TL299 | 500299 |
| TR1 | TOROIDE |  | *PHILIPS | 432202097200 | 35.027 |


| OUT-PUT FILTER MODULE 2 |  | T2130 | ECI A/S | 5-0-25642J / 4-0-25642M | 625642 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| C1-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C2-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C3-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C4-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C5-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C6-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C7-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C8-2 | CAPACITOR MICA | 1n8F 5\% 500VDC | N-T-D | DM20 C 182 J 5 | 16.625 |
| c9-2 | CAPACITOR MICA | 1n1F 5\% 500VDC | N-T-D | DM20 C 112 J 5 | 16.620 |
| C10-2 | CAPACITOR MICA | 680pF 5\% 500VDC | N-T-D | DM20 C 681 J 5 | 16.615 |
| C11-2 | CAPACITOR MICA | 430pF 5\% 500VDC | N-T-D | DM20 C 431 J 5 | 16.609 |
| C12-2 | CAPACITOR MICA | 240pF 5\% 500VDC | N-T-D | DM20 C 241 J 5 | 16.604 |
| C13-2 | CAPACITOR MICA | 150pF 5\% 500VDC | N-T-D | DM20 C 151 J5 | 16.599 |
| C14-2 | CAPACITOR MICA | 2noF 5\% 500VDC | N-T-D | DM20 C 202 J 5 | 16.626 |
| C15-2 | CAPACITOR MICA | 1n3F 5\% 500VDC | N-T.D | DM20 C 132 J 5 | 16.622 |
| C16-2 | CAPACITOR MICA | 750pF 5\% 500VDC | N-T-D | DM20 C 751 J 5 | 16.616 |
| C17-2 | CAPACITOR MICA | 510pF 5\% 500VDC | N-T-D | DM20 C 511 J 5 | 16.611 |
| C18-2 | CAPACITOR MICA | 270pF 5\% 500VDC | N-T-D | DM20 C 271 J 5 | 16.603 |
| C19-2 | CAPACITOR MICA | 160pF 5\% 500VDC | N-T-D | DM20 C 161 J 5 | 16.600 |
| C20-2 | CAPACITOR MICA | 1n8F 5\% 500VDC | N-T-D | DM20 C 182 J 5 | 16.625 |
| C21-2 | CAPACITOR MICA | 1n1F 5\% 500VDC | N-T-D | DM20 C 112 J 5 | 16.620 |
| C22-2 | CAPACITOR MICA | 680pF 5\% 500VDC | N-T-D | DM20 C 681 J 5 | 16.615 |
| C23-2 | CAPACITOR MICA | 430pF 5\% 500VDC | N-T-D | DM20 C 431 J 5 | 16.609 |
| C24-2 | CAPACITOR MICA | 240pF 5\% 500VDC | N-T-D | DM20 C 241 J5 | 16.604 |
| C25-2 | CAPACITOR MICA | 150pF 5\% 500VDC | N-T-D | DM20 C 151 J 5 | 16.599 |
| C26-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |


| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C27-2 | CAPACITOR MKT | 10nF 5\% 250VDC | ERO | MKT 1818-310/25 4-G | 11.167 |
| C28-2 | CAPACITOR CERAMIC | 12pF 5\% NPO 500VDC | KCK | RT-HM60-SK CH 120 J | 15.575 |
| C29-2 | CAPACITOR CERAMIC | 51pF 5\% NPO 50VDC | KCK | RT-HE60-SK CH 510 J | 15.110 |
| C30-2 | CAPACITOR CERAMIC | 110pF 10\% NPO 500VDC | KCK | RT-HM11-SK CH 111 K | 15.140 |
| C31-2 | CAPACITOR TRIMMING | $5-60 \mathrm{pF}$ PTFE $\cdot 9$ | DAU | 109.4901 .060 | 17.210 |
| C32-2 | CAPACITOR MKT | 2n2F 10\% 400VDC | ERO | MKT 1818-222/63 5-G | 11.143 |
| C33-2 | CAPACITOR MKT | 2n2F 10\% 400VDC | ERO | MKT 1818-222/63 5-G | 11.143 |
| C34-2 | CAPACITOR CERAMIC | 1n0F 10\% CL2 500VDC | KCK | RT-HM60 SK YB 102 K | 15.160 |
| C35-2 | CAPACITOR CERAMIC | 1n0F 10\% CL2 500VDC | KCK | RT-HM60 SK YB 102 K | 15.160 |
| C36-2 | CAPACITOR MKT | 1u0F 10\% 63VDC | ERO | MKT 1818-510/06 5-G | 11.138 |
| C37-2 | CAPACITOR MKT | 1u0F 10\% 63VDC | ERO | MKT 1818-510/06 5-G | 11.138 |
| C38-2 | CAPACITOR MKT | 10nF 5\% 250VDC | ERO | MKT 1818-310/25 4-G | 11.167 |
| C39-2 | CAPACITOR MKT | 10nF 5\% 250VDC | ERO | MKT 1818-310/25 4-G | 11.167 |
| C40-2 | CAPACITOR MKT | $10 \mathrm{nF} 5 \% 250 \mathrm{VDC}$ | ERO | MKT 1818-310/25 4-G | 11.167 |
| C41-2 | CAPACITOR MKT | 10nF 5\% 250VDC | ERO | MKT 1818-310/25 4-G | 11.167 |
| C42-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C43-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C44-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C45-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C46-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C47-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C48-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C49-2 | CAPACITOR MICA | 360pF 5\% 500VDC | N-T-D | DM20 C 361 J 5 | 16.605 |
| C50-2 | CAPACITOR MICA | 270pF 5\% 500VDC | N-T-D | DM20 C 271 J 5 | 16.603 |
| C51-2 | CAPACITOR MICA | 220pF 5\% 500VDC | N-T-D | DM20 C 221 J 5 | 16.602 |
| C52-2 | CAPACITOR MICA | 180pF 5\% 500VDC | N-T-D | DM20 C 181 J 5 | 16.601 |
| C53-2 | CAPACITOR MICA | 150pF 5\% 500VDC | N-T-D | DM20 C 151 J 5 | 16.599 |
| C54-2 | CAPACITOR MICA | 100pF 5\% 500VDC | N-T-D | DM20 C 101 J 5 | 16.595 |
| C55-2 | CAPACITOR MICA | 82pF 5\% 500VDC | N-T-D | DM20 C 820 J 5 | 16.593 |
| C56-2 | CAPACITOR MICA | 68pF 5\% 500VDC | N-T-D | DM20 C 680 J 5 | 16.591 |
| C57-2 | CAPACITOR MICA | 47pF 5\% 200VDC | N-D-T | DM20 C 470 J 5 | 16.587 |
| C58-2 | CAPACITOR MICA | 39pF 5\% 500VDC | N-T-D | DM20 C 390 J 5 | 16.585 |
| C59-2 | CAPACITOR MICA | 33pF 5\% 500VDC | N-T-D | DM20 C 330 J 5 | 16.583 |
| C60-2 | CAPACITOR MICA | 22pF 5\% 500VDC | N-T-D | DM20 C 220 J 5 | 16.579 |
| C61-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C62-2 | CAPACITOR MKT | 100nF 10\% 100VDC | ERO | MKT 1818-410/01 5-G | 11.180 |
| C63 | CAPACITOR MICA | 33pF 5\% 500VDC | N-T-D | DM20 C 330 J 5 | 16.583 |
| D9-2 | DIODE SCHOTTKY BARRIER | 70V/15mA 1N5711/5082-2800 | SGS-THOMSON | 1N5711 | 27.500 |
| D10-2 | DIODE SCHOTTKY BARRIER | 70V/15mA 1N5711/5082-2800 | SGS-THOMSON | 1N5711 | 27.500 |
| D11-2 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D12-2 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| J1-2 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| J2-2 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| J3-2 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| J4-2 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| L1-2 | COIL | TL525 | ECI A/S | 6-0-26000A | 400525 |
| L2-2 | COIL | TL529 | ECI A/S | 6-0-26112 | 400529 |
| L3-2 | COIL | TL503 | ECI A/S | 6-0-25757B | 400503 |
| L4-2 | COIL | TL505 | ECI A/S | 6-0-25759A | 400505 |
| L5-2 | COIL | TL505 | ECI A/S | 6-0-25759A | 400505 |
| L6-2 | COIL | TL506 | ECI A/S | 6-0-25760A | 400506 |
| L7-2 | COIL | TL508 | ECI A/S | 6-0-25762A | 400508 |
| L8-2 | COIL | TL532 | ECI A/S | 6-0-26312A | 400532 |
| L9-2 | COIL | TL510 | ECI A/S | 6-0-25764A | 400510 |
| L10-2 | COIL | TL511 | ECI A/S | 6-0-25765C | 400511 |
| L11-2 | COIL | TL512 | ECI A/S | 6-0-25766A | 400512 |
| L12-2 | COIL | TL513 | ECI A/S | 6-0-25767A | 400513 |
| L13-2 | COIL | TL508 | ECI A/S | 6-0-25762A | 400508 |
| L14-2 | COIL | TL532 | ECI A/S | 6-0-26312A | 400532 |
| L15-2 | COIL | TL510 | ECI A/S | 6-0-25764A | 400510 |
| L16-2 | COIL | TL511 | ECI A/S | 6-0-25765C | 400511 |
| L17-2 | COIL | TL512 | ECI A/S | 6-0-25766A | 400512 |
| L18-2 | COIL | TL513 | ECI A/S | 6-0-25767A | 400513 |
| L19-2 | COIL | TL502 | ECI A/S | 6-0-25756A | 400502 |
| L20-2 | COIL | TL529 | ECI A/S | 6-0-26112 | 400529 |
| L21-2 | COIL | TL504 | ECI A/S | 6-0-25758A | 400504 |
| L22-2 | COIL | TL505 | ECI A/S | 6-0-25759A | 400505 |
| L23-2 | COIL | TL513 | ECI A/S | 6-0-25767A | 400513 |
| L24-2 | COIL | TL507 | ECI A/S | 6-0-25761A | 400507 |
| L25-2 | CHOKE FIXED | 39mH 5\% | NEOSID | 00612243 | 20.218 |
| L26-2 | COIL | TL503 | ECI A/S | 6-0-25757B | 400503 |
| L27-2 | COIL | TL510 | ECI A/S | 6-0-25764A | 400510 |
| L28-2 | COIL | TL524 | ECI A/S | 6-0-25999B | 400524 |
| L29-2 | COIL | TL530 | ECI A/S | 6-0-26113 | 400530 |

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| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L30-2 | COIL | TL523 | ECI A/S | 6-0-25998A | 400523 |
| L31-2 | COIL | TL512 | ECI A/S | 6-0-25766A | 400512 |
| L32-2 | COIL | TL507 | ECI A/S | 6-0-25761A | 400507 |
| L33-2 | COIL | TL505 | ECI A/S | 6-0-25759A | 400505 |
| L34-2 | COIL | TL521 | ECI A/S | 6-0-25996A | 400521 |
| L35-2 | COIL | TL513 | ECl A/S | 6-0-25767A | 400513 |
| L36-2 | COIL | TL522 | ECI A/S | 6-0-25997A | 400522 |
| L37-2 | COIL | TL521 | ECI A/S | 6-0-25996A | 400521 |
| P1-2 | PLUG | 2x7 POLES | 3M | 3598-6002 / 7614-6002 JL | 78.254 |
| R1-2 | RESISTOR MF | 5 k 6 OHM 5\% 0.4W | PHILIPS | 232218153562 | 01.218 |
| R2-2 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| R3-2 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| R4-2 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| R5-2 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| R6-2 | RESISTOR MF | 100 OHM 5\% 0.4W | PHILIPS | 232218153101 | 01.175 |
| R7-2 | RESISTOR MF | 5 k 6 OHM 5\% 0.4W | PHILIPS | 232218153562 | 01.218 |
| R8-2 | RESISTOR MF | 5 k 6 OHM 5\% 0.4W | PHILIPS | 232218153562 | 01.218 |
| R9-2 | RESISTOR MF | 22k OHM 5\% 0.4W | PHILIPS | 232218153223 | 01.233 |
| R10-2 | RESISTOR MF | 22k OHM 5\% 0.4W | PHILIPS | 232218153223 | 01.233 |
| R11-2 | RESISTOR MF | 220k OHM 5\% 0.4W | PHILIPS | 232218153224 | 01.258 |
| R12-2 | RESISTOR MF | 220k OHM 5\% 0.4W | PHILIPS | 232218153224 | 01.258 |
| R13-2 | RESISTOR MF | 150k OHM 5\% 0.4W | PHILIPS | 232218153154 | 01.254 |
| R14-2 | RESISTOR MF | 150k OHM 5\% 0.4W | PHILIPS | 232218153154 | 01.254 |
| R15-2 | RESISTOR MF | 33 K OHM 5\% 0.4W | PHILIPS | 232218153333 | 01.237 |
| R16-2 | RESISTOR MF | 33k OHM 5\% 0.4W | PHILIPS | 232218153333 | 01.237 |
| R17-2 | RESISTOR MF | 100k OHM 5\% 0.4W | PHILIPS | 232218153104 | 01.250 |
| R18-2 | RESISTOR MF | 100k OHM 5\% 0.4W | PHILIPS | 232218153104 | 01.250 |
| R19-2 | RESISTOR MF | 47 OHM 5\% 0.4W | PHILIPS | 232218153479 | 01.166 |
| R20-2 | RESISTOR MF | 47 OHM 5\% 0.4W | PHILIPS | 232218153479 | 01.166 |
| R21-2 | RESISTOR POWER | 100 OHM 5\% 5W NON INDUCT. | ARCOL | NHS 10 100R 5\% | 06.374 |
| R22-2 | RESISTOR POWER | 100 OHM 5\% 5W NON INDUCT. | ARCOL | NHS 10 100R 5\% | 06.374 |
| R23-2 | RESISTOR POWER | 100 OHM 5\% 5W NON INDUCT. | ARCOL | NHS 10 100R 5\% | 06.374 |
| R24-2 | RESISTOR POWER | 100 OHM 5\% 5W NON INDUCT. | ARCOL | NHS 10 100R 5\% | 06.374 |
| R25-2 | RESISTOR POWER | 100 OHM 5\% 5W NON INDUCT. | ARCOL | NHS 10 100R 5\% | 06.374 |
| R26-2 | RESISTOR POWER | 100 OHM 5\% 5W NON INDUCT. | ARCOL | NHS 10 100R 5\% | 06.374 |
| R27-2 | RESISTOR WIRE WOUND | 100 OHM 5\% 25W NON INDUCT | ARCOL | NHS-25-100-5\% \& | 06.375 |
| R28-2 | RESISTOR WIRE WOUND | 100 OHM 5\% 25W NON INDUCT | ARCOL | NHS-25-100-5\% \& | 06.375 |
| RE1-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE2-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE3-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE4-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE5-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE6-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE7-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE8-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE9-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE10-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE11-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE12-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE13-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE14-2 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE15 | RELAY 12VDC 1A 1 SHIFT | V23026-A1002-B201 | SIEMENS | V23026-A1002-B201 | 21.029 |
| TR1-2 | TRANSFORMER | TL501 | ECI A/S | 6-0-25786 | 400501 |
| U1-2 | QUAD OP.AMP. | 324 | NAT/SGS | LM324N | 31.065 |
| TX-PROC | ESSOR MODULE 3 | T2130 | ECI A/S | 5-0-25643M / 4-0-256430 | 625643 |
| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| VARIOUS | SOCKET | 28POL | AMP | 641605-3 | 30.928 |
| VARIOUS | SHUNT CONNECTOR | FEMALE 2 POLES | AMP | 142270-1 | 78.325 |
| C1-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C2-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C3-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C4-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C5-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C6-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C7-3 | CAPACITOR MKT | 1000pF 10\% 400VDC | ERO | MKT 1818-210/63 5-G | 11.139 |
| C8-3 | CAPACITOR MKT | 10nF 5\% 63VDC | PHILIPS | 222237089103 | 11.134 |
| C9-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C10-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C12-3 | CAPACITOR MKT | 1000pF 10\% 400VDC | ERO | MKT 1818-210/63 5-G | 11.139 |


| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C13-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C14-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C15-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C16-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C17-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C18-3 | CAPACITOR ELECTROLYTIC | 10uF 20\% 35VDC | ELNA | RJ2-35-V-100-M-T58 | 14.512 |
| C19-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 2 2२2 37075104 (78104) | 11.136 |
| C20-3 | CAPACITOR ELECTROLYTIC | 10uF 20\% 35VDC | ELNA | RJ2-35-V-100-M-T58 | 14.512 |
| C21-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C22-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C23-3 | CAPACITOR MKT | $0.14 \mathrm{~F} 10 \% 63 \mathrm{VDC}$ | PHILIPS | 222237075104 (78104) | 11.136 |
| C24-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C25-3 | CAPACITOR ELECTROLYTIC | 10uF 20\% 35VDC | ELNA | RJ2-35-V-100-M-T58 | 14.512 |
| C26-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 2 2२2 37075104 (78104) | 11.136 |
| C27-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C28-3 | CAPACITOR MKT | $0.14 \mathrm{~F} 10 \% 63 \mathrm{VDC}$ | PHILIPS | 222237075104 (78104) | 11.136 |
| C29-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C30-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 2 2२2 37075104 (78104) | 11.136 |
| C31-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C32-3 | CAPACITOR MKT | 1000pF 10\% 400VDC | ERO | MKT 1818-210/63 5-G | 11.139 |
| C33-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C35-3 | CAPACITOR MKT | 10nF 5\% 63VDC | PHILIPS | 222237089103 | 11.134 |
| C36-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C37-3 | CAPACITOR ELECTROLYTIC | 4.7uF 20\% 50VDC | ELNA | RJ2-50-V-4R7-M-T58 | 14.510 |
| C38-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C39-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C40-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C41-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C42-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C43-3 | CAPACITOR MKT | 33nF 5\% 100VDC | PHILIPS | 222237089333 | 11.176 |
| C44-3 | CAPACITOR MKT | 0.1 uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C45-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C46-3 | CAPACITOR MKT | 33nF 5\% 100VDC | PHILIPS | 222237089333 | 11.176 |
| C47-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| C48-3 | CAPACITOR ELECTROLYTIC | 10uF 20\% 35VDC | ELNA | RJ2-35-V-100-M-T58 | 14.512 |
| C49-3 | CAPACITOR MKT | 0.1uF 10\% 63VDC | PHILIPS | 222237075104 (78104) | 11.136 |
| D1-3 | DIODE ZENER | 5.1V 5\% 0.4W BZX79C5V1 | PHILIPS | BZX79C5V1 | 26.527 |
| D2-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1 N4448 | 25.147 |
| D4-3 | DIODE ZENER | 5.1V 5\% 0.4W BZX79C5V1 | PHILIPS | BZX79C5V1 | 26.527 |
| D5-3 | DIODE ZENER | 5.1V 5\% 0.4W BZX79C5V1 | PHILIPS | BZX79C5V1 | 26.527 |
| D6-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D7-3 | DIODE ZENER | 9V15\% 0.4W BZX79C9V1 | PHILIPS | BZX79C9V1 | 26.546 |
| D8-3 | DIODE ZENER | 18V 5\% 0.4W BZX79C18 | PHILIPS | BZX79C18 | 26.564 |
| D9-3 | DIODE HIGH SPEED | 1 N 4448 | PHILIPS | 1N4448 | 25.147 |
| D10-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D11-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D12-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D13-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D14-3 | DIODE VOLTAGE REFERENCE | 2.5V 1.5\% LM385-2.5 | MOTOROLA | LM385BZ-2.5 | 26.880 |
| D15-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D16-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1N4448 | 25.147 |
| D17-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1 N4448 | 25.147 |
| D18-3 | DIODE ZENER | 5.1V 5\% 0.4W BZX79C5V1 | PHILIPS | BZX79C5V1 | 26.527 |
| D19-3 | DIODE HIGH SPEED | 1N4448 | PHILIPS | 1 N4448 | 25.147 |
| D20-3 | DIODE ZENER | 3.9V 5\% 0.4W BZX79C3V9 | PHILIPS | BZX79C3V9 | 26.512 |
| J1-3 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| L1-3 | CHOKE FIXED | 180uH 5\% | FASTRON | SMCC-181J-02 | 20.313 |
| OC1-3 | OPTO COUPLER | DUAL DARLINGTON | SHARP | PC 825 | 32.536 |
| OC2-3 | OPTO COUPLER | CNY17-2 | MOTOROLA | CNY17-2 | 32.530 |
| OC3-3 | OPTO COUPLER | CNY17-2 | MOTOROLA | CNY17-2 | 32.530 |
| P2-3 | MULTIPLUG | 1/10" DIL SQ PINS 5x2 POL | AMP | 826656-5 | 78.321 |
| P3-3 | SIL SQUARE PINS | 2 POLES CC=1/10" | AMP | 0-826629-2 | 78.322 |
| P4-3 | PLUG | $2 \times 7$ POLES | 3M | 3598-6002 / 7614-6002 JL | 78.254 |
| P5-3 | PLUG | $2 \times 5$ POLES | 3M | 3654-6002 / 7610-6002 JL | 78.251 |
| P6-3 | PLUG | $2 \times 7$ POLES | 3M | 3598-6002 / 7614-6002 JL | 78.254 |
| Q1-3 | TRANSISTOR AF | BC558 PNP TO-92 | PHILIPS | BC558 (-A/-B/-C)-126 | 28.095 |
| Q2-3 | TRANSISTOR AF SMALL SIGNA | BC640 | PHILIPS | BC640-126 | 28.124 |
| Q3-3 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |
| Q5-3 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |
| Q6-3 | TRANSISTOR AF POWER | PNP TO-220 | MOTOROLA | BD808 (BD810) | 29.095 |
| Q7-3 | TRANSISTOR AF SMALL SIGNA | BC640 | PHILIPS | BC640-126 | 28.124 |
| Q8-3 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |
| Q9-3 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |
| Q10-3 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |


| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Q11-3 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |
| R1-3 | RESISTOR MF | 22k1 OHM 1\% 0.6W | PHILIPS | 232215612213 | 03.441 |
| R2-3 | RESISTOR MF | 1 k 96 OHM 1\% 0.6W | PHILIPS | 232215611962 | 03.401 |
| R3-3 | RESISTOR MF | 1M OHM 5\% 0.33W | PHILIPS | 232218773105 | 02.544 |
| R4-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R5-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R6-3 | RESISTOR MF | 12k OHM 5\% 0.33W | PHILIPS | 232218773123 | 02.498 |
| R7-3 | RESISTOR MF | 120k OHM 5\% 0.33W | PHILIPS | 232218773124 | 02.522 |
| R8-3 | RESISTOR MF | 2 k 7 OHM 5\% 0.33W | PHILIPS | 232218773272 | 02.482 |
| R9-3 | RESISTOR MF | 12k OHM 5\% 0.33W | PHILIPS | 232218773123 | 02.498 |
| R10-3 | RESISTOR MF | 1 k 2 OHM 5\% 0.33W | PHILIPS | 232218773122 | 02.474 |
| R11-3 | RESISTOR MF | 5.6 OHM 5\% 0.33W | PHILIPS | 232218773568 | 02.418 |
| R12-3 | RESISTOR MF | 5.6 OHM 5\% 0.33W | PHILIPS | 232218773568 | 02.418 |
| R13-3 | RESISTOR MF | $12 \mathrm{k} \mathrm{OHM} \mathrm{5} \mathrm{\%} \mathrm{0.33W}$ | PHILIPS | 232218773123 | 02.498 |
| R14-3 | RESISTOR MF | 51R1 OHM 1\% 0.6W | PHILIPS | 232215615119 | 03.370 |
| R15-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R16-3 | RESISTOR MF | 39k2 OHM 1\% 0.6W | PHILIPS | 232215613923 | 03.439 |
| R18-3 | RESISTOR MF | 10kO OHM 1\% 0.6W | PHILIPS | 232215611003 | 03.427 |
| R19-3 | RESISTOR MF | $1 \mathrm{k00}$ OHM 1\% 0.4W | PHILIPS | 232215611002 | 03.395 |
| R20-3 | RESISTOR MF | 10k0 OHM 1\% 0.6W | PHILIPS | 232215611003 | 03.427 |
| R21-3 | RESISTOR ARRAY | 8x10k OHM 5\% 1/8W | PANASONIC | EXB-F9E-103 J | 08.630 |
| R24-3 | RESISTOR MF | 330 OHM 5\% 0.33W | PHILIPS | 232218773331 | 02.460 |
| R25-3 | RESISTOR MF | 1 kO OHM 5\% 0.33W | PHILIPS | 232218773102 | 02.472 |
| R26-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R27-3 | RESISTOR MF | $3 \mathrm{k3}$ OHM 5\% 0.33W | PHILIPS | 232218773332 | 02.484 |
| R28-3 | RESISTOR MF | 330 OHM 5\% 0.33W | PHILIPS | 232218773331 | 02.460 |
| R29-3 | RESISTOR MF | 330 OHM 5\% 0.33W | PHILIPS | 232218773331 | 02.460 |
| R30-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |
| R31-3 | RESISTOR MF | 510 OHM 5\% 0.33W | PHILIPS | 232218773511 | 02.465 |
| R32-3 | RESISTOR MF | 4k7 OHM 5\% 0.33W | PHILIPS | 232218773472 | 02.488 |
| R33-3 | RESISTOR MF | 1 kO OHM 5\% 0.33W | PHILIPS | 232218773102 | 02.472 |
| R34-3 | RESISTOR MF | 510 OHM 5\% 0.33W | PHILIPS | 232218773511 | 02.465 |
| R35-3 | RESISTOR MF | 4k7 OHM 5\% 0.33W | PHILIPS | 232218773472 | 02.488 |
| R36-3 | RESISTOR MF | 1kO OHM 5\% 0.33W | PHILIPS | 232218773102 | 02.472 |
| R37-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R38-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R39-3 | RESISTOR MF | 56k2 OHM 1\% 0.6W | * PHILIPS | 232215615623 | 03.237 |
| R40-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R41-3 | RESISTOR MF | 1 kO OHM 5\% 0.33W | PHILIPS | 232218773102 | 02.472 |
| R42-3 | RESISTOR MF | 10k0 OHM 1\% 0.6W | PHILIPS | 232215611003 | 03.427 |
| R43-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R44-3 | RESISTOR | $30 \mathrm{KOHM} 1 \% 0.4 \mathrm{~W}$ | *PHILIPS | 232215613003 | 03.460 |
| R45-3 | RESISTOR MF | 2 kO OHM 1\% 0.6W | * PHILIPS | 232215612002 | 03.403 |
| R46-3 | RESISTOR | 8.06 KOHM 1\% 0.4W | *PHILIPS | 232215618062 | 03.422 |
| R47-3 | RESISTOR MF | $90 \mathrm{~kg} \mathrm{OHM} \mathrm{1} \mathrm{\%} \mathrm{0.6W}$ | PHILIPS | 232215619093 | 03.476 |
| R48-3 | RESISTOR MF | 100 OHM 5\% 0.33W | PHILIPS | 232218773101 | 02.448 |
| R49-3 | RESISTOR MF | 75k OHM 5\% 0.33W | PHILIPS | 232218773753 | 02.517 |
| R50-3 | RESISTOR MF | 2k2 OHM 5\% 0.33W | PHILIPS | 232218773222 | 02.480 |
| R51-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |
| R52-3 | RESISTOR MF PRECISION | 10kO OHM 0.1\% 75mW | DRALORIC | SMA 0207S-TK25-10k0-0.1\% | 06.130 |
| R53-3 | RESISTOR MF PRECISION | 10kO OHM 0.1\% 75mW | DRALORIC | SMA 0207S-TK25-10k0-0.1\% | 06.130 |
| R54-3 | RESISTOR MF | $1 \mathrm{k00}$ OHM 1\% 0.4W | PHILIPS | 232215611002 | 03.395 |
| R55-3 | RESISTOR MF | 1 kOO OHM 1\% 0.4W | PHILIPS | 232215611002 | 03.395 |
| R56-3 | RESISTOR MF | $3 \mathrm{k92}$ OHM 1\% 0.6W | PHILIPS | 232215613922 | 03.409 |
| R57-3 | RESISTOR MF PRECISION | 2k58 OHM 0.1\% 75mW | DRALORIC | SMA 0207S-TK25-2k58-0.1\% | 06.120 |
| R58-3 | RESISTOR MF PRECISION | 642 OHM 0.1\% 75mW | DRALORIC | SMA 0207S-TK25-642R-0.1\% | 06.110 |
| R59-3 | RESISTOR MF PRECISION | 499 OHM 0.1\% 75mW | PHILIPS | $232214150 x x x$ | 06.105 |
| R60-3 | RESISTOR MF | 8k2 OHM 5\% 0.33W | PHILIPS | 232218773822 | 02.494 |
| R61-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R62-3 | RESISTOR MF | 2 kO OHM 1\% 0.6W | * PHILIPS | 232215612002 | 03.403 |
| R63-3 | RESISTOR MF | 15k4 OHM 1\% 0.6W | PHILIPS | 232215611543 | 03.456 |
| R64-3 | RESISTOR MF | 2k0 OHM 1\% 0.6W | * PHILIPS | 232215612002 | 03.403 |
| R65-3 | RESISTOR MF | $3 \mathrm{kg2}$ OHM 1\% 0.6W | PHILIPS | 232215613922 | 03.409 |
| R66-3 | RESISTOR MF | 470 OHM 5\% 0.33W | PHILIPS | 232218773471 | 02.464 |
| R67-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |
| R68-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R69-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |
| R70-3 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| R71-3 | RESISTOR MF | 1 k 87 OHM 1\% 0.6W | PHILIPS | 232215611872 | 03.474 |
| R72-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |
| R73-3 | RESISTOR MF | $220 \mathrm{OHM} 5 \% 0.33 \mathrm{~W}$ | PHILIPS | 232218773224 | 02.528 |
| R74-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |
| R75-3 | RESISTOR MF | 220 k OHM 5\% 0.33W | PHILIPS | 232218773224 | 02.528 |
| R76-3 | RESISTOR MF | 5 k 1 OHM 5\% 0.33W | PHILIPS | 232218773512 | 02.489 |


| POSITION | DESCRIPTION |  | MANUFACTOR | TYPE | PART NO. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R77-3 | RESISTOR MF | 470 OHM 5\% 0.33W | PHILIPS | 232218773471 | 02.464 |
| U1-3 | PROGRAMMED PROM T2130 | U1-3 T2130 | ECI A/S | C10834- DC3A / 0-0-26103 | 726103 |
| U2-3 | MASTER PROCESSOR UNIT | 8 BIT SERIAL INTERFACE | HITACHI | HD63B03YP | 32.575 |
| U3-3 | UC SUPERVISORY CIRCUIT | MAX 690 | MAXIM | MAX 690 CPA (EJA-MJA) | 32.585 |
| U4-3 | NAND SCHMIDT TRIGGER | 74HC132 | TEXAS | 74HC132N | 34.521 |
| U5-3 | QUAD 2-INP.POS.AND GATE | 74HC08 | TEXAS | SN74HC08N | 34.517 |
| U6-3 | DUAL OPERATIONAL AMP. | MC1458/LM1458 | MOTOROLA | MC1458CP1 | 31.215 |
| U7-3 | 3 to 8 LINE DECODER |  | MOTOROLA | MC74HC237N | 34.550 |
| U8-3 | DARL.DRIVERS HI.CURR/VOLT | ULN2003/MC1413 | MOTOROLA | MC1413P | 31.077 |
| U9-3 | DARL.DRIVERS HI.CURR/VOLT | ULN2003/MC1413 | MOTOROLA | MC1413P | 31.077 |
| U10-3 | 8 BIT SHIFT REG.SERIAL IO | 74HC595 | MOTOROLA | MC74HC595P / MC74HC595AN | 34.502 |
| U11-3 | EEPROM 1k BIT SERIAL | $93 \mathrm{C46}$ | NATIONAL | NM93C46N | 32.709 |
| U12-3 | EEPROM 1k BIT SERIAL | $93 \mathrm{C46}$ | NATIONAL | NM93C46N | 32.709 |
| U13-3 | TRIPLE 3-INPUT NAND GATES | 74HC10 | TEXAS | SN74HC10 | 34.519 |
| U14-3 | 8 BIT SHIFT REG.SERIAL IO | 74HC595 | MOTOROLA | MC74HC595P / MC74HC595AN | 34.502 |
| U15-3 | ANALOG MULTIPLEXER | MC14053BCP | MOTOROLA* | MC14053BCP | 33.201 |
| U16-3 | INTEGRATED CIRCUIT | TL072CP | TEXAS | TL072CP | 31.710 |
| U17-3 | A/D CONVERTER 8 BIT RES. | 4 CHANNELS ADC0834 | NATIONAL | ADC0834CCN (BCN-CCJ-BCJ) | 32.805 |
| XR1-3 | CERAMIC RESONATOR |  | MURATA | CST 800MT-TR | 41.505 |


| CONNECTION BOARD MODULE 6 |  | T2130 | ECI A/S | 5-0-25646I / 4-0-25646L | 625646 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| POSITION | DESCRIPTION |  |  | MANUFACTOR TYPE | PART NO. |
| C1-6 | CAPACITOR CERAMIC | 10nF -20/+80\% CL2 50VDC | KCK | RT-HE70 SK YF 103 Z | 15.170 |
| C2-6 | CAPACITOR CERAMIC | 10nF -20/+80\% CL2 50VDC | KCK | RT-HE70 SK YF 103 Z | 15.170 |
| C3-6 | CAPACITOR MKT | 2u2F 10\% 100VDC | ERO | MKT 1822-522/01 5 R | 11.142 |
| C4-6 | CAPACITOR MKT | 2u2F 10\% 100VDC | ERO | MKT 1822-522/01 5 R | 11.142 |
| C5-6 | CAPACITOR MKT | 1u0F 10\% 100VDC | PHILIPS | 222237325105 | 11.079 |
| C6-6 | CAPACITOR MKT | 1u0F 10\% 100VDC | PHILIPS | 222237325105 | 11.079 |
| D1-6 | DIODE ZENER | 5.1V 5\% 0.4W BZX79C5V1 | PHILIPS | BZX79C5V1 | 26.527 |
| D2-6 | DIODE RECTIFIER 50V/6ADC | MR750, RL750 | MOTOROLA | MR750 ( $51,52,54,56,60$ ) | 25.219 |
| F1-6 | FUSE | 3.15A M $\cdot 5 \times 20 \mathrm{~mm}$ | WICKMANN | 919201 | 45.552 |
| F2-6 | FUSE | 20AM $6.3 \times 32 \mathrm{~mm}$ | LITTELFUSE | 314020. | 45.631 |
| F3-6 | FUSE | 20AM $6.3 \times 32 \mathrm{~mm}$ | LITTELFUSE | 314020. | 45.631 |
| F4-6 | FUSE | 2AF $5 \times 20 \mathrm{~mm}$ | LITTELFUSE | 217002. | 45.556 |
| F6-6 | FUSE | $5 \times 20 \mathrm{~mm} 6 \mathrm{A3}$ T 250V | *ELU | 17912006300 | 45.510 |
| F7-6 | FUSE | $5 \times 20 \mathrm{~mm} 6 \mathrm{A3}$ T 250V | *ELU | 17912006300 | 45.510 |
| J1-6 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| J2-6 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| J3-6 | SOCKET COAX 45 DEG. | PCB VERSION | TAIKO | TMP-J01X-A2 | 78.517 |
| L1-6 | CHOKE | TL531 | TRANS-ELECTRO | 6-0-26309A | 400531 |
| OC1-6 |  |  | SIEMENS | CNY17-4 | 82500001 |
| OC2-6 | OPTO COUPLER | CNY17-3 | MOTOROLA | CNY17-3 | 32.533 |
| P1-6 | PLUG | $2 \times 5$ POLES | 3M | 3654-6002 / 7610-6002 JL | 78.251 |
| P2-6 | PLUG | $2 \times 13$ POLES | 3M | 2526-6002 / 7626-6002 JL | 78.248 |
| P3-6 | MULTIPLUG | $2 \times 4$ POLES PCB VERSION | MOLEX | 39-28-1083 | 78.218 |
| Q1-6 | TRANSISTOR AF | NPN BC639 TO-92 | MOTOROLA | BC639ZL1 | 28.120 |
| R4-6 | RESISTOR MF | 390 OHM 5\% 0.4W | PHILIPS | 232218153391 | 01.189 |
| R5-6 | RESISTOR MF | 1k0 OHM 5\% 0.4W | PHILIPS | 232218153102 | 01.200 |
| R6-6 | RESISTOR MF | 4k7 OHM 5\% 0.33W | PHILIPS | 232218773472 | 02.488 |
| R7-6 | RESISTOR MF | 10k OHM 5\% 0.33W | PHILIPS | 232218773103 | 02.496 |
| RE1-6 | RELAY 12VDC DPDT 1.25A | M1B-12-H/AZ 820-2C212DE | MEISEI | M1B-12-H | 21.295 |
| RE2-6 | RELAY 12VDC 1A 1 SHIFT | V23026-A1002-B201 | SIEMENS | V23026-A1002-B201 | 21.029 |
| S1-6 | SWITCH TOGGLE DPDT | ON-NONE-ON PCB VERSION | C\&K | 7201-S-Y-C-Q-E | 43.018 |
| ST1-6 | TERMINAL BLOCK | 10 POLES 1.5 mm 2 | PTR | AK300/10b m.MESS.SKRUER | 81.017 |
| ST2-6 | TERMINAL BLOCK | 16 POLES 1.5 mm 2 | PTR | AK300/16b m.MESS SKRUER | 81.014 |
| ST3-6 | TERMINAL BLOCK | 14 POLES 1.5mm2 | PTR | AK300/14b m.MESS.SKRUER | 81.029 |
| ST4-6 | TERMINAL BLOCK | SINGLE POLE | RIACON | 360291 | 81.028 |
| ST5-6 | TERMINAL BLOCK | 3 POLES 1.5mm2 | PTR | AK500/3DS-5.0V•M | 81.008 |
| ST7-6 | TERMINAL BLOCK | 10 POLES 1.5 mm 2 | PTR | AK300/10b m.MESS.SKRUER | 81.017 |
| TR1-6 | TRAFO AF | 1:1600 OHMS | TDK | L04EE13-C10153 | 22.500 |
| TR2-6 | TRAFO AF | 1:1600 OHMS | TDK | L04EE13-C10153 | 22.500 |


[^0]:    26043A 5/9

[^1]:    Seen from component side with lower side tracks.
    PCB rev. 256461

