# Tektronix <br> COMMITTED TO EXCELLENCE 

# PLEASE CHECK FOR CHANGE INFORMATION AT THE REAR OF THIS MANUAL. 

## PROGRAMMABLE PULSE HEAD <br> 015-0311-01

Tektronix, Inc.
P.O. Box 500
$\qquad$

Copyright i 1980 Tektronix, inc. All rights reserved. Contents of this publication may not be reproduced in any form without the written permission of Tektronix, Inc.

Products of Tektronix, Inc. and its subsidiaries are covered by U.S. and foreign patents and/or pending patents.

TEKTRONIX, TEK, SCOPE-MOBILE, and are registered trademarks of Tektronix, Inc. TELEQUIPMENT is a registered trademark of Tektronix U.K. Limited.

Printed in U.S.A. Specification and price change privileges are reserved.

## INSTRUMENT SERIAL NUMBERS

Each instrument has a serial number on a panel insert, tag, or stamped on the chassis. The first number or letter designates the country of manufacture. The last five digits of the serial number are assigned sequentially and are unique to each instrument. Those manufactured in the United States have six unique digits. The country of manufacture is identified as follows:

B000000 Tektronix, Inc., Beaverton, Oregon, USA
100000 Tektronix Guernsey, Ltd., Channel Islands
200000 Tektronix United Kingdom, Ltd., London
300000 Sony/Tektronix, Japan
700000 Tektronix Holland, NV, Heerenveen,
The Netherlands

# DIGITALY REMASTERED OUT OF PRINT- MANUAL SCANS 

By Artek Media
$18265200^{\text {th }}$ St. Welch, MN 55089
www.artekmedia.com
"High resolution scans of obsolete technical manuals"

If your looking for a quality scanned technical manual in PDF format please visit our WEB site at www.artekmedia.com or drop us an email at manuals@artekmedia.com and we will be happy to email you a current list of the manuals we have available.

If you don't see the manual you need on the list drop us a line anyway we may still be able to point you to other sources. If you have an existing manual you would like scanned please write for details. This can often be done very reasonably in consideration for adding your manual to our library.

Typically the scans in our manuals are done as follows;

1) Typed text pages are typically scanned in black and white at 300 dpi .
2) Photo pages are typically scanned in gray scale mode at 600 dpi
3) Schematic diagram pages are typically scanned in black and white at 600 dpi unless the original manual had colored high lighting (as is the case for some 70's vintage Tektronix manuals).
4) Most manuals are text searchable
5) All manuals are fully bookmarked

All data is guaranteed for life (yours or mine ... which ever is shorter). If for ANY REASON your file becomes corrupted, deleted or lost, Artek Media will replace the file for the price of shipping, or free via FTP download.

Thanks

## TABLE OF CONTENTS

|  | Page |
| :---: | :---: |
| LIST OF ILLUSTRATIONS . . . . . . . . . . . . . iii |  |
| LIST OF TABLES . . . . . . . . . . . . . . . . . . . . iii |  |
| OPERATORS SAFETY SUMMARY . . . . . . . . . iv |  |
| SERVICE SAFETY SUMMARY . . . . . . . . . . . v |  |
| Section 1 | SPECIFICATION |
|  | Introduction . . . . . . . . . . . . . . 1-1 |
|  | Accessories . . . . . . . . . . . . . . 1-1 |
|  | Performance Conditions . . . . . . 1-1 |
|  | Electrical Characteristics . . . . . . 1-1 |
|  | Environmental Characteristics . . . 1-2 |
|  | Physical Characteristics . . . . . . 1-3 |
| Section 2 | OPERATING INSTRUCTIONS |
|  | Introduction . . . . . . . . . . . . . 2-1 |
|  | Connecting to the CG 551AP . . . 2-1 |
|  | Controls and Connectors . . . . . 2-1 |
|  | General Operating Information .. 2-1 |
|  | Programming Commands Via |
|  | GPIB . . . . . . . . . . . . . . . . . . 2-2 |
|  | Repacking Information . . . . . . . 2-3 |
|  | WARNING |
| THE FOLLOWING SERVICING INSTRUCTIONS |  |
| ARE FOR USE BY QUALIFIED PERSONNEL ONLY. |  |
| TO AVOID PERSONAL INJURY, DO NOT PER- |  |
| FORM ANY SERVICING OTHER THAN THAT CON- |  |
| TAINED IN OPERATING INSTRUCTIONS UNLESS |  |
| Section 3 | THEORY OF OPERATION |
|  | Introduction . . . . . . . . . . . . . . 3-1 |
|  | Relay Switching Circuit . . . . . . . 3-2 |
|  | Fast Edge Driving Circuits . . . . . 3-4 |
|  | Positive Fast Edge Generator . 3-4 |
|  | Negative Fast Edge Generator . 3-4 |
|  | Straight-Through (Direct) |
|  | Mode . . . . . . . . . . . . . . . . 3-6 |

Section 4 CALIBRATION
Performance Check . . . . . . . . . 4-1
Introduction . . . . . . . . . . . . . 4-1
Calibration Interval . . . . . . . . . 4-1
Services Available . . . . . . . . . 4-1
Test Equipment Required . . . . 4-1
Performance Check Procedure . . 4-2
Adjustment Procedure . . . . . . . . 4-6
Introduction . . . . . . . . . . . . . 4-6
Test Equipment Required . . . . 4-6
Preparation . . . . . . . . . . . . . 4-6
Section 5 MAINTENANCE
Recalibration . . . . . . . . . . . . . 5-1
Disassembly and Reassembly .. . 5-1
Bottom Cover Removal and
Replacement . . . . . . . . . . . . 5-1
Top Cover Removal and
Replacement . . . . . . . . . . . . 5-2
Hypcon Connector . . . . . . . . . . 5-2
Disassembly and Removal . . . . 5-4
Reassembly and Replacement . 5-4
Board Removal and Replacement 5-4
Cable Removal and Replacement . 5-4
Log Cell Removal and Replacement 5-4
Cleaning Instructions . . . . . . . . . 5-5
Exterior . . . . . . . . . . . . . . . . 5-5
Interior . . . . . . . . . . . . . . . 5-5
Obtaining Replacement Parts ... 5-5
Ordering Parts . . . . . . . . . . . . . . 5-6
Static-Sensitive Components . . . . 5-6
Test Equipment . . . . . . . . . . . . 5-6

## Section 6 OPTIONS

Section 7 REPLACEABLE ELECTRICAL PARTS

Section 8 DIAGRAMS AND ILLUSTRATIONS
Schematic Diagrams
Parts Location Grids

## TABLE OF CONTENTS (cont)

| Section 9 | REPLACEABLE MECHANICAL CHANGE INFORMATION |
| :--- | :--- |
|  | PARTS |
|  | Exploded View |
|  | Accessories |

## LIST OF ILLUSTRATIONS

| Figure No. |  | Page | Figure No. |  | Page |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Programmable Pulse Head, 015-0311-01 |  | vi | 3-8 | From NEGATIVE FAST EDGE Mode To Direct Mode | 3-6 |
| 2-1 | Pulse Head Connector | 2-3 | 4-1 | Pulse Head Calibration And Performance |  |
| 3-1 | Pulse Head Block Diagram | 3-1 |  | Check Set-up | 4-2 |
| 3-2 | From Negative to positive while in | 3-2 | 4-2 | Fast Edge Pulse Risetime | 4-4 |
| 3-3 | FAST EDGE Mode . . . . . . . . . . . . |  | 4-3 | Fast Edge Pulse Leading Edge (Aberrations And Adjacent Peaks) | 4-4 |
|  | FAST EDGE Mode | 3-3 | 4-4 | Fast Edge Pulse Frequency Output Check |  |
| 3-4 | From Direct Mode To POSITIVE FAST |  |  | Set-up | 4-5 |
|  | EDGE Mode | 3-3 | 5-1 | Maintenance Diagram (Exploded View) | 5-1 |
| 3-5 | From Direct Mode To NEGATIVE FAST | 3-4 | 5-2 | Hypcon Connector (Exploded View) | 5-3 |
|  | EDGE Mode |  | 8-1 | Edge Driver Board (A20) (Parts Location) |  |
| 3-6 | Polarity And Output Relay Switching | 3-5 | 8-2 |  |  |
| 3-7 | From POSITIVE FAST EDGE Mode To |  | 8-2 | Fast Edge Board (A22) (Parts Location) |  |
|  | Direct Mode | 3-6 | 8-3 | Fast Edge Board (A22) (Adjust Location) |  |

## LIST OF TABLES

| Table |  | Page | Table |  | Page |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1-1 | ELECTRICAL CHARACTERISTICS | 1-1 | 4-1 | LIST OF TEST EQUIPMENT |  |
| 1-2 | ENVIRONMENTAL CHARACTERISTICS | 1-2 |  | REQUIREMENTS | 4 |
| 1-3 | PHYSICAL CHARACTERISTICS | 1-3 | 5-1 | RELATIVESUSCEPTIBILITY TO STATIC |  |
| 2-1 | CG 551AP SETTING COMMANDS | 2-2 |  | DISCHARGE DAMAGE | 5-6 |

## OPERATORS SAFETY SUMMARY

The general safety information in this part of the summary is for both operating and servicing personnel. Specific warnings and cautions will be found throughout the manual where they apply, but may not appear in this summary.

## TERMS

## In This Manual

CAUTION statements identify conditions or practices that could result in damage to the equipment or other property.

WARNING statements identify conditions or practices that could result in personal injury or loss of life.

## As Marked on Equipment

CAUTION indicates a personal injury hazard not impmediately accessible as one reads the marking, or a hazard to property including the equipment itself.

DANGER indicates a personal injury hazard immediately accessible as one reads the marking.

## SYMBOLS

## In This Manual



This symbol indicates where applicable cautionary or other information is to be found.

## As Marked on Equipment



## Danger Arising From Loss of Ground

Upon loss of the protective-ground connection, all accessible conductive parts (including knobs and controts that may appear to be insulating) can render an electric shock.

## Use the Proper Power Cord

Use only the connector specified for your product.
Refer connector changes to qualified service personnel.

## Do Not Operate in Explosive Atmospheres

To avoid explosion, do not operate this product in an explosive atmosphere unless it has been specifically certified for such operation.

## Do Not Remove Covers or Panels

To avoid personal injury, do not remove the product covers or panels. Do not operate the product without the covers and panels properly installed.

# SERVICE SAFETY SUMMARY FOR QUALIFIED SERVICE PERSONNEL ONLY 

Refer also to the preceding Operators Safety Summary.

## Do Not Service Alone

Do not perform internal service or adjustment of this product unless another person capable of rendering first aid and resuscitation is present.

## Use Care When Servicing With Power On

To avoid personal injury, do not touch exposed connections and components while power is on.

Disconnect power before removing protective panels, soldering, or replacing components.


## SPECIFICATION

## Introduction

The Pulse Head is an accessory to the CG 551AP Programmable Calibration Generator. It connects to the main output of the CG 551AP and is programmed and stimulated by signals from the CG 551AP. This accessory generates 1 V square waves with a well defined leading edge. This edge is used to verify and calibrate transient response in wide-band oscilloscopes.

## NOTE

The references to the CG 551AP in this manual apply equally to the CG 5001. The CG 5001 has a newly designed Power Module to plug-in GPIB interface connector. This allows it to be used in all TM 5000 Power Modules. The CG 551AP functional information also applies to the CG 5001.

## Accessories

This instruction manual is the only standard accessory.

## Performance Conditions

The electrical characteristics are valid only if the Pulse Head has been calibrated at an ambient temperature between $+20^{\circ} \mathrm{C}$ and $+30^{\circ} \mathrm{C}$ and is operating at an ambient temperature between $0^{\circ} \mathrm{C}$ and $+50^{\circ} \mathrm{C}$, unless otherwise noted.

Items listed in the Performance Requirements column of the Electrical Characteristics are verified by completing the Performance Check in the Calibration section of this manual.

Items listed in the Supplemental Information column are not verified in this manual.

Table 1-1
ELECTRICAL CHARACTERISTICS

| Characteristics | Performance Requirements | Supplemental Information |
| :---: | :---: | :---: |
| Fast Edge Pulse <br> Amplitude <br> Variable Range | $\begin{aligned} & 1.1 \vee \text { peak, } \pm 5 \% \text {. } \\ & \pm 10 \% \text {. } \end{aligned}$ | ```Required Input Signals: V Control Pin = m9.6 V, \pm1%. V Coax = \pm5 V, \pm1%.``` |
| Polarity | Positive rising from ground to +1 V or negative falling from ground to -1 V . | In the straight-through mode, the pulse will output any signal routed through the CG 551AP OUTPUT connector. |
| Risetime | $\leqslant 200$ ps. | Driving waveform $\mathrm{T}_{\mathrm{r}}<10 \mathrm{~ns}$. <br> Triggered on edge going to ground. |
| Leading Edge Aberrations | $\pm 3 \%$ of pulse amplitude; not to exceed $4 \%$, p-p for adjacent peaks. | Valid from 0 to 50 ns . |
| Long Term Flatness |  | $\pm 1 \%$, after 50 ns. |
| Frequency | 100 Hz to 100 kHz in decade steps. |  |
| Source Resistance |  | $50 \Omega, \pm 2 \%$. |
| Control Pin Signals <br> Programming <br> Operating |  | $\pm 12 \mathrm{~V}, 150 \mathrm{~mA}$ maximum. <br> $\pm 10 \mathrm{~V}, 60 \mathrm{~mA}$ maximum. |

Table 1-1 (cont)

| Characteristic | Performance Requirement | Supplemental Information |
| :--- | :--- | :--- |
| Coax Signals |  |  |
| Programming |  | $\pm 5 \mathrm{~V}, 30 \mathrm{~mA}$ maximum (dc). |
| Operating |  | $\pm 5 \mathrm{~V}, 30 \mathrm{~mA}$ maximum (square wave). |
| Maximum Power Requirements |  | $<2 \mathrm{~W}$. |
| Programming |  | $<1 \mathrm{~W}$. |
| Operating |  | $<0.05 \mathrm{~W}$. |

Table 1-2
ENVIRONMENTAL CHARACTERISTICS

| Characteristics | Description |  |
| :---: | :---: | :---: |
| Temperature |  | Meets MIL-T-28800B, class 5. |
| Operating | $0^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$. |  |
| Non operating | $-55^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$. |  |
| Humidity | $90-95 \% \mathrm{RH}$ for 5 days to $50^{\circ} \mathrm{C}$. | Exceeds MIL-T-28800B, class 5. |
| Altitude |  | Exceeds MIL-T-28800B, class 3. |
| Operating | 4.6 km ( 15,000 feet). |  |
| Non operating | 15 km ( 50,000 feet). |  |
| Vibration | 0.64 mm ( $0.0252^{\prime \prime}$ ) 10 Hz to 55 Hz , 75 minutes. | Meets or exceeds MIL-T-28800B, class 3. |
| Shock | 50 g 's ( $1 / 2$ sine), $11 \mathrm{~ms}, 18$ shocks. | Meets or exceeds MIL-T-28800B, class 3. |
| Bench Handling | $45^{\circ}$ or $4^{\prime \prime}$ equilibrium, whichever occurs first. | Meets MIL-T-28800B, class 3. |
| EMI Compatibility |  |  |
| Conducted Emissions |  | Meets MIL-T-28800B, class 3 MIL-STD- |
| Conducted Susceptibility |  | 461A when performed in accordance with MIL-STD-462 with following excep- |
| Radiated Emissions |  | tions: Radiated emissions, tested to |
| Radiated Susceptibility |  | 30 dB above specification from dc to 700 MHz . |
| Electrical Discharge | 20 kV maximum. | Charge applied to each protruding area of the product under test except the output terminals. |
| Transportation |  |  |
| Vibration <br> Package Drop | $25 \mathrm{~mm}\left(1^{\prime \prime}\right)$ at 270 rpm for 1 hour. <br> 10 drops from $91 \mathrm{~cm}(3 \mathrm{ft})$. | Qualified under National Safe Transit Association Preshipment Test Procedures $1 \mathrm{~A}-\mathrm{B}-1$ and $1 \mathrm{~A}-\mathrm{B}-2$. |

Table 1-2 (cont)

| Characteristics | Description |
| :--- | :--- |
| Cables |  |
|  | 10,000 cycles at $120^{\circ}$ flex with 0.68 kg |
|  | $(1.5 \mathrm{lb})$ weight. |
|  | $15.88 \mathrm{~kg}(35 \mathrm{lbs})$ axial pull at 1 minute |
|  | duration. |

Table 1-3
PHYSICAL CHARACTERISTICS

| Characteristics | Description |
| :--- | :--- |
| Finish | Light and dark gray painted metal. |
| Overall Dimensions | $196.9 \mathrm{~mm}\left(7.75^{\prime \prime}\right) \mathrm{L} \times 53.4 \mathrm{~mm}\left(2.102^{\prime \prime}\right) \mathrm{W} \times 34.3 \mathrm{~mm}\left(1.35^{\prime \prime}\right) \mathrm{H}$. |
| Net Weight | $0.27 \mathrm{~kg}(0.6 \mathrm{lb})$. |

# THIS <br> PAGE <br> LEFT BLANK 

## SCANS <br> By <br> Artek Media

## OPERATING INSTRUCTIONS

## Introduction

The Pulse Head is an accessory designed to operate with the CG 551AP Programmable Calibration Generator and is calibrated and ready to use when received.

The attached cable from the Pulse Head contains signal as well as power lines and connects directly to the CG 551AP front panel OUTPUT connector. Power for the head is taken from the CG 551 AP through this connector.

The Pulse Head is programmed and stimulated by signals from the CG 551AP. The head generates a squarewave whose leading edge is used to verify and calibrate transient responses in other instruments.

## Connecting to CG 551AP



Use care when connecting the Pulse Head plug to the CG 551AP to avoid pin misalignment and possible connector damage.

Observe the positioning dot on the Pulse Head plug and align this dot with the positioning dot on the outside ring of
the CG 551AP OUTPUT connector. Insert the plug into this connector slowly.

## Controls and Connectors

OUTPUT connector-Output for CG 551AP amplitude mode voltage, time signals, or current signals (direct mode operation). Output for Pulse Head generated positive-going or negative-going fast rise pulses (pulse mode operation).

## General Operating Information

With the appropriate CG 551AP settings and proper triggering of the oscilloscope, a fast edge pulse will appear on the crt screen. This pulse will indicate that the Pulse Head is functioning properly.

Attach the Pulse Head OUTPUT connector to the oscilloscope under calibration. The oscilloscope being calibrated should be checked for time base accuracy and linearity.

After warm-up time, press to light the CG 551AP OUTPUT ON pushbutton and the FAST EDGE pushbutton. Select either the $\boldsymbol{F}$ (positive) or $\mathcal{Y}$ (negative) EDGE POLARITY pushbuttons on the CG 551AP.


Fig. 2-1. Pulse Head connector.

With the appropriate plug-in settings and proper triggering of the oscilloscope, a fast edge pulse will appear on the crt screen. This pulse will indicate that the Pulse Head is functioning properly.

## Programming Commands Via GPIB

The Pulse Head can be programmed from the CG 551AP via commands received from the GPIB. The commands (Header and Argument) and descriptions are given in Table 2-1.

Table 2-1
CG 551AP SETTING COMMANDS

| Header | Argument | Description |
| :---: | :---: | :---: |
| MODE | FE or FASTEDGE | Sets instrument to FAST EDGE mode. |
| POS |  | Sets positive EDGE polarity. |
| NEG |  | Sets negative EDGE polarity. |
| TRIG | ON | Turns TRIGGER OUTPUT on. |
|  | OFF | Turns TRIGGER OUTPUT off. |
|  | NORM | Sets trigger rate same as output signal rate. |
|  | X. 1 | Turns on TRIGGER OUTPUT and sets trigger rate to one-tenth output signal rate. |
|  | X. 01 | Turns on TRIGGER OUTPUT and sets trigger rate to onehundredth output signal rate. |
| FXD |  | Sets instrument to 0.0\% error with error display off. |
| VAR |  | Sets instrument to display device under test percent error readout. |
| PCT | <nr 2> | Sets device under test percent readout. |
| INC |  | Adds 0.1 to present device under test error readout for HIGH and FAST indications or subtracts 0.1 for LOW and SLOW indications. |
| DEC |  | Subtracts 0.1 from present percent error readout for HIGH and FAST indications or adds 0.1 for LOW and SLOW indications |
| FREQ | <nr 3> | Sets chop frequency from 100 Hz to 100 kHz . |
| TRIG | ON | Turns TRIGGER OUTPUT on. |
|  | OFF | Turns TRIGGER OUTPUT off. |
|  | NORM | Sets trigger rate same as output signal rate. |
|  | X. 1 | Turns on TRIGGER OUTPUT and sets trigger rate to one-tenth output signal rate. |
|  | X. 01 | Turns on TRIGGER OUTPUT and sets trigger rate to onehundredth output signal rate. |
| OUT | ON | Sets main OUTPUT on. |
|  | OFF | Sets main OUTPUT off. |

NOTE
Refer to the CG 551AP instruction manual Programming section for more detailed information.

## Repackaging Information

If shipping this instrument to a Tektronix Service Center for service or repair, attach a tag showing owner (with address) and the name of an individual to contact. include the complete instrument serial number and a description of the service required.

Save and reuse the package in which the instrument was shipped. If the original packaging is unfit for use or not available, repackage the instrument as follows:

1. Obtain a corrugated carton having inside dimensions of no less than six inches more than the instrument dimensions; this will allow for cushioning. Use a carton having a test strength of at least 200 pounds.
2. Surround the instrument with protective polyethylene sheeting.
3. Cushion the instrument on all sides by tightly packing dunnage or urethane foam between carton and instrument, allowing three inches on all sides.
4. Seal carton with shipping tape or industrial staples

# THIS <br> PAGE <br> LEFT BLANK 

## SCANS <br> By <br> Artek Media

## THEORY OF OPERATION

## Introduction

Power, control logic, and signal input to the Pulse Head is obtained from the CG 551AP OUTPUT connector, through two leads and a coaxial cable.

After connecting the Pulse Head, the CG 551AP Head Sense circuit senses the particular head connected. When a Pulse Head is connected, the CG 551AP connector control pin has, momentarily, approximately +3 V dc When this voltage is sensed by the CG 551AP Head Sense circuit, the relays are energized for the straight-through mode.

The Pulse Head circuitry is composed of three functional blocks; positive fast-edge generator, negative fastedge generator and the relay drivers. See Fig. 3-1.

Two different signals are required to drive the Pulse Head circuits:

1. A variable $10 \mathrm{Vdc}( \pm 10 \%)$ to supply power to the relay drivers and fast edge generators. After programming, this voltage also determines the amplitude of the 1 V fast edge output.
2. A squarewave $\pm 5 \vee$ to trigger the drive circuitry and to program the relays.

In the straight-through (direct) mode the output relay, K 1010 , is set to allow voltage, timing, or current signals generated in the CG 551AP to pass directly to the Pulse Head OUTPUT connector. With relay K1010 switched to the FAST EDGE mode position, either positive-going or negative-going fast rise pulses (generated by Pulse Head


Fig. 3-1. Pulse Head block diagram.
circuitry) are passed to the OUTPUT connector. See waveforms in Fig. 3-2 and Fig. 3-3 for output pulses. Signals controlling this action come from the CG 551AP during the first 35 ms after power on, or a mode switching, or polarity change occurs (see waveforms in Fig. 3-4 and Fig. 3-5). Switching is arranged so that only one relay (log celi) is switched at a time. The 35 ms settling delay prevents both relays switching at the same time.

## NOTE

The waveforms shown are idealized and only approximate the display readout for the given signal conditions.

## Relay Switching Circuit

The input relay, K1210, closes whenever the control line goes to + or -12 V . The output relay, K1010, and polarity relay, K1110, are dual coil latching switches. A 10 ms pulse is required to set or reset them. The CG 551AP generates all programming signals for the relays. Relay K1010 is pulsed when the control pin and the coaxial line both have the same polarity. The $\pm 5 \mathrm{~V}$ is dc coupled to the bases of transistors Q1211 and Q1213. Relay K1110 is driven when the 10 V changes polarity. The
signal is ac coupled through C1103 (located on the Edge Driver board) to the bases of transistors Q1200 and Q1203. This signal, depending on polarity, causes a current pulse in the collector of either Q1200 or Q1203. With 10 V on the control pin, the input relay K 1210 is closed connecting the coax center conductor to the edge driver circuits.

After entering the FAST EDGE mode, the CG 551AP programs the control pin positive ( +12 V ). After 35 ms settling delay, the coaxial signal cable is programmed positive for another 35 ms . As the control pin draws current through R1202, (located on the Edge Driver board) K 1210 closes. A positive voltage ( +10 V ) is applied through CR1100 to the collector of Q1200. This sets K1110 (see Fig. 3-6). Positive drive is also applied to Q1211 (also through CR1100), which sets K1010. A few milliseconds later, the CG 551 AP applies dc voltage and signal voltage as required for the pulse polarity selected by the EDGE POLARITY pushbuttons on the CG 551AP.

When the positive EDGE POLARITY pushbutton on the CG 551AP is pressed, the operation for the Pulse Head circuit requires the control pin to remain at +10 V and the coaxial line to supply a square wave that switches between ground and -5 V through R1117 (see Fig. 3-6). With these two lines carrying opposite polarity voltages, Q1211


Fig. 3-2. From NEGATIVE to POSITIVE while in FAST EDGE mode.


Fig. 3-3. From POSITIVE to NEGATIVE while in FAST EDGE mode.


Fig. 3-4. From direct mode to POSITIVE FAST EDGE mode.


Fig. 3-5. From direct mode to NEGATIVE FAST EDGE mode.
remains off and no further switching of K1010 occurs. Q1200 is off. The time constant set by R1200 and C1103 (located on the Edge Driver board) in the base of Q1200 determines the length of time Q1200 is on. The +10 V is now applied through diode CR1100 as supply voltage for the positive fast-edge generator circuit. The CG 551AP has now changed the signal on the coaxial line from +5 V to a negative square wave (between ground and -5 V ). The repetition rate is determined by the lighted FREQUENCY pushbutton on the CG 551AP.

## Fast Edge Driving Circuits

Positive Fast Edge Generator. This generator is composed of transistors Q1001, Q1202, Q1101, Q1000, and associated circuitry.

When the signal on the coaxial line is $-5 \mathrm{~V}, \mathrm{Q} 1202$ and Q1001 are turned off. Diode CR1000 conducts. When Q1001 is not conducting, Q1101 is turned on to maintain a constant current through diode CR1100 and a constant voltage on Q1001 emitter. This improves the waveform long term flatness at low repetition rates. This action connects Q 1000 (current source) to -5 V to forward bias a snap-off diode located in the hybrid pulse shaper circuit, U1112. During forward conduction, the snap-off diode stores current carriers. When the coaxial line-driving wavef orm rises toward ground, Q1000turns off and Q1202 turns on. This causes Q1001 to turn on. Diode CR1102 prevents Q1001 from going into saturation. The positive voltage now applied to the shaper circuit in the Hybrid

Pulser causes the current to reverse. The snap-off diode momentarily acts like a battery (until it runs out of stored carriers). When the diode stops conducting, the voltage across the diode snaps positive. This positive excursion develops a fast step ( 200 ps ) at the OUTPUT connector. The output must be terminated in $50 \Omega$ to obtain the proper waveshape.

As the coaxial line driving signal goes to - $5 \mathrm{~V}, \mathrm{CR} 1000$ conducts causing Q1000 to turn on. The snap-off diode in the hybrid shaper circuit is again forward biased and the cycle repeats.

The 5.1 V zener diode, VR1205 acts as a voltage stabilizer in the base circuit of Q1202 to prevent changes in time delay with amplitude. To minimize jitter, the bias on VR1205 is chosen so that triggering occurs at the steepest point of the 5 V driving waveform.

Negative Fast Edge Generator. This generator is composed of transistors Q1212, Q1111, Q1012, Q1011, and associated circuitry.

The negative fast edge generator operation is similar to the positive fast edge operation. Refer to the Positive Fast Edge Generator circuit description.


Fig. 3-6. Polarity and output relay switching.

Straight-Through (Direct) Mode. When the CG 551AP is switched out of the fast edge mode, both the control pin and coaxial lines go negative. See waveforms in Fig. 3-7 and Fig. 3-8. This applies a negative voltage and negative base drive to Q1213 which switches K1010 to the reset (direct mode) position (see Fig. 3-6). Approximately 10 ms
later, the CG 551AP shifts the control line to near 0 V which opens the input relay, K1210.

The CG 551AP output signal is now connected directly to the OUTPUT connector on the Pulse Head.


Fig. 3-7. From POSITIVE FAST EDGE mode to direct mode.


Fig. 3-8. From NEGATIVE FAST EDGE mode to direct mode.

## CALIBRATION

## PERFORMANCE CHECK

## Introduction

This procedure checks the electrical performance requirements as listed in the Specification section in this manual. Perform the Adjustment Procedure if the Pulse Head fails to meet these checks. In some cases, recalibration may not correct the discrepancy; circuit troubleshooting is then indicated.

## Calibration Interval

To ensure instrument accuracy, check the calibration every 1000 hours of operation or at a minimum of every six months if used infrequently.

## Services Available

Tektronix, Inc. provides complete instrument repair and adjustment at local field service centers and at the factory service center. Contact your local Tektronix field office or representative for further information.

## Test Equipment Required

The following test equipment, or equivalent is suggested to perform the Performance Check and Adjustment Procedure (refer to Table 4-1).

Table 4-1

## LIST OF TEST EQUIPMENT REQUIREMENTS

| Description | Minimum Specifications | Applications | Example |
| :---: | :---: | :---: | :---: |
| Power Module | GPIB Compatible | All tests | TEKTRONIX TM 506 (MOD JB) or TM 515 (MOD UB) |
| Programmable Calibration Generator, CG 551AP |  | All tests | TEKTRONIX CG 551AP |
| Oscilloscope mainframe | Must accept sampling type plug-ins. | All tests | TEKTRONIX 7603 or equivalent |
| Vertical plug-in | Must accept S-6 Sampling Head | All tests | TEKTRONIX 7S11 |
| Vertical plug-in | $\mathrm{T}_{\mathrm{s}}<10 \mathrm{~ns}$. | Fast edge low frequency test | TEKTRONIX 7A26 or equivalent |
| Horizontal plug-in | Maximum sweep rate 200 ps /div. | All tests | TEKTRONIX 7 T11 |
| Horizontal plug-in | Maximum sweep rate $10 \mathrm{~ns} / \mathrm{div}$. | Fast edge low frequency test | TEKTRONIX 7B80 or equivalent |
| Sampling head |  | All tests | TEKTRONIX S-6 |
| $50 \Omega$ termination male | 3 mm | All tests | Tektronix Part No. 015-1022-00 |
| $50 \Omega 5 \times$ Attenuator <br> Bnc connectors |  | All tests | Tektronix Part No. 011-0060-02 |
| Coaxial cable, $8^{\prime \prime} 3 \mathrm{~mm}$ semi-rigid | $50 \Omega \pm 1 \Omega, 1$ ns line | All tests | Tektronix Part No. 015-1023-00 |

Table 4-1 (cont)

| Description | Minimum Specifications | Applications | Example |
| :--- | :--- | :--- | :--- |
| $50 \Omega$ bnc to 3 mm <br> adapter (2 req) |  | All tests | Tektronix Part No. <br> $131-2038-00$ |
| 3' sampling head <br> extender | Flexible couplings sampler <br> to oscilloscope | All tests | Tektronix Part No. <br> $012-0124-00$ |
| Insulated adjustment <br> tool |  | Adjustment Procedure | Tektronix Part No. <br> 003-0675-00 |
| Coaxial Cable | Bnc connectors | All tests | Tektronix Part No. <br> $012-0057-01$ |

## PERFORMANCE CHECK PROCEDURE

Turn on CG 551AP and oscilloscope. Refer to Fig. 4-1 for the following check set-up.


Fig. 4-1. Pulse Head Calibration and Performance Check set-up.

## Preliminary control seftings:

Set CG 551AP controls:
AMPLITUDE MODE
FAST EDGE
(delayed mode)

Depress and hold FAST EDGE pushbutton to light SHIFT pushbuttons (SHIFT $\rightarrow$ and SHIFT -). This places the Pulse Head in delayed mode.

| VARIABLE | off |
| :--- | :--- |
| EDGE POLARITY | $-\varsigma$ (positive) |
| FREQUENCY | 100 kHz |
| OUTPUT | on |
| TRIGGER OUTPUT | NORM, on |

Set 7T11 controls:

| TIME/DIV VARIABLE | (CAL IN) |
| :--- | :--- |
| TIME POS RNG | 50 ns |
| TIME/DIV | 5 ns |
| TRIG AMP | $\times 1$ |
| SEQUENTIAL | in |
| SLOPE | + |
| TRIG INPUT | EXT $50 \Omega 2 \vee$ MAX |
|  | (in) |
| SCAN | approximately midrange |
| REP | in |

Set 7S11 controls:

| DELAY | midrange |
| :--- | :--- |
| DOT RESPONSE |  |
| $\quad$ NORMAL | in |
| DC OFFSET | midrange |
| + UP | in |
| VARIABLE | in |
| mVOLTS/DIV | 50 |

## NOTE

Make certain that the $7 T 11$ and $7 S 11$ plug-in units are calibrated to the mainframe being used.

## 1. Check Fast Edge Pulse Amplitude

a. CHECK-for a waveform on the crt display.
b. Set 7T11 TRIG LEVEL for a stable crt display and rotate TIME POSITION to display the pulse leading edge on first major vertical graticule division. Adjust 7S11 DELAY, if necessary.
c. CHECK-pulse for 1.1 V amplitude $\pm 5 \%$ ( 4.4 major graticule divisions).
d. Set the CG 551AP VARIABLE control to ON and rotate VARIABLE control to change pulse amplitude on the crt display.
e. CHECK-for the adjustable range $> \pm 10 \%$ of the pulse amplitude.
f. Press and hold to light CG 551AP EDGE POLARITY (negative) pushbutton and set the CG 551AP VARIABLE control to OFF.
g. Repeat parts cthrough e.

## 2. Check Fast Edge Pulse Risetime

Maintain same check setup and control settings as above, with exception of:

$$
\begin{array}{ll}
\text { CG 551AP VARIABLE } & \text { off } \\
\text { EDGE POLARITY } & \underset{\sim}{\gamma} \text { (positive) } \\
\text { 7S11 VARIABLE } & \text { out }
\end{array}
$$

a. CHECK—for a displayed pulse on the crt.
b. Rotate the 7S11 VARIABLE control to align the top and bottom of the displayed pulse with the 0\% and $100 \%$ crt reference marks.
c. Change the 7 T 11 TIME/DIV control to $.5 \mathrm{~ns}(500 \mathrm{ps})$.
d. CHECK-for a displayed pulse on the crt display.
e. Rotate the 7T11 TIME POSITION control to position pulse as indicated in Fig. 4-2.
f. CHECK-that the pulse risetime ( $10 \%$ to $90 \%$ points) is no greater than 200 ps .
g. Press on to light CG 551AP EDGE POLARITY $\longleftarrow$ (negative) pushbutton.
h. Press the 7S11 INVERT switch.

## Performance Check Procedure

i. Change the 7 T 11 TIME/DIV control to 5 ns and repeat parts a through e (the pulse in Fig. 4-2 will be inverted).
j. CHECK-that the pulse falltime is no greater than 200 ps.


Fig. 4-2. Fast edge pulse risetime.

## 3. Check Fast Edge Leading Edge Aberrations

Maintain same check setup and control settings as above with exceptions of:

| CG 551AP |  |
| :---: | :---: |
| EDGE POLARITY | (positive) |
| 7 T 11 |  |
| TIME/DIV | 1 ns |
| 7S11 |  |
| DOT RESPONSE | ccw |
| SMOOTH | in |
| +UP | in |

Refer to Fig. 4-3 for following check:
a. Adjust the 7S11 VARIABLE control for 5 divisions of display.
b. Rotate 7T11 TRIG LEVEL control for a stable crt display
c. Set 7T11 SCAN control to the approximate $90^{\circ}$ clock position and rotate TIME POSITION control to line up the pulse leading edge on the first vertical major graticule line.
d. Set 7S11 mVOLTS/DIVision to 5 (2.0\%/div)
e. Position the top edge of the pulse on the center graticule line.
f. CHECK—that the pulse leading edge aberrations are less than $\pm 3 \%$ of pulse amplitude ( $\pm 1.5$ major graticule divisions).
g. CHECK-that the pulse aberrations do not exceed $4 \%$, peak-to-peak for adjacent peaks ( 2.0 major graticule divisions).


Fig. 4-3. Fast edge pulse leading edge. (a) $\leqslant \pm 3 \%$ aberrations. (b) $\leqslant \pm 4 \%$ adjacent peaks.

## 4. Check Fast Edge Puise Frequency Output ( 100 Hz to 100 kHz )

Refer to check set-up in Fig. 4-4.

Suggested control settings:
7A26
VOLTS/DIV . 5
7B80
TIME/DIV
1 ms
EXT TRIG IN
(pushbutton)
IN
CG 551AP FREQUENCY (pushbutton) $\quad 100 \mathrm{~Hz}$
a. Set the 7 B80 TRIGGERING LEVEL control for a stable crt display.


Fig. 4-4. Fast edge pulse frequency output check set-up.
b. CHECK-for a displayed pulse.
c. Change 7 B80 TIME/DIV switch to .1 ms and CG 551AP FREQUENCY to 1 kHz .
d. CHECK-for a displayed pulse
e. Change 7B80 TIME/DIV switch to $10 \mu \mathrm{~s}$ and CG 551AP FREQUENCY to 10 kHz .
f. CHECK—for a displayed pulse.
g. Change 7880 TIME/DIV switch to $1 \mu \mathrm{~s}$ and CG 551AP FREQUENCY to 100 kHz .
h. CHECK-for a displayed pulse.

This completes the Performance Check Procedure.

## ADJUSTMENT PROCEDURE

## Introduction

Use this Adjustment Procedure to restore the Pulse Head to original factory calibration.

If this instrument has undergone repairs, the Adjustment Procedure is recommended.

## Test Equipment Required

Refer to Table 4-1 for applicabletest equipment used in this procedure.

## Preparation

Access to the internal adjustments is achieved with the Pulse Head top cover removed (see Maintenance Procedure in this manual).

After 30 minutes warm-up period, make Pulse Head adjustments at an ambient temperature between $+20^{\circ} \mathrm{C}$ and $+30^{\circ} \mathrm{C}\left(+68^{\circ} \mathrm{F}\right.$ and $\left.+86^{\circ} \mathrm{F}\right)$.

Refer to Check Fast Edge Leading Edge Aberrations in the Performance Check (maintain same check set-up and control settings) when making following adjustments. See Adjustment Locations (Fig. 8-3) in the pull-out section of this manual.

1. Adjust Positive Back Termination, R1200 and C1100 (located on Fast Edge board)
a. Set CG 551AP EDGE POLARITY to $\boldsymbol{\sigma}$ (positive) and change the 7 S $11 \mathrm{mVOLTS} /$ DIVision to 5 .
b. Adjust 7S11 DC OFFSET $\pm 1 \mathrm{~V}$ control to lineup top of pulse with horizontal center graticule line (see Fig. 4-3).
c. Adjust 7T14 TIME POSITION control to lineup the pulse leading edge approximately on first vertical graticule line.
d. Adjust R1200 for maximum flatness of the displayed pulse top.
e. Adjust C1100 to equalize the aberrations on each side of graticule center line.

Interaction between R1200 and C1100 may require slight readjustment to obtain the optimum displayed pulse. See Fig. 4-3.
f. Check displayed pulse for aberrations less than $\pm 3 \%$ of pulse amplitude and adjacent pulse peaks not to exceed $4 \%$, peak-to-peak.

## 2. Adjust Negative Back Termination, R1210 and C1110 (located on Fast Edge board)

a. Set CG 551AP EDGE POLARITY to $\subsetneq$ (negative).
b. Repeat parts b through fof previous check (adjust R1210 and C1110).

This completes the Adjustment Procedure.

## MAINTENANCE

## Disassembly and Reassembly

## Recalibration

To ensure accurate measurements, check the calibration of this instrument after each 1000 hours of operation or every six months if used infrequently. In addition, replacement of components may necessitate recalibration of the effected circuits. Refer to the Adjustment Procedure in the Calibration section.

## note

Refer to Fig. 5-1 for the following procedures:

## Bottom Cover Removal and Replacement

a. Remove cover screw (1) and four end screws (2).
b. Carefully lift top cover away from side rails


Remove side rails for better board access.


Fig. 5-1. Maintenance diagram (exploded view).
c. To replace bottom cover, set side rails in place and position cover in the side rail grooves.
d. Replace cover screw and four end screws.

## Top Cover Removal and Replacement

a. Remove four end screws (4)
b. Carefully lift bottom cover away from side rails (3). Side rails can be removed, if desired.
c. To replace top cover, set side rails in place and position cover in side rail grooves.
d. Replace four end screws.

## Hypcon Connector

The Hypcon Connector (hybrid-printed connector) is precision-made and designed to provide a low loss electrical and a thermally efficient connection between the printed circuit board and hybrid integrated circuit (see Fig. 5-2).

Care must be taken, when replacing the hybrid IC's, not to touch the elastomer gold-plated contacts or to use a cleaner which will degrade contact reliability.

The Hypcon Connector and hybrid IC (see Fig. 5-1, 12 ) should be removed if it is necessary to use a cleaning solvent near ( $1 / 2^{\prime \prime}$ ) the connector.

## IMPORTANT

Remove all traces of solder flux or foreign material from the circuit board contact area before replacing the connector.

Contamination usually takes place during the soldering and cleaning process. Flux, oil, or other contaminants can be carried under the connector during the cleaning operation. When the solvent evaporates, nonconductive contaminants may remain on or near the contact interfaces.

The cleaning process, either hand cleaning with a solvent or machine cleaning in an automatic detergent wash, is not recommended for the board containing the Hypcon Connector.

If a component adjacent to the Hypcon Connector must be replaced, the following steps are recommended:

1. Remove the hybrid IC and Hypcon Connector before any soldering or cleaning, and store in a dirt free covered container. See Disassembly and Removal instructions.
2. Hand soldering recommendations:
a. Use small diameter solder ( 0.030 " $-0.040^{\prime \prime}$ ).
b. Use low power soldering irons (15-20 watts).
c. Use care with solder amount and placement.
3. Remove solder flux and contact contamination with isopropyl alcohol or denatured alcohol.
4. Flush the hybrid and Hypcon Connector mounting area with isopropyl alcohol. Do not use cotton-tipped applicators. The elastomer should be examined for dust. hair, etc., before it is reinstalled.

If the etched circuit board surfaces require additional cleaning, scrub with a soft rubber eraser and blow or vacuum clean while dusting surface with a small clean brush.
5. If the hybrid IC and elastomer contact holder are contaminated, clean the contact holder and hybrid by flushing or spraying with alcohol and oven dry at $+50^{\circ} \mathrm{C}$. Do not scrub with a cotton tipped applicator or similar device. If the contact holder is excessively contaminated. replace it with a new one.

Make sure that the elastomer is properly seated in the contact holder before remounting the assembly to circuit board. Exercise care when mounting the plastic frame elastomer contact holder, and hybrid IC assembly to the circuit board to prevent misalignment between the connector and board.


Because of close tolerances involved, special care must be taken to assure correct index alignment of each Hypcon Connector part during reassembly. Failure to do so can result in a cracked hybrid substrate. See Fig. 5-2 for index locations.

A maximum of 2 inch pounds of torque should be applied to the mounting screws to secure the Hypcon Connector to the circuit board.


Fig. 5-2. Hypcon Connector (exploded view).

## Disassembly and Removal

a. Note index arrow on circuit board and Hypcon Connector plastic frame pointed mounting ear.
b. Note screw locations then unscrew and remove the four screw and washer assemblies.
c. Carefully lift the Hypcon Connector from the board.
d. Note index location of hybrid and carefully remove the board with tweezers.
e. Note index location of elastomer contact holder and remove by grasping a corner of the contact holder with tweezers and lifting up.


Avoid touching the hybrid and elastomer contact holder. Skin oils can degrade reliability.

## Reassembly and Replacement

a. Grasp corner of elastomer contact holder with tweezers and place holder in plastic frame slot using care to match the flat contact holder with the flat frame corner. Place a clean plastic envelope over finger and press to seat contact holder in the frame. The contact holder must be evenly seated on all four sides.
b. Match hybrid flat corner with board arrow. Line up the hybrid gold index runs with the circuit board runs.
c. Match pointed mounting ear of Hypcon Connector with flat corner of receptacle and guide registration pins into the board holes. Make certain the corners of hybrid line up with the corners of connector.
d. Insert mounting hardware and apply a maximum of 2 inch pounds of torque to secure the connector assembly.

## NOTE

After replacement of Hypcon Connector, check the fast edge pulse for accuracy before attempting any adiustments. See Performance Check in the Calibration section.

## Board Removal and Replacement (See Fig. 5-1)

After removing covers, siderails (see Cover Removal and Replacement) and coax connector and disconnecting log cell connectors, (see Hypcon Connector) remove the Fast Edge board and Fast Edge Driver board using the following procedure:
a. Remove the two screws (5) securing the Fast Edge board to the Fast Edge Driver board.
b. Pull the boards apart, using care not to bend any of the eight board interconnect pins.
c. To replace boards, line up the eight Fast Edge board interconnect pins with the Fast Edge Driver board pin sockets. Carefully insert the pins into their respective sockets.


To force the pins into the sockets wifhout proper alignment can cause damage to the pins and sockets.
d. After boards are properly connected together, replace the two screws.

## Cable Removal and Replacement (from Fast Edge board)

a. After board removal, carefully unsolder the cable connections (6) and remove the cable.
b. To replace the cable, reverse above procedure.

## Log Cell Removal and Replacement (Refer to Fig. 5-1)

## Log Cell 1 Removal

a. Loosen two screws securing clamp (7). Slide clamp forward to expose coaxial center conductor.
b. With aid of a solder wick and tweezers, carefully unsolder wire connected to center conductor, detaching wire with tweezers. Removal of the two clamp screws detaches coaxial connector from board.
c. Note the log cell (8) wires lead dress to the board (essential for proper high frequency operation of the unit).
d. Using tweezers, unsolder the three board leads from the log cell.
e. Disconnect log cell connector. Unscrew four Fast Edge board screws (10) securing the log cell to board.
f. Carefully remove the log cell.

## Log Cell 1 Replacement

a. Position log cell on board, lining up cell wires to their respective solder points on the board.
b. Replace the four Fast Edge board screws
c. Using tweezers, properly dress log cell wire leads as close as possible to the board and carefully solder the connections.
d. Carefully solder center conductor wire connections and slide clamp over this solder connection and tighten clamp screws. Make certain center wire does not touch the clamp.
e. Attach the log cell connector.

## Log Cell 2 Removal

a. Note log cell (9) wires dress with respect to the board.
b. Using tweezers, unsolder the four board leads from the log cell.
c. Disconnect log cell connector. Unscrew four Fast Edge board screws (11) securing log cell to board.
d. Carefully remove the log cell.

## Log Cell 2 Replacement

a. Position log cell on board lining up cell wires to their respective solder points on board.
b. Replace the four bottom board screws
c. Using tweezers, properly dress log cell wire leads to the board and carefully solder all connections.
d. Attach the log cell connector.

## Cleaning Instructions

This instrument should be cleaned as often as operating conditions require. Accumulation of dirt on components acts as an insulating blanket and prevents efficient heat dissipation that can cause overheating and component breakdown.


Avoid the use of chemical cleaning agents that might leave a film or damage the plastic material used in this instrument. Use a non-residue type of cleaner; preferably, isopropyl alcohol or totally denatured ethyl alcohol. Before using any other type of cleaner, consult your Tektronix Service Center or represendative.

Exterior. Loose dust accumulated on the covers can be removed with a soft cloth or a small brush. Dirt that remains can be removed with a soft cloth dampened with a mild detergent and water solution. Abrasive cleaners should not be used.

Interior. Dust in the interior of the instrument should be removed occasionally due to its electrical conductivity under high humidity conditions. The best way to clean the interior is to blow off the accumulated dust with dry low pressure air; then use a soft brush.

After making minor board repairs, cleaning is best accomplished by carefully flaking or chipping the solder flux from the repaired area. See Hypcon Connector for further cleaning instructions.

Isopropyl alcohol can be used to clean major repairs to the circuit board. After cleaning, flush the board well with clean, isopropyl alcohol. Make certain that resin or dirt is carefully removed from the board.

## Obtaining Replacement Parts

Electrical and mechanical parts can be obtained through your local Tektronix Field Office or representative. However, many of the standard electronic components are available from local commercial sources. Before purchasing or ordering parts from a source other than Tektronix, Inc., check the Replaceable Electrical Parts list for the proper value, rating, tolerance, and description.

## Ordering Parts

When ordering replacement parts from Tektronix, Inc., it is important to include all of the following information:

1. Instrument type (include modification or option numbers).
2. Instrument serial number
3. A description of the part (if electrical, include the component number).
4. Tektronix part number.

## Static-Sensitive Components



Static discharge may damage semiconductor components in this instrument.

This instrument contains electrical components that are susceptible to damage from static discharge. See Table 5-1 for relative susceptibility of various classes of semiconductors. Static voltages of 1 kV to 30 kV are common in unprotected environments.

Observe the following precautions to avoid damage:

1. Minimize handling of static-sensitive components.
2. Transport and store static-sensitive components or assemblies in their original containers, on a metal rail, or on conductive foam. Label any package that contains static-sensitive assemblies or components.
3. Discharge the static voltage from your body by wearing a wrist strap while handling these components. Servicing static-sensitive assemblies or components should be performed only at a staticfree work station by qualified service personnel.
4. Nothing capable of generating or holding a static charge should be allowed on the work station surface.
5. Keep the component leads shorted together whenever possible.
6. Pick up components by the body, never by the leads.
7. Do not slide the components over any surface
8. Avoid handling components in areas that have a floor or work surface covering capable of generating a static charge.
9. Use a soldering iron that is connected to earth ground.
10. Use only special antistatic suction type or wick type desoldering tools.

## Test Equipment

Before using any test equipment to make measurements on static-sensitive components or assemblies, be certain that any voltage or current supplied by the test equipment does not exceed the limits of the component to be tested.

Table 5-1

## RELATIVE SUSCEPTIBILITY TO STATIC DISCHARGE DAMAGE

| Semiconductor Classes |
| :--- | :---: | \(\left.\begin{array}{c}Relative <br>

Susceptibility <br>
Levels\end{array}\right]\)
${ }^{2}$ Voltage equivalent for levels:

| $=100$ to 500 V | $4=500 \mathrm{~V}$ | $7=400$ to 1000 V (est.) |
| :---: | :---: | :---: |
| $2=200$ to 500 V | $5=400$ to 600 V | $8=900 \mathrm{~V}$ |
| $\mathbf{3}=250 \mathrm{~V}$ | $6=600$ to 800 V | $9=1200 \mathrm{~V}$ |

(Voltage discharged from a 100 pF capacitor through a resistance of $100 \Omega$.)

## OPTIONS

There are no options available at this time.

# THIS <br> PAGE <br> LEFT BLANK 

## SCANS <br> By <br> Artek Media

# REPLACEABLE ELECTRICAL PARTS 

## PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable

If a part you have ordered has been replaced with a new or improved part, your local Textronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

## LIST OF ASSEMBLIES

A list of assemblies can be found at the beginning of the Electrical Parts List. The assemblies arelisted in numerical order. When the complete component number of a part is known, this list will identify the assembly in which the part is located.

## CROSS INDEX-MFR. CODE NUMBER TO MANUFACTURER

The Mir. Code Number to Manufacturer index for the Electrical Parts List is located immediately after this page. The Cross Index provides codes, names and addresses of manufacturers of components listed in the Electrical Parts List.

## ABBREVIATIONS

Abbreviations conform to American National Standard Y1.1

## COMPONENT NUMBER (column one of the Electrical Parts List)

A numbering method has been used to identify assemblies, subassemblies and parts. Examples of this numbering method and typical expansions are illustrated by the following:


Read: Resistor 1234 of Assembly 23


[^0]Only the circuit number will appear on the diagrams and circuit board illustrations. Each diagram and circuit board illustration is clearly marked with the assembly number Assembly numbers are also marked on the mechanical exploded views located in the Mechanical Parts List. The component number is obtained by adding the assembly number prefix to the circuit number

The Electrical Parts List is divided and arranged by assemblies in numerical sequence (e.g., assembly A1 with its subassemblies and parts, precedes assembly A2 with its subassemblies and parts).

Chassis-mounted parts have no assembly number prefix and are located at the end of the Electrical Parts List

## TEKTRONIX PART NO. (column two of the Electrical Parts List)

Indicates part number to be used when ordering replacement part from Tektronix.

## SERIAL/MODEL NO. (columns three and four of the Electrical Parts List)

Column three (3) indicates the serial number at which the part was first used. Column four (4) indicates the serial number at which the part was removed. No serial number entered indicates part is good for all serial numbers

## NAME \& DESCRIPTION (column five of the Electrical Parts List)

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an ltem Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

## MFR. CODE (column six of the Electrical Parts List)

Indicates the code number of the actual manufacturer of the part. (Code to name and address cross reference can be found immediately after this page.)

## MFR. PART NUMBER (column seven of the Electrical Parts List)

Indicates actual manufacturers part number

## CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. <br> Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 01121 | ALLEN-BRADLEY CO | 1201 SOUTH 2ND ST | MILWAUKEE WI 53204 |
| 03508 | GENERAL ELECTRIC CO | W GENESEE ST | AUBURN NY 13021 |
|  | SEMI-CONDUCTOR PRODUCTS DEPT |  |  |
| 04222 | AVX CERAMICS DIV OF AVX CORP | 19TH AVE SOUTH P O BOX 867 | MYRTLE BEACH SC 29577 |
| 04713 | MOTOROLA INC | 5005 E MCDOWELL RD | PHOENIX AZ 85008 |
|  | SEMICONDUCTOR GROUP |  |  |
| 14433 | ITT SEMICONDUCTORS DIV |  | WEST PALM BEACH FL |
| 14552 | MICRO/SEMICONDUCTOR CORP | 2830 S FAIRVIEW ST | SANTA ANA CA 92704 |
| 15636 | ELEC-TROL INC | 26477 N GOLDEN VALLEY RD | SAUGUS CA 91350 |
| 19701 | MEPCO/ELECTRA INC <br> A NORTH AMERICAN PHILIPS CO | P 0 B0X 760 | MINERAL WELLS TX 76067 |
| 22526 | DU PONT E I DE NEMOURS AND CO INC DU PONT CONNECTOR SYSTEMS DIV MILITARY PRODUCTS GROUP | 515 FISHING CREEK RD | NEW CLMBERLAND PA 17070-3007 |
| 32997 | BOURNS INC <br> TRIMPOT DIV | 1200 COLUMBIA AVE | RIVERSIDE CA 92507 |
| 50434 | HEWLETT-PACKARD CO OPTOELECTRONICS DIV | 640 PAGE MILL RD | PALO ALTO CA 94304 |
| 57668 | ROHM CORP | 16931 MILLIKEN AVE | IRVINE CA 92713 |
| 59660 | TUSONIX INC | 2155 N FORBES BLVD | TUCSON, ARIZONA 85705 |
| 80009 | TEKTRONIX INC | 4900 S W GRIFFITH DR P 0 BOX 500 | BEAVERTON OR 97077 |


| Camponent No. | Tektronix <br> Part No. | Serial/Assenbly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A20 | 670-6096-00 |  | CIRCUIT BD ASSY:EDGE DRIVE | 80009 | 670-6096-00 |
| A22 | 670-6095-00 |  | CIRCUIT BD ASSY:FAST EDGE | 80009 | 670-6095-00 |
| A20 | 670-6096-00 |  | CIRCUIT BD ASSY:EDGE DRIVE | 80009 | 670-6096-00 |
| A20C1000 | 283-0177-00 |  | CAP, FXD, CER DI: $1 \mathrm{UF},+80-20 \%, 25 \mathrm{~V}$ | 04222 | SR302E105ZAATR |
| A20C1001 | 283-0177-00 |  | CAP, FXD, CER DI:1UF, +80-20\%,25V | 04222 | SR302E105ZAATR |
| A20C1004 | 281-0763-00 |  | CAP, FXD, CER DI:47PF, $10 \%$, 100 V | 04222 | MA101A470KAA |
| A20C1011 | 283-0177-00 |  | CAP, FXD, CER DI:1UF, $+80-20 \%$, 25V | 04222 | SR302E105ZAATR |
| A20C1012 | 283-0177-00 |  | CAP, FXD,CER DI:1UF, +80-20\%,25V | 04222 | SR302E105ZAATR |
| A20C1013 | 281-0799-00 |  | CAP, FXD, CER DI:62PF, 2\%, 100V | 04222 | MA101A620GAA |
| A20C1102 | 281-0810-00 |  | CAP, FXD, CER DI:5.6PF,+/-0.5PF,100V | 04222 | MA101A5R60AA |
| A20C1103 | 283-0164-00 |  | CAP, FXD, CER DI: $2.2 \mathrm{UF}, 20 \%$, 25V | 04222 | SR402E225MAA |
| A20C1105 | 281-0811-00 |  | CAP, FXD, CER DI: $10 \mathrm{PF}, 10 \%$, 100 | 04222 | MA101A100KAA |
| A20C1110 | 281-0810-00 |  | CAP, FXD, CER DI: 5.6 PF, $+/-0.5 \mathrm{PF}, 100 \mathrm{~V}$ | 04222 | MA101A5R6DAA |
| A20C1113 | 281-0811-00 |  | CAP, FXD, CER DI: $10 \mathrm{PF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA101A100KAA |
| A20CR1000 | 152-0536-00 |  | SEMICOND DVC, DI :SW, 4V,C132 | 04713 | SMV1110 (MBD101) |
| A20CR1002 | 152-0141-02 |  | SEMICOND DVC,DI:SW,SI,30V,150MA,30V, D0-35 | 03508 | DA2527 (1N4152) |
| A20CR1010 | 152-0536-00 |  | SEMICOND DVC, DI:SW, 4V,C132 | 04713 | SMV1110 (MBD101) |
| A20CR1011 | 152-0141-02 |  | SEMICOND DVC, DI:SW, SI, 30V,150MA, 30V, 00-35 | 03508 | DA2527 (1N4152) |
| A20CR1100 | 152-0141-02 |  | SEMICOND DVC,DI:SW,SI,30V,150MA, 30V, DO-35 | 03508 | DA2527 (1N4152) |
| A20CR1102 | 152-0322-00 |  | SEMICOND DVC,DI:SCHOTTKY,SI,15V, D0-35 | 50434 | 5082-2672 |
| A20CR1103 | 152-0322-00 |  | SEMICOND DVC.DI:SCHOTTKY,SI, 15V,00-35 | 50434 | 5082-2672 |
| A20CR1110 | 152-0322-00 |  | SEMICOND DVC,DI:SCHOTTKY,SI,15V,D0-35 | 50434 | 5082-2672 |
| A20CR1111 | 152-0141-02 |  | SEMICOND DVC,DI:SW,SI,30V,150MA,30V,D0-35 | 03508 | DA2527 (1N4152) |
| A20CR1116 | 152-0322-00 |  | SEMICOND DVC,DI:SCHOTTKY,SI,15V, D0-35 | 50434 | 5082-2672 |
| A20CR1200 | 152-0141-02 |  | SEMICOND DVC,DI:SW,SI, 30V,150MA,30V, D0-35 | 03508 | DA2527 (1N4152) |
| A20CR1203 | 152-0141-02 |  | SEMICOND DVC,DI:SW, SI, 30V,150MA, 30V, DO-35 | 03508 | DA2527 (1N4152) |
| A20CR1212 | 152-0141-02 |  | SEMICOND DVC,DI:SW, SI, 30V,150MA,30V, DO-35 | 03508 | DA2527 (1N4152) |
| A20CR1213 | 152-0141-02 |  | SEMICOND DVC,DI:SW, SI, 30V,150MA,30V, D0-35 | 03508 | DA2527 (1N4152) |
| A20J1204 | 131-0608-00 |  | TERMINAL, PIN: $0.365 \mathrm{~L} \times 0.025 \mathrm{BRZ}$ GLD PL (QUANTITY 4) | 22526 | 48283-036 |
| A20J1214 | 131-0608-00 |  | TERMINAL, PIN: $0.365 \mathrm{~L} \times 0.025 \mathrm{BRZ}$ GLD PL (QUANTITY 4) | 22526 | 48283-036 |
| A20P1002 | 136-0263-04 |  | SOCKET,PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1004 | 136-0263-04 |  | SOCKET,PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1005 | 136-0263-04 |  | SOCKET,PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1007 | 136-0263-04 |  | SOCKET, PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1009 | 136-0263-04 |  | SOCKET, PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1012 | 136-0263-04 |  | SOCKET.PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1013 | 136-0263-04 |  | SOCKET, PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A20P1014 | 136-0263-04 |  | SOCKET, PIN TERM:U/W 0.025 SQ PIN | 22526 | 75377-001 |
| A2001000 | 151-0441-03 |  | TRANSISTOR:CHECKED | 80009 | 151-0441-03 |
| A2001001 | 151-0450-00 |  | TRANSISTOR:PNP, SI, T0-39 | 04713 | SRF507 |
| A2001011 | 151-0451-00 |  | TRANSISTOR:NPN, SI, TO-39 | 04713 | SRF503 |
| A2001012 | 151-0434-01 |  | TRANSISTOR:SELECTED | 04713 | SS7144H |
| A2001101 | 151-0441-03 |  | TRANSISTOR:CHECKED | 80009 | 151-0441-03 |
| A2001111 | 151-0434-01 |  | TRANSISTOR:SELECTED | 04713 | SS7144H |
| A2001200 | 151-0302-01 |  | TRANSISTOR:SELECTED | 80009 | 151-0302-01 |
| A2001202 | 151-0441-03 |  | TRANSISTOR:CHECKED | 80009 | 151-0441-03 |
| A2001203 | 151-0301-01 |  | TRANSISTOR:SELECTED | 80009 | 151-0301-01 |
| A2001211 | 151-0302-01 |  | TRANSISTOR:SELECTED | 80009 | 151-0302-01 |
| A2001212 | 151-0434-01 |  | TRANSISTOR:SELECTED | 04713 | SS7144H |
| A2001213 | 151-0301-01 |  | TRANSISTOR:SELECTED | 80009 | 151-0301-01 |
| A20R1000 | 315-0301-00 |  | RES, FXD, FILM 300 OHM , 5\%, 0.25W | 57668 | NTR25J-E300E |
| A20R1001 | 315-0390-00 |  | RES.FXD, FILM:39 OHM, 5\%, 0.25W | 57668 | NTR25J-E39E0 |
| A20R1002 | 315-0471-00 |  | RES, FXD, FILM 470 OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E470E |
| A20R1003 | 315-0560-00 |  | RES, FXD, FILM: 56 OHM, 5\%, 0.25W | 57668 | NTR25J-E56E0 |
| A20R1004 | 317-0201-00 |  | RES, FXD, CMPSN: 200 OHM, 5\%, 0.125W | 01121 | BB2015 |


| Component No. | Tektronix <br> Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A20R1010 | 315-0390-00 |  | RES, FXD, FILM:39 OHM, 5\%, 0.25W | 57668 | NTR25j-E39E0 |
| A20R1011 | 315-0471-00 |  | RES, FXD, FILM:470 OHM, 5\%,0.25W | 57668 | NTR25J-E470E |
| A20R1012 | 315-0560-00 |  | RES, FXD, FILM: 56 OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E56E0 |
| A20R1013 | 317-0201-00 |  | RES, FXD, CMPSN: 200 OHM, 5\%, 0.125 | 01121 | 882015 |
| A20R1100 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM, 5\%, 0.25W | 57668 | NTR25J-E470E |
| A20R1101 | 315-0201-00 |  | RES, FXD, FILM: 200 OHM, 5\%, 0.25W | 57668 | NTR25J-E200E |
| A20R1104 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM, 5\%, 0.25W | 57668 | NTR25J-E470E |
| A20R1106 | 315-0472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%$, 0.25 W | 57668 | NTR25J-E04K7 |
| A20R1107 | 315-0102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25JE01K0 |
| A20R1111 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM, 5\%, 0.25W | 57668 | NTR25J-E470E |
| A20R1112 | 315-0472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E04K7 |
| A20R1114 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E470E |
| A20R1115 | 315-0201-00 |  | RES, FXD, FILM: 200 OHM, 5\%, 0.25W | 57668 | NTR25J-E200E |
| A20R1117 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM, 5\%,0.25W | 57668 | NTR25J-E470E |
| A20R1118 | 315-0102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25JE01K0 |
| A20R1200 | 315-0222-00 |  | RES, FXD, FILM $2.2 \mathrm{CK} 0 \mathrm{MM}, 5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E02K2 |
| A20R1201 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM, $5 \%$, 0.25 W | 57668 | NTR25J-E470E |
| A20R1202 | 315-0472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E04K7 |
| A20R1204 | 315-0272-00 |  | RES, FXD, FILM 2.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E02K7 |
| A20R1211 | 315-0272-00 |  | RES, FXD, FILM 2.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E02K7 |
| A20R1213 | 315-0472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E04K7 |
| A20R1214 | 315-0471-00 |  | RES, FXD, FILM: 470 OHM , 5\%, 0.25W | 57668 | NTR25]-E470E |
| A20VR1204 | 152-0127-00 |  | SEMICOND DVC, DI : ZEN, SI, 7.5V,5\%, 0.4W, D0-7 | 14433 | 25347 (1N958B) |
| A20VR1205 | 152-0279-00 |  | SEMICOND DVC, DI:ZEN,SI,5.1V,5\%,0.4W, D0-7 | 14552 | TD3810989 |
| A20VR1210 | 152-0279-00 |  | SEMICOND DVC, DI:ZEN,SI, 5.1V,5\%,0.4W, D0-7 | 14552 | TD3810989 |
| A20VR1211 | 152-0127-00 |  | SEMICOND DVC, DI: ZEN, SI, 7.5V, $5 \%, 0.4 W, 00-7$ | 14433 | 25347 (1N9588) |
| A22 | 670-6095-00 |  | CIRCUIT BD ASSY:FAST EDGE | 80009 | 670-6095-00 |
| A22C1100 | 281-0161-00 |  | CAP, VAR, CER DI: $5-15 \mathrm{PF}, 350 \mathrm{~V}$ | 59660 | 518-000A5-15 |
| A22C1110 | 281-0161-00 |  | CAP, VAR, CER DI:5-15PF,350V | 59660 | 518-000A5-15 |
| A22.J1002 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22526 | 47359-000 |
| A22J1004 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22525 | 47359-000 |
| A22J1005 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22526 | 47359-000 |
| A22J1007 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22526 | 47359-000 |
| A22J1009 | 131-0787-00 |  | TEPMINAL, PIN: $0.64 \mathrm{X} \times 0.025 \mathrm{SQ}$ PH BRZ | 22526 | 47359-000 |
| A22J1012 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22526 | 47359-000 |
| A22J1013 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22526 | 47359-000 |
| A22J1014 | 131-0787-00 |  | TERMINAL, PIN: $0.64 \mathrm{~L} \times 0.025$ SQ PH BRZ | 22526 | 47359-000 |
| A22K1010 | 148-0132-01 |  | RELAY. LATCHING: FORM C, SPDT | 80009 | 148-0132-01 |
| A22K1110 | 148-0132-01 |  | RELAY,LATCHING:FORM C, SPDT | 80009 | 148-0132-01 |
| A22K1210 | 148-0079-02 |  | RELAY,REED: 2 FORM A, $110 \mathrm{MA}, 28 \mathrm{VDC}$, COIL 5 SVC 2 00 OHM | 15636 | R6738-1 |
| A22R1200 | 311-0605-00 |  | RES, VAR, NONWW: TRMR, 200 OHM, 0.5W | 32997 | 3329H-G48-201 |
| A22R1202 | 301-0271-00 |  | RES, FXX, FILM: 270 OHM, 5\%, 0.5W | 19701 | 5053CX270R0J |
| A22R1210 | 311-0605-00 |  | RES, VAR, NONWW: TRMR, 200 OHM, 0.5W | 32997 | 3329H-648-201 |
| A22U1112 | 155-0209-00 |  | MICROCKT, DGTL: PULSAR HYBRID, H548D | 80009 | 155-0209-00 |

## DIAGRAMS AND CIRCUIT BOARD ILLUSTRATIONS

## Symbols

Graphic symbols and class designation letters are based on ANSI Standard Y32.2-1975.

Logic symbology is based on ANSI Y32.14-1973 in terms of positive logic. Logic symbols depict the logic function performed and may differ from the manufacturer's data.

The overline on a signal name indicates that the signal performs its intended function when it is in the low state.

## Abbreviations are based on ANSI Y1.1-1972.

Other ANSI standards that are used in the preparation of diagrams by Tektronix, Inc. are:

Y14.15, 1966 Drafting Practices.
Y14.2, 1973 Line Conventions and Lettering.
Y10.5, 1968 Letter Symbols for Quantities Used in Electrical Science and Electrical Engineering.

American National Standard Institute 1430 Broadway
New York, New York 10018

## Component Values

Electrical components shown on the diagrams are in the following units unless noted otherwise:

Capacitors $=$ Values one or greater are in picofarads (pF). Values less than one are in microfarads ( $\mu \mathrm{F}$ ).
Resistors $=$ Ohms $(\Omega)$.

## The information and special symbols below may appear in this manual.

## Assembly Numbers and Grid Coordinates

Each assembly in the instrument is assigned an assembly number (e.g., A20). The assembly number appears on the circuit board outline on the diagram, in the title for the circuit board component location illustration, and in the lookup table for the schematic diagram and corresponding component locator illustration. The Replaceable Electrical Parts list is arranged by assemblies in numerical sequence; the components are listed by component number *(see following illustration for constructing a component number).

The schematic diagram and circuit board component location illustration have grids. A lookup table with the grid coordinates is provided for ease of locating the component. Only the components illustrated on the facing diagram are listed in the lookup table. When more than one schematic diagram is used to illustrate the circuitry on a circuit board, the circuit board illustration may only appear opposite the first diagram on which it was illustrated; the lookup table will list the diagram number of other diagrams that the circuitry of the circuit board appears on.




Fig. 8-2. Fast Edge board (A22)


# REPLACEABLE <br> MECHANICAL PARTS 

## PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important. when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

## ITEM NAME

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

FIGURE AND INDEX NUMBERS
Items in this section are referenced by figure and index numbers to the illustrations.

## INDENTATION SYSTEM

This mechanical parts list is indented to indicate item relationships. Following is an example of the indentation system used in the aescription column.
$12345 \quad$ Name \& Description
Assembly and/or Component
Attaching parts for Assembly and/or Component
.... END ATtACHING PARTS ....
Detail Part of Assembly and/or Component
Attaching paris for Detail Part
.... end attaching parts ....
Parts of Detail Part
Attaching parts for Parts of Detail Part
.... END ATTACHING PARTS ....

Attaching Parts always appear in the same indentation as the item it mounts, while the detail parts are indented to the right. Indented items are part of, and included with, the next higher indentation.

Attaching parts must be purchased separately, unless otherwise specified.

ABBREVIATIONS

| " | 1 NCH | ELCTRN | ELECTRON | IN | INCH | SE | SINGLE END |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| * | NUMBER SIZE | ELEC | ELECTRICAL | INCAND | INCANDESCENT | SECT | SECTION |
| ACTR | ACTUATOR | ELCTLT | ELECTROLYTIC | INSUL | INSULATOR | SEMICOND | SEMICONDUCTOR |
| ADPTR | ADAPTER | ELEM | ELEMENT | INTL | INTEANAL | SHLO | SHIELD |
| ALIGN | ALIGNMENT | EPL | ELECTRICAL PARTS LIST | LPHLDR | LAMPHOLDER | SHLDR | SHOULDEAED |
| AL | ALUMINUM | EOPT | EQUIPMENT | MACH | MACHINE | SKT | SOCKET |
| ASSEM | ASSEMBLED | EXT | EXTERNAL | MECH | MECHANICAL | SL | SLIDE |
| ASSY | ASSEMBLY | FIL | FILLISTER HEAD | MTG | MOUNTING | SLFLKG | SELF-LOCKING |
| ATTEN | ATTENUATOR | FLEX | FLEXIBLE | NiP | NIPPLE | SLVG | SLEEVING |
| AWG | AMERICAN WIRE GAGE | FLH | FLAT HEAD | NON WIRE | NOT WIRE WOUND | SPR | SPRING |
| 80 | BOARD | FLTR | FILTER | OBD | ORDER BY DESCRIPTION | SQ | SQUARE |
| BRKT | BRACKET | FR | FRAME or front | OO | OUTSIDE DIAMETER | SST | STAINLESS STEEL |
| BRS | BRASS | FSTNR | FASTENER | OVH | OVAL HEAD | STL | STEEL |
| BRZ | BRONZE | FT | FOOT | PH BRZ | PHOSPHOR BRONZE | SW | SWITCH |
| BSHG | BUSHING | FXD | FIXED | PL | Plain or Plate | T | TUBE |
| CAB | CABINET | GSKT | GASKET | PLSTC | PLASTIC | TERM | TERMINAL |
| CAP | CAPACITOR | HOL | HANDLE | PN | PART NUMBER | THD | THREAD |
| CER | CERAMIC | HEX | HEXAGON | PNH | PAN HEAD | THK | THICK |
| CHAS | CHASSIS | HEX HD | HEXAGONAL HEAD | PWR | POWER | TNSN | TENSION |
| CKT | CIRCUIT | HEX SOC | HEXAGONAL SOCKET | RCPT | RECEPTACLE | TPG | TAPPING |
| COMP | COMPOSITION | HLCPS | HELICAL COMPRESSION | RES | RESISTOA | TRH | TRUSS HEAD |
| CONN | CONNECTOR | HLEXT | HELICAL EXTENSION | fGD | RIGID | $\checkmark$ | VOLTAGE |
| COV | COVER | HV | HIGH VOLTAGE | RLF | RELIEF | VAR | VARIABLE |
| CPLG | COUPLING | IC | INTEGRATED CIRCUIT | RTNA | RETAINER | W/ | WITH |
| CRT | CATHODE RAY TUBE | 10 | INSIDE DIAMETER | SCH | SOCKET HEAD | WSHR | WASHER |
| DEG | DEGREE | IDENT | IDENTIFICATION | SCOPE | OSCILLOSCOPE | XFMR | TRANSFORMER |
| DWR | DRAWER | IMPLR | IMPELLER | SCR | SCREW | XSTR | TRANSISTOR |

## CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 01536 | TEXTRON INC |  | ROCKFORD IL 61108 |
|  | CAMCAR DIV | 1818 CHRISTINA ST |  |
|  | SEMS PRODUCTS UNIT |  |  |
| 09772 | WEST COAST LOCKWASHER CO INC | $\begin{aligned} & 16730 \text { E JOHNSON DRIVE } \\ & \text { PO BOX } 3588 \end{aligned}$ | CITY OF INDUSTRY CA 91744 |
| 12327 | FREEWAY CORP | 9301 ALLEN DR | CLEVELAND OH 44125 |
| 22526 | DU PONT E I DE NEMOURS AND CO INC DU PONT CONNECTOR SYSTEMS DIV MILITARY PROOUCTS GROUP | 515 FISHING CREEK RD | NEW CLMBERLAND PA 17070-3007 |
| 46384 | PENN ENGINEERING AND MFG CORP | P 0 B0X 311 | DOYLESTOWN PA 18901 |
| 70318 | ALLMETAL SCREW PRODUCTS CO INC | 821 STEWART AVE | GARDEN CITY NY 11530 |
| 73743 | FISCHER SPECIAL MFG CO | 446 MORGAN ST | CINCINNATI OH 45206 |
| 77900 | SHAKEPRCOF <br> DIV OF ILLINOIS TOOL WORKS | SAINT CHARLES RD | ELGIN IL 60120 |
| 80009 | TEKTRONIX INC | 4900 S W GRIFFITH DR P 0 BOX 500 | BEAVERTON OR 97077 |
| TK0435 | LEWIS SCREW CO | 4114 S PEORIA | CHICAGO IL 60609 |
| TK0456 | AROW FASTENERS INC | 2112 AMERICAN AVE | HAYWARD CA 94545 |
| TK1582 | DELTA WEST CO | 7185 SW SANDBURG ST SUITE C | TIGARD WA 97223 |

Fig. \&

| Index No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Oty | 12345 Nane \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1-1 | 204-0777-01 |  | 1 | BODY HALF, PLS H:TOP (ATTACHING PARTS) | 80009 | 204-0777-01 |
| -2 | 211-0118-00 |  | 4 | SCREW,MACHINE: 2-56 $\times 0.25$, PNH STL (END ATTACHING PARTS) | TK1582 | 1152-406 |
| -3 | 361-0848-00 |  | 2 | SPACER, PLATE: $0.156 \times 3.875 \times 0.468 . \mathrm{AL}$ | 80009 | 361-0848-00 |
| -4 | 204-0776-00 |  | 1 | BODY HALF,PLS H:BOTTOM (ATTACHING PARTS) | 80009 | 204-0776-00 |
| -5 | 211-0118-00 |  | 4 | SCREW,MACHINE: $2-56 \times 0.25$, PNH, STL | TK1582 | 1152-406 |
| -6 | 211-0105-00 |  | 1 | SCREW,MACHINE:4-40 $\times 0.188$, FLH, 100 DEG (END ATTACHING PARTS) | TK0435 | ORDER BY DESCR |
| -7 | 175-2038-03 |  | 1 | CA ASSY, SP, ELEC: 50 OHM COAX, 2,30 AWG, 1 METE R <br> (ATTACHING PARTS) | 80009 | 175-2038-03 |
| -8 | 210-0583-00 |  | 1 | NUT, PLAIN, HEX: 0.25-32 X 0.312, BRS CD PL | 73743 | 2X-20319-402 |
| -9 | 210-0046-00 |  | 1 | WASHER,LOCK: 0.261 IO, INTL, 0.018 THK, STL (END ATTACHING PARTS) | 77900 | 1214-05-00-0541C |
| -10 | 200-2096-02 |  | 1 | COVER, END:REAR, PULSE HEAD | 80009 | 200-2096-02 |
|  | 672-0882-00 |  | 1 | CIRCUIT BD ASSY: PULSE HEAD | 80009 | 672-0882-00 |
| -11 | - |  | 1 | .CKT BOARD ASSY: EDGE DRIVER(SEE A20 REPL) <br> . (ATTACHING PARTS) |  |  |
| -12 | 220-0627-00 |  | 4 | .NUT, PLAIN, HEX:2-56 X 0.156 HEX, BRS NP | 73743 | 10002-56-101 |
| -13 | 210-1008-00 |  | 8 | .WASHER, FLAT: 0.09 ID $\times 0.188$ OD $\times 0.02$, BRS | 12327 | ORDER BY DESCR |
| -14 | 211-0287-00 |  | 4 | .SCREW, MACHINE:2-56 $\times 0.5, \mathrm{PNH}, \mathrm{SST}$ | TK0456 | ORDER BY DESCR |
| -15 | 129-0659-00 |  | 2 | .SPACER, POST:0.188 L, 2-56 THRU,AL, 0.188 HEX | 80009 | 129-0659-00 |
| -16 | 407-1983-01 |  | 1 | .BRACKET, COAX: BRASS <br> (END ATTACHING PARTS) <br> .CKT BOARD ASSY INCLUDES: | 80009 | 407-1983-01 |
| -17 | - |  | 8 | $\begin{aligned} & \text {. SOCKET,PIN TERM: (SEE A2OP1002, P1004, P1005, } \\ & \text {..P1007,P1009, P1012,P1013, P1014 REPL) } \end{aligned}$ |  |  |
| -18 | 136-0252-07 |  | 6 | .. SOCKET, PIN CONN:W/O DIMPLE | 22526 | 75060-012 |
| -19 | ----- ----- |  | 8 | ..TERMINAL, PIN: (SEE A20J1204,J1214 REPL) |  |  |
| -20 | ----- ----- |  | 1 | .CKT BOARD ASSY:FAST EDGE(SEE A22 REPL) |  |  |
| -21 | ----- ----- |  | 8 | $\begin{aligned} & \text {..TERMINAL, PIN: (SEE A22J1002, } 11004, \mathrm{J1005}, \\ & \text {. J1007,J1009, J1013,J1014 REPL) } \end{aligned}$ |  |  |
| -22 | - |  | 2 | ..RELAY,LATCHING: (SEE AZ2K1010,K1110 REPL) <br> .. (ATTACHING PARTS) |  |  |
| -23 | 211-0175-00 |  | 8 | . .SCREW, MACHINE: $0-80 \times 0.312$,FILH, SST <br> ..(END ATTACHING PARTS) | 70318 | ORDER BY DESCR |
| -24 | 426-1337-00 |  | 1 | ..FRAME,MICROCKT:1.22 CM <br> .. (ATTACHING PARTS) | 80009 | 426-1337-00 |
| -25 | 211-0259-00 |  | 4 | .. SCR,ASSEM WSHR:2-56 X 0.437, PNH, STL, POZ | 01536 | 4821-00021 |
| -26 | 220-0797-00 |  | 4 | .. NUT,CAPTIVE:2-56 X 0.218 DIA,STL CD PL <br> .. (END ATTACHING PARTS) | 46384 | KF2-256 CC |
|  | 131-1923-00 |  | 1 | . CONTACT, ELEC:MICROCIRCUIT | 80009 | 131-1923-00 |
| -27 | 220-0449-00 |  | 1 | .NUT, SLEEVE:4-40 X 0.187 HEX,BRS CD PL <br> . (ATtACHING PARTS) | 80009 | 220-0449-00 |
| -28 | 211-0116-00 |  | 1 | .SCR,ASSEM WSHR:4-40 X 0.312, PNH,BRS, POZ <br> . (END ATTACHING PARTS) | 77900 | ORDER BY DESCR |
| -29 | 131-1778-02 |  | 1 | .CONN,RCPT, ELEC: BNC, FEMALE,W/SHELL | 80009 | 131-1778-02 |
| -30 | 358-0072-00 |  | 1 | . INSULATOR, BSHG: 0.192 ID X $0.19200 \times 0.323$ | 80009 | 358-0072-00 |
| -31 | 204-0755-00 |  | 1 | .BODY, CONNECTOR: BNC, BRASS <br> . (ATTACHING PARTS) | 80009 | 204-0755-00 |
| -32 | 220-0495-00 |  | 1 | .NUT, PLAIN, HEX:0.375-32 $\times 0.438$ HEX, BRS | 73743 | ORDER BY DESCR |
| -33 | 210-0012-00 |  | 1 | .WASHER, LOCK:0.384 ID,INTL,0.022 THK,STL <br> . (END ATTACHING PARTS) | 09772 | ORDER BY DESCR |
| -34 | 220-0807-00 |  | 1 | .NUT BLOCK: $2-56 \times 0.60 \times 0.58, \mathrm{AL}$ | 80009 | 220-0807-00 |
| -35 | 131-2026-01 |  | 1 | .CONTACT, ELEC:W/PIN TERMINAL SOCKET | 80009 | 131-2026-01 |
| -36 | 342-0381-00 |  | 1 | . INSULATOR, BSHG: BNC, TEFLON | 80009 | 342-0381-00 |
| -37 | 103-0195-01 |  | 1 | .ADAPTER,CONN: BNC TO CKT BD,W/RIGID COAX | 80009 | 103-0195-01 |
| -38 | 200-2096-01 |  | 1 | .COVER, END:FRONT, PULSE HEAD | 80009 | 200-2096-01 |

STANDARD ACCESSORIES
$070-2818-00$
1 MANUAL,TECH:INSTRUCTION 80009 070-2818-00


## ACCESSORIES

Fig. \&


## MANUAL CHANGE INFORMATION

At Tektronix, we continually strive to keep up with latest electronic developments by adding circuit and component improvements to our instruments as soon as they are developed and tested.

Sometimes, due to printing and shipping requirements, we can't get these changes immediately into printed manuals. Hence, your manual may contain new change information on following pages.

A single change may affect several sections. Since the change information sheets are carried in the manual until all changes are permanently entered, some duplication may occur. If no such change pages appear following this page, your manual is correct as printed.


[^0]:    Read: Resistor 1234 of Subassembly 2 of Assembly 23

