# 2245A PORTABLE OSCILLOSCOPE <br> <br> SERVICE 

 <br> <br> SERVICE}

## WARNING


#### Abstract

THE FOLLOWING SERVICING INSTRUCTIONS ARE FOR USE BY QUALIFIED PERSONNEL ONLY. TO AVOID PERSONAL INJURY, DO NOT PERFORM ANY SERVICING OTHER THAN THAT CONTAINED IN OPERATING INSTRUCTIONS UNLESS YOU ARE QUALIFIED TO DO SO. REFER TO OPERATORS SAFETY SUMMARY AND SERVICE SAFETY SUMMARY PRIOR TO PERFORMING ANY SERVICE.


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## INSTRUMENT SERIAL NUMBERS

Each instrument has a serial number on a panel insert, tag, or stamped on the chassis. The first two digits designate the country of manufacture. The last five digits of the serial number are unique to each instrument. The country of manufacture is identified as follows:

B000000 Tektronix, Inc., Beaverton, Oregon, U.S.A.
E200000 Tektronix United Kingdom, Ltd., London
G100000 Tektronix Guernsey, Ltd., Channel Islands
HKOOOOO Hong Kong
H700000 Tektronix Holland, NV, Heerenveen, The Netherlands

J300000 Sony/Tektronix, Japan

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## OPERATORS SAFETY SUMMARY

The safety information in this summary is for operating personnel. Warnings and cautions will a/so be found throughout the manual where they apply.

## Terms in this Manual

CAUTION statements identify conditions or practices that could result in damage to the equipment or other property.

WARNING statements identify conditions or practices that could result in personal injury or loss of life.

## Terms as Marked on Equipment

CAUTION indicates a personal injury hazard not immediately accessible as one reads the markings, or a hazard to property, including the equipment itself.

DANGER indicates a personal injury hazard immediately accessible as one reads the marking.

## Symbols in this Manual

This symbol indicates where applicable cautionary or other information is to be found. For maximum input voltage see Table 1-1.

## Symbols as Marked on Equipment

DANGER-High voltage.

Protective ground (earth) terminal.
$\triangle$
ATTENTION-Refer to manual.

## Power Source

This product is intended to operate from a power source that does not apply more than 250 V rms between the supply conductors or between either supply conductor and ground. A protective ground connection, by way of the grounding conductor in the power cord, is essential for safe operation.

## Grounding the Product

This product is grounded through the grounding conductor of the power cord. To avoid electrical shock, plug the power cord into a properly wired receptacle before making any connections to the product input or output terminals. A protective ground connection, by way of the grounding conductor in the power cord, is essential for safe operation.

## Danger Arising From Loss of Ground

Upon loss of the protective-ground connection, all accessible conductive parts, including knobs and controls that may appear to be insulating, can render an electric shock.

## Use the Proper Power Cord

Use only the power cord and connector specified for your product.

Use only a power cord that is in good condition.
For detailed information on power cords and connectors, see Figure 2-1.

## Use the Proper Fuse

To avoid fire hazard, use only a fuse of the correct type, voltage rating and current rating as specified in the parts list for your product.

## Do Not Operate in an Explosive Atmosphere

To avoid explosion, do not operate this instrument in an explosive atmosphere.

## Do Not Remove Covers or Panels

To avoid personal injury, do not remove the product covers or panels. Do not operate the product without the covers and panels properly installed.

# SERVICING SAFETY SUMMARY 

## FOR QUALIFIED SERVICE PERSONNEL ONLY

Refer also to the preceding Operators Safety Summary

## Do Not Service Alone

Do not perform internal service or adjustment on this product unless another person capable of rendering first aid and resuscitation is present.

## Use Care When Servicing With Power On

Dangerous voltages exist at several points in this product. To avoid personal injury, do not touch exposed connections or components while power is on.

Disconnect power before removing protective panels, soldering, or replacing components.

## Power Source

This product is intended to operate from a power source that does not apply more than 250 volts rms between the supply conductors or between either supply conductor and ground. A protective ground connection by way of the grounding connector in the power cord is essential for safe operation.


## SPECIFICATION

## DESCRIPTION

The TEKTRONIX 2245A is a 100 MHz , four-channel, dual-sweep, portable oscilloscope for generalpurpose use. A microprocessor-based operating system controls most of the functions in the instrument, including a voltage and time cursor measurement system and a single-button automatic frontpanel setup feature. A menu-driven service mode provides for configuring of single-sweep readout displays, internal calibration, and servicing diagnostics.

The vertical deflection system has four input channels. Two channels have 11 basic deflection factors from 2 mV to 5 V per division, and two channels have two basic deflection factors of 0.1 V and 0.5 V per division. Basic deflection factors can be extended with attenuator probes. VOLTS/DIV readouts are switched to display the correct vertical scale factors when properly coded probes are connected to the vertical input connectors.

The horizontal deflection system provides single, dual, or delayed sweeps from 0.5 s to 20 ns per division (delayed sweep, 5 ms to 20 ns per division). The trigger system provides stable triggering over the full bandwidth of the vertical deflection system.

Alphanumeric crt readouts of the vertical and horizontal scale factors are displayed at the bottom of the screen. On-screen vertical and horizontal cursors provide accurate voltage, time, and frequency measurements; measurement values are displayed at the top of the crt.

The measurement system provides direct readout of delta voltage, delta time, and frequency from positionable cursors. Delay-time and delta-delay measurements for time and frequency are available in ALT and B Horizontal Modes.

By pressing a single button (AUTO SETUP), the front-panel controls can be set up to produce a usable waveform display based on the voltage and time characteristics of the input signals.

## ACCESSORIES

The following items are standard accessories shipped with the 2245A instrument:

2 Probes, 10X, 1.5 meter, with accessories<br>1 Power cord<br>1 Power cord clamp<br>1 Operators manual<br>1 Reference guide<br>1 Crt filter, blue plastic (installed)<br>1 Fuse, 2A, 250 V, slow-blow<br>1 Accessory pouch, Ziploc

Refer to the Accessories page at the back of this manual for part numbers and further information about both standard and optional accessories. Available options are described in Section 7. Your Tektronix representative, local Tektronix Field Office, or Tektronix products catalog can provide additional information on options and accessories.

## PERFORMANCE CONDITIONS

The electrical characteristics in Table 1-1 apply when the 2245A has been calibrated at an ambient temperature between $+20^{\circ} \mathrm{C}$ and $+30^{\circ} \mathrm{C}$, has had a warmup period of at least 20 minutes, and is operating in an ambient temperature between $-10^{\circ} \mathrm{C}$ and $+55^{\circ} \mathrm{C}$ (unless otherwise noted).

Items listed in the "Performance Requirements" column are verifiable qualitative or quantitative limits that define the measurement capabilities of the instrument.

Environmental specifications of the 2245A are listed in Table 1-2, and mechanical specifications are in Table 1-3.

## RECOMMENDED CALIBRATION SCHEDULE

To ensure accurate measurements, check the performance of this instrument ever 2000 hours of operation, or once each year if used infrequency. When components are replaced, affected circuits may have to be readjusted.

## Specification-2245A Service

Table 1-1
Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| VERTICAL DEFLECTION SYSTEM - CH 1 AND CH 2 |  |
| Deflection Factor Range | $2 \mathrm{mV} /$ div to $5 \mathrm{~V} /$ div in $1-2-5$ sequence. ${ }^{\text {a }}$ |
| Accuracy (includes ADD MODE and CH 2 INVERT) $15^{\circ} \mathrm{C} \text { to } 35^{\circ} \mathrm{C}$ | - Within $\pm 2 \%$. |
| $-10^{\circ} \mathrm{C}$ to $15^{\circ} \mathrm{C}$ and $35^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | Within $\pm 3 \%{ }^{\text {a }}$ a |
| Variable Range | Increases deflection factor by at least 2.5:1. |
| Frequency Response ( -3 dB bandwidth) |  |
| $-10^{\circ} \mathrm{C} \text { to } 35^{\circ} \mathrm{C}$ <br> $5 \mathrm{mV} / \mathrm{div}$ to $5 \mathrm{~V} / \mathrm{div}$ | Dc to 100 MHz (at the input BNC and at the probe tip). |
| $2 \mathrm{mV} / \mathrm{div}$ | Dc to 90 MHz (at the input BNC and at the probe tip). |
| $35^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | Dc to 90 MHz (at the input BNC and at the probe tip). ${ }^{\text {a }}$ |
| AC Coupled Lower -3 dB Point |  |
| 1X Probe | 10 Hz or less. |
| 10X Probe | 1 Hz or less. |
| Step Response (5-division step) |  |
| Rise Time |  |
| $-10^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$ |  |
| $5 \mathrm{mV} / \mathrm{div}$ to $5 \mathrm{~V} /$ div | 3.5 ns or less (calculated). ${ }^{\text {a }}$ |
| $2 \mathrm{mV} / \mathrm{div}$ | 3.9 ns or less (calculated). ${ }^{\text {a }}$ |
| $35^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | 3.9 ns or less (calculated). ${ }^{\text {a }}$ |
| Delay Match ( CH 1 to CH 2 ) | Less than 200 ps difference. |

${ }^{\text {a }}$ Performance Requirement not checked in manual.

Table 1-1 (cont)
Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| Common Mode Rejection Ratio (CMRR) | At least 10:1 at 50 MHz for signals of eight divisions or less with VOLTS/DIV VAR adjusted for best CMRR at 50 kHz . |
| Channel Isolation (attenuation of deselected channel) <br> $2 \mathrm{mV} /$ Div to $0.5 \mathrm{~V} /$ Div | 10 MHz 100 MHz <br> 50 dB or more 34 dB or more <br> Channel isolation tested with eight-division input signal. |
| Trace Shift as VAR VOLTS/DIV is Turned | 1 division or less. |
| Invert Trace Shift | 1 division or less. |
| Trace Shift Between VOLTS/DIV Switch Positions | 0.2 division or less. |
| Trace Shift Between GND and DC Input Coupling $-10^{\circ} \mathrm{C} \text { to } 35^{\circ} \mathrm{C}$ | Less than 0.5 mV . |
| $35^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | Less than 2 mV . ${ }^{\text {a }}$ |
| Position Range | At least $\pm 11$ divisions from graticule center. |
| Input Characteristics <br> Resistance | $1 \mathrm{M} \Omega \pm 0.15 \%{ }^{\text {a }}$ |
| Capacitance | $20 \mathrm{pF} \pm 1 \mathrm{pF} .^{\text {a }}$ |
| Capacitance Match Between Any Two VOLTS/DIV Settings | $\pm 0.5 \mathrm{pF}$. |
| Maximum Input Volts $\square$ $\triangle$ | 400 V (dc + peak ac); $800 \mathrm{Vp-p}$ at 10 kHz or less. ${ }^{\text {a }}$ (See Figure 1-1.) |

[^0]Table 1-1 (cont)

## Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| VERTICAL DEFLECTION SYSTEM - CH 3 AND CH 4 |  |
| Deflection Factor |  |
| Range | 0.1 V per division and $0.5 \vee$ per division. ${ }^{\text {a }}$ |
| Accuracy |  |
| $15^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$ | Within $\pm 2 \%$. |
| $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | Within $\pm 3 \%$. |
| Frequency Response ( -3 dB bandwidth) |  |
| $-10^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$ | Dc to 100 MHz (at the input BNC and at the probe tip). |
| $35^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | Dc to 90 MHz (at the input BNC and at the probe tip). ${ }^{\text {a }}$ |
| Step Response (5-division step) Rise Time |  |
| $-10^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$ | 3.5 ns or less. ${ }^{\text {a }}$ |
| $35^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ | 3.9 ns or less. ${ }^{\text {a }}$ |
| Delay Match ( CH 3 to CH 4 ) | Less than 200 ps difference. |
| Trace Shift Between VOLTS/DIV Settings | 1 division or less. |
| Position Range | At least $\pm 11$ divisions from graticule center. |
| Channel Isolation (attenuation of deselected channel) | 34 dB or more at 100 MHz . <br> Channel isolation tested with eight-division input signal. |
| Input Characteristics Resistance | $1 \mathrm{M} \Omega \pm 1.0 \%{ }^{\text {a }}$ |
| Capacitance | $20 \mathrm{pF} \pm 1 \mathrm{pF} .^{\text {a }}$ |
| Maximum Input Volts | ```400 V (dc + peak ac); 800 V p-p at 10 kHz or less.a (See Figure 1-1).``` |

[^1]Table 1-1 (cont)
Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| VERTICAL DEFLECTION SYSTEM - ALL CHANNELS |  |
| Bandwidth Limit ( -3 dB bandwidth) | $20 \mathrm{MHz} \pm 15 \%$. |
| Low-Frequency Linearity (relative to center screen) | Within $\pm 5 \%$. <br> Linearity is measured by positioning a two-division test signal anywhere on screen and noting the amplitude change. |
| TRACE SEP Control Position Range | At least $\pm 4$ divisions. |
| CHOP Mode Clock Rate | $625 \mathrm{kHz} \pm 10 \% .^{\text {a }}$ |
| Delay Match (CH 1 or CH 2 to CH 3 or CH 4 ) | Less than 200 ps difference. |
| HORIZONTAL DEFLECTION SYSTEM |  |
| Sweep Range A Sweep | $0.5 \mathrm{~s} / \mathrm{div}$ to $20 \mathrm{~ns} / \mathrm{div}$ in a $1-2-5$ sequence. ${ }^{\text {a }}$ <br> X10 magnifier extends maximum sweep speed to $2 \mathrm{~ns} / \mathrm{div}$. |
| B Sweep | $5.0 \mathrm{~ms} / \mathrm{div}$ to $20 \mathrm{~ns} / \mathrm{div}$ in a $1-2-5$ sequence. ${ }^{\text {a }}$ <br> X10 magnifier extends maximum sweep speed to $2 \mathrm{~ns} / \mathrm{div}$. |
| Accuracy | Unmagnified $\quad$ Magnified |
| $15^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$ | $\pm 2 \% \quad \pm 3 \%$ |
| $-10^{\circ} \mathrm{C}$ to $15^{\circ} \mathrm{C}$ | $\pm 3 \% \quad \pm 4 \%$ |
|  | Sweep Accuracy applies over the center eight divisions. Excludes the first $1 / 4$ division or 25 ns from the start of the magnified sweep and anything beyond the 100th magnified division. |

[^2]Table 1-1 (cont) Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| HORIZONTAL DEFLECTION SYSTEM (cont) |  |
| Sweep Linearity (relative to center two displayed divisions) | $\pm 5 \%$. |
| POSITION Control Range Normal Displays | Able to move the start of the sweep to the right of the center vertical graticule; able to move a time mark corresponding to the end of the tenth division of an unmagnified sweep to the left of the center graticule. |
| X-Y Displays | At least $\pm 13$ divisions. ${ }^{\text {a }}$ |
| X10 Magnifier <br> Registration ( X 10 to X 1 ) | Expands the normal sweep by ten times around that portion of the sweep positioned at the center vertical graticule line. ${ }^{\text {a }}$ <br> 0.5 division or less shift. |
| Variable Control Range | Continuously variable between calibrated SEC/DIV settings. Extends both the A and B sweep time per division by at least a factor of 2.5 . |
| Sweep Length | Greater than 10 divisions. |
| Delay Time <br> Delay Control Range | Less than 0.1 division to 10 times the A SEC/DIV switch setting. Maximum value does not exceed end of the A sweep. |
| Jitter | 1 part in 20,000, or less, peak-to-peak, during a twosecond time interval. |
| Delta Time <br> Delta Control Range | 0 to greater than 9.9 divisions to the right of setting of DELAY control, but maximum value does not exceed end of the $A$ sweep. |

a Performance Requirement not checked in manual.

Table 1-1 (cont)

## Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| A AND B TRIGGER |  |
| Sensitivity-CH 1 through CH 4: AUTO LEVEL, AUTO NORM AND SINGLE SEQUENCE | Trigger sensitivity is defined as the minimum peak-to-peak sine-wave trigger signal amplitude required to show the test signal with horizontal jitter of less than $3.0 \%$ of one period ( $p-p$ viewed over two seconds). |
| COUPLING DC | 0.35 division from dc to 25 MHz , increasing to 1.0 division at 150 MHz ( 100 MHz in AUTO LEVEL). |
| NOISE REJECT | 1.4 division from dc to 25 MHz ; increasing to 2.2 division at 100 MHz .0 .5 division or less will not trigger. |
| HF REJECT | 0.35 division from dc to 50 kHz ; attenuates signals above upper -3 dB cutoff frequency of 70 kHz . |
| LF REJECT | 0.35 division from 100 kHz to 25 MHz , increasing to 1.0 division at 150 MHz ( 100 MHz in AUTO LEVEL); attenuates signals below the lower -3 dB cutoff frequency of 50 kHz . |
| AC | 0.35 division from 50 Hz to 25 MHz , increasing to 1.0 division at 150 MHz ( 100 MHz in AUTO LEVEL); attenuates signals below the lower -3 dB cutoff frequency of 20 Hz . |
| TV LINE, TV FIELD | 0.5 division of composite sync will achieve a stable display. |
| AUTO LEVEL and AUTO MODE Trigger Low-Frequency Limit | 10 Hz . |
| LEVEL Control Range AUTO, NORM, and SGL SEQ | $\pm 20$ divisions referred to the appropriate vertical input. <br> This range is sufficient to allow triggering at any point on a displayed waveform for all modes except "ADD". In ADD, the combined range of the two position controls exceeds the trigger level range, making it possible (though unlikely) to pull a signal on screen for display but fail to trigger on it due to insufficient trigger level range. |
| AUTO LEVEL | Does not exceed the peak-to-peak amplitude of the trigger signal that was present when the AUTO LEVEL limits were set. ${ }^{\text {a }}$ |

[^3]Table 1-1 (cont)
Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| TRIGGER LEVEL READOUT Accuracy | $\pm(0.3 \%$ of reading $+10 \%$ of one vertical division). |
| HOLDOFF Control Range | Increases A Sweep holdoff time by at least a factor of 10. |
| FUNCTIONS WITH DIGITAL READOUT |  |
|  | Specifications for functions with digital readout are valid only when the ambient temperature is within $\pm 10^{\circ} \mathrm{C}$ of the temperature at the time of the last SELF CAL. For maximum performance, a recent SELF CAL is recommended. |
| CURSOR FUNCTIONS <br> TIME (manually positioned cursors) Accuracy | $\pm(0.5 \%$ of reading $+2 \%$ of the SEC/DIV setting). |
| 1/TIME (manually positioned cursors) Accuracy | Readout calculated from TIME cursor positions. |
| CURSOR VOLTS (manually positioned cursors) Accuracy | $\pm(0.5 \%$ of reading $+2 \%$ of the VOLTS/DIV setting + high frequency display errors). |
| Delay Accuracy, A Sweep Trigger Point to Start of B Sweep | $\pm(0.5 \%$ of reading $+5 \%$ of one division of the A Sweep $+25 \mathrm{~ns})$. |

Table 1-1 (cont)

## Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| X-Y OPERATION |  |
| Deflection Factors <br> Accuracy <br> $Y$ Axis <br> $15^{\circ} \mathrm{C}$ to $35^{\circ} \mathrm{C}$ | Same as Vertical deflection system with the VOLTS/DIV variable controls in calibrated detent position. ${ }^{\text {a }}$ <br> Within $\pm 2 \%$. |
| $\begin{aligned} & -10^{\circ} \mathrm{C} \text { to } 15^{\circ} \mathrm{C} \\ & \text { and } 35^{\circ} \mathrm{C} \text { to } 55^{\circ} \mathrm{C} \end{aligned}$ | Within $\pm 3 \%{ }^{\text {a }}$ |
| $\begin{aligned} & \mathrm{X} \text { Axis } \\ & 15^{\circ} \mathrm{C} \text { to } 35^{\circ} \mathrm{C} \end{aligned}$ | Within $\pm 3 \%$. |
| $\begin{aligned} & -10^{\circ} \mathrm{C} \text { to } 15^{\circ} \mathrm{C} \\ & \text { and } 35^{\circ} \mathrm{C} \text { to } 55^{\circ} \mathrm{C} \end{aligned}$ | Within $\pm 4 \% .^{\text {a }}$ |
| Horizontal (X-Axis) -3 dB Bandwidth | 3 MHz or more. |
| Phase Match (DC Coupled) | $\pm 3$ degrees from dc to 50 kHz . |
| EXTERNAL Z-AXIS INPUT |  |
| Active Region Lower Threshold (intensity decreases above this voltage) | +1.8 volts or less. |
| Signal Required to Modulate an A or B Trace of Normal Intensity | +3.8 volts or less (usable frequency: Dc to 10 MHz ). <br> External Z-Axis signal does not affect the readout or the intensified zone intensity. |
| Maximum input Voltage | 30 V (dc + peak ac); $30 \mathrm{Vp-p} \mathrm{ac} \mathrm{at} 1 \mathrm{kHz}$ or less. ${ }^{\text {a }}$ |
| Input Loading | Represents less than one LSTTL load. ${ }^{\text {a }}$ |

[^4]
## Specification-2245A Service

Table 1-1 (cont) Electrical Characteristics

| CHARACTERISTICS | PERFORMANCE REQUIREMENTS |
| :---: | :---: |
| PROBE ADJUST OUTPUT |  |
| Overshoot (rising and falling edge) | 0.1\% or less. |
| Output Voltage on PROBE ADJUST Jack | $0.5 \mathrm{~V} \pm 2 \%$ into $1 \mathrm{M} \Omega$ load. |
| Repetition Rate | $1 \mathrm{kHz} \pm 25 \%$. |
| FRONT PANEL SETUP MEMORY |  |
| Battery | 3.0 V, 1200 mAH , Type BR-2/3AE2P, Lithium. ${ }^{\text {a }}$ <br> WARNING - To avoid personal injury, have battery replaced only by a qualified service person who understands proper handling and disposal procedures for Lithium batteries. |
| Battery Shelf Life | At least five years. ${ }^{\text {a }}$ |
| Data Retention Time | At least three years or the remainder of battery shelf life, whichever is less. ${ }^{\text {a }}$ |
| POWER SOURCE |  |
| Line Voltage Range | 90 Vac to $250 \mathrm{Vac}^{\text {a }}$ |
| Line Frequency | 48 Hz to $445 \mathrm{~Hz} .^{\text {a }}$ |
| Line Fuse | $2 \mathrm{~A}, 250 \mathrm{~V}$, slow blow. ${ }^{\text {a }}$ |
| Maximum Power Consumption | 100 Watts (155 VA). ${ }^{\text {a }}$ |
| CRT DISPLAY |  |
| Display Area | 8 by $10 \mathrm{~cm} .^{\text {a }}$ |
| Geometry |  |
| Vertical | $\pm 1 / 2$ minor ( 0.1 div ) at 8 by 8 cm centered area. |
| Horizontal | $\pm 1 / 2$ minor ( 0.1 div) at 8 by 10 cm centered area. |
| Trace Rotation Range | Adequate to align trace with center horizontal graticule line. |
| Standard Phosphor | $\text { P31. }{ }^{\mathbf{a}}$ |
| Y-Axis Orthogonality | 0.1 division or less, over eight vertical divisions. No adjustment. |
| Nominal Accelerating Voltage | $16 \mathrm{kV} .^{\text {a }}$ |

a Performance Requirement not checked in manual.


Figure 1-1. Maximum input voltage vs frequency derating curve for the $\mathrm{CH} 1, \mathrm{CH} 2, \mathrm{CH} 3$, or CH 4 input connectors.

Table 1-2
Environmental Characteristics

| CHARACTERISTICS | DESCRIPTION |
| :---: | :---: |
| STANDARD INSTRUMENT |  |
| Environmental Requirements | Instrument meets or exceeds the environmental requirements of MIL-T-28800D for Type III, Class 3, Style D equipment, as described below. ${ }^{\text {a }}$ |
| Temperature Operating | $-10^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right.$ to $\left.+131^{\circ} \mathrm{F}\right)$. |
| Non-Operating | $-51^{\circ} \mathrm{C} \text { to }+71^{\circ} \mathrm{C}\left(-60^{\circ} \mathrm{F} \text { to }+160^{\circ} \mathrm{F}\right) .$ <br> Tested to MLL-T-28800D paragraphs 4.5.5.1.3 and 4.5.5.1.4, except in 4.5.5.1.3, steps 4 and $5\left(-10^{\circ} \mathrm{C}\right.$ operating test) are performed ahead of step $2\left(-51^{\circ} \mathrm{C}\right.$ non-operating test). Equipment shall remain off upon return to room ambient during step 6. Excessive condensation shall be removed before operating during step 7 . |
| Altitude |  |
| Operating | To $7,620 \mathrm{~m}(25,000 \mathrm{ft})$. Maximum operating temperature decreases $1^{\circ} \mathrm{C}$ per 1000 ft above 5000 ft . |
| Non-Operating | To $15,240 \mathrm{~m}(50,000 \mathrm{ft})$. <br> Exceeds requirements of MIL-T-28800D paragraph 4.5.5.2. |
| Humidity (operating and non-operating) | Five cycles ( 120 hours) referenced to MIL-T-28800D paragraph 4.5.5.1.2.2, for Type III, Class 3 instruments. <br> Non-operating and operating at $95 \%,-0 \%$ to $+2 \%$ relative humidity. Operating at $+30^{\circ} \mathrm{C}$ and $+55^{\circ} \mathrm{C}$ for all modes of operation. Non-operating at $+30^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$. |
| Radiated and Conducted Emission Required per VDE 0871 | Meets Category B. |
| Electrostatic Discharge | Conforms to Tektronix Standard 062-2862-00. <br> Withstands discharge of up to 20 kV . Test performed with probe containing a 500 pF capacitor with $1 \mathrm{k} \Omega$ series resistance charged to the test voltage. |
| Vibration (operating) | 15 minutes along each of 3 major axes at a total displacement of 0.25 inch $\mathrm{p}-\mathrm{p}(4 \mathrm{~g}$ at 55 Hz ) with frequency varied from 10 Hz to 55 Hz in 1-minute sweeps. Hold for 10 minutes at 55 Hz in each of the three major axes. All major resonances must be above 55 Hz . |

$a_{\text {performance not checked in manual. }}$

Table 1-2 (cont)
Environmental Characteristics

| CHARACTERISTICS | DESCRIPTION |
| :--- | :--- |
| Bench Handling Test <br> (cabinet on and cabinet off) | MIL-STD-810D, Method 516.2, Procedure VI (MIL-T-28800D, <br> Paragraph 4.5.5.4.3). |
| Transportation |  |
| Packaged Vibration Test | Meets the limits of the National Safe Transit Association test <br> procedure 1A-B-1; excursion of 1 inch p-p at 4.63 Hz (1.1 g$)$ <br> for 30 minutes on the bottom and 30 minutes on the side <br> (for a total of 60 minutes). |
| Package Drop Test | Meets the limits of the National Safe Transit Association test <br> procedure 1A-B-2; 10 drops of 36 inches. |

Table 1-3

## Mechanical Characteristics

| CHARACTERISTICS | DESCRIPTION |
| :---: | :---: |
| STANDARD INSTRUMENT |  |
| Weight |  |
| With Front Cover, Accessories, and Accessories Pouch (without manual) | $8.9 \mathrm{~kg}(19.5 \mathrm{lb})$. |
| With Power Cord | $7.9 \mathrm{~kg} \mathrm{(17.3} \mathrm{lb)}$. |
| Shipping Weight (Domestic) | 11.7 kg ( 25.8 lb ) . |
| Overall Dimensions Height | See Figure 1-2, Dimensional drawing. |
| With Feet and Accessories Pouch (empty) | Approx. 176.5 mm ( 6.95 in ) . |
| Without Accessories Pouch | 164 mm ( 6.44 in ). |
| Width (with handle) | 362 mm (14.25 in). |
| Depth |  |
| With Front Cover on | 445.3 mm ( 17.53 in ) |
| With Handle Extended | 521 mm (20.53). |
| Cooling | Forced air circulation; no air filter. |
| Finish | Tek Blue, painted finish on pebble-grain aluminum cabinet. |
| Construction | Aluminum alloy chassis. Plastic-laminate front panel. |

Table 1-3 (cont)

## Mechanical Characteristics

| CHARACTERISTICS | DESCRIPTION |
| :---: | :---: |
| RACKMOUNT INSTRUMENT |  |
| Weight With Power Cord | $10.0 \mathrm{~kg}(22.0 \mathrm{lb})$. |
| Shipping Weight <br> Domestic, includes manual | $14.2 \mathrm{~kg}(31.3 \mathrm{lb})$. |
| Overall Dimensions Height Overall | See Figure 1-3, Dimensional drawing. $168 \mathrm{~mm}(6.6 \mathrm{in})$ |
| Center of mounting rail to bottom of cabinet | 89 mm (3.5 in) . |
| From cabinet top or bottom to respective front-panel mounting holes | 38 mm (1.5 in). |
| Between front-panel mounting holes | 102 mm (4.0 in). |
| Width |  |
| Overall | 483 mm (19.0 in). |
| Between mounting hole centers | 464 mm (18.3 in). |
| Between outer edges of mounting rails | 427 mm (16.8 in). |
| Between handle centers | 450 mm ( 17.7 in ). |
| Depth |  |
| Overall | 516 mm (20.35 in). |
| Front panel to rear of mounting rail (inside) | 465 mm (18.3 in). |
| Front panel to rear of mounting rail (outside) | 472 mm (18.6 in). |
| Handles | 44 mm (1.75 in) |

Table 1-3 (cont)
Mechanical Characteristics

| CHARACTERISTICS | DESCRIPTION |
| :--- | :--- |
| Required Clearance dimensions | $\geq 178 \mathrm{~mm}(7 \mathrm{in})$. |
| Height | $\geq 448 \mathrm{~mm}(17-5 / 8 \mathrm{in})$. |
| Width | $\geq 508 \mathrm{~mm}(20 \mathrm{in})$. |
| Depth | Forced air circulation; no air filter. |
| Cooling | Aluminum alloy chassis, front-panel frame, and rear support. <br> Plastic-laminate front panel. |
| Construction |  |



Figure 1-2. Dimensional outline drawing, standard cabinet.


Figure 1-3. Dimensional outline drawing, rackmount cabinet.

## PREPARATION FOR USE

## SAFETY

This section tells how to prepare for and to proceed with the initial start-up of the instrument.

Refer to the Safety Summaries at the front of this manual for power source, grounding, and other safety information about the use of the instrument. Before connecting the 2245A to a power source, read this section and the Safety Summaries.

## LINE VOLTAGE AND POWER CORD

The 2245A operates on line voltages from 90 to 250 V with line frequencies ranging from 48 to 440 Hz . No line voltage selection is necessary. Instruments are shipped with the power cord that was requested on the order. The power cord must match the power-source outlet; if it does not, contact your Tektronix representative or local Tektronix Field Office. See Figure 2-1 for optional power cords available.

## WARNING

The detachable three-wire power cord has a threecontact plug for connection to the power source and the protective ground. The power cord is held to the rear panel by a clamp. The protective ground contact on the plug connects (through the power cord protective-ground conductor) to the accessible metal parts of the instrument.
(2931-21)6555-20
Figure 2-1. Optional power cords.

## LINE FUSE



This instrument can be damaged if the wrong line fuse is installed.

Verify the proper value of the power-input fuse with the following procedure:

1. Disconnect the power cord from the power-input source.
2. Press in the fuse-holder cap and release it with a slight counterclockwise rotation.
3. Pull the cap (with the attached fuse inside) out of the fuse holder.
4. Verify proper fuse value.
5. Install the proper fuse and reinstall the fuseholder cap.

## INSTRUMENT COOLING

To prevent instrument damage from overheated components, make sure the internal airflow is not blocked. Before turning on the power, check that the ventilation holes on the bottom and side of the cabinet are not covered. After turning the instrument on, check that air is being exhausted from the rightside ventilation holes.

## START-UP

When the power is turned on, the instrument does a self-diagnostic check. If the instrument does not turn on and operate normally, turn power off and then on again. If the instrument still does not turn on properly, the TRIGGER MODE LEDs may be flashing to indicate the circuit location of a start-up error. Refer to Troubleshooting in the Maintenance section of this manual for an explanation of the start-up error codes.

When the 2245A is turned on, a self-cal routine may run to set the voltage- and timing-measurement constants. The power-on self cal runs only if the stored constants have been lost, possibly due to a dead memory back-up battery. The following warning message will be displayed for 5 seconds: "WARNING PROBABLE BATTERY FAILURE TURN OFF AND ON TO VERIFY." The instrument can still be used for accurate measurements by running the SELF CAL MEASUREMENTS routine from the SERVICE MENU after the instrument has warmed up for at least 20 minutes.

To run the SELF CAL MEASUREMENTS routine:
Press the left and right VERTICAL MODE buttons (CH 1 and CHOP/ALT). When the SERVICE MENU appears on the screen, press the ADD button (down-arrow) to underline SELF CAL MEASUREMENTS and then press the CH 2 button (RUN) to start the routine. Press the CH 4 button (QUIT) or the CLEAR MEAS'MT button to return to the normal oscilloscope mode.

## DETAILED OPERATING INFORMATION

For operating information about specific instrument functions, refer to the 2245A Operators Manual.

## THEORY OF OPERATION

## SECTION ORGANIZATION

This section contains general and detailed descriptions of the 2245A Oscilloscope circuitry. The Block Diagram Description describes the general operation of the instrument functional circuits. Each major circuit is explained in detail in the Detailed Circuit Description. Schematic and block diagrams show the circuit components and interconnections between parts of the circuitry. The circuit descriptions are arranged in the same order as the schematic diagrams.

The detailed block diagrams and the schematic diagrams are in the Diagrams section at the rear of this manual. Smaller functional diagrams are in this section near the associated text. The schematic diagram associated with each circuit description is identified in the text. For best understanding of the circuit being described, refer to the applicable schematic and functional block diagrams.

## INTEGRATED CIRCUIT DESCRIPTIONS

## Digital Logic Conventions

Digital logic circuits perform many functions within the instrument. Functions and operation of the logic
circuits are represented by logic symbology and terminology. Most logic functions are described using the positive-logic convention. Positive logic is a system where the more positive of two levels is the TRUE (or 1) state; the more negative level is the FALSE (or 0 ) state. In this logic description, the TRUE state is high, and the FALSE state is low. Voltages of a high or low state vary among individual devices. For specific device characteristics of common parts, refer to the manufacturer's data book.

## Hybrids

The Channel 1 and Channel 2 attenuators and input buffers are hybrid devices combining thick-film and semiconductor technologies. These devices are made with interconnected circuitry on a single ceramic carrier and have improved performance characteristics over a more discrete type circuit.

## Linear Devices

The operation of individual linear integrated circuit devices is described in this section using waveforms or graphic techniques when needed to illustrate their circuit action.

## BLOCK DIAGRAM DESCRIPTION

## INTRODUCTION

The Block Diagram Description gives an overview of the schematic circuit functions as illustrated in Figure 3-1. It is provided as an aid in understanding the overall operation of the 2245A Oscilloscope circuitry before individual circuits are discussed in detail. The Simplified Block Diagram illustration shows the basic interconnections for signal flow and control signals. Schematic diagram numbers that are referred to in the text are shown by a diamond symbol in each block of the figure.

## VERTICAL INPUTS (Diagram 1)

The signals for viewing or for triggering are applied to the CH 1 through CH 4 vertical input BNC connectors via coaxial cables or probes. Channels 1 and 2 have a choice of AC or DC input coupling or GND. Channels 3 and 4 have DC input coupling only. Scaling of the Channel 1 and Channel 2 input signals has a range of 2 mV per division to 5 V per division without the use of external attenuators. Channels 3 and 4 are limited to two input attenuator choices: 0.1 V per div and 0.5 V per div.


Figure 3-1. Simplified block diagram.


Scaling of the Channel 1 and Channel 2 signals is done by a series of switchable attenuators that provide either no attenuation, X10 attenuation, or X100 attenuation of the input signal. A low-impedance attenuator following an input signal buffer produces $X 1, X 2$, and $X 5$ attenuation steps. Additional control of input signal scaling is provided by the selectable gain Vertical Preamplifiers (shown in Diagram 2).

Channel 3 and Channel 4 input signals are buffered by high input impedance FET amplifiers; no input attenuation of the signal is provided. The gain choices for Channel 3 and Channel 4 are selected by the choice of Vertical Preamplifier gain setting only.

The Measurement Processor controls the operation of much of the switchable circuitry of the 2245A via a common shift register data line (SR DATA). Data bits loaded into the attenuator control and gain shift register (designated SRO) set the magnetic relay switches for the input coupling and attenuator settings and select the gain settings of the Preamplifiers.

## VERTICAL PREAMPS AND OUTPUT AMPLIFIER (Diagram 2)

Each vertical channel has identical selectable-gain Preamplifiers. The calibrated gain for each is manually set during adjustment. Enabling of the Preamplifiers to display a channel input signal is controlled by the Display Sequencer (U600, Diagram 4). Preamplifier gain settings are controlled by the Measurement Processor via control bits loaded into the attenuator control and gain shift register (Diagram 1). Vertical channel trigger signal outputs are produced by each of the Preamplifiers for triggering the sweep from the applied signal.

The vertical outputs of each preamplifier are connected to a summing node at the input to the DelayLine Driver. There, the signal current (from the enabled Preamplifiers) and the no-signal standing currents (from the disabled Preamplifiers) are added with the current from the position signal switching circuit.

The signal current for the enabled channel (vertical channel signal plus its position offset) or the readout position current (enabled to the summing node during text and cursor displays) is applied to the Delay-Line Driver. There, it is buffered and compensated to drive the vertical delay line. The
delay line produces enough delay in the signal to permit the trigger circuitry to start the sweep before the vertical signal arrives at the crt deflection plates, and the rising edge of the triggering signal may be viewed.

From the output of the delay line, the signals are applied to the Vertical Output integrated circuit. The Vertical Output IC (U701) has provisions for vertical BEAM FIND, bandwidth limiting, and vertical centering of the readout displays. External filter elements on the Vertical Output IC produce the bandwidth limiting when switched into the amplifier circuitry. The output signal from U701 is then applied to the Vertical Output Amplifier where it gets its final boost in power to drive the vertical crt deflection plates.

An auxiliary Vertical Comparator circuit (U702 and Q703) is shown in Diagram 2. Its purpose is to measure the gains and offsets during SELF CAL to determine the vertical calibration constants needed for the measurements and tracking cursor displays.

## A AND B TRIGGER SYSTEM (Diagram 3)

The A and B Trigger System provides the circuitry for trigger source, slope, coupling, and bandwidth selection; trigger level comparison; tv trigger detection; and do measurements of the measurement source signal.

Trigger selection signals from the Display Sequencer (U600, Diagram 4) drive the switching circuitry internal to U421 and U431. The signals select the correct trigger source, slope, and coupling choice for the present front-panel control setting. For VERT MODE triggering with more than one vertical channel displayed, the trigger source selection changes as each channel is displayed. When the ADD Vertical Mode is selected, a special amplifier arrangement in U421 (for A) or U431 (for B) sums the CH 1 and CH 2 signals to provide an ADD trigger signal for display of the ADD waveform.

The Trigger CPLG (coupling) selections are AC, DC, HF REJ (high-frequency reject), LF REJ (lowfrequency reject), and NOISE REJ. Of these, all but NOISE REJ coupling are produced by selecting a filter path with the necessary bandwidth characteristics. NOISE REJ coupling, is done in the Trigger Level Comparator circuit by decreasing the sensitivity of the comparator.

When the trigger signal level crosses the comparator threshold set by the Trigger LEVEL and SLOPE control settings, the comparator output changes states. That state change is applied to the Trigger Logic IC (U602, Diagram 4). The Trigger Logic circuitry then produces the gating that starts the A or B Sweep as appropriate.

Separate A and B Trigger bandwidth limit circuits before the Trigger Level Comparators allow the flexibility that is needed for using the B Trigger circuitry as the measurement signal channel. Even when the B Trigger signal itself is bandwidth limited, full bandwidth is used for making measurements. Signals are measured by using the B Trigger Level Comparator as a successive-approximation analog-to-digital converter to determine the peaks or dc level of the applied signal. When making a measurement, the B Trigger Level signal is driven in a binary search by the Measurement Processor (via the DAC system, Diagram 9) while the output of the B Trigger Level Comparator is monitored. When the smallest resolution output of the DAC system causes the comparator output to change states, the Measurement Processor stops the search and uses the DAC input value at that point as the measured value of the applied signal.

Video signal processing to obtain either Field or Line triggering is done in the TV Trigger Detector. Peak detectors determine the negative or positive peaks of the applied video signal. Those levels set the voltage at the reference input of the video signal comparator at a level that strips off all the video information (when the slope selection is correct for the polarity of the applied signal). The remaining composite sync signal is applied directly to the trigger system for Line triggering. Field triggering is obtained by filtering the composite sync to obtain only the vertical sync pulse.

The operating modes of the Trigger circuitry are controlled by the Measurement Processor. Auxiliary Data Shift Register U1103 (the last device in shift register 1) is serially loaded with control bits from the SR DATA line by the SR1 TTL clock. The state (high or low) of the control bits select the bandwidth setting of the $A$ and $B$ Triggers, TV LINE or TV FIELD triggering for the A Trigger system, and the TV FIELD signal for the B Trigger system. Additional control bits output from the Auxiliary Data Shift Register are the MAG signal (X10 Magnification on or off), $\overline{X-Y}$ signal ( $X-Y$ or $Y-T$ displays), and the VERT COMP ENABLE signal (when vertical SELF CAL is done).

## DISPLAY AND TRIGGER LOGIC AND PROCESSOR INTERFACE (Diagram 4)

Control of the display states and the trigger system is done by two special devices. The Display Sequencer (U600, also know as SLIC or slow-logic IC) controls activities that enable the vertical channels for display and select the A and B Trigger System operating states. The Trigger Logic IC (U602, also known as FLIC or fast-logic IC) monitors the A and $B$ Trigger signals, the $A$ and $B$ SWP END signals, the DLY END 0 and DLY END 1 signals, and controlling signals from the Display Logic IC. It outputs the A and B GATE and the Z-Axis signals that start the sweeps and unblank the crt at the appropriate times.

Setup data to the internal registers of the two logic devices is sent from the Measurement Processor over the MB DATA line. A register is enabled for loading by the address that is latched on the ADDR0-ADDR3 lines (from Diagram 8). Data bits are written to U600 with the SLIC WR strobe, and to U602 with the FLIC WR strobe. The contents of the internal registers of the Display Logic IC may also be read by the Measurement Processor using the $\overline{S L I C ~ R D ~ s t r o b e . ~}$

The Processor Interface portion of Diagram 4 handies the serial communications between the serial shift registers and the Measurement Processor. This circuitry is the Measurement Processor's means of controlling the circuit hardware setups in response to a front-panel control setting. Data controlling the state of the serial data bit to be loaded into the shift registers is placed on the ADDRO-ADDR2 bus lines. That address is decoded to produce either a high or a low that is latched on the SR DATA signal line. The appropriate shift register clock is then generated to load the latched bit. Each bit is loaded in succession until all the control bits of a shift register are loaded.

The purpose of shift register (U502) is to permit the Measurement Processor to read back the outputs of the shift registers for diagnostic purposes and the output of the Vertical Comparator during vertical SELF CAL. The last bit from shift register 0 and shift register 1 ( $\overline{R O}$ FREEZE and $\overline{B W}$ LIMIT respectively) and the Vertical Comparator (VERT COMP) state are loaded in parallel and serially shifted out onto the MB RETURN line to be read by the Measurement Processor.

## A AND B SWEEPS AND DELAY COMPARATORS (Diagram 5)

The $A$ and $B$ Sweep circuitry sets the timing and produces the $A$ and $B$ ramp signals to drive the crt horizontal deflection plates. The Measurement Processor sets the hardware states using control bits loaded into shift register 1. One register (U302) holds the bits for selecting the A Sweep timing resistors and capacitors, and one register (U3O3) holds the $B$ Sweep control bits. The timing resistors are selected by multiplexers (U307 and U308 for A Sweep timing; U310 and U311 for B Sweep timing) that are switched by the states of the control bits; timing capacitors are selected directly by the control bits.

The starting level of the sweeps is held steady by a Baseline Stabilizing circuit, and the sweep ends are determined by two Sweep-End Comparators. A and B GATE signals from the Trigger Logic IC (U602, Diagram 4) control the start of the sweep ramps. A constant charging current to the timing capacitors produces a linear voltage rise across the capacitors. That voltage is buffered by the A and B Sweep Buffers for application to the Horizontal Output Amplifier (Diagram 6).

The SEC/DIV VAR control, when out of the calibrated detent position, changes the charging current delivered to the sweep timing capacitors proportional to its rotation. Decreasing the current lengthens the ramp to decrease the sweep speed.

Two comparator circuits are used to check the A Sweep ramp amplitude against the Reference Delay and Delta Delay voltages. Both Delay End Comparator outputs are applied to the Trigger Logic IC (U602, Diagram 4). The Trigger Logic IC monitors the delays to determine when the B Sweep may either run (for RUNS AFTER B Trigger Mode) or accept a B Trigger (for any of the triggered B Sweep modes).

## HORIZONTAL OUTPUT AMPLIFIER (Diagram 6)

Deflection signals applied to the Horizontal Preamplifier (U802) are the A Sweep Ramp, the B Sweep Ramp, the horizontal readout, and the $X$-Axis input signal for $X-Y$ displays. Mode control signals HDO and HD1 (from Display Logic IC U600 to the Horizontal Preamplifier) select the horizontal display mode (A Sweep only, B Sweep only, Alternate, or $X-Y$ display). Other control signals to the Horizontal Preamplifier are the MAG signal (for X10 magnification of the sweep), the BEAM FIND signal
(decreases horizontal gain), and the horizontal position signal for positioning the display. The $X-Y$ signal controlling U301B reduces the range of the Horizontal POSITION signal delivered to the Horizontal Preamplifier when in the $X-Y$ display mode.

Five manual adjustments are associated with the Horizontal Preamplifier. They are the X10 and X1 gain, the Readout gain, the $X$-Axis signal gain, and Mag Registration. Mag Registration compensates for offset between X10 and X1 gains, but it is primarily used to center the readout displays horizontally.

The active single-ended deflection signal input to the Horizontal Preamplifier is amplified and converted to a differential output signal. That signal is further amplified and compensated by the Horizontal Output Amplifier to drive the horizontal deflection plates of the crt. The final output amplifier consists of four MOSFET transistors (Q801, Q802, Q805, and Q806). Two transistors are used for each deflection plate (left and right) to divide the power-handling requirements.

## Z-AXIS, CRT, PROBE ADJUST, AND CONTROL MUX (Diagram 7)

This block of circuitry is divided into several different functions. The largest division is the Z-Axis and CRT circuitry. A INTEN, B INTEN, and RO INTEN input signals from the Analog Control Auto Setup (Diagram 11) and the front-panel controls are applied to the $Z$-Axis circuit to set the associated display intensities. Enabling gates from the Display Controller (Diagram 4) select the appropriate Z-Axis input signal for application to the $\mathbf{Z}$-Axis amplifier as the different display types are enabled. The amplified Z-Axis signals are then level shifted to the negative voltage of the crt cathode ( -2.7 kV ) in a dc restorer circuit. A similar de restorer circuit provides auto focusing (at the fixed focus level set by the front-panel FOCUS control) in response to the intensity level changes. The intensity and auto focus control voltages are applied to the crt where they modulate the electron beam flow that produces the display seen on the screen.

Multiplexer U506, under control of the Measurement Processor, scans the front-panel intensity potentiometers and the probe code lines to check for a change. Signal selection for routing through the multiplexer is controlled by the three bits on the POT5-POT7 bus lines from the Pot Data Latch (Diagram 11). Output from the multiplexer is routed to the Front-Panel Multiplexer (U2309, Diagram 11) and multiplexed with other front-panel control levels. Outputs from U2309 are routed to the A-to-D Converter (U2306, Diagram 11) where a digital value
representing their analog voltage level is determined. That value is checked against the previously obtained value for a selected potentiometer or probe code to determine if a change has occurred and, if so, the amount and direction of the change. The Measurement Processor uses that information to generate new control voltages to the circuitry affected by the change.

The Probe Adjust circuit (U930 and associated circuitry) produces a square-wave signal which is output to the front-panel PROBE ADJUST jack for compensating voltage probes and checking the vertical deflection system of the oscilloscope.

The Volts Cal circuit (U931 and an associated precision voltage divider) provides the accurate dc voltage levels used during vertical SELF CAL to check the gain and offset of the measurement channels.

The Scale lllumination circuit is made up of three incandescent graticule lamps and current-source transistors. The SCALE ILLUM potentiometer sets the bias level on (and thereby the current through) the transistors.

## MEASUREMENT PROCESSOR (Diagram 8)

Many of the oscilloscope circuitry functions are directed by the Measurement Processor (U2501). The Measurement Processor, under firmware control, monitors the front-panel controls and sets up the circuitry under its control according to the settings made and the instructions contained in the System ROM.

The Measurement Processor communicates directly with the devices on its eight-bit data bus. The Measurement Processor selects the device to transfer data to or from by placing the address of the device on the Measurement Processor Address Bus. That address is decoded to produce a strobe that enables the bus device corresponding to the address. Writing to or reading from the enabled device is controlled by write or read ( $\overline{W R}$ and $\overline{R D}$ ) pulses from the Measurement Processor. Communication on the data bus is usually limited to highspeed data transfer only (to and from the System RAM and from the System ROM) and not direct control of any circuit functions.

For controlling most of the circuit operating states, the Measurement Processor places serial bits on the bidirectional MB DATA line. Appropriate enabling strobes and clocks are generated either in its
address-decoding circuitry or by the Processor Interface circuitry (Diagram 4) to load the control data into 24 -bit or 32-bit shift registers. The outputs of these registers control such things as attenuator settings, preamplifier gains, sweep timing, and trigger operating modes; all circuit operating functions that either change with front-panel settings only or at a slow rate.

Scanning of the front-panel controls and lighting of the front-panel LEDs that back-light the buttons is under control of the Measurement Processor. These events occur at long intervals compared to the operating speed of the Measurement Processor. The front-panel switch closures are read by the Measurement Processor over a serial communication line (SW BD DATA).

## READOUT SYSTEM (Diagram 9)

## Readout System

The Readout Processor (U2400) controls the display of text and cursor readouts as directed by the Measurement Processor. The ASCll code of each character (blanks included) in a full screen of readout (one field) is loaded into the appropriate memory location of the Character Code RAM (U2406) by the Measurement Processor. It is then up to the Readout Processor to control the display process.

When the Readout Processor addresses the Character Code RAM for display of the loaded characters, the address of a memory location dictates the place that the addressed character will appear on the face of the crt. The ASCIl code found at the addressed location in the Character Code RAM then accesses the character to be displayed from the Character Dot Position ROM (U2408). The screen position of an individual dot within an addressed character is directed by the character data obtained from the Character Dot Position ROM.

The data bits specifying the character position on screen and the dot position within a given character are converted to analog vertical and horizontal position signals by the readout DACs (U2412 for vertical and U2413 for horizontal). For cursors and cursor-related text, voltages representing the cursor positions are added in the output mixer circuitry ( $\mathrm{U} 2414, \mathrm{U} 2415$, and U 2416 ) to place the readout correctly on screen. Vertical position information needed for the measurement-tracking cursors and readouts is added in the Vertical Position Switching circuit (Diagram 2).

The dots are continually refreshed to maintain a flicker-free readout. When the readout data needs changing, the Measurement Processor halts the refreshing and loads the new screen of data into the Character Codes RAM.

## SWITCH BOARD AND INTERFACE (Diagram 10)

Most of the front-panel switches that can be read by the Measurement Processor are "soft" switches; they are not connected directly into the circuit to be controlled. The front-panel control physical parameters of capacitance, leakage resistance, and inductance, therefore, cannot affect the operation of the controlled circuit. The wiper voltage of the potentiometers is digitized, and that digitized data is used by the Measurement Processor to set up the circuitry under its control as dictated by the control change.

The momentary push-button switches are rapidly scanned at short intervals by the Measurement Processor to check if one is being pressed. When a switch closure is detected, the Measurement Processor makes the necessary circuit or display changes as directed by its firmware instructions for that button and the existing operating states.

Functions are shown to be on by turning on the LED (light-emitting diode) that back-lights the push button or panel label. The Measurement Processor controls the lighting via control registers (U2523 and U2524) that it reloads with control data to enable the correct LED with each button or mode change.

## ADC AND DAC SYSTEM (Diagram 11)

The ADC and DAC system is the Measurement Processor's control link to the analog circuitry. When the Measurement Processor does a scan to determine the front-panel control settings, the DAC system drives the input to the A-to-D converter comparator (U2306) in a binary search pattern to determine the voltage level applied to the other input of the comparator. The smallest incremental change in the DAC input data that produces a switch in the comparator's output identifies the digital value of the unknown voltage. The output of the comparator (AD COMP) is applied to the Data Buffer U2515 on Diagram 8.

## POWER SUPPLY (Diagram 12)

The low and high voltages required to power the 2245A are produced by a high-efficiency, switching power supply. Input ac voltage from 90 to 250 volts and from 48 to 445 Hz is converted to a dc voltage that powers a preregulator circuit. The preregulator supplies regulated power to an inverter switching circuit in the primary of the power transformer (T2204). The secondary voltages produced at the secondary windings of the transformer are rectified and filtered to provide the low voltage power requirements of the instrument.

High voltage to drive the crt is generated by a multiplier circuit (U2203) that provides the +14 kV postdeflection anode voltage and the -2.7 kV to the cathode. The 6.2 Vac heater voltage is supplied by a isolated secondary winding from the power transformer that is referenced to the -2.7 kV cathode voltage.

## DETAILED CIRCUIT DESCRIPTION

## VERTICAL INPUTS (Diagram 1)

Channel 1 and Channel 2 input circuits on this schematic diagram are arranged identically. Only Channel 1 circuit numbers are referred to in the discussion. CH 3 and CH 4 are also arranged identically to each other and described separately from CH 1 and CH 2.

## Input Coupling

Signals applied to the CH 1 BNC connector are coupled to the CH 1 attenuator via the CH 1 Input Coupling circuit. Relay K100, switches between direct (DC) and capacitive coupling (AC) of the input signal; K101 switches between connecting the applied input signal and the VOLT CAL signal to the input of the attenuator. The VOLT CAL signal line provides either the ground for GND Coupling in normal
oscilloscope operation or a test voltage input for characterization during vertical SELF CAL. With the Input Coupling set to GND (both AC and DC off), the signal path is bypassed by C113. That capacitor filters any noise from the VOLT CAL signal line. There is no precharge of the input coupling capacitor (C112)' when the coupling is in ground (GND). Resistor (R111), in series with the BNC input, is a damping resistor.

The probe coding signal (CH1 PRB) is applied to a multiplexer (U500, Diagram 7) where it is selected to be digitized in turn with the other probe-code signals and the front-panel potentiometers. The Measurement Processor determines, from the digitized value of the voltage, the attenuation factor of any attached coded probe (Tektronix coded probes). The scale factor of the VOLTS/DIV readout is then switched to reflect the correct scaling of the displayed signal. Uncoded probes and coaxial cables are interpreted as having no attenuation for setting the readout scale factors.

## High-Impedance Attenuator

Switching relays K 102 and K 103 control the signal path through the high-impedance attenuator, AT117. Signal attenuation is done by two 10 X attenuator sections; for 100 X attenuation, the two sections are cascaded. The $1 \mathrm{M} \Omega$ termination resistance at the output of the attenuator is divided into two parts: $750 \mathrm{k} \Omega$ and $250 \mathrm{k} \Omega$. An output taken across the total resistance is applied to the buffer amplifier fast-path input; another output taken across the $250 \mathrm{k} \Omega$ section is applied to the slowpath input. Low-frequency compensation for the hybrid attenuators is adjusted by C10 and C11 (parts of the hybrid circuit on the ceramic carrier); input $C$ is adjusted using C114.

## Input Buffer Amplifier and 1X, 2X, 5X Attenuators

Input Buffer Amplifier U112 (for CH 1) is a hybrid device. The amplifier portion of the circuitry is a fast-path/slow-path buffer having unity voltage gain that presents a high-resistance, low-capacitance load to the signal from the high-impedance attenuator and a low output impedance to the
low-impedance attenuator at the output of the amplifier. The switchable low-impedance, voltage divider network of U112 provides 1, 2, and 5 times attenuation of the output signal for application to the Vertical Preamplifier.

The input signal is applied to pin 2 (fast-path input) and pin 4 (slow-path input) of U112 from the $1 \mathrm{M} \Omega$ divider at the output of the high-impedance attenuator. Internal circuitry of U112 isolates the signal from loading of the low-impedance attenuator and provides the slow-path and fast-path signal amplification. The fast amplifier path quickly passes the fast leading and falling edges of an input signal with the slow path catching up to complete the signal transfer. The output of the buffer sees a $300 \Omega$ input impedance to the low-impedance attenuator, and the preamplifier sees a $75 \Omega$ output impedance at pin 8 of U112 for all VOLTS/DIV switch settings.

## Attenuator and Vertical Mode Control Registers

The switching relays of Channel 1 are driven by transistor array U174. Drive to each of the transistors in the array to switch the relay states is supplied by the Measurement Processor (U2501) via U171. That device is a portion of a shift register formed by U171, U172 (for channel 2 relays), and U173 (for Preamplifier gains). The devices are connected in series to form one long shift register (designated Shift Register 0). Serial data bits for the entire register string are loaded at pin 2 of U171 from the SR DATA line by the SRO CLOCK applied to pin 3 of all three devices. See Table 3-1 for data bit assignments. Tables 3-2, 3-3, 3-4, and 3-5 define the bit states for controlling the switching.

## CH 3 and CH 4 Input Amplifiers

The CH 3 and CH 4 input buffer amplifiers are identical discrete FET amplifiers. Input coupling for these two vertical inputs is always DC; there is no coupling switch. The $1 \mathrm{M} \Omega$ input is formed by a series voltage divider that attenuates the input signal by five times for application to the gate of the input FETs. The VOLTS/DIV setting (either 0.1 V or 0.5 V ) is made in the Preamplifier stage of the channel. Operation of CH 3 is described; like components in CH 4 do the same job.

Table 3-1
Shift Register 0 Bit Assignment

| Pin | Signal | Controls |
| :---: | :---: | :---: |
| U171 |  |  |
| 4 | $\overline{\mathrm{CH} 1 \text { GND }}$ | K101-CH 1 GND Coupling (last bit) |
| 5 | CH 1 AC | $\mathrm{K} 100-\mathrm{CH} 1$ AC Coupling |
| 6 | CH $1 \times 101$ | K102-CH 1 X10 Attenuator 1 |
| 7 | $\mathrm{CH} 1 \times 102$ | K103-CH $1 \times 10$ Attenuator 2 |
| 14 | $\mathrm{CH} 1 \times 1$ | $\mathrm{K} 105-\mathrm{CH} 1 \times 1$ Buffer Attenuation |
| 13 | NOT USED | No connection |
| 12 | $\mathrm{CH} 1 \times 5$ | K104-CH 1 X5 Buffer Attenuation |
| 11 | CH 1 PREAMP 1 | U210-CH 1 Preamplifier Gain |
| U172 |  |  |
| 4 | CH 1 PREAMP 0 | U210-CH 1 Preamplifier Gain |
| 5 | $\overline{\mathrm{CH}} 2 \mathrm{GND}$ | K108-CH 2 GND Coupling |
| 6 | CH 2 AC | K107-CH 2 AC Coupling |
| 7 | CH $2 \times 101$ | K109-CH $2 \times 10$ Attenuator 1 |
| 14 | $\mathrm{CH} 2 \times 102$ | $\mathrm{K} 110-\mathrm{CH} 2 \times 10$ Attenuator 2 |
| 13 | $\mathrm{CH} 2 \times 1$ | $\mathrm{K} 112-\mathrm{CH} 2 \times 1$ Buffer Attenuation |
| 12 | NOT USED | No connection |
| 11 | $\mathrm{CH} 2 \times 5$ | $\mathrm{K} 111-\mathrm{CH} 2 \times 5$ Buffer Attenuation |
| U173 |  |  |
| 4 | CH 2 PREAMP 1 | U220-CH 2 Preamplifier Gain |
| 5 | CH 2 PREAMP 0 | U220-CH 2 Preamplifier Gain |
| 6 | CH 2 Invert | U220-CH 2 Preamplifier Invert |
| 7 | CH 3 PREAMP 1 | U230-CH 3 Preamplifier Gain |
| 14 | CH 4 PREAMP 1 | U240-CH 4 Preamplifier Gain |
| 13 | ZERO HYST | U431C-B Trigger Comparator Hysteresis |
| 11 | RO FREEZE | U509C-Controls Readout for SELF CAL (first bit loaded) |

From the gate of Q131A, diode CR131 provides protection from negative overvoltages exceeding about -8 V . Input C is adjusted by C 134 for low-frequency compensation. High-frequency response is compensated by C138 across load resistor R137. Step balance is adjusted by R141 in the source lead of Q131B. The single-ended output of U131A is applied via R139 (a $75 \Omega$ resistor) to the CH 3 Preamplifier. The impedance seen by the other differential input of the Preamplifier (U230, pin 8, Diagram 2) is
matched by the parallel combination of R158 and C159 in series with R160.

The probe-coding signal, CH 3 PRB, is read the same way as the CH 1 and CH 2 probe-coding signals. The VOLTS/DIV readout for Channel 3 is switched to correctly match the probe attenuation factor (when properly coded probes are used).

## VERTICAL PREAMPS AND OUTPUT AMPLIFIER (Diagram 2)

## Vertical Preamplifiers

Each input channel has it own Vertical Preamplifier (CH 1-U210, CH $2-\mathrm{U} 220, \mathrm{CH} 3-\mathrm{U} 230, \mathrm{CH} 4-\mathrm{U} 240$ ). The gain setting of the Preamplifier is controlled by Measurement Processor U2501 via the assigned control bits from Shift Register 0 (see Table 3-2). Channel 1 and Channel 2 gains require two control bits (on pins 1 and 2 of the Preamplifiers) to set three different gains for $2 \mathrm{mV}, 5 \mathrm{mV}$, and 10 mV VOLTS/DIV scaling. From 10 mV per division and up, the gain of the CH 1 and CH 2 Vertical Preamplifiers is set to 10 mV per division. The $1,2,5$ scaling sequence for the remaining VOLTS/DIV switch settings is obtained by switching the high- and lowimpedance attenuators. Gain of the CH 3 and CH 4 preamplifiers is controlled by one bit each (on pin 2), since there are only two scaling settings ( 0.1 V and 0.5 V per division) to select (see Table 3-5 for the gain-control bit states).

The internal circuitry of each Vertical Preamplifier is matched for the $2 \mathrm{mV}, 5 \mathrm{mV}$, and 10 mV gain
settings and the dc offsets. The output gain of each Preamplifier is adjusted by varying the commonmode resistance across the output pins (pin 13 to pin 14) to produce calibrated gain for each of the vertical channels.

Each Vertical Preamplifier has a trigger pickoff (pins 17, 18, 19, and 20) for supplying the internal trigger signal to the A and B Trigger Source Selector Multiplexers. Capacitor coupling from pins 17 and 18 to pins 19 and 20 provides a fast-path signal into a duplicate, but level-shifted, slow-path signal line. The negative side of the differential trigger signal is terminated in a capacitor to ground (from pin 19) to provide a balance for the transmission line.

Table 3-2
Input Coupling Control Bit States

| Coupling | GND | AC |
| :---: | :---: | :---: |
| GND/CAL | 0 | 1 |
| AC | 1 | 1 |
| DC | 1 | 0 |

Table 3-3
CH 1 and CH 2 Attenuator and Gain Control Bit States

| VOLTS/DIV | $\overline{\mathrm{X101}}$ | $\overline{\mathrm{X102}}$ | $\mathrm{X1}$ | NC | X 5 | PREAMP1 | PREAMP0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 mV | 1 | 0 | 1 | 0 | 0 | 0 | 0 |
| 5 mV | 1 | 0 | 1 | 0 | 0 | 0 | 1 |
| 10 mV | 1 | 0 | 1 | 0 | 0 | 1 | 1 |
| 20 mV | 1 | 0 | 0 | 1 | 0 | 1 | 1 |
| 50 mV | 1 | 0 | 0 | 0 | 1 | 1 | 1 |
| 100 mV | 1 | 1 | 1 | 0 | 0 | 1 | 1 |
| 200 mV | 1 | 1 | 0 | 1 | 0 | 1 | 1 |
| 500 mV | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 V | 0 | 1 | 1 | 0 | 0 | 1 | 1 |
| 2 V | 0 | 1 | 0 | 1 | 0 | 1 | 1 |
| 5 V | 0 | 1 | 0 | 0 | 1 | 1 | 1 |

Table 3-4
CH 2 INVERT Control Bit

| Setting | CH 2 INV |
| :--- | :---: |
| Normal | 0 |
| INVERT | 1 |

Table 3-5
CH 3 and CH 4 Gain Control Bit

| VOLTSIDIV | PREAMP1 |
| :--- | :---: |
| 0.1 V | 0 |
| 0.5 V | 1 |

The VOLTS/DIV VAR controls for CH 1 and CH 2 (R2101 and R2103) directly vary the gain of the Vertical Preamplifiers between the calibrated VOLTS/DIV settings. The Measurement Processor detects whether the VAR control for a channel is in or out of its detent position; and, if out, a greater-than symbol ( $>$ ) is placed in front of the VOLTS/DIV readout to show that the channel is uncalibrated.

Each Preamplifier produces a standing current of about 11 mA into a common summing node. Output of the vertical signal from a Preamplifier is controlled by enabling signals (CH 1 EN through CH 4 EN ) from Display Logic IC U600 (shown on Diagram 4). The enabling signal that turns on a vertical channel signal also enables the position signal current for that channel through the Vertical Position Switching circult (either U202 or U201) into the summing node.

## Delay Line Driver

The Delay Line Driver is a differential amplifier that provides the signal amplification needed to drive the delay line. The circuit is compensated to produce the needed circuit response at the output of the delay line. Both sides of the differential amplifier are identical, and circuit operation of the positive side components is described.

Transistors Q250 and Q252 are arranged as a feedback amplifier. The parallel combination of R250F and R250G supplies the feedback from the emitter of Q252 back to the base of Q250. Diode CR260 provides a one-diode voltage drop in the feedback loop for proper biasing of the base-to-collector junction of the input transistor (Q250). Gain of the
amplifier is set by the value of common-mode resistor R270 (there is a small dc voltage gain). If the Vertical Preamplifier and Vertical Position circuit output currents are exactly 11 mA (no signal and no offsets) the feedback current is zero. Some standing feedback current will be present if the sum of the input currents is not exactly 55 mA . A 1 mA current change of the input base current to Q250 produces a 41 mV change at the collector of Q252. The no-signal dc output voltage from Q252 is +7.5 V , and the standing current is about 15 mA . The differential voltage between the positive and negative side of the delay line with no signal input is $0 \mathrm{~V} \pm 0.5 \mathrm{~V}$. The differential signal voltage input to the delay line is about 29 mV per graticule division of deflection.

Biasing of the input transistor bases is supplied by R262 and R264 (for Q250) and R263 and R265 (for Q251). Two resistors in series are used to provide the power handling needed (they are low-wattage precision resistors). The dc voltage at the bases of Q250 and Q251 is maintained at 7.5 V by a bias stabilization circuit. Operational amplifier U260 compares the common-mode voltage at the junction of R254 and R255 to the $+7.5 \vee$ supply on its pin 3 input. If the base voltage is too low, U260 raises the common-mode emitter voltage (and thereby the base voltage) of the two input transistors.

Compensation components peak up the circuit response to counteract the roll-off effects of the delay line. The three series-rc combinations (C272 and R272, C273 and R273, and C274 and R247) between the emitters of Q252 and Q253 compensate different frequency ranges to correctly shape the circuit response. The series-rc circuit between the collectors of Q252 and Q253 (C275 and R275) damps the gain at high frequencies to prevent oscillation. Impedance matching and input termination of the $75 \Omega$ delay line is done by the parallel-series combination of R278, R279, R280, and R281.

## Vertical Position Switching

The Vertical Position Switching circuit consists of buffer amplifiers for the four vertical channel position signals (U203A, B, C, and D), two solid state switch arrays (U201 and U202), and a transistor paraphase amplifier circuit (U280, Q284, and Q285).

The vertical positioning voltages from the frontpanel POSITION controls are applied to the noninverting inputs of the four voltage-follower buffer amplifiers (U203A through U203D). The inputs and outputs of the amplifiers are capacitively bypassed to eliminate noise from the position signals. The buffered output signals are applied to switching arrays U201 and U2O2 for selection at the correct time for positioning the displayed trace and positionrelated readouts.

POSITION VOLTAGE SWITCHES. Selection of the channel or readout position signals to be supplied to the paraphase amplifier summing node is controlled by several sources. The vertical channel enable signals ( CH 1 EN through CH 4 EN ) from Display Sequencer U600. (Diagram 4) turn on the appropriate channel position signal for the enabled Vertical Preamplifier when displaying waveforms. The nominal position range of the vertical signal is $\pm 12$ divisions.

When position-dependent readout (labeled cursors that follow the vertical channel position controls) is displayed, the RO CH 1 POS EN through RO CH 4 POS EN signals from tri-state latch U2403 (shown on Diagram 9) enable the appropriate vertical position signal into the summing node at the input to the paraphase amplifier. The Readout Position Enable signal lines are tri-stated (open) during display of the channel signals so that the Vertical Channel Enable signals have control of the position enable lines. Also, the Readout Position signals cannot override the Vertical Channel Enable signal levels to turn on a Vertical Channel Preamplifier with the series resistors (R212, R222, R232, and R242) in the signal path. The vertical position of the enabled vertical channel is added to the position of the readout so that the cursors appear at the correct vertical position in the display.

When non-position tracking readout is displayed (i.e., menus and scale-factor readouts), the vertical screen position of the readout is conveyed by the RO VERT signal only. The RO VERT signal is enabled into the summing node input of the paraphase amplifier by the RO VERT EN signal for both readout types (position-tracking or fixed). Extra noise bypassing provided by decoupling components R205, R207, and C268 on the RO VERT signal line reduces jitter of the readout display.

During vertical SELF CAL, the RO CH 1 POS EN through RO CH 4 POS EN signals disable the appropriate vertical position signal into the summing node at the input to the paraphase amplifier without turning off a channel Vertical Preamplifier. The gain and offset of the preamplifiers may then be calculated. The computed offsets are then used by the Measurement Processor to correctly place the positiontracking readouts (cursors) on the display relative to the vertical position of the waveform.

The TRACE SEP EN and RO TR SEP EN signals operate the same as described for the channel enable and readout position enable signals. A slight difference between the channel vertical position signals and the TRACE SEP signal is that TRACE SEP is attenuated more. The higher value of R206 on pin 13 of U201 reduces the TRACE SEP range to $\pm 4$
divisions as compared to $\pm 12$ divisions for the vertical signals.

POSITION PARAPHASE AMPLIFIER. The Position Paraphase amplifier circuitry is formed by a transistor array (U280) driving two discrete transistors (Q284 and Q285). The circuit is configured as two negative-feedback amplifiers that produce a differential output current from the summed singleended input current. Transistors U280B and U280E are constant-current sources for their associated amplifier pairs in the array. The feedback path for the U280A-U280F amplifier combination is via R286 from the emitter of Q284. The no-signal feedback current through R286 is 1 mA . Feedback for the U280C-U280D combination is via R289 from the emitter of Q285. Feedback current in R289 is $100 \mu \mathrm{~A}$. Both Q284 and Q285 are high beta transistors requiring little base-drive current. The overall vertical displacement response from the input (at the base of U280F) to the output is $200 \mu \mathrm{~A}$ per division of vertical screen displacement.

The signal applied to the base of U280C is the inverted position signal developed across R290 in the emitter of Q284. The signal is again inverted by U280C to drive the base of Q285 in the opposite direction from the signal at the base of Q284. The standing dc current (no signal input) output current into the delay line input summing node is 11 mA , the same as the output of the vertical preamplifiers. Vertical centering of the menu and readout displays within the graticule area is done using VERTICAL READOUT CENTERING potentiometer R260.

## Vertical Output Amplifier

## WARNING

Vertical Output IC U701 runs hot and can burn you if touched. The metal tab on top of the device is NOT ground; it is the -5 V supply to the IC.

Vertical Output IC U701 buffers the signal output of the delay line and provides the circuitry for the BW LIMIT and BEAM FIND functions and for the vertical signal gain adjustment. The inputs to the Vertical Amplifier are terminated in $75 \Omega$ by external resistors R706 and R707. External filter components C707, L701, and L702 produce the bandwidth limiting of the vertical signal when internally switched into the output amplifier circuitry of U701.

Manual calibration of the vertical signal display to the crt graticule is done using VO Gain potentiometer R703. The components between pins 12 and 22 of U701 (Q704, R726, R727, and R728) provides gain
correction for the small difference in gain between full bandwidth and bandwidth-limited operation of the Vertical Output IC. Correction for a thermal change between display of the signal and display of the readout is provided by the RO Jitter adjustment (R724).

WARNING<br>Vertical Output Amplifiers Q701 and Q702 run hot and can burn you if touched.

Vertical Output Amplifiers Q701 and Q702 provide the signal gain necessary to drive the vertical crt deflection plates. The deflection plates have a comparatively large capacitance, and to change the voltage as fast as necessary to deflect the crt beam, the Vertical Output Amplifiers have to handle large current demands. A reduction in circuit capacity is made by reducing the collector capacitance of the output transistors. The cases of Q701 and Q702 are NOT the collectors; they are connected to the transistors' base material; the case tabs mark the collector leads. In the collector circuits, T-coils L703 and L704 boost the vertical bandwidth of the output amplifiers; and R731 and R732 are damping resistors.

## Vertical Comparator

The Vertical Comparator circuit (U702, Q703, and associated components) allows the Measurement Processor to determine the gain and offset of the vertical system up to the input to the Vertical Preamplifier. The circuit is enabled only during the vertical self characterization routine. Known dc voltage levels are applied to the attenuator inputs, and U702 compares the voltage from the delay line to the HORIZ POS signal which is being driven in a binary search pattern. The output voltage is found by successively narrowing the search levels until the smallest change possible from the DAC system causes the Vertical Comparator output to change states. Using the measured value to compare against the known input voltage, the Measurement Processor determines a Vertical Calibration constant that must be applied to produce accurate voltage measurements.

## A AND B TRIGGER SYSTEM (Diagram 3)

Most of the trigger signal switching and trigger level comparator circuitry is contained on two integrated circuit devices (U421 and U431). Within the devices is the logic eircuitry that drives the selectable variables of Trigger SOURCE, Trigger CPLG, and Trigger SLOPE for both the A and the B Triggers. Selection of the trigger variables is done by control bits generated by Display Sequencer U600 (Diagram 4). The remaining portions of the circuitry shown in Diagram 3 include the $A$ and $B$ Trigger bandwidth limiting circuitry, the TV Trigger Detector circuitry, and the Auxiliary Control Register (part of Shift Register 1).

## A and B Trigger Source Selectors

Analog switching of the Trigger signal sources is done by the circuitry in U421A (for the A Trigger) and U431A (for the B Trigger). The possible Trigger SOURCE selections are the same for both the A and the B Trigger system. They are $\mathrm{CH} 1, \mathrm{CH} 2, \mathrm{CH} 3$, CH 4, LINE, and VERT. In ALT Vertical MODE, when VERT is the selected source a trigger is obtained in succession for each displayed channel. A stably triggered display will be obtained for each channel signal without regard to frequency relationships between the applied signals. If ADD Vertical MODE is selected, a special adder circuit in U421A and U431A, adds the CH 1 and CH 2 signals to produce an ADD trigger signal composed of the two inputs. The LINE Trigger signal is a sample of the power-line input voltage. Multiplexer U1106A, in the input path for the LINE trigger signal, selects between the LINE signal (for oscilloscope operation) and the TB CAL signal (used for horizontal self characterization).

When a Voltage Measurement is being done, U431A in the B Trigger circuit acts as the measurement channel selector and selects either the CH 1 or the CH 2 input signal to be measured.

## A and B Trigger Coupling Selectors

Coupling selections for DC, AC, HF REJ, and LF REJ are done by U421B for the A Trigger and U431B for the B Trigger. The trigger signal path is through a filter circuit having the proper bandpass characteristics for the selected trigger coupling. NOISE REJ coupling is done differently. The two Trigger LEVEL Comparators (U421C and U431C) have selectable hysteresis. For NOISE REJ Trigger CPLG, the hysteresis is increased so that a larger signal change is required to produce a state change at the output of the comparators. Trigger Coupling control logic is shown in Table 3-6.

Another signal source selectable in the Trigger Coupling Selectors is the output of the TV Trigger Detector (TV LINE or TV FIELD). An applied composite video signal is separated so that the horizontal line or vertical field sync pulse can be used to trigger the oscilloscope for television signal display (see TV Trigger Detector description). Selection
between LINE or FIELD for the A Trigger source is done by multiplexer U1104A with its output being applied to pin 18 of U421B. Pin 18 of U431B in the B Trigger system has an input of either the TV Line sync signal, for TV triggering of the B Sweep, or the output of the Measurement Signal Low-Pass Filter, when the $D C$ measurement mode is active.

Table 3-6
Trigger Selection Logic

| Front Panel Coupling Selection | Latched Bit Values |  |  |  | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | SLOPE | TS2 | TS1 | TSO |  |
| A Sweep Mode (U421) Auto Lvl, Auto, Normal, or Single Seq |  |  |  |  |  |
| DC | 0 | 0 | 1 | 0 | DC Coupled |
| NOISE REJ | 1 | 0 | 1 | 0 | DC Coupled, Noise Reject |
| HF REJ | 0 | 1 | 0 | 1 | HF Reject |
| LF REJ | 0 | 0 | 1 | 1 | LF Reject |
| AC | 0 | 1 | 0 | 0 | AC Coupled |
| A Sweep Mode (U421) TV Line, or TV Field |  |  |  |  |  |
| DC | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| NOISE REJ | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| HF REJ | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| LF REJ | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| AC | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| B Sweep Mode (U431) Auto Lvl, Runs After, or Normal |  |  |  |  |  |
| DC | 0 | 0 | 1 | 0 | DC Coupled |
| NOISE REJ | 1 | 0 | 1 | 0 | DC Coupled, Noise Reject |
| HF REJ | 0 | 1 | 0 | 1 | HF Reject |
| LF REJ | 0 | 0 | 1 | 1 | LF Reject |
| AC | 0 | 1 | 0 | 0 | AC Coupled |
| B Sweep Mode (U432) TV Line |  |  |  |  |  |
| DC | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| NOISE REJ | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| HF REJ | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| LF REJ | 1 | 0 | 0 | 0 | TV Input, Noise Reject |
| AC | 1 | 0 | 0 | 0 | TV Input, Noise Reject |

MEASUREMENT SIGNAL LOW-PASS FILTER. The average dc level of a signal is obtained for measurement by filtering the measurement channel signal to remove all but the dc component of the signal. A active RC filter circuit formed by U1101B, R1154, R1155, C1154, and C1155 does the filtering with U1101B buffering the filtered output voltage to isolate it from loading. The dc level is applied back to the Trigger Coupling switch (U431B, pin 18) for input to the B Trigger Comparator (U431C) where the actual measurement is done (see the B Trigger Comparator description).

## A and B Trigger Bandwidth Limit Circuits

The A Trigger Bandwidth Limit circuit components (Q440, U441F, CR432, C432, L432, R432, Q444, and U441E) act to roll off the trigger circuit bandwidth when BW LIMIT is active (low). The B Trigger Bandwidth Limit circuit components do the same job (with some additional compensation components), but can be selected independently of the SCOPE BW front-panel setting (by the Measurement Processor using the BW FULL B signal). That is because the B Trigger Channel is used for the Measurement system, and the circuit bandwidth must be full for making measurements. The actual circuit operation for both is the same, and only the A Trigger Bandwidth limiting action is described.

For full trigger bandwidth, the $\overline{\text { BW LIMIT }}$ signal from Auxiliary Register U1103 is written high by the Measurement Processor. That high is inverted to a low by U441E and U441F and applied to the bases of Q440 and Q444. The low output turns off Q444 and disconnects C444 from ground. The purpose of C444 is to act as part of an LC filter that rolls off the signal. The low applied to the base of Q440 turns that transistor on, pulling the anode of CR432 up and forward biasing it. The trigger signal ac path then bypasses L432 and R432 through CR432 and C432. The dc component of the trigger signal is still via L432 and R432.

When the bandwidth is limited, the BW LIMIT signal is low. That is inverted to a high that turns on Q444 (connecting C444 to ground) and turns off Q440 (reverse biasing CR432). The trigger signal path is now through L432 and R432 with C444 connected to ground to roll off the circuit bandwidth.

## A Trigger Comparator

The Trigger signal is compared with the A Trigger LEVEL setting by U421C to determine the signal level and slope of the trigger signal that produces a
sweep trigger. The comparator slope is set internally by the switching logic; the Trigger comparison level is set using the front-panel Trigger LEVEL control. A fixed amount of hysteresis in the A Trigger Level Comparator prevents double triggering on signals accompanied by normal noise. NOISE REJ coupling increases the hysteresis by a factor of four to reduce the Comparator's sensitivity to noise if triggering on very noisy signals is required. Once a level state change occurs, a larger change in the opposite direction is required (because of the circuit hysteresis) to reverse the state change. The differential output of U421C is applied to the Trigger Logic IC (U602, Diagram 4) where the gating signals to start the display sweep are generated.

## B Trigger Comparator

For B Trigger signal comparison, the B Trigger Level Comparator (U431C) works the same as the A Trigger Level Comparator. The output of the B Trigger Level Comparator is applied to the B Trigger input of U602 (Diagram 4) via delay line DL22. The 18 ns delay produced permits the leading edge of the $B$ trigger signal to be viewed when displaying the $B$ Sweep.

## Auxiliary Shift Register

Auxiliary Shift Register U1103 is the last register in Shift Register 1. Control bits loaded into the register from the AUX DATA signal line (from U303 pin 9, Diagram 5) are serially shifted through Sweep Shift Register U3O2 and U3O3 (Diagram 5). Circuit functions controlled by the bits in $\cup 1103$ are the following:

B TV TRIG EN: Switches between the B TV Trigger signal and the $D C$ measurement signal voltage (U1106C).

TV FIELD SEL: Switches the A Trigger between TV FIELD and TV LINE (U1104A).

MAG: Controls the X10 Magnification function of the Horizontal Output Preamplifier (U802, Diagram 6).

[^5]BW LIMIT : Switches between full and limited A Trigger bandwidth. The BW LIMIT signal has a second use. As the last bit in Shift Register 1, it is fed back to the Measurement Processor during diagnostic checks done on the Shift Registers.
$\overline{X-Y}$ : Switches the range of the horizontal position signal (HORIZ POS) between that needed for Y-T display and that needed for $X-Y$ display (U301B, Diagram 6).

Multiplexer (U1106A) normally provides the Line Trigger signal picked off from the Power Supply input. For self characterization (SELF CAL) of the Time Base, the switch outputs the TB CAL signal obtained from the Measurement Processor (U2501, Diagram 8).

## TV Trigger Detector

INPUT AMPLIFIER. The signal at pin 19 of U421A is applied to pin 3 of U1101A via a low-pass filter formed by R426, L426, and C426. The filter limits the bandwidth of the X -AXIS signal to about 5 MHz for application to the Horizontal Preamplifier (U802, Diagram 6) and to the TV Trigger Detector circuitry. Operational amplifier U1101A provides low-pass gain of the applied composite video signal that further attenuates the video portion of the signal relative to the sync pulses. The output signal from U1101A is applied to the Peak Detectors and the Sync Comparator.

PEAK DETECTORS. The peak detectors determine the positive and negative peaks of the applied composite video signal. Those peaks voltages are applied across a voltage divider circuit used to set the comparison level (slice level) to one input of a comparator. That level is such that, when the user selects the correct sync polarity for the applied signal, the middle of the sync tips is at the threshold level of the comparator. The output of the comparator then switches only on the sync tips of the applied signal. The peak detectors are complementary in that the positive-peak detector transistors (Q1101, Q1102, and Q1103) and the negative-peak detector transistors (Q1104, Q1105, and Q1106) are complementary types (PNP-NPN). Both detectors are driven from the same input signal; the positive peaks of the video signal forward bias Q1101, and the negative peaks forward bias Q1104. The operation of the positive peak detector is described.

The composite video signal is applied to the emitter of Q1101. A positive-going signal increases the current through Q1101, causing the collector voltage to rise. The rising collector voltage biases on Q1102 harder, and C1114 charges up rapidly following the positive-going signal up to its positive peak. When the input signal starts negative, Q1101 is turned off immediately by the charge held on C1114. That leaves C1114 holding the positive peak voltage of the input signal. Emitter-follower Q1103 applies that peak voltage level to U1104B pin 3 via R1117. R1136 to the -7.5 V from pin 3 provides a fixed offset to the signal level. The negative-peak detector does the same type of operation on the signal to apply the negative peak voltage to pin 5 of U1104B.

When the sync polarity is selected to match the sync of the applied video signal (by the user with the A SLOPE switch), the voltage level at the selected input of U1104B is at the middle of the sync-tip voltage. If the wrong polarity is selected, triggering will take place on the video signal. For signal generator signals, the effect may not be noticeable, except for a shift of the trigger point; but if composite video signals are being viewed, the display will be unstable when the wrong polarity is selected.

SYNC COMPARATOR. The incoming composite video signal is applied to the plus input (pin 3) of the Video Sync Comparator (U1102A). The Video Sync Comparator looks at the signal level on pin 2 and compares it with the incoming video signal level. When the incoming level crosses the comparison threshold, the output of U1102A switches state. That state change occurs at the mid level of the sync pulses. The output signal of U1102A (TV LINE) is applied directly to U1104A pin 2 and U1106C pin 1 to be available for selection for the A and the B Trigger systems for TV LINE triggering.

FIELD SYNC FILTER. The filter circuit composed of R1132, R1133, C1106, C1107, and U1102B processes the output of U1102A further to determine when the vertical field sync signal is present. The time constant of the filter elements is such that the line sync pulses between vertical fields cannot move the voltage on U1102B pin 5 across the comparison threshold (ground on pin 6).

During the vertical field sync pulse, the frequency of the serration pulses (line and equalizing) doubles. The filter capacitors will then be discharged enough to go below ground and switch the output state of U1102B. That signal is applied to U1104A pin 1 to be available as the TV FIELD Sync trigger signal for the A Trigger system.

SYNC SWITCHING. Solid-state switches U1104A and U1106C provide switching between the TV FIELD and the TV LINE signal for the A Trigger and between TV LINE from A SOURCE and the average DC level of the measurement channel for the B Trigger. The switching states are controlled by the Measurement Processor via the TV FIELD SEL and the B TV TRIG EN control signals from the Auxiliary Control Register (U1103).

## DISPLAY AND TRIGGER LOGIC AND PROCESSOR INTERFACE (Diagram 4)

The Display Sequencer or SLIC (slow-logic integrated circuit, U600) performs most of the slow logic functions required to run the display functions. This integrated circuit contains a microprocessor interface, the display sequencer logic circuitry, the trigger holdoff timer, the chop clock, and an interface to the on-screen readout control logic.

The microprocessor interface of U600 provides the capability to serially load the internal control register, write the internal read/write memory, do some limited real-time control over a few sequencer functions, and monitor status information.

The Display Sequencer contains a read/write memory for storing the display states to be sequenced through and logic for sequencing the $A$ and B Sweep displays and trigger sources. The sequencer also provides control signals that are needed to do waveform measurements.

An internal trigger holdoff timer provides a pulse with programmable width that is triggered on at the end of A Sweep (or at the end of B Sweep). The pulse width may be set from $1 \mu \mathrm{~s}$ to greater than 0.5 s , depending on the internal counter divide ratio, and the holdoff oscillator frequency at pin 15.

The chop clock circuit generates a phase-dithered chop clock and blanking signal, derived from an external frequency source. With 10 MHz applied, the chop rate can be 1.25 MHz or 625 kHz , with a blanking time of about 200 ns ( 625 kHz is used in the 2245A).

The readout interface circuit responds to the readout request and readout blanking inputs, and generates a blanking signal (BLANK, pin 18) to control the $Z$-Axis Amplifier enabling signals from

U602. The chop blanking signal also gets routed through this circuit.

## Pin Description

The following is a description of Display Sequencer U600 pin functions (see Figure 3-2 for pin numbers).

DIO: Data 10 pin. This pin is tied to the Measurement Processor MB DATA line. Data to be clocked into the control register is presented here, and status data can be read out on this pin when the $\overline{R D}$ input is low (tristate output). See Table 3-7.

TDI: Trigger data input pin. When $A 3=A 2=1$, data on this pin is sent to the DIO pin (when $\overline{R D}$ is low).
$\overline{\text { RD: Read enable input (active low). Bringing }}$ this pin low causes internal status data (selected with A3-AO) to be presented on the DIO pin for transfer to the Measurement Processor.

WR: Write enable input (active low). A negative-going pulse on this pin performs actions described in the Table 3-7.

SOUT: Strobe output pin (active low). When $A 3, A 2, A 1$, and $A 0=1111$, SOUT goes low when the $\overline{W R}$ pin is pulled low. Otherwise, $\overline{\text { SOUT }}$ is always high.

A3, A2, A1, A0: Address inputs. The ADDRO-ADDR3 selection bits are latched from the Measurement Processor address bus by U2512, Diagram 8.

A GATE: A Sweep Gate input (active low).

B GATE: B Sweep Gate input (active low).

TC: Timing clock input.

LFC: Low-frequency clock input. A signal derived from the calibrator circuit is used for skewing the chop-clock phase.

ROR: Readout request input (active low). A low causes the CH $1 \mathrm{EN}, \mathrm{CH} 2 \mathrm{EN}, \mathrm{CH} 3 \mathrm{EN}$, CH 4 EN, HD1, HDO, and TS outputs to all go low, and allows the $\overline{\mathrm{ROB}}$ input to have complete control of the BLANK output. If $\overline{R O B}$ is low when $\overline{R O R}$ goes low, then the internal timing will be such that the BLANK output will go high quickly enough to blank the display before switching transients can be shown on screen (see the detailed description of the readout interface).
$\overline{R O B}$ : Readout blank input (active low). During readout active time ( $\overline{\mathrm{ROR}}=\mathrm{low}$ ), the $\overline{\mathrm{ROB}}$ input is inverted and sent to the BLANK output.

OSC OUT: The external holdoff oscillator output drives this pin. A falling edge causes the internal holdoff counter to increment.

OSC RST: Oscillator reset output. Internal logic causes this output to go high to discharge the external holdoff oscillator timing capacitor at the end of holdoff (see detailed description of the holdoff timer operation).

CH 1 EN: Channel 1 enable output (active high).

CH 2 EN: Channel 2 enable output (active high).

CH 3 EN: Channel 3 enable output (active high).

CH 4 EN: Channel 4 enable output (active high).


Figure 3-2. Display Sequencer IC (SLIC, U600) pin out diagram.

Table 3-7
Display Sequencer (U600) Control Bit Assignments

| A3 | A2 | A1 | AO | DIO when $\overline{R D}$ LO | Action when WR Strobed |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 0 | 0 | 0 | 0 | Control Reg. msb | DIO clocked into Control Reg. (a) |
| 0 | 0 | 0 | 1 | RAM comparator | RAM written from Control Reg. |
| 0 | 0 | 1 | 0 | EOSS flag | RAM address incremented (b) |
| 0 | 0 | 1 | 1 | EOS signal (c) | RESET is strobed (d) |
| 0 | 1 | 0 | 0 | A Gate Detect flag | MRESET is strobed (e) |
| 0 | 1 | 0 | 1 | B Gate Detect flag | RAM load mode enabled (f) |
| 0 | 1 | 1 | 0 | A Gate Detect flag | A/B GATE-detect flags reset |
| 0 | 1 | 1 | 1 | B Gate Detect flag | Set A slope output (g) |
| 1 | 0 | 0 | 0 | (h) | Forces B1/B2 Source/Slope/Delay (i) |
| 1 | 0 | 0 | 1 | (h) | Forces B Slope output (j) |
| 1 | 0 | 1 | 0 | (h) | Sets BLANK output HI (k) |
| 1 | 0 | 1 | 1 | (h) | Sets THO output HI (k) |
| 1 | 1 | 0 | 0 | TDI data | (see description of TEST input) |
| 1 | 1 | 0 | 1 | TDI data | (see description of TEST input) |
| 1 | 1 | 1 | 0 | TDI data | Sets norm B Source/Slope/Delay (I) |
| 1 | 1 | 1 | 1 | TDI data | SOUT pin gets strobed |

## Notes:

(a) Data is clocked into the control register on the rising edge of $\overline{W R}$.
(b) RAM load mode must be enabled; the address increments on the rising edge of $\overline{W R}$.
(c) EOS (end of sequence) goes high for the last state of any display sequence. EOS is read out for test purposes.
(d) The THO output should be set high when RESET is strobed for proper initialization. This does the following:
a. It initiallzes the display sequencer back to the first display state (RAM address 000). In ALT VERT Mode, all vertical enable, horizontal enable, and trig source outputs are initialized. In CHOP VERT Mode, the horizontal enable and trig source outputs are initialized, but the vertical enable outputs continue to cycle at the chop clock rate.
b. It resets the EOSS (end of single sequence) flag.
c. It resets the trigger holdoff timer.
(e) Used for initiallzation, during testing of the device.
(f) A rising edge on $\overline{W R}$ with DIO $=1$ enables the RAM load mode; a rising edge on $\overline{W R}$ with DIO $=0$ disables the RAM load mode.
(g) A rising edge on $\overline{W R}$ with DIO $=1$ sets the A Slope output high; a rising edge on $\bar{W}$ with DIO $=0$ sets the A Slope output low.
(h) Used for device testing only.
(I) A rising edge on $\overline{W R}$ with DIO $=1$ forces the B1 Trigger Source, the B1 Slope, and sets the DS output high; a rising edge on $\overline{W R}$ with DIO $=0$ forces the B2 Trigger Source, the B2 Slope, and sets the DS output low.
(J) A rising edge on $\overline{W R}$ with DIO $=1$ forces the $B$ SLOPE output high; a rising edge on $\overline{W R}$ with DIO $=0$ forces the $B$ SLOPE output low. This forcing function takes precedence over the force B1/B2 Source/Slope/Delay feature described in note (I) above. This forcing function is canceled by applying a negative strobe to the WR input with the address $=1110$.
(k) A rising edge on $\overline{W R}$ with $D I O=1$ sets the output high; a rising edge on $\overline{W R}$ with $D I O=0$ allows the output to behave normally. (I) A negative pulse on $\overline{W R}$ with address $=1110$ will cancel the effects of (i) above and allow the B Source, B Slope, and DS outputs to behave normally.

ATS 2, ATS 1, ATS 0: A Trigger Source Select outputs. These bits either correspond to three bits of the control register, or they track with the vertical channel enable outputs (in ALT Vertical Mode with VERT MODE trigger selected). These outputs change state on the rising edge of the THO output, or when RESET is strobed while THO is high. The encoding scheme is shown in Table 3-8.

Table 3-8
A Trigger Source Select Bits

| ATS 2 | ATS 1 | ATS 0 | SOURCE |
| :---: | :---: | :---: | :--- |
| 0 | 0 | 0 | CH 1 |
| 0 | 0 | 1 | CH 2 |
| 0 | 1 | 0 | $\mathrm{CH} \mathrm{1}+\mathrm{CH} 2$ |
| 0 | 1 | 1 | CH 3 |
| 1 | 0 | 0 | CH 4 |
| 1 | 0 | 1 | Line |

A SLOPE: A Trigger slope output.

BTS 2, BTS 1, BTS 0: B Trigger Sourcé Select outputs. These bits correspond to either one of two sets of three bits in the control register, or they can track with the vertical channel enable outputs (in ALT Vertical MODE). These outputs normally change state on the rising edge of the THO output, or when RESET is strobed while THO is high. If B1 or B2 Source/Slope/Delay is being forced, the outputs will correspond directly with one of the two three-bit sets in the control register. The encoding scheme matches that used for the A trigger source select bits shown in Table 3-8.

B SLOPE: B Trigger Slope output. This output is set to either one of two bits in the control register. This output normally changes state on the rising edge of the THO output, or when RESET is strobed while THO is high. It may also be forced high or low by the Measurement Processor via the processor interface.

HD1, HD0: Horizontal display enable outputs. These outputs normally change state on the rising edge of the THO output, or when RESET is strobed while THO is high. The encoding scheme is shown in Table 3-9.

DS: Delay select output. This output normally changes state on the rising edge of the THO output, or when RESET is strobed while THO is high. It may also be forced by the Measurement Processor via the processor interface. DS high selects the first delay (B1), and DS low selects the second delay (B2).

TS: Trace separation output. This output changes state on the rising edge of the THO output, or when RESET is strobed while THO is high. TS goes high to enable trace separation; TS goes low during a readout request cycle.

ZEN: Z-Axis enable output (active low). This output goes low when the ZAP control bit is set high, or when the selected B trigger source channel (as presented on the BTS 2, BTS 1, and BTS 0 output pins) is the same as the channel being enabled for display.

MGE: Measurement gate enable output (active low). This output behaves the same way as ZEN, except in chop vertical mode, in which MGE stays in a low state. Also, the ZAP control bit has no effect on MGE.

THO: Trigger holdoff output (active high). Outputs the variable holdoff pulse. In single sequence mode, this output will go high after the last A Sweep of the sequence and stay high until RESET is strobed. This output may also be forced high via the Measurement Processor interface.

BLANK: This output is controlled from three sources. At the end of a readout request cycle (when $\overline{R O R}$ goes high), the BLANK output will be asserted for four to six timing clock periods (to hide vertical source switching transients). Chop blanking pulses can be routed to this output (however, when
$\overline{R O R}$ is low, chop blanking is automatically inhibited). Lastly, this output may be forced high via the Measurement Processor interface.

TEST : Test mode enable input (active low). $\overline{\text { TEST }}$ is held high and not used in normal operation. This pin is pulled high to force normal operation, but may be pulled low to enable the test mode. Enabling test mode does the following:

1. Disables single sequence and $B$ Ends $A$ modes, no matter what code is in the control register.
2. Reconfigures the trigger holdoff timer to make it more easily testable (see control register description for control bits H4-HO).
3. $\mathrm{A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0=1100$ allows a negativegoing pulse on $\overline{W R}$ to reset only the control register.
4. $A 3, A 2, A 1, A 0=1101$ allows a negativegoing pulse on $\overline{W R}$ to preset control register bits B1-B6.

## Control Register Description

The Display Sequencer internal control register is a 26-bit, serial-shift register that receives control-bit data from the Measurement Processor. Table 3-10 lists the control signal name(s) associated with each register bit. Bit number 1 receives the data from the DIO pin (via the Processor Interface) after one low-to-high transition on the WR input pin (A3 = A2 = A1 $=A 0=0$ ). Bit number 26 receives this data after 25 more low-to-high transitions on the $\overline{W R}$ input. Bit number 26 is the most-significant bit position of the internal shift register.

RD5-RD0: Data inputs to the internal RAM. The RAM address comes from a three-bit, binary up-counter. To write data into the RAM, the first six bits are loaded into the control register with the RAM data word. With $\mathrm{A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{AO}=0001$, a negativegoing pulse on the $\overline{W R}$ input will write the data into RAM. To set the RAM address, the RAM load mode must be enabled. In RAM load mode, a low-to-high transition on the $\overline{W R}$ input (with $A 3, A 2, A 1, A 0=0010$ ) will increment the RAM address by one. There are eight consecutive RAM locations (addresses 000 to 111); the address counter will increment to 111 , then wrap around to 000. Strobing RESET resets the

Table 3-10
Shift Register 1 Control Bit Data

| Bit Nr | Control Signal Name(s) |  |  |
| :---: | :--- | :--- | :--- |
|  |  |  |  |
| 1 | ȦS2 | RD5 | AC3 |
| 2 | AS1 | RD4 | AC2 |
| 3 | AS0 | RD3 | AC1 |
| 4 | ZAP | RD2 |  |
| 5 | B1S2 | RD1 | BC3 |
| 6 | B1S1 | RD0 | BC2 |
| 7 | B1S0 |  | BC1 |
| 8 | B1SLOPE |  |  |
| 9 | B2S2 |  |  |
| 10 | B2S1 |  |  |
| 11 | B2S0 |  |  |
| 12 | B2SLOPE |  |  |
| 13 | VM1 |  |  |
| 14 | VM0 |  |  |
| 15 | HM1 |  |  |
| 16 | HM0 |  |  |
| 17 | DD |  |  |
| 18 | SSE |  |  |
| 19 | B ENDS A |  |  |
| 20 | H4 |  |  |
| 21 | H3 |  |  |
| 22 | H2 |  |  |
| 23 | H1 |  |  |
| 24 | H0 |  |  |
| 25 | FSEL |  |  |
| 26 | CBEN |  |  |
|  |  |  |  |

counter to 000 . See the Display Sequencer detailed description to find out what the RAM outputs do.

The RD5-RD0 bits also go to the inputs of an internal RAM comparator. The RAM outputs are sensed by the other comparator input. If the two inputs match, the comparator output will be high. The RAM comparator output can be read by the Measurement Processor through the processor interface.

AC3-AC1: The A Trigger CPLG select bits. BC3-BCO are the B Trigger CPLG and SLOPE select bits. To write these bits into the trigger coupling circuits, the Measurement Processor loads the control register as follows: Bits 1, 2, and 3 are set to AC3, AC2,
and AC1 respectively, and the A SLOPE output is set to ACO. Bits 5, 6, 7, and 8 are set to $\mathrm{BC} 3, \mathrm{BC} 2, \mathrm{BC} 1$, and BCO respectively. The RAM load mode is enabled, the force B1/B2 feature is disabled, and THO is strobed once (or RESET is strobed once while THO is high). At this point, output pins ATS2, ATS1, ATS0, and A SLOPE are set to $A C 3, A C 2, A C 1$, and $A C 0$ respectively; and output pins BTS2, BTS1, BTS0, and B SLOPE are set to $\mathrm{BC} 3, \mathrm{BC} 2, \mathrm{BC} 1$, and BC 0 respectively. The Measurement Processor then strobes the latches in the Trigger Coupling Select Logic circuits to make the trigger coupling selections. The RAM load mode is then disabled to resume normal Display Sequencer operation.

AS2, AS1, ASO: A Trigger SOURCE select bits. See Table 3-11 for the bit encoding of the control signals when not loading the RAM or coupling circuits.

For any binary code except 111; AS2, AS1, and ASO are presented on output pins ATS2, ATS1, and ATSO respectively after a THO rising edge. For binary code 111, the data on the three output pins will correspond to the channel being enabled for display; it alternates as the channel displays alternate and change state on the rising edges of THO. The RAM load mode is disabled to get the A Trigger SOURCE to alternate.

Table 3-11
Trigger Source Select

| AS2 | AS1 | AS0 | SOURCE |
| :--- | :--- | :--- | :--- |
| 0 | 0 | 0 | CH 1 |
| 0 | 0 | 1 | CH 2 |
| 0 | 1 | 0 | $\mathrm{CH} \mathrm{1}+\mathrm{CH} \mathrm{2}$ |
| 0 | 1 | 1 | CH 3 |
| 1 | 0 | 0 | CH 4 |
| 1 | 0 | 1 | Line |
| 1 | 1 | 0 | -- |
| 1 | 1 | 1 | VERT MODE |

ZAP: Setting this bit high forces the $\overline{Z E N}$ output low. This bit is low for allow normal operation of the $\overline{Z E N}$ output.

B1S2, B1S1, B1S0: B1 Trigger SOURCE select bits. Bit encoding is the same as the
encoding for the A Trigger SOURCE select bits.

B2S2, B2S1, B2S0: B2 Trigger SOURCE select bits. Encoded the same as A Trigger SOURCE select bits, except that code 111 does not select VERT Mode trigger. Selection between B1 SOURCE and B2 SOURCE is normally made with the DS (delay select) output signal. $D S=1$ selects $B 1$, and $D S=0$ selects B2. If the B1 select bits are 111 and the B1 SOURCE is selected (not forced), then the data on output pins BTS2, BTS1, and BTSO will track with the selected vertical channel (similar to the A Trigger SOURCE select outputs).

B1 SLOPE, B2 SLOPE: B Trigger SLOPE bits. One of these two bits is presented on the $B$ SLOPE output pin (if B SLOPE isn't being forced), in the same way that the B1 and B2 sources are selected. When B1 SOURCE is selected, then B1 SLOPE is also selected, and B2 SLOPE gets selected when B2 SOURCE is selected.

VM1, VM0: Vertical MODE control bits. See Table 3-12 for encoding.

Table 3-12
Vertical MODE Select

| VM1 | VMO | MODE |
| :---: | :---: | :--- |
| 0 | 0 | Not used |
| 0 | 1 | Chop Mode |
| 1 | 0 | Alt Mode (with no measurement) |
| 1 | 1 | Alt Mode (with measurement) |

HM1, HMO: Horizontal MODE control bits. See Table 3-13 for encoding.

Table 3-13
Horizontal MODE Select

| HM1 | HM0 | MODE |
| :---: | :---: | :--- |
| 0 | 0 | A only |
| 0 | 1 | ALT |
| 1 | 0 | $B$ only |
| 1 | 1 | $X-Y$ |

Table 3-14
Holdoff Counter Encoding

| H4 | H3 | H2 | H1 | HO | Count Length | H4 | H3 | H2 | H1 | H0 | Count Length |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 10000 |
| 0 | 0 | 0 | 0 | 1 | 2 | 1 | 0 | 0 | 0 | 1 | 20000 |
| 0 | 0 | 0 | 1 | 0 | 5 | 1 | 0 | 0 | 1 | 0 | 50000 |
| 0 | 0 | 0 | 1 | 1 | 5 | 1 | 0 | 0 | 1 | 1 | 50000 |
| 0 | 0 | 1 | 0 | 0 | 10 | 1 | 0 | 1 | 0 | 0 | 100000 |
| 0 | 0 | 1 | 0 | 1 | 20 | 1 | 0 | 1 | 0 | 1 | 200000 |
| 0 | 0 | 1 | 1 | 0 | 50 | 1 | 0 | 1 | 1 | 0 | 500000 |
| 0 | 0 | 1 | 1 | 1 | 50 | 1 | 0 | 1 | 1 | 1 | 500000 |
| 0 | 1 | 0 | 0 | 0 | 100 | 1 | 1 | 0 | 0 | 0 | 100000 |
| 0 | 1 | 0 | 0 | 1 | 200 | 1 | 1 | 0 | 0 | 1 | 200000 |
| 0 | 1 | 0 | 1 | 0 | 500 | 1 | 1 | 0 | 1 | 0 | 500000 |
| 0 | 1 | 0 | 1 | 1 | 500 | 1 | 1 | 0 | 1 | 1 | 500000 |
| 0 | 1 | 1 | 0 | 0 . | 1000 | 1 | 1 | 1 | 0 | 0 | 100000 |
| 0 | 1 | 1 | 0 | 1 | 2000 | 1 | 1 | 1 | 0 | 1 | 200000 |
| 0 | 1 | 1 | 1 | 0 | 5000 | 1 | 1 | 1 | 1 | 0 | 500000 |
| 0 | 1 | 1 | 1 | 1 | 5000 | 1. | 1 | 1 | 1 | 1 | $1^{\text {a }}$ |

a Strobing RESET presets the holdoff counter to 499999 to simplify testing.

DD: Dual-delay control bit. $D D=1$ for dual delay (delta time), and $D D=0$ for single delay.

SSE: SGL SEQ enable. SSE $=1$ for single sequence mode or 0 for repetitive mode.

B ENDS A: $B$ ends $A$ enable (active high).

H4, H3, H2, H1, H0: Holdoff time. Encoded as in Table 3-14. With the TEST pin held high for normal operation.)

FSEL: Chop frequency select bit. With 10 MHz on the TC input pin, FSEL $=1$ provides a chop frequency of 625 kHz ; FSEL $=0$ produces 1.25 MHz ( 625 kHz is used).

CBEN: Chop blank enable bit. CBEN $=1$ allows the chop blanking signal to be passed out the BLANK output pin (when $\overline{\text { ROR }}$ is high); CBEN $=0$ inhibits chop blanking.

## Display Sequencer Operation

The internal RAM is programmed for the desired vertical channel display sequence, for both CHOP and ALT Vertical Modes. In ALT mode, the RAM also controls the horizontal display control outputs. In CHOP mode, the RAM still controls the vertical channel displays, but different logic controls the horizontal display selection.

RAM data bits RD5, RD4, and RD3 are programmed for a particular channel display (see Table 3-15).

Table 3-15
Display Sequencer Channel Select Logic Bits

| RD5 | RD4 | RD3 | Channel |
| :---: | :---: | :---: | :--- |
| 0 | 0 | 0 | CH 1 |
| 0 | 0 | 1 | CH 2 |
| 0 | 1 | 0 | $\mathrm{CH} 1+\mathrm{CH} 2$ |
| 0 | 1 | 1 | CH 3 |
| 1 | 0 | 0 | CH 4 |

Bit RD2 selects between the A Sweep display and the B Sweep display (only used in ALT Vertical Mode (with measurement). The A Sweep is displayed if this bit is set high (outputs HD1, HDO = 01), otherwise the B Sweep is displayed (outputs HD1, HDO = 10). Bit RD1 controls the DS (delay select) output pin in ALT Vertical Mode (with or without measurement). Finally, bit RDO marks the last state in a display sequence. When the RDO bit goes high, the sequencer finishes its current state and jumps back to the initial state (RAM address 000 is the initial state). In ALT Vertical Mode, the sequencer will advance to the next state either on each rising edge of the trigger holdoff pulse (ALT Vertical Mode with measurement), or on every other rising edge of the trigger holdoff pulse (ALT Vertical Mode with no measurement).

The first type of ALT Mode is used when there is an intensified zone (with or without an accompanying B Sweep) for only one or two of the displayed channel(s); every display state can be completely specified by programming the RAM properly (no more than eight display states are ever needed for any measurement display sequence; hence, the RAM is limited to eight addresses). The second type of ALT Mode is used when there are intensified zones and B Sweeps for all channels displayed. In this mode, HD1 and HDO automatically alternate between the A sweep and the B Sweep on each rising edge of the trigger holdoff pulse. Whenever HD1 and HD0 switch from the B Sweep back to the A Sweep, the vertical sequencer advances to its next state. This second type of ALT Vertical Mode is used only when more than eight RAM locations are needed to define a long display sequence in ALT Horizontal Mode.

In ALT Vertical Mode, the vertical and horizontal display enable outputs are initialized as follows: the trigger holdoff output is forced high (via the processor interface), RESET is strobed, then trigger holdoff is unforced to allow sweeps to occur. This procedure ensures that the display enable and trigger source outputs are initialized to the first state of the programmed display sequence.

In CHOP Vertical Mode, the leading edge of the chop blanking pulses advance the vertical display enable outputs. RAM bits RD5, RD4, and RD3 still determine the vertical channel displayed, and RAM bit RDO marks the last display state in the sequence. RAM bits RD2, and RD1 are not used in CHOP Mode. Other circuitry, clocked by the trigger holdoff pulse, drives the horizontal display control outputs. The same initialization procedure as described above for ALT Vertical Mode is used. However, only the trigger source and horizontal display enable outputs are initialized. The vertical-display-enable outputs cycle at the CHOP rate. Table 3-16 specifies the behavior of the horizontal-display-enable outputs for all horizontal and vertical modes.

## Trigger Holdoff Timer

When the B ENDS A control bit is low, the holdoff timer is triggered by the rising edge of $\bar{A}$ GATE. When the B ENDS A control bit is high, the holdoff timer is triggered by either the rising edge of $\bar{B}$ GATE, or the rising edge of $\bar{A}$ GATE, whichever occurs first. The THO output pin will go high immediately, and go low after the programmed number of holdoff oscillator cycles. In SGL SEQ Mode (again, with the TEST input pin high), the EOSS (end of single sequence) flag will go high and the THO output will stay high after the last A Sweep of the programmed sequence. Strobing RESET will reset the EOSS flag, and set the THO output back low again, if THO hasn't been forced high via the Measurement Processor interface.

HOLDOFF OSCILLATOR. A relaxation oscillator circuit formed by U601, Q600, Q601 and associated components is connected between the OSC OUT and OSC RST pins to provide the input count pulses to the holdoff timer. The HOLDOFF voltage applied to the base of Q600 sets up a charging current into timing capacitor C600. When the holdoff timer is inactive, the OSC RST output pin is high, and C600 is held discharged. With the capacitor discharged, the output of the oscillator is held high. When a rising edge of $\overline{A \text { GATE }}$ (or $\overline{B G A T E}$ in $B$ ends $A$ mode) occurs, the OSC RST output will go low and allow the voltage across C600 to ramp up. When this voltage crosses an upper threshold, the output of U601 at pin 7 goes low. This negative transition increments the internal holdoff counter, and causes the OSC RST output to go high, again discharging C600. When the voltage drops below a lower threshold, the oscillator output again goes high to repeat the oscillation cycle. After the last negative transition on the OSC OUT pin for a particular count length, the OSC RST output will go high and stay there until the next time the THO timer is triggered.

Table 3-16
Horizontal and Vertical Display Response

| Delay and Vertical Modes |  |  | HORIZONTAL CONTROL SIGNAL OUTPUTS |  |  |  |  | $\begin{aligned} & \text { Readout } \\ & \text { Active } \\ & (\overline{\operatorname{ROR}}=0) \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Signal Names | Readout Inactive ( $\overline{\mathrm{ROR}}=1$ ) |  |  |  |  |
|  |  |  | Horizontal Modes (HM1 HM0) |  |
| DD | VM1 | Vm0 |  | A Only $(00)$ | A Alt B <br> ( 0 1) | B Only $\left(\begin{array}{ll} 1 & 0 \end{array}\right)$ | $\left.\begin{array}{c} X / Y \\ (1 \end{array}\right)$ |  |
| $\begin{aligned} & 0 \\ & 0 \end{aligned}$ | $\begin{aligned} & 0 \\ & \text { or } \\ & 0 \end{aligned}$ |  |  | $\begin{gathered} \text { NSSS (a) } \\ \text { DS } \\ \text { HDO } \\ \text { HD1 } \\ \text { TS } \end{gathered}$ | $\begin{aligned} & 1 \\ & \mathrm{H} \\ & \mathrm{HI} \\ & \mathrm{LO} \\ & \mathrm{LO} \end{aligned}$ | $\begin{gathered} 2 \\ \text { HI } \\ \text { (d) } \\ \text { HDO } \\ \text { HDD } \end{gathered}$ | $\begin{aligned} & 1 \\ & \mathrm{HI} \\ & \mathrm{HI} \\ & \mathrm{H} \\ & \mathrm{LO} \end{aligned}$ | (b) HI LO HI LO | $\begin{aligned} & \text { (c) } \\ & \text { (c) } \\ & \text { LO } \\ & \text { LO } \\ & \text { LO } \\ & \hline \end{aligned}$ |
| $1$ | $\begin{aligned} & 0 \\ & \text { or } \\ & 0 \end{aligned}$ |  | $\begin{gathered} \text { NSSS (a) } \\ \text { DS } \\ \text { HDO } \\ \text { HD1 } \\ \text { TS } \end{gathered}$ | $\begin{aligned} & 2 \\ & \text { (d) } \\ & \text { H } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ | $\begin{gathered} 4 \\ \text { (e) } \\ \text { (d) } \\ \text { HDO } \\ \text { HD1 } \end{gathered}$ | $\begin{aligned} & 2 \\ & \text { (d) } \\ & \text { LO } \\ & \text { HI } \\ & \text { LO } \end{aligned}$ | $\begin{aligned} & \text { (b) } \\ & \text { LO } \\ & \text { HI } \\ & \text { HI } \\ & \text { LO } \end{aligned}$ | (c) <br> (c) <br> LO <br> LO <br> LO |
| 0 | 1 | 0 | $\begin{gathered} \text { NSSS (a) } \\ \text { DS } \\ \text { HDO } \\ \text { HD1 } \\ \text { TS } \\ \hline \end{gathered}$ | $\begin{aligned} & \text { (f) } \\ & \text { HI } \\ & \text { HI } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ | $\begin{gathered} \text { (f) } \\ \text { HI } \\ \text { (d) } \\ \text { HDO } \\ \text { HD' } \end{gathered}$ | $\begin{aligned} & \text { (f) } \\ & \text { HI } \\ & \text { LO } \\ & \text { HI } \\ & \text { LO } \end{aligned}$ | $\begin{aligned} & \text { (b) } \\ & H \\ & H \\ & H \\ & H \\ & \text { LI } \end{aligned}$ | $\begin{aligned} & \text { (c) } \\ & \text { (c) } \\ & \text { LO } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ |
| 0 | 1 | 1 | $\begin{gathered} \text { NSSS (a) } \\ \text { DS } \\ \text { HDO } \\ \text { HD1 } \\ \text { TS } \end{gathered}$ | $\begin{aligned} & \text { (g) } \\ & \text { HI } \\ & \text { HI } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ | $\begin{gathered} \text { (g) } \\ \text { HI } \\ \text { (h) } \\ \hline \text { HDO } \\ \text { HD } \end{gathered}$ | $\begin{aligned} & \text { (g) } \\ & \text { H } \\ & \text { LO } \\ & \text { H } \\ & \text { LO } \end{aligned}$ | $\begin{aligned} & \text { (b) } \\ & \text { HI } \\ & \mathrm{HI} \\ & \mathrm{HI} \\ & \mathrm{LO} \end{aligned}$ | $\begin{aligned} & \text { (c) } \\ & \text { (c) } \\ & \text { LO } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ |
| 1 | 1 | 0 | $\begin{gathered} \text { NSSS (a) } \\ \text { DS } \\ \text { HDO } \\ \text { HD1 } \\ \text { TS } \\ \hline \end{gathered}$ | $\begin{aligned} & \text { (f) } \\ & \text { (i) } \\ & \text { H } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ | $\begin{array}{r} \text { (f) } \\ \text { (i) } \\ \text { (h) } \\ \text { FDD } \\ \text { HDD } \\ \hline \end{array}$ | $\begin{aligned} & \text { (f) } \\ & \text { (i) } \\ & \text { LO } \\ & \text { HI } \\ & \text { LO } \end{aligned}$ | (b) <br> (i) <br> HI <br> H LO | $\begin{aligned} & \text { (c) } \\ & \text { (c) } \\ & \text { LO } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ |
| 1 | 1 | 1 | $\begin{aligned} & \text { NSSS (a) } \\ & \text { DS } \\ & \text { HDO } \\ & \text { HD1 } \\ & \text { TS } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { (g) } \\ & \text { (h) } \\ & \text { HI } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ | (g) <br> (h) <br> $\frac{(\mathrm{h})}{\mathrm{HDO}}$ <br> HD1 | $\begin{aligned} & \text { (g) } \\ & \text { (h) } \\ & \text { LO } \\ & \text { HI } \\ & \text { LO } \end{aligned}$ | (b) <br> (b) (h) HI HI LO <br> (h) <br> HI | $\begin{aligned} & \text { (c) } \\ & \text { (c) } \\ & \text { LO } \\ & \text { LO } \\ & \text { LO } \end{aligned}$ |

NOTES:
(a) NSSS = Complete A Sweep cycles in a single sequence.
(b) Not applicable in single sequence mode.
(c) Signal state not affected by readout.
(d) Signal changes state after each rising edge of THO; Initialized to a high state in single sequence mode.
(e) Signal changes state after every other rising edge of THO; it is initialized to a high state in SGL SEQ mode.
(f) NSSS = Two times the number of states programmed into the vertical sequencer. In ALT Vertical Mode with no measurement, the vertical sequencer advances to its next state at the end of every other A GATE.

## NOTES (cont):

(g) NSSS = The number of states programmed into the vertical sequencer.
(h) Programmable with the vertical sequencer.
(I) Programmable with the vertlcal sequencer. There are two A Sweeps per vertical display state.

## Sweep Gate Detection

Display Logic IC U600 also contains sweep gate detect latches that can be read out and reset via the Measurement Processor interface. The A GATE detect latch output will go high on the rising edge of $\bar{A}$ GATE after a falling edge of $\bar{A}$ GATE, if the $\overline{M G E}$ signal is low (i.e., the latch is armed by $\overline{M G E}$ ). The B GATE detect latch output goes high when B GATE goes low (level sensitive). The A GATE latch is reset on the leading edge of the A/B RESET signal, so that the latch will not miss an A GATE occurring before the end of the latch reset interval. The B GATE latch resets when the $A / B$ RESET signal is low.

## Chop Clock

The clock frequency applied to the TC input pin is either divided by 8 (FSEL $=0$ ), or divided by 16 (FSEL = 1), producing a positive-going pulse at the BLANK output pin (when enabled) with a width equal to about two times the period of the clock signal on the TC input. To produce phase skewing, the chop frequency divider circuit is forced to skip ahead by four TC clock periods on a rising edge of $\bar{A}$ GATE. This skipping is gated on and off by applying a low-frequency clock signal (about 1 kHz from the Calibrator circuit) to the LFC (low-frequency clock)
input pin. Internally, the LFC signal is divided by two, and when the resulting square wave is high, count skip-ahead is enabled.

## Readout Interface

The Readout Interface accepts inputs from the $\overline{R O R}$ and $\overline{R O B}$ pins, and drives the BLANK output pin. When $\overline{R O R}$ is high, the BLANK output is controlled by the chop blank signal (when enabled by the CBEN control bit).

When the $\overline{R O R}$ input is low, chop blanking is disabled and the $\overline{R O B}$ input is inverted and allowed to control the BLANK output. When the ROR input goes from low to high, the BLANK output remains connected to the readout blank signal for an additional four to six TC clock periods. Normally, the $\overline{R O B}$ input will be low during this time so that the BLANK output will be high to mask vertical source-switching transients. The HD1, HDO, and TS outputs are disabled two to four TC periods after $\overline{R O R}$ goes low, and are again enabled two TC periods before the BLANK output is disconnected from the readout blank signal $(\overline{\mathrm{ROB}})$. For any readout request cycle, the $\overline{R O R}$ input remains low for greater than six TC clock periods. Relative timing of $\overline{R O R}$, BLANK, HDO and HD1 (HDx), TS, and vertical channel enables ( $\mathrm{CH} \times \mathrm{EN}$ ) is shown in Figure 3-3.


Figure 3-3. Readout interface relative signal timing.

## Trigger Logic IC (FLIC)

The Trigger Logic IC or FLIC (fast-logic integrated circuit, U602 Diagram 4) does most of the fast logic functions required to run the oscilloscope. The functions are: A Sweep control, B Sweep control and measurement gate generation, Z-Axis control, and trigger status detection.

The A Sweep logic generates the A Sweep gate signal (A GATE), and provides trigger status information about the state of the A Trigger. The B Sweep logic interfaces to the Delay Time Comparators (Diagram 3) and generates the B Sweep gate (B GATE) and measurement gate signals. There is also some logic that monitors the B Trigger signal status when making voltage measurements with the B Trigger circuit. The Z-Axis control logic provides outputs for controlling the crt beam intensity.

The Trigger Logic circuit is done in an ECL (emittercoupled logic) gate array, and all inputs and outputs are compatible with standard ECL components.

## Pin Description

The following is a description of the fast logic pin outs (see Figure 3-4).

BLANK: Blanking input, from the Display Logic IC (U600).

HD1, HDO: Horizontal display select inputs, from the Display Logic IC.
$\overline{Z E N}: Z-A x i s$ enable input, from the Display Logic IC. Active low.

BUSY: Counter busy signal. Not used in the 2245A.

ATRIG: A Sweep trigger input.

EOAS: End of A Sweep. This signal goes high when the A Sweep ramp crosses its end-of-sweep threshold.

THO: Trigger holdoff input from the Display Logic IC.


Figure 3-4. Trigger Logic IC (FLIC, U602) pin out diagram.
$\overline{\text { SIN }}$ : Strobe input. Latches data into the internal register. Active low.

A1, A0: Address inputs. See Table 3-17 for addressing codes.

EOBS: End of B Sweep. This signal goes high when the B Sweep ramp crosses its end-of-sweep threshold.

DLY12: input from first delay comparator. The comparator for the delay input switches from low to high after the end of either the first or the second sweep delay.

DLY2: Input from second delay comparator. This comparator normally switches from low to high after the end of the second sweep delay (in dual-delay mode).

B TRIG: B Sweep trigger input.
$\overline{\text { MGE : Measurement gate enable input from }}$ the Display Logic IC. Active low.

MSEL: Measurement select input. MSEL=1 causes the DLY12 signal rising edges to sample the B TRIG input in strobed volts measurements. MSEL=0 selects the DLY2 signal rising edges.

DS: Delay select signal from the Display Logic $I C$. $D S=1$ selects first delay.

DATA: Data input to the internal, control shift register.

S1: Crt beam-intensity control output. Turns on the beam current for the A Sweep displays. Active Iow.

S2: Crt beam-intensity control output. Turns on the beam current for the B Sweep displays. Active low.

S3: Crt beam-intensity control output. Turns on the beam current for the A Sweep intensified zone displays. Active low.

S4: Crt beam-intensity control output. Turns on the beam current for the Readout displays. Active low.

A GATE: A Sweep gate output. Starts the A Sweep ramp. Active high.

TDO: Trigger data output. Data to be read is selected via the A1 and AO inputs (see Table 3-17).

B GATE: B Sweep gate output. Starts the B Sweep ramp. Active high.
$\overline{B U B}: B$ Sweep unblanking output. Active low.

C GATE : Measurement gate output. Not used externally in the 2245A.

Table 3-17
Trigger Logic IC Addressing Logic

| A1 | A0 | Output of TDO pin | Action when <br> SIN Strobed |
| :--- | :--- | :--- | :--- |
| 0 | 0 | Strobed Volts Latch | DATA clocked <br> into Control Reg |
| 0 | 1 | Auto baseline Latch | Resets Auto base-- <br> line Latch |
| 1 | 0 | A Trigger Latch | Resets A Trigger <br> Latch |
| 1 | 1 | Peak Volts Latch | Resets Peak Volts <br> _atch |

## Trigger Logic IC Control Register Description

The control register of U602 is an 8-bit shift register that receives input from the DATA pin. Bit 1 receives the data on a low-to-high transition on the $\overline{\mathrm{SIN}}$ pin ( $\mathrm{A} 1=\mathrm{AO}=0$ ). Bit 8 receives this data after seven more low-to-high transitions on the $\overline{\operatorname{SiN}}$ pin. Bit 8 is the msb of the control register. Table 3-18 lists the control signal name associated with each control register bit.

DM1, DMO: These bits select the delay mode (see Table 3-19).

BRUN: This bit determines whether the B Sweep is in RUNS AFTER delay mode or Triggered After delay mode. BRUN=1 selects RUNS AFTER Mode.

PM1, PM0: These bits select the peak volts detection mode as shown in Table 3-20.

ZM1, ZM0: These bits determine the intensified zone mode. See the Z-Axis logic discussion.

ARUN: This bit determines whether the A Sweep is in the free-run mode or in the triggered mode. ARUN $=1$ selects the free-run mode.

Table 3-18
Control Register Signal-bit Names

| Bit | Name |
| :---: | :--- |
| 1 | DMO |
| 2 | DM1 |
| 3 | BRUN |
| 4 | PM0 |
| 5 | PM1 |
| 6 | ZMO |
| 7 | ZM1 |
| 8 | ARUN |

Table 3-19
Delay Mode Selection Control Bits

| DM1 | DM0 | Delay Mode |
| :---: | :---: | :--- |
| 0 | 0 | First delay set to zero |
| 0 | 1 | First and second delays set to zero |
| 1 | 0 | Normal delay mode |
| 1 | 1 | B Sweep disabled |

Table 3-20
Peak Volts Detection Mode Logic

| PM1 | PM0 | Peak Detection Mode |
| :---: | :---: | :--- |
| 0 | 0 | Nongated |
| 0 | 1 | Gated from end of delay to <br> end of A Sweep |
| 1 | 0 | Gated with C GATE |
| 1 | 1 | Gated with A GATE |

[^6]
## A Sweep Logic

When ARUN is high, the A Sweep logic works as follows. A high on the THO input causes the A GATE output to go low. As soon as THO goes low, the A GATE output will go high and the A Sweep runs. At the end of the A Sweep there is a low-to-high transition on the EOAS input. That sets the the internal end-of-A-sweep latch causing the A GATE output to go low, and the A Sweep shuts off. This state exists during sweep retrace and the baseline stabilization period until the end of holdoff when the THO input once again goes high. That resets the end-of-A-sweep latch and starts another A Sweep cycle. Normally, the falling edge of A GATE will cause an externally generated pulse to be presented on the THO input, thus completing the loop and allowing the A Sweep to free-run (auto-level and auto triggered mode when the sweep is not triggered).

When ARUN is low, the operation is similar except that after a pulse on the THO input, A GATE won't go high until a low-to-high transition is presented on the A TRIG input (triggered sweep mode).

For either free-run or triggered modes, THO going high will cause the A GATE output to immediately go low, if the end-of-A-Sweep latch is set or not. Once the end-of-A-Sweep latch has been set, no more A Sweeps can happen until the THO input is pulsed (at the end of the holdoff). The end-of-A-Sweep latch can only be set with the EOAS input when A GATE is high.

The A Sweep logic of U602 also monitors the A TRIG input to latch certain A Trigger events. One latch (the auto-baseline latch) will set on any low-to-high transition on the A TRIG input. Another latch (the A Trigger latch) is level sensitive and will set when the A TRIG input is high. Both latches may be read out through the TDO (trigger-data out) pin, selected by the A1 and AO address input pins. That data is applied to the TDI (trigger data in) pin of U600 and placed in the Display Logic IC's internal register to be read by the Measurement Processor. Both latches may also be reset via the SIN pin (see description of $A 1, A O$, and $\overline{S I N}$ input pins).

## B Sweep Logic

The B Sweep logic functions about the same as the A Sweep logic, except that more signals must be monitored to determine when the B Sweep can run. When DM1 and D'MO $=11$, the B Sweep can't run at all. When DM1 and $D M 0=10$, the B Sweep won't be allowed to run or trigger until the DLY12 input goes high while the A GATE signal is also high (the normal delayed sweep mode). When DM1 and DMO $=01$, the B Sweep will be allowed to run or trigger immediately after the A GATE signal goes high (no B Sweep delay). When DM1 and DMO $=00$, then the B Sweep will be allowed to run or trigger immediately after the A GATE signal goes high, if the DS (delay select) input is high. If DS is low, the B Sweep is allowed to run or trigger as soon as the DLY12 input goes high while the A GATE signal is also high.

The B Sweep logic behaves as follows. The B GATE signal goes high and $\overline{B U B}$ (B Sweep unblanking) goes low together when the appropriate conditions (described in the preceding paragraph) are met. A low-to-high transition on the EOBS input will then set the end-of-B--sweep latch, causing BUB to go high. B GATE doesn't go low until the A GATE signal goes low. This is used internally to generate the $\overline{\mathrm{S} 2}$ and $\overline{\mathrm{S} 3}$ outputs in some modes, and is used externally to carry out the B ends A mode.

The DLY12 input goes to a level-sensitive latch; if A GATE is high and DLY12 momentarily goes high, the latch will be set, so that the DLY12 input does not need to be held high throughout the sweep cycle. A high level on the THO input will cause the A GATE signal to go low. That resets this latch and causes the reset of the rest of the sweep logic, forcing $B$ GATE IOw and $\overline{B U B}$ high.

The DLY2 input also goes to a level sensitive latch. This second latch also gets reset when A GATE goes low. Together with the DLY1 latch output, A GATE, and the $\overline{M G E}$ input, the $\bar{C}$ GATE output signal gets generated (not used externally in the 2245A). C GATE goes low if A GATE is high, the DLY1 latch
has been set, the DLY2 latch is still reset, and the $\overline{M G E}$ input is low.

## Z-Axis Logic

This logic drives the Z-Axis control outputs ( $\overline{\mathrm{S} 1}-\overline{\mathrm{S4}}$ ). These outputs have the following control action:
$\overline{\mathrm{S} 1}$ Turns on the A intensity current switch (active low).
$\overline{\mathrm{S} 2}$ Turns on the B intensity current switch (active low).
$\overline{S 3}$ Turns on the A intensified current switch (active low).
$\overline{\mathrm{S} 4}$ Turns on the Readout intensity current switch (active low).

Table 3-21 describes what the $\overline{\mathrm{S} 1}-\overline{\mathrm{S} 4}$ outputs do as a function of ZM1, ZMO, HD1, HDO, $\overline{\mathrm{A} G A T E}$, $\overline{B U B}, \bar{C}$ GATE, $\overline{B U S Y}, B L A N K$, and ZEN.

## ECL-to-CMOS Level Shifters

The Trigger Logic IC U602 is an ECL device. Its output signal swing is the standard ECL range of about 0.6 V . All the ECL logic devices in the 2245A are powered from the +5 V supply rather than a -5 V supply. The resulting output voltage swing is from about 4.5 V to about 3.9 V between the high and low ECL logic levels. As $U 602$ must pass signals to the Display Sequencer IC (U600) at CMOS highs and lows (about 3.9 V and $0 \vee$ respectively in this application), logic level translators are required. That job is done by an identical translator circuit for each of the three signals that must be sent. The circuit action of U603C, Q604, and Q605 (the $\overline{\text { A GATE }}$ translator) is described.

Table 3-21
Z-Axis Switching Logic

| ZM1 | ZM0 | HD1 | HD0 | $\overline{\mathbf{S 1}}$ | $\overline{\mathbf{S 2}}$ | $\overline{\mathbf{S 3}}$ | $\overline{\mathbf{S 4}}$ | Display Mode |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| 0 | 0 | 0 | 0 | 1 | 1 | 1 | (c) | Readout |
| 0 | 0 | 0 | 1 | (a) | 1 | (e) | 1 | A Sweep intensified by BUSY |
| 0 | 0 | 1 | 0 | 1 | (b) | 1 | 1 | B Sweep |
| 0 | 0 | 1 | 1 | (c) | 1 | 1 | 1 | X/Y |
| 0 | 1 | 0 | 0 | 1 | 1 | 1 | (c) | Readout |
| 0 | 1 | 0 | 1 | (a) | 1 | (d) | 1 | A Sweep intensified by C GATE |
| 0 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | Blank |
| 0 | 1 | 1 | 1 | (c) | 1 | 1 | 1 | X/Y |
| 1 | 0 | 0 | 0 | 1 | 1 | 1 | (b) | Readout |
| 1 | 0 | 0 | 1 | (a) | 1 | (b) | 1 | A Sweep intensified by BUB |
| 1 | 0 | 1 | 0 | 1 | (b) | 1 | 1 | B Sweep |
| 1 | 0 | 1 | 1 | (c) | 1 | 1 | 1 | X/Y |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | (c) | Readout |
| 1 | 1 | 0 | 1 | (a) | 1 | 1 | 1 | A Sweep no intensified zone |
| 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | Blank |
| 1 | 1 | 1 | 1 | (c) | 1 | 1 | 1 | X/Y |

Notes
(a) = BLANK or $\overline{\text { A GATE }}$
(b) = BLANK or $\overline{\mathrm{A} \text { GATE }}$ or $\overline{\mathrm{BUB}}$ or $\overline{\mathrm{ZEN}}$
(c) $=$ BLANK
(d) = BLANK or $\overline{\text { A GATE }}$ or C GATE or $\overline{Z E N}$
$(e)=$ BLANK or $\bar{A}$ GATE or $\overline{B U S Y}$ or $\overline{Z E N}$ or is a logical-or function.

The single-ended A GATE output signal of U602 at pin 14 is applied to pin 4 of U603B. With its other input pin left open, U603B is used as a line driver only to produce a differential output signal. That differential signal is applied to the bases of a differential amplifier pair of pnp transistors (Q604 and Q605). The output signal is taken across R612 in the emitter of Q604. The emitter of Q605 is connected directly to ground. When the A GATE output of U602 is high (at 4.5 V ), the voltage applied to the base of Q604 is 4.5 V , and the voltage on the base of Q605 is 3.9 V . These voltage levels bias Q605 on and Q604 off, with a resulting output level across emitter resistor R612 of 0 V to the $\bar{A}$ GATE (active low) input of U600. When the A GATE output of U602
goes low at the end of the sweep, the bias voltage levels on Q604 and Q605 reverse, and Q604 is biased on (and Q605 off). Signal current through emitter resistor R612 develops a voltage of about 3.9 V (the unasserted level) to the A GATE input of U600.

## Display Logic Clock

The Display Logic clock signal at 10 MHz is generated by a transistor oscillator circuit composed of Q608, Y600, and associated components. The frequency of oscillation is controlle'd by a ceramic resonator, Y600, in the feedback path from the collector to the base of Q608.

# A AND B SWEEPS AND DELAY COMPARATORS (Diagram 5) 

Sweep Control Shift Registers

Two serial shift registers provide the control interface between the Measurement Processor and the A and B Sweep circuitry. Control bits loaded into registers U302 for A Sweep and U303 for B Sweep are serially clocked from the SR DATA line by the SR1 CLK pulse. The states of the loaded bits select the A and B Sweep timing by choosing the correct charging current and timing capacitor to provide the full range of sweep speeds. Other control bits loaded into the two registers select the delay voltage applied to the Delay Comparators and the output voltage from the VOLTS CAL circuit (used for measurement SELF CAL). Extra bits are shifted through the two shift registers into the Auxiliary Data Register (U1103, Diagram 3) via the AUX DATA signal line to control the trigger bandwidth, the TV Sync Detector switching, and the functions of 10X MAG, X-Y display, and Vertical Comparator enabling.

## A and B Sweep Timing

Refer to Figure 3-5 for a simplified schematic of the A Sweep circuitry.

TIMING RESISTORS. The Sweep Timing resistors in resistor pack R313 are shared between the A Sweep and the $B$ Sweep circuitry; those in resistors pack R321 are divided between the two sweep circuit. Timing Resistor selection is done by multiplexers U308 and U307 for the A Sweep and by U310 and U311 for the B Sweep. The multiplexers are driven by the Measurement Processor via control bits loaded into Shift Register 1 (U302 and U303). (See Table 3-22 for the control bit coding.)

SECIDIV VAR CIRCUIT. Variable sweep speed is controlled by the TIME VAR voltage applied to operational amplifier U309B. The amplifier controls the current passing through Darlington transistor Q301 to the voltage divider formed by resistor pack R313. The voltages at the taps of the voltage divider set the forward bias on the charging-current pass transistor, Q307, via operational amplifier U304. When the SEC/DIV VAR control is in its detent (calibrated) position, diode CR301 is reverse biased,
and the divider formed by R311 and R314 between the +2.5 V reference and ground precisely sets the input voltage to the noninverting input of U309B. With a fixed voltage output from U309B, the current through Q301 and R313 is also a fixed value. When the SEC/DIV VAR control is rotated out of its detent position, the voltage at the junction of R309 and R310 decreases to forward bias CR301. The input voltage to U309B and, therefore, the current to R313 decreases in proportion to the amount of rotation of the SEC/DIV VAR control. A decreasing voltage at the output taps of R313 decreases the charging current through Q307 to increase the sweep ramp time.

A AND B SWEEP TIMING CAPACITORS. The timing capacitor selection circuitry is similar for the $A$ and the B Sweep, but the B Sweep has fewer range steps and doesn't require two selectable capacitors. Only the A Sweep timing capacitor selection is described; like components in the B Sweep circuit do the same job.

Timing capacitance for the A Sweep is made up of a combination of fixed, variable, stray, and selectable components. Sweep timing for the fastest A Sweep speeds is done with a combination of the fixed, variable, and stray capacitance and the selectable charging current supplied through R321, U308, Q307 and Q330. When the slower sweep speeds are selected, additional capacitors must be switched into the circuit to produce a longer charging time. The capacitors that are always in the A Sweep charging path are C315 (a fixed capacitor), C314 (a variable capacitor used to adjust the A Sweep timing at the fastest sweep speeds), and the stray circuit capacitance.

The base-to-collector junction capacitance Q330 changes as the voltage between the base and collector of Q330 increases during ramp up. At the fastest A Sweep speeds, that change would affect the timing at the start of the charging ramp. To compensate for the junction-capacity effect of Q330, transistor Q328 (connected as a diode) is added between the charging current path and the A Sweep Buffer output. The capacitive current through the reverse-biased junction of Q328 adds current to the output to make up for the current required to charge the base-to-collector capacity of Q330 in the input of the Sweep Buffer.


Figure 3-5. Simplified Sweep Circuit.

The selectable sweep timing capacitors come in a matched set of three capacitors, two for the A Sweep timing (C307A and C307B) and one for the B Sweep timing (C307C). When added capacitance is needed for a sweep speed setting, the Measurement Processor loads selection control bits into Shift Register 1 (U302 for the A Sweep) that turn on either Q305 or Q306 or both. Assume that Q305 is biased on by a high control bit from pin 5 of U302. Capacitor C307B is then added in parallel to the capacitors in the charging path, and a longer ramp time is needed to reach the end-of-sweep voltage level. Control bits selecting the charging current are also loaded at the same time. See Table 3-22 for the A Sweep timing and control bit selections (asO-as5) and Table 3-23 for the B Sweep bit selections (bs0-bs4).

## Baseline Stabilizer

The job of the Baseline Stabilizer circuit (Q302, Q303, and Q304 for the A Sweep and Q315, Q316, and Q317 for the B Sweep) is to tie the start of the sweep ramps to the same fixed level for each sweep. Operation of the A Sweep stabilizer is described.

A differential circuit formed by Q302 and Q303 compares the A Sweep feedback signal on the base of Q303 against the reference voltage on the base of Q302 to control the base bias current to Q304 and, thereby, the sweep baseline level. Operational amplifier U309A generates the fixed reference that the baseline voltage level is compared against. The reference voltage amplifier has a gain of -0.8 (less than one and inverted); and, with $+2.5 \vee$ applied to the inverting input and the noninverting input grounded, the output level is -2 V . Capacitor C305 filters the output to eliminate noise that could cause sweep start jitter. The filtered voltage is applied to the junction of R317, R354, and C305 and references both Baseline Stabilizer circuits.

## A and B Sweep Start

The A and B Sweep Start circuits operate the same way, with like components in each doing the same job; only the A Sweep Start circuit is described. Sweep time may be divided into three periods:
baseline, run-up, and retrace (see Figure 3-6). Sweep start and length of sweep run-up is controlled by the A GATE and A GATE signals from the Trigger Logic IC (U602, Diagram 4).

A GATE SIGNALS. The A GATE and A GATE signals are applied via 8.2 V zener diodes (VR301 and VR302) to the bases of Q308 and Q309 in a differential amplifier configuration. The input circuit to the differential pair level shifts the ECL signals ( 4.3 V to 3.4 V ) to the proper biasing levels ( -3.9 V to -4.8 V ) for the bases of the differential amplifier transistors. Transistor Q326 in the emitter circuit of Q308 and Q309 is the current source for the differential pair. Transistor Q311 is part of the bias circuit for Q326 and provides feedback to the base of Q326 that controls the current provided to Q308 while the sweep is being held at the baseline level.

BASELINE STATE. In the baseline state (during sweep holdoff), Q308 and Q304 are on and Q309 is off, and the level at the collector of Q308 is held at -2.8 V . That voltage is buffered by the A Sweep Buffer (with about a 0.7 V rise across the base-toemitter junction of Q312) and fed back to the base of Q303 where it is compared with the -2 V reference produced by operational amplifier U309A. If the baseline voltage is too low compared to the output of U309A, Q303 (the retrace current regulator) is biased on a little harder. Additional base current is available to Q304, and it conducts harder to raise the output baseline voltage to the reference voltage level. The opposite action occurs if the baseline voltage is too high.

A smaller feedback loop formed by Q311 and R305 controls the gain of Q326 so that the standing current available (about 3 mA ) is just enough to keep Q304 biased on during the baseline state. When the states of the gate signals reverse, Q309 is turned on and Q308 turns off. The standing current then conducts through Q309 to rapidly pull the base of Q304 down to shut it off. When the base voltage reaches about -2.7 V , Q333 conducts. That action clamps the base voltage of Q304 (and the collector voltage of Q309) at that level and prevents Q309 from saturating so that it will have a short turn-off time when the sweep ends.

Table 3-22
A Sweep Timing Selections

| SPEED | Itiming | $\mathrm{C}_{\text {timing }}$ | as5 | as 4 | as3 | as2 | as1 | as0 | Min H.O. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 ns | 4 mA | C314/C315 | 0 | 0 | 1 | 0 | 1 | 0 | $2.0 \mu \mathrm{~s}$ |
| 20 ns | 2 mA | 1 | 0 | 0 | 0 | 1 | 1 | 0 | $2.0 \mu \mathrm{~s}$ |
| 50 ns | $800 \mu \mathrm{~A}$ | 11 | 0 | 0 | 0 | 0 | 1 | 0 | 2.0 ms |
| 100 ns | $400 \mu \mathrm{~A}$ | 11 | 0 | 0 | 1 | 0 | 0 | 1 | $2.0 \mu \mathrm{~s}$ |
| 200 ns | $200 \mu \mathrm{~A}$ | 11 | 0 | 0 | 0 | 1 | 0 | 1 | $2.0 \mu \mathrm{~s}$ |
| 500 ns | $80 \mu \mathrm{~A}$ | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 2.0 ms |
| $1 \mu s^{\text {a }}$ | $40 \mu \mathrm{~A}$ | 11 | 0 | 0 | 1 | 0 | 0 | 0 | $2.0 \mu \mathrm{~s}$ |
| $2 \mu \mathrm{~s}^{\text {a }}$ | $20 \mu \mathrm{~A}$ | 1 | 0 | 0 | 0 | 1 | 0 | 0 | $4.0 \mu \mathrm{~s}$ |
| $5 \mu \mathrm{~s}^{\text {a }}$ | $8 \mu \mathrm{~A}$ | 1 | 0 | 0 | 0 | 0 | 0 | 0 | $10 \mu \mathrm{~s}$ |
| $1 \mu \mathrm{~s}$ | 4 mA | C307B | 0 | 1 | 1 | 0 | 1 | 0 | $2.0 \mu \mathrm{~s}$ |
| $2 \mu \mathrm{~s}$ | 2 mA | 1 | 0 | 1 | 0 | 1 | 1 | 0 | $4.0 \mu \mathrm{~s}$ |
| $5 \mu \mathrm{~s}$ | $800 \mu \mathrm{~A}$ | 11 | 0 | 1 | 0 | 0 | 1 | 0 | $10 \mu \mathrm{~s}$ |
| $10 \mu \mathrm{~s}$ | $400 \mu \mathrm{~A}$ | 11 | 0 | 1 | 1 | 0 | 0 | 1 | $20 \mu \mathrm{~s}$ |
| $20 \mu \mathrm{~s}$ | $200 \mu \mathrm{~A}$ | 1 | 0 | 1 | 0 | 1 | 0 | 1 | $40 \mu \mathrm{~s}$ |
| $50 \mu \mathrm{~s}$ | $80 \mu \mathrm{~A}$ | 1 | 0 | 1 | 0 | 0 | 0 | 1 | $100 \mu \mathrm{~s}$ |
| $100 \mu \mathrm{~s}$ | $40 \mu \mathrm{~A}$ | 11 | 0 | 1 | 1 | 0 | 0 | 0 | $200 \mu \mathrm{~s}$ |
| $200 \mu \mathrm{~s}$ | $20 \mu \mathrm{~A}$ | 11 | 0 | 1 | 0 | 1 | 0 | 0 | $400 \mu \mathrm{~s}$ |
| $500 \mu \mathrm{~s}$ | $8 \mu \mathrm{~A}$ | 11 | 0 | 1 | 0 | 0 | 0 | 0 | 1.0 ms |
| 1 ms | 4 mA | C307A | 1 | 0 | 1 | 0 | 1 | 0 | 2.0 ms |
| 2 ms | 2 mA | 1 | 1 | 0 | 0 | 1 | 1 | 0 | 4.0 ms |
| 5 ms | $800 \mu \mathrm{~A}$ | 11 | 1 | 0 | 0 | 0 | 1 | 0 | 10 ms |
| 10 ms | $400 \mu \mathrm{~A}$ | " | 1 | 0 | 1 | 0 | 0 | 1 | 20 ms |
| 20 ms | $200 \mu \mathrm{~A}$ | 11 | 1 | 0 | 0 | 1 | 0 | 1 | 40 ms |
| 50 ms | $80 \mu \mathrm{~A}$ | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 100 ms |
| 100 ms | $40 \mu \mathrm{~A}$ | 11 | 1 | 0 | 1 | 0 | 0 | 0 | 200 ms |
| 200 ms | $20 \mu \mathrm{~A}$ | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 400 ms |
| 500 ms | $8 \mu \mathrm{~A}$ | " | 1 | 0 | 0 | 0 | 0 | 0 | 1 s |

a Used only during horizontal characterization.

Table 3-23
B Sweep Timing Selections

| SPEED | Itiming | $\mathrm{C}_{\text {timing }}$ | bs4 | bs3 | bs2 | bs 1 | bs0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 ns | 4 mA | C329/C330 | 0 | 1 | 0 | 1 | 0 |
| 20 ns | 2 mA | " | 0 | 0 | 1 | 1 | 0 |
| 50 ns | $800 \mu \mathrm{~A}$ | 11 | 0 | 0 | 0 | 1 | 0 |
| 100 ns | $400 \mu \mathrm{~A}$ | 11 | 0 | 1 | 0 | 0 | 1 |
| 100 ms | $200 \mu \mathrm{~A}$ | " | 0 | 0 | 1 | 0 | 1 |
| 100 ms | $80 \mu \mathrm{~A}$ | 11 | 0 | 0 | 0 | 0 | 1 |
| $1 \mu \mathrm{~s}$ | $40 \mu \mathrm{~A}$ | 1 | 0 | 1 | 0 | 0 | 0 |
| $2 \mu \mathrm{~s}$ | $20 \mu \mathrm{~A}$ | 11 | 0 | 0 | 1 | 0 | 0 |
| $5 \mu \mathrm{~s}$ | $8 \mu \mathrm{~A}$ | 11 | 0 | 0 | 0 | 0 | 0 |
| $10 \mu \mathrm{~s}$ | 4 mA | C307C | 1 | 1 | 0 | 1 | 0 |
| $20 \mu \mathrm{~s}$ | 2 mA | 1 | 1 | 0 | 1 | 1 | 0 |
| $50 \mu \mathrm{~s}$ | $800 \mu \mathrm{~A}$ | 11 | 1 | 0 | 0 | 1 | 0 |
| $100 \mu s$ | $400 \mu \mathrm{~A}$ | " | 1 | 1 | 0 | 0 | 1 |
| $100 \mu \mathrm{~s}$ | $200 \mu \mathrm{~A}$ | 11 | 1 | 0 | 1 | 0 | 1 |
| $100 \mu \mathrm{~s}$ | $80 \mu \mathrm{~A}$ | 11 | 1 | 0 | 0 | 0 | 1 |
| 1 ms | $40 \mu \mathrm{~A}$ | 11 | 1 | 1 | 0 | 0 | 0 |
| 2 ms | $20 \mu \mathrm{~A}$ | " | 1 | 0 | 1 | 0 | 0 |
| 5 ms | 8 uA | 11 | 1 | 0 | 0 | 0 | 0 |

RUNUP STATE. With Q304 and Q308 off, the charging current from the timing circuit can begin charging the timing capacitors, and the voltage at the emitter of Q304 ramps up linearly. That ramp is buffered by the A Sweep Buffer (U310A and B and Q312) to drive the Horizontal Output Amplifier. As the ramp is running up, it is being compared with a fixed reference level by the Sweep End Comparators. When the ramp level reaches the comparison level, the A SWP END signal goes high. That signals the Trigger Logic IC, U602, to end the A GATE signal, and the sweep is switched to the retrace state. The sweep ramp is also being fed back to the base of Q303. At the point in the ramp that the base voltage of Q303 exceeds that on the base of Q302 (the -2 V baseline reference), Q303 is biased off and Q302 conducts. This biasing condition disables the feedback loop that stabilizes the baseline voltage level, and it remains off until the
feedback voltage during the retrace period falls back to near the -2 V baseline reference voltage on the base of Q302.

RETRACE STATE. At the end of the sweep, the gate signals reverse state. Transistor Q309 is biased off, and Q308 is biased on. Retrace current supplied by Q308 quickly returns the voltage across the timing capacitor to a little below the baseline voltage level. That retrace current is regulated by Q311 and Q326 to produce a rapid, yet rate-controlled retrace. At the point of the fall in feedback voltage where Q303 starts to turn on, base current becomes available to Q304 to turn it on, and the feedback loop that stabilizes the voltage at the baseline level again becomes active.


Figure 3-6. A Sweep Start circuit waveforms.

## A and B Sweep Buffers

The A Sweep Buffer (Q310A and B, and Q312) and B Sweep Buffer (Q323A and B, and Q325) buffer the voltage ramp as the timing capacitors charge. In the A Sweep circuit, Q310A and Q310B are highimpedance FET amplifiers driving emitter follower Q312. The output signal from the emitter of Q312 is applied to the Delay Time Comparators, the End-ofSweep Comparators, fed back to the Baseline Stabilizer circuit, and sent to the Horizontal Output Amplifier (Diagram 6) as the A RAMP horizontal deflection signal.

## Sweep End Comparators

The sweep ramp signals must horizontally deflect the electron beam across the entire face of the crt. Comparators U316A, B, C, and D determine when the $A$ and $B$ Sweeps have reached the required amplitude. These comparators check the sweep voltage against the reference level that defines the end of the sweep and generate the A SWP END and B SWP END signals when that level is reached. The sweep-end signals are applied to the Trigger Logic IC (U602) so that device knows when the sweeps
are done. The Trigger Logic IC then switches the states of the A GATE or the B GATE signal (as appropriate) to reset the sweep circuitry to its baseline level.

## Delay Time Comparators

When the A Sweep ramp runs, its amplitude is compared against two delay levels by the comparators of U313. The differential outputs of the REF delay comparator change states when the A Sweep crosses the first delay level. The differential output signal from the delay comparator is applied to ECL line receiver U315C. That device has a high gain and produces a fast-rise signal at an ECL level. When the DLY END 0 (reference delay completed) is received by the Trigger Logic IC (U602, Diagram 4), a B GATE is produced to start the B Sweep in RUNS AFTER B Trigger mode. That B Sweep displays the applied waveform at the first (reference) delay setting. At the end of the delay in RUNS AFTER mode, the Trigger Logic IC begins watching for a $B$ Trigger signal that must occur before a B GATE is produced.

The differential output of the second delay comparator in U313 changes states when the A Sweep
ramp at pin 9 crosses the second (delta) delay level applied to pin 6. At that point, the DLY END 1 signal is produced at the output of U315A (pin 2) and applied to U602. A second B GATE signal is then produced to start another B Sweep ramp to display the signal at the delta delay setting.

## Delay Time Switching

The DELTA DELAY and REF DELAY voltage level are applied to multiplexer U301 from the DAC circuit. The Measurement Processor established those voltages based on the settings of the CURSOR/TIME POSITION controls made by the user from the front panel. Switch section U301A is held permanently switched to direct the DELTA DELAY signal to its output pin.

## HORIZONTAL OUTPUT AMPLIFIER (Diagram 6)

## Horizontal Preamplifier

Horizontal Preamplifier IC U802 converts singleended horizontal signals (A sweep, B sweep, horizontal readout, and X-Axis) into differential outputs to drive the crt horizontal deflection plates. The horizontal preamplifier signals are selected by the HDO and HD1 logic signals from Display Sequencer U600 on Diagram 4. Magnified sweep, beam find, horizontal positioning, and horizontal gain adjustments (X1 and X 10 ) are provided in $U 802$ and associated components.

The function of each pin of U 802 is as follows:

RO (Pin 1): RO HORIZ. Input for horizontal component of the readout display.

GA1 (Pin 2): Adjustment of R825 sets the horizontal X1 gain.

A RAMP (Pin 3): Input for the A Sweep signal.

GND (Pin 4): Ground connection for U802.
B RAMP (Pin 5): Input for the B Sweep signal.

MAG (Pin 6): Selects X10 magnified sweep when high or normal sweep when low. Magnified mode is selected when in $X-Y$ horizontal mode.
$X$ (Pin 7): $X$-AXIS. This is the $X$-Axis signal input when in $X-Y$ horizontal mode. The
signal source is the CH 1 trigger signal from U421A (Diagram 3). Adjustment of R827 sets the gain of the $X$-Axis signal.

HDO (Pin 8): Pin 8 (HDO) and pin 11 (HD1) are logic lines that select the horizontal input signal to output differentially at pins 18 and 19. Table 3-24 gives the selection logic.

Table 3-24
HDO and HD1 Logic

| HD1 | HDO | Horiz Signal Selected |
| :---: | :---: | :---: |
| 0 | 0 | RO HORIZ |
| 0 | 1 | A SWEEP |
| 1 | 0 | B SWEEP |
| 1 | 1 | X-AXIS |

$V_{\text {EE }}$ (Pin 9): -5 V supply to $\cup 802$.
GA10 (Pin 10): Adjustment of R826 sets the horizontal X10 gain.

HD1 (Pin 11): See the description for HDO above.

ROUT (Pin 12): Horizontal Preamplifier differential output signal for the right deflection plate.

LOUT (Pin 13): Horizontal Preamplifier differential output signal for the left deflection plate.

BF (Pin 14): The BEAM FIND signal from U503 (Diagram 4) switch the Beam Find feature on or off. BEAM FIND on reduces the horizontal deflection to within the graticule area. Vertical deflection is also reduced and the intensity is set to a fixed viewing level to aid in locating off-screen, over-deflected, or under-intensified displays.

POSITION (Pin 15): Input for the horizontal position control signal. Multiplexer section U301B switches to reduce the range of the Horizontal POSITION control to match that of the Vertical POSITION controls when in $X-Y$ horizontal mode. When $\mathrm{X}-\mathrm{Y}$ display mode is selected, a low $\overline{X Y}$ signal on Pin 9 of U301B connects the pin 5 input to the horizontal position input of U802. The signal at pin 5 is a reduced horizontal positioning signal produced by the R353/R358 voltage divider.
$\mathrm{V}_{\mathrm{CC}}($ Pin 16): +7 V supply to U 802.$$

## Driver Amplifiers

The differential output current signal from U802 passes through common-base current amplifiers Q809 and Q810. These transistors drive current-tovoltage converters Q803-Q804 and Q807-Q808. Emitter followers Q804 and Q803 convert the current signal to a voltage signal to drive the complementary-FET output amplifiers, Q801 and Q802, to produce the negative-going deflection voltage. Emitter followers Q808 and Q807 convert the other side of the differential current to drive Q805 and Q806 to produce the positive-going horizontal deflection voltage.

The circuit of Q804 and Q803 is configured to respond rapidly to a negative-going feedback signal; the circuit of Q807 and Q808 is configured to respond quickly to the positive-going feedback signal. Zener diode VR802 and associated resistors R843 and R844 maintain the collector bias of Q803 and Q808 at 24 V .

Magnifier registration and horizontal readout centering is set by MAG REG potentiometer R809. Adjustment of R809 is done to balance the currents into the emitters of Q809 and Q810 to obtain the correct horizontal position of the readout within the graticule display area.

## Output Amplifier

The differential circuitry of both sides of the Horizontal Output Amplifier is similar; operation of only one side of the amplifier is described. Complementary-FET amplifiers Q801 and Q802 produce the negative-going horizontal signal to drive the left deflection plate. Two transistors are used to provide adequate power handling. Since the two gates are at different bias levels, signal voltage is applied to the gate of transistor Q801 via C803. Resistor R828, connected between the source and drain of Q801, is a parallel current path around Q801 that balances the power-handling requirements of the two FETs. The amplifier FETs are high gain devices, and the overall gain must be reduced to maintain circuit stability at the faster sweep rates. To provide the high-frequency gain reduction, resistor R850 is in series with C802, from the source of Q802 to the drain of Q801, to damp the driving-energy to Q801 supplied by C802 during the sweep retrace transitions. Feedback resistor R806 provides positive feedback and sets the overall gain of the output amplifier stage. A parallel trimmer capacitor across the feedback resistor, C807, adjusts the 2 ns sweep timing for its best linearity. Impedance matching to the deflection plate and additional signal damping is provided by R802.

As the gate voltage of Q802 increases to follow the input ramp signal, the drain voltage goes negative from about 87 V toward the 15 V source voltage. At the same time, the signal on the gate of complementary-FET Q801 is reducing the current through Q801, thereby allowing its source voltage to fall. At the end of the ramp signal, the input voltage falls, and through the positive feedback, Q802 is rapidly biased off. That also biases Q801 on, and the energy stored in C802 quickly returns the deflection plate voltage back to its starting point.

## Common-Mode Stabilizer

Operation amplifier U801A compares the node voltage at the junction of R820, R821, and R822 to ground. Its output drives the amplifier input common-mode point (at the junction of R811 and R812). The purpose of this dc feedback circuit is to keep the average voltage level on the right and left horizontal deflection plates set to the center of the amplifier's dynamic operating range (about 70 V ).

## Z-AXIS, CRT, PROBE ADJUST, AND CONTROL MUX (Diagram 7)

## Z-Axis and Auto Focus Amplifiers

The 'Z-Axis and Auto Focus Amplifiers circuits operate on the same principle and both get their drive signal from the Z-Axis Focus Driver. However, the differences are enough that both circuits are described.

Z-AXIS AMPLIFIER. Intensity-control signal current from the Z-Axis/Focus driver is applied to the Z -Axis amplifier via Q2707. That transistor acts as a current buffer amplifier. The input signal line is clamped at 5.4 V by Q2715 to prevent an overdrive of the ZAxis circuit. The Z-Axis Amplifier output transistors consist of Q2701 and Q2702 on one side of the complementary-symmetry totem-pole output amplifier and Q2703 and Q2704 on the other side. Two transistors are used on each side to divide the power handling requirements needed to drive the crt control grid. The crt grid capacity is large and requires a relatively large amount of power to change the intensity level quickly.

In the base circuit of Q2704, CR2705 prevents the base-to-emitter voltage from exceeding 0.6 V . Zener diode VR2701 dc level-shifts the signal voltage level at the emitter of Q2705 for proper biasing of Q2704. The ac signal components are bypassed around VR2701 by C2703. Base biasing for Q2702 and Q2703 is taken from a series-resistance divider formed by R2711, R2712, R2713, and R2714 between ground and the +130 V supply. Base
biasing for Q2701 is provided by R2715 and R2716 in series between ground and the +130 V supply.

A negative-going input signal to the base of Q2705 causes that transistor to decrease conduction, and the voltage at the top of C2705 goes negative following the input signal. Transistor Q2701 is biased on harder by the negative transition, and Q2704 decreases in conduction. At the Z-Axis output signal line (collector of Q2702), the increasing conduction causes the voltage to rise towards the +130 V supply level. A positive-going input signal has the reverse effect on the output signal. The full output-voltage swing of about 60 V is produced by a 3 mA current change of the Z-Axis Focus/Driver signal current.

Gain of the Z-Axis Amplifier stage is set by the feedback through R2708 and R2709 from the collector of Q2702 to the base of Q2705. The amplifier is compensated by the variable capacitor (C2704, Z-Axis Response) in parallel with the feedback resistors.

BEAM FIND. The Z-Axis portion of the BEAM FIND circuit consists of R2705 and Q2706. When BEAM FIND is active, Q2706 is biased on. This clamps the Z-Axis signal line via R2706 and raises the voltage at the base of Q2705 to a level that produces a bright trace.

## Auto Focus Amplifier

The Auto Focus Amplifier (Q2708, Q2709, Q2711, Q2712, and Q2713) uses a sample of the Z-Axis/Focus Driver signal current from W2701 to drive the auto-focus circuit. The input signal is inverted by Q2708 to drive Q2711 in a complementary fashion to Q2705 in the Z-Axis Amplifier circuit (as the opposite circuit action must happen to produce the correct auto-focus response). The auto-focus output amplifier is similar to the Z-Axis amplifier, but it uses only one complementary transistor on each side (not as much power is needed to drive the focus grid as needed to drive the intensity grid).

## Dc Restorers

The Z-Axis and the Auto Focus DC Restorers are similar in operation. Both circuits are described, but only the added portions of Auto Focus circuitry are included in the discussion of the Auto Focus circuit.

The Dc Restorers set the crt control-grid and focusgrid biases and couple the ac and dc components of
the Z-Axis and the Auto Focus Amplifier outputs to the crt grids. Direct coupling of the Z-Axis and Auto Focus signals to the crt control grid is not employed because of the high potential differences involved. Refer to Figure 3-7 during the following discussion.

Z-AXIS DC RESTORER. Ac drive to the Z-Axis Dc Restorer circuit is obtained from pin 12 of T2204. The drive voltage has a peak amplitude of about $\pm 130 \mathrm{~V}$ at a frequency of about 18 kHz and is coupled into the Z-Axis Dc Restorer circuit through R2722 and C2713. The cathode of diode CR2704 is biased by Grid Bias potentiometer R2719 and referenced to ground via R2720. The ac-drive voltage is clamped to the voltage set by the Grid Bias potentiometer wiper whenever the positive peaks forward bias diode CR2704. Capacitor C2710 prevents significant loading of the potentiometer wiper voltage when CR2704 conducts.

The Z-Axis Amplifier output voltage, which varies between +16 V and +66 V , is applied to the Dc Restorer at the anode of CR2703. The ac-drive voltage holds CR2703 reverse biased until the voltage falls below the Z-Axis Amplifier output voltage level. At that point, CR2703 becomes forward biased and clamps the junction of CR2703, CR2704, and C2713 to the Z-Axis output level. Thus, the 18 kHz ac-drive voltage is clamped at two levels to produce a roughly square-wave 18 kHz signal with a positive dc-offset level.

The Dc Restorer is referenced to the -2750 V crt cathode voltage through CR2702 and R2723. Initially, both C2712 and C2711 charge up to a level determined by the difference between the $Z$-Axis output voltage and the crt cathode voltage. Capacitor C2712 charges from the Z-Axis output through R2721, R2723, CR2702, and CR2703, to the crt cathode. Capacitor C2711 charges through R2723 (a series damping resistor), CR2702, and CR2701 to the crt cathode.

During the positive transitions of the ac drive (from the lower clamped level toward the higher clamped level) the charge on C2712 increases due to the rising voltage. The voltage increase across C2712 is equal to the amplitude of the positive transition. The negative transition is coupled through C2712 to reverse bias CR2702 and forward bias CR2701. The increased charge of C 2712 is then transferred to C2711 as C2712 discharges toward the Z-Axis output level. Successive cycles of the ac input to the Dc Restorer charge C2711 to a voltage equal to the initial level plus the amplitude of the clamped square-wave input.


Figure 3-7. Simplified diagram of the DC Restorer circuitry.

The charge held by C2711 sets the control-grid bias voltage. If more charge is added to that already present on C2711, the control grid becomes more negative (display dimmer). Conversely, if less charge is added, the control-grid voltage level becomes closer to the cathode-voltage level, and the display becomes brighter. During periods that C2712 is charging, the crt control-grid voltage is held constant by the long time-constant discharge path of C2711 through R2724.

Fast-rise and fast-fall transitions of the Z-Axis output signal are coupled to the crt control grid through C2711 to start the crt writing-beam current toward the new intensity level. The Dc Restorer output level then follows the Z-Axis output-voltage level to set the new bias voltage for the crt control grid.

Neon lamps DS2702 and DS2701 protect the crt from excessive grid-to-cathode voltage if the potential on either the control grid or the cathode is lost for any reason.

AUTO FOCUS DC RESTORER. The action of the Auto Focus circuit has to be in reverse of the action of the Z-Axis circuit. The differential transistor pair of Q2708 and Q2709 provides drive to the Auto Focus Amplifier that is inverted in polarity to the ZAxis signal. As the intensity increases (more beam current), the focus grid bias must become more positive to maintain the focus of the beam. Also, since the focus grid operates at a less negative level than the control grid, the Auto Focus DC Restorer is referenced to the $-2750 \vee$ supply via a voltage divider chain.

The FOCUS potentiometer (R2758) voltage is taken across the middle resistor of the divider string to provide an adjustable focus voltage that sets the nominal focus level. Capacitor C2758 filters the reference supply voltage for the focus circuit.

## Volts Cal Signal Source

This circuit provides the precision voltages required for setting the voltage measurement constants during the SELF CAL routine. Ground is connected to the vertical input when GND Input Coupling is selected.

Five voltages are selected from a precision voltage divider, R921, and multiplexed through U931 to the vertical inputs at the appropriate time during the SELF CAL routine. Selection is controlled by three binary coded lines (VOLT CAL 0, 1, 2) from U303. Those control bits and the selected output voltage may be checked one at a time by running the VOLT REF exerciser from the Service Menu.

## Control Multiplexer

Multiplexer U506, controlled by Data Latch U2313 on Diagram 11, selects the A INTEN, B INTEN, and READOUT control levels and probe code voltages to be sent on the PROBE MUX signal line to multiplexer U2309 on Diagram 11. The bit coding is shown in Table 3-25. The selected output from U2309 is applied to the A-to-D Converter (U2306, Diagram 11) where it is digitized and sent to the Measurement Processor.

Table 3-25
Front-Panel Multiplexer Channel Select Bits

| CONTROL LINE |  |  | Analog <br> Signal <br> Selected |
| :---: | :---: | :---: | :---: |
| POT7 | POT6 | POT5 |  |
| 0 | 0 | 0 | A INTEN |
| 0 | 0 | 1 | RO INTEN |
| 0 | 1 | 0 | CH 1 PROBE |
| 0 | 1 | 1 | CH 2 PROBE |
| 1 | 0 | 0 | CH 3 PROBE |
| 1 | 0 | 1 | CH 4 PROBE |
| 1 | 1 | 0 | B INTEN |
| 1 | 1 | 1 | ANALOG GND |

## Scale Illumination

Front-panel SCALE ILLUM control R905 varies the base current of Q905, Q907, and Q908 to set the intensity levels of the scale illumination bulbs (DS901, DS902, DS903).

## NOTE

Bulb life is extended by keeping SCALE ILLUM control set low or off except when full intensity is required.

## Probe Adjust Circuit

The Probe Adjust circuit generates a 0.5 V square wave signal at about 1 kHz . Operational amplifier U930A has a gain of about 4 . The +2.5 V reference on its noninverting input produces a little over 10 V at the output pin. That voltage is divided by the voltage divider formed by R936, CR936, and R937 for a peak amplitude of the signal of 0.5 V during the time CR936 is forward biased. When CR936 is reverse biased by the output of U930B, the Probe Adjust output voltage is pulled down to 0 V through R937 to ground.

Operational amplifier U930B is a free-running oscillator circuit with a period of about 1 ms . The oscillator frequency is determined mainly by the charging time constant of C935 and R935. The voltage divider formed by R938, R934, and R939 divides the +15 V supply to provide a positive voltage on pin 5 of the oscillator to get the circuit into oscillation. (When the circuit is oscillating, the feedback signal switches the pin 5 voltage between about +8 V to 0 V .) The gain of the amplifier is high enough to drive pin 7 to the positive supply voltage level at about 14 V , and the signal voltage level on pin 5 rises to a little over 8 V from the feedback current supplied by R933. The CLK 1 K signal taken from the junction of R934 and R939 is supplied to U600 and is used to skew the chop-clock frequency. The skew prevents the oscilloscope from triggering on the chop frequency when displaying multiple traces in CHOP Mode.

At that level CR935 is reverse biased, and CR936 is forward biased (by the output of U930A) to pass the Probe Adjust high level output signal current. Charging current through feedback resistor R934 charges C935 up from 0 V toward the output voltage level. As soon as the charge on C935 (and the voltage on pin 6 of U930B) reaches the voltage level on pin 5, the output level at pin 7 drops to about -5 V , and C935 must then begin discharging to the new voltage level. At that point CR935 is forward biased and that reverse biases CR936 so that the Probe Adjust output voltage drops to 0 V . Resistor R940, in series with CR935, limits current flow to protect U930 and CR935 in the event of a static discharge to the Probe Adjust output connector.

## Crt

The Trace Rotation adjustment, R911, varies the current through the Trace Rotation coil. The Trace Rotation coil is located between the crt face and the vertical and horizontal deflection plates, and it affects both the vertical and horizontal alignment of the trace.

The Geometry adjustment, R2784, varies the voltage level on the horizontal deflection-plate shields to control the overall geometry of the display (minimizes bowing of the display).

The Astigmatism adjustment, R2788, varies the voltage level on the astigmatism grid to obtain the best-focused display over the whole face of the crt.

## MEASUREMENT PROCESSOR (Diagram 8)

The Measurement Processor circuitry includes the Processor (U2501), the System RAM (U2521), the System ROM (U2519), communication bus latches
and transceivers, the Address Decoding circuitry, and the Power-On Reset IC (U2502).

## Power-On Reset

The +5 V supply is monitored by U 2502 to generate the reset signals throughout the instrument. These reset signals initialize the states of the logic devices and ensure that memory writes to any of the RAM spaces cannot occur until the +5 V supply is up to its correct operating level. The RESET signal output at pin 6 is initially high during power up (as soon as the voltage has reached the operating level of the RESET IC, U2502). That high signal is inverted by U2506C to produce the SYS RESET signal. The SYS RESET signal holds Processor U2501 in its reset state.

The SYS RESET signal also resets and initializes the Readout Processor (U2400, Diagram 9). At pin 5 of U2502, a $\overline{R E S E T}$ signal is generated. That signal biases Q2507 off to prevent System RAM U2521 from being selected by any random states that might occur on the address lines during reset as the voltage is rising.

About 5 ms after the +5 V supply reaches the operating level required for the Processor, the RESET condition is removed, allowing the Processor to operate. At power off (and for a momentary drop in the +5 V supply), when the +5 V supply falls below the safe operating level of the logic devices, the RESET condition occurs to prevent random operation.

## Measurement Processor

FUNCTION. Measurement Processor U2501 is a multitask device. Its major functions are the following:

1. Continually refreshes the front-panel indicator LEDs. One column of the six-column LED matrix is refreshed every 2.048 ms .
2. Continually scans the front-panel switch settings, sensing rotation of rotary switches and closures or openings of momentary-contact switches. One column of the six-column switch matrix (the same column number of LEDs being refreshed) is read every 2.048 ms .
3. Communicates with the Readout Processor and Readout RAM to' set attributes for each readout field, put text into each field, and turn the readout fields on or off.
4. Scans the front-panel pots and sets control voltage levels. The Measurement Processor
selects a pot to be scanned by connecting it to Comparator U2306 (Diagram 11) in the D-to-A circuitry. The Measurement Processor does a successive-approximation A-to-D conversion on each pot, using the DAC (U2302) to output the search values to the Comparator. Pot values are scanned, processed, and converted to analog control values by the DAC. The analog levels from the DAC are output to the controlled devices via sample-and-hold circuits (U2304, U2305 on Diagram 11).
5. Sets up the hardware state of the instrument, including shift registers 0 and 1, BEAM FIND, and the operating states of U600 (SLIC) and 0602 (FLIC). This setup takes place as needed for every change of a front-panel momentary-contact or rotary-contact switch.
6. Keeps track of trigger status and controls the trigger levels when in AUTO LEVEL mode. It uses FLIC (U602) to find the A Trigger status (writing to FLIC to reset the A Trigger latch, and reading from it to get the status). It uses SLIC (U600) to find the B Trigger status (writing to SLIC to reset the B Gate latch, and reading from it to get the status). To reacquire the trigger level (positive and negative peaks of the trigger source waveform) it uses the Trigger ICs (U421 and U431), and the Trigger Comparators in FLIC (it writes to FLIC to reset the Trigger comparator latches, and reads from FLIC to get the status of the latches). To switch between free-running and triggered mode in AUTO LEVEL and AUTO trigger modes, it writes to the control register in FLIC; it switches to triggered mode when trigger frequency is sufficiently high and to free-run mode when too low.
7. When $k$ SEC $\rightarrow$, $k 1 /$ SEC $\rightarrow 1$, and $\leftarrow$ VOLTS $\rightarrow$ measurements are running, a new digital value is displayed, and the cursor or delay-zone position is changed only when the user changes the setting of one of the continuous-rotation CURSOR/TIME POSITION controls.
8. Controls the AUTOSET function by setting up the vertical, horizontal, triggering, and crt controls to obtain a usable display based on the input signal characteristics.
9. Calibrates the measurement system. The vertical and horizontal gains of the instrument are set by manual potentiometer
adjustments; therefore, the Processor does not control the match between the waveform display and the graticule. However, it does adjust the measurement results to compensate for any error in the vertical or horizontal gain. (An example of this is that there could be more than $0.5 \%$ error in matching a time base signal to the graticule, but less than $0.5 \%$ error in a time measurement done on that signal).

In the Time Base calibration routine, the Measurement Processor uses the TB Cal signal, the Trigger circuitry, the A Sweep system, and U602 (FLIC) to find the match between the delay levels (REF DELAY and DELTA DELAY) and edges of the calibration signal. In the Vertical System calibration, the Processor uses the Voltage Reference Generator (U931, Diagram 7), the Readout System, the Vertical Preamplifiers, the Delay Line Driver, and the Vertical Comparator (U702) to find the match between Readout REF CURSOR and DELTA CURSOR levels and vertical outputs generated by the preamplifiers. It uses the Voltage Reference Generator, the Vertical Preamplifiers, and the Trigger circuitry to find the match between trigger levels and trigger signals picked off from the Vertical Preamplifiers.
measurement processor signals. Table $3-26$ is a listing of signal name and function of the Measurement Processor signals.

## Data Buffers

BUS 0 BIDIRECTIONAL BUFFER. Buffer U2515 communicates the serial bit data to and from the Measurement Processor. Seven data lines of the eight available are used in this application. The remaining one is connected to the +5 V supply to prevent random states and noise from affecting the other data lines in the device. The buffer is enabled via $U 25038$ when both pins 38 (MCSO) and 39 (DEN) of the Processor are low. The direction of transfer is controlled by the DT//R output of the processor.

BUS 1 BIDIRECTIONAL DATA BUFFER. Data communication to and from the Measurement Processor is via Buffer U2514. Direction of the data transfer is controlled by the $D T / \bar{R}$ (Data Transmit/Received) output from the Measurement Processor. Data enabling occurs when pin 39 ( $\overline{\mathrm{DEN}}$ ) goes low while pin 38 (MCSO) is high.
bus arbitration gates. The Bus Arbitration logic (U2503A and B, and U2506D) controls which Bus Buffer is enabled for communication with the Measurement Processor. This control logic is
necessary since both buffers cannot be active at the same time. Bus 1 (U2514) is the eight-bit data communication bus, and Bus 0 (U2515) uses seven bits to communicate single-bit data to the Measurement Processor. On the Bus 0 ADO signal line, the Measurement Processor sends the serial MB DATA to each of the operating mode Shift Registers and to SLIC (U600) and FLIC (U602). Additional arbitration is provided by U2503C to produce a $\overline{S L I C ~ R D ~ s t r o b e ~}$ when the Measurement Processor wants to read the status of the Display Controller.

## Address Latches

MULTIPLEXED AD BUS ADDRESS LATCH. Since the ADO through AD7 bits are multiplexed between address and data information, the addressing information needs to be latched to hold it for stable addressing (demultiplexed). The ALE (Address Latch Enable) signal from the Measurement

Processor (pin 61) goes high when the address bits are stable, and the bits are latched into U2513. The device is permanently enabled by the grounded enable pin.

NONMULTIPLEXED ADDRESS BUS ADDRESS LATCH (U2512). Some of the nonmultiplexed address bits are also latched to maintain them between ALE strobes. The latching also prevents address line problems on the Main board from locking up the Measurement Processor. From U2512, latched addresses ADDRO-ADDR3 (A12-A15) are routed to the Display Controller (U600) for addressing the internal registers in that device. Those address lines are also applied to U501 (Diagram 4) for additional decoding to load the Analog Control Shift Registers with the serial data supplied from the MB DATA signal line. Two address lines (A16-A17) are latched in U2512 for use by the System ROM U2519.

Table 3-26
Measurement Processor Signals

| Signal Name | Signal Function |
| :--- | :--- |
| SYS RESET | Master reset for the Processor board. |
| CLK 8M | 8 MHz clock for the Readout and DAC Processors. |
| AD0-AD7 | Multiplexed address/data lines for the Measurement Processor. |
| A8-A15 | Address lines for the Measurement Processor. |
| A16-A17 | Multiplexed address/status lines. |
| DO-D7 | Data lines for Bus 1 (to memory and readout). |
| ADDR3-ADDR0 | Latched addresses to Main board. |
| $\overline{R O}$ INTR | Indicates the Readout System is busy when asserted. |
| $\overline{\text { DAC INTR }}$ | Indicates the DAC Subsystem is busy when asserted. |
| MB RETURN | Return data from the Main board Shift Register 2. |
| SW BD DATA | Data from the switch board. |
| AD COMP | Output of the A-to-D Converter Comparator, U2306. |
| MB DATA | Bidirectional data line to/from the Main board. |
| TB CAL | Time-base calibration signal to trigger circuit. |

## Measurement Processor ROM

The operating code for the Measurement Processor is stored in the System ROM (U2519). Immediately after the Power On Reset ends, the Measurement Processor fetches, the first command from the reset vector and begins running the program.

## Measurement Processor RAM

The Measurement Processor RAM (U2521) provides storage space for intermediate-step calculation results, the front-panel settings, store/recall system setups, and the system calibration constants. The Processor RAM is battery backed up so that data stored during operation remains intact during periods of power off. When the instrument is turned on again, the stored front-panel settings return the oscilloscope to the same operating state that was present at power off. The stored calibration constants preserve the accuracy of the measurement system (assuming the instrument is warmed up and was warmed up when the SELF CAL routine was last done). If the backup battery is dead, or if the stored calibration constants are lost for some other reason, the instrument will do a SELF CAL at power on. This restores accuracy to the instrument (unless the problem is a RAM fault, in which case the instrument cannot SELF CAL), but the battery circuitry should be checked and the battery replaced if necessary. Also, the SELF CAL routine should be run again after the instrument is warmed up to generate accurate calibration constants at the operating temperature. If the power-off front-panel settings are lost for any reason, the power-on conditions that are set up are only restored in valid states (but not any predefined setup).

## Address Decoder

The Address Decoders (U2517 and U2518) allow the Measurement Processor to enable any device on the busses for communication. Enabling signals $\overline{B U S O ~ S E L ~ a n d ~ D A C ~ S E L ~ f r o m ~ t h e ~ p r o c e s s o r ~ s e l e c t ~}$ the Address Decoder (either U2517 or U2518) that is actively decoding when the $\overline{W R}$ signal is low.

## Backup Battery

To keep the data stored in the Measurement Processor RAM (U2521) during power off, a back-up battery system (BT2501, CR2502, and R2506) is used. The battery supplies the energy to maintain the memory states of the static RAM. The lithium battery is not rechargeable and has an operating life of over three years. When the instrument is on, CR2502 becomes reverse biased to prevent any reverse current; when off, CR2501 is reverse biased
to isolate the back-up battery from the +5 V supply. If the battery requires replacement, observe the proper safety precautions in the handling and disposition of the replaced battery (see the WARNING under "Battery" in the Specification).

## READOUT SYSTEM (Diagram 9)

## Readout Processor

The Readout Processor (U2400) is an eight-bit microcomputer, containing its own internal ROM and RAM. The Readout Processor controls the display of text and cursors on the crt. It refreshes each character in the display every 16 ms . When the refresh rate becomes too high, refresh stops until the rate is low enough again. When the refresh rate becomes too low, refresh is done by taking control of the crt beam for a character at a time (Fast mode) until the refresh catches up. When the refresh rate is just right, refresh is done a dot at a time (Slow mode).

Each refreshed dot or character is refreshed with the appropriate display position attributes. The attributes define the characters or dots as:

Stationary text that stays put at a fixed point on screen (examples are scale factor and menu displays);

Cursor-level offset characters whose position is determined by the REF CURSOR or DELTA CURSOR control levels only (examples are the time-measurement cursors); or

Cursor-level and position-level offset characters whose display position is determined by both the cursor levels and the vertical position controls.

The Readout Processor also communicates with the Measurement Processor system to obtain its RAM programming (for determining the display types) and report its status.

## Measurement/Readout Processor Communication Protocol

A data byte is transmitted between the Measurement Processor and Readout Processor as follows:

1. The Measurement Processor waits until $\overline{\text { RO INTR is unasserted (the Readout }}$ Processor is ready to receive).
2. The Measurement Processor writes a byte to tri-state Write Latch U2401 by strobing $\overline{\text { RO BUF WR ; this asserts } \overline{\operatorname{RO} \text { INTR }} \text { (from }}$ Interrupt Latch U2417C and D) and causes an interrupt to the Readout Processor.
3. The Readout Processor, when interrupted, reads the Write Latch (U2401); it then unasserts $\overline{\text { RO INTR }}$ by clocking the interrupt Latch to reset it. (This is the same clock used when the Readout Processor writes to tristate Read Latch U2402.)

Communication from the Readout Processor to the Measurement Processor is done for diagnostics only and can be started only by the Measurement Processor. The Measurement Processor may check the communication link by comparing bytes sent to bytes received, query the Character Code RAM contents, and check the Character ROM identification header. The replies are all sent between the Readout Processor and Measurement Processor a byte at a time as follows.

1. The Readout Processor waits until $\overline{\mathrm{RO} \text { INTR }}$ is asserted (the Measurement Processor is ready to receive).
2. The Readout Processor writes a byte to tristate latch U2402; the clock that does the write also unasserts $\overline{\mathrm{RO} \text { INTR }}$.
3. The Measurement Processor waits until $\overline{\mathrm{RO} \text { INTR }}$ is unasserted, then reads tri-state latch U2402. It then strobes $\overline{\mathrm{RO} B U F W R}$ to assert $\overline{R O \mathbb{I N T R}}$ (if another byte is coming from the Measurement Processor).

## Display Refreshing

READOUT FIELD. A Readout field is refreshed in this way:

1. The display field is selected by latching the top address bits for the field into U2411 (FLD2-FLDO).
2. The mixing attributes for the field are latched into U2411 (MIX3-MIXO).
3. The position-tracking attributes for the field are latched into U2403 (CH 4 POS EN through CH 1 POS EN and RO TRACE SEP EN).
4. The starting address for the field (set by communication with the Measurement Processor) is latched into counters U2404 and U2405 ( $\mathrm{CH} 7-\mathrm{CHO}$ ).
5. One character at a time, all the characters in the field are refreshed until the top address for the field (set by communication with the Measurement Processor) has been refreshed.

READOUT CHARACTER. A Readout character is refreshed in this way:

1. $\overline{R O R U N}$ is asserted. This tells the Dot Refresher PAL (U2410) to begin the character refresh and releases the reset on the Dot Counter (U2407) and the Dot Refresher divider (U2409B).
2. For each dot in the character, the next dot is refreshed.
3. When the final dot is refreshed, $\overline{\mathrm{EOCH}}$ (end-of-character at $\cup 2408$ pin 17) becomes asserted, and $\overline{Q E O C H}$ (the latched version) becomes asserted. The Readout Processor unasserts $\overline{\mathrm{RO}} \mathrm{RUN}$, and increments the character address counter lines $\mathrm{CH} 7-\mathrm{CHO}$.

READOUT DOT. A Readout dot is refreshed in this way:

1. $\overline{R O}$ REQ is unasserted (this causes RO HORIZ and RO VERT to control the crt horizontal and vertical) briefly to show the dot.
2. $\overline{R O}$ BLANK is unasserted then asserted (this unblanks then blanks the crt beam).
3. $\overline{\text { DOT CLK }}$ is asserted and unasserted (this increments the dot counter lines DOT4-DOTO).

FAST REFRESH. Fast refresh occurs when the Processor asserts FAST (whenever the refresh rate is too low) or when $\overline{\text { A GATE }}$ is unasserted (the sweep is in holdoff). In this mode, $\overline{R O R E Q}$ is asserted at the start of a character, and unasserted at the end. Whenever $\overline{R O R E Q}$ is asserted, the Readout system controls the crt beam intensity and the vertical and horizontal position of the beam. Dots are refreshed every $1.6 \mu$ s during fast refresh.

SLOW REFRESH. Slow refresh occurs when the Processor unasserts FAST (when the refresh rate is not falling behind in refreshing, the readout) and $\bar{A}$ GATE is asserted. In this mode, $\overline{R O R E Q}$ is asserted before each dot in a character, and unasserted after each dot.

Data flow for the dots in a character is roughly this:

1. FLD2-FLDO give the current field being refreshed.
2. $\mathrm{CH} 7-\mathrm{CHO}$ give the position of the character within that field. $\mathrm{CH} 7-\mathrm{CH} 5$ gives the row within the Readout (row 0 at the bottom, and 7 at the top), and $\mathrm{CH} 4-\mathrm{CHO}$ gives the column (column 0 at the left, column if hex at the right).
3. Given the field and character position, the RAM (U2406) outputs the character code (the code for the character that is to be displayed at that position) on R7-RO.
4. DOT4-DOTO gives the dot that is being refreshed within the character.
5. Given the character code and dot number, ROM U2408 outputs the position of the dot within the character. There are up to 31 dots in a character, in an array of 128 possible dot positions (16 vertical by 8 horizontal). DD6-DD3 gives the vertical position of the dot, and DD2-DDO gives the horizontal position.
6. Given the row and column containing the character, and the vertical and horizontal position of the dot, U2412 generates the vertical analog current for the dot, and U2413 the horizontal analog current.
7. U2414 sets up the mixing for the vertical output signal (see Readout Position Mixer).
8. U2415 sets up the mixing for the horizontal output signal.

## Interrupt Request Latch

When the Measurement Processor wants to write new display data to the Readout Processor or Character Codes RAM (U2406), it latches the new data into the Readout Write Latch (U2401) from the DO-D7 bus lines by issuing the $\overline{\text { RO BUF WR (readout }}$ buffer write) strobe to the Interrupt Request Latch (U2417). The output of U2417D (pin 11) is latched low and the Readout Processor is interrupted from its display processes ( $\overline{\mathrm{RO} \mathbb{I N T R}}$ goes low). The Readout Processor enables the Readout Write Latch and reads in the new data. When the character is received, the Readout Processor transfers the byte to the Character Code RAM and resets the Interrupt Request Latch (U2417D) to let $\overline{\mathrm{RO} \text { INTR go high }}$ again.

## Communication Latches

Communication from the Measurement Processor and the Readout Processor is done via the Readout Write Latch (U2401). The Readout Read Latch (U2402) is used only for diagnostics communication.

## Character Position Address Counter

The starting address of a readout field to be displayed is loaded into the Character Position Address Counter (U2404 and U2405). The counter then sequences through the addresses of the characters loaded in Character Code RAM U2406. The vertical and horizontal position of the character being displayed is also defined by the output of the counter and is supplied to the Vertical and Horizontal DACS on the $\mathrm{CHO}-\mathrm{CH} 7$ bus lines.

## Character Codes RAM

The ASCII codes needed to display a field of readout are loaded into the Character Codes RAM (U2406) from the Measurement Processor via the Readout Writer Buffer (U2401) on the RO-R7 bus lines. When the field is displayed, the RAM is addressed in sequence by the Character Position Address Counter to output those codes for a display refresh. The field of codes accessed by the FLD0-FLD2 address lines defines either text (menus, measurement readouts, and error messages), vertical cursors, or horizontal cursors. Each field has space for up to 255 characters, and each field can be superimposed over the others on the crt. The difference between the horizontal and vertical cursors is a $90^{\circ}$ rotation of the character field. Hexadecimal addresses for a field are shown in Figure 3-8.


Figure 3-8. Display addresses.

## Character Dot Counter

The Character Dot Counter (U2407A and B) is reset before the start of each character display. When $\overline{R O}$ RUN goes low (the start of a refresh cycle), the reset is released and the Dot Clock (active low) from the Dot Refresher (U2410) clocks the output of the counter through the number of counts needed to address all the dots in a character stored in the Character Dot Position ROM (U2408).

## Character Dot Position ROM

The dot sequence and dot position to display each character is stored in the Character Dot Position ROM (U2408). Character addressing for the display is provided by the Character Codes RAM (U2406) on the R0-R6 bus lines. Addressing of the individual dots within a character is provided from the Character Dot Counter (U2407A and U2407B) on the DOTO-DOT4 signal lines. The pixel information output by the Character Dot Position ROM defines the vertical and horizontal position of the dot to be displayed. At the end of a character display, the $\overline{\mathrm{EOCH}}$ signal is generated from U2408 pin 17 to the Dot Refresher (U2410) to let that device know that the character is finished and the next character can be started.

## Dot Refresher

Dot Refresher U2410 is a programmable-AND, fixed-OR logic (PAL) device. It monitors $\overline{R O}$ RUN for its low states to determine when a refresh cycle starts. It then assert $\overline{\mathrm{RO} R E Q}$ to take control of the display for refreshing the displayed character dots. $\overline{R O}$ BLANK goes high then low again for each displayed dot. The Dot Clock signal then goes low and high again to clock the Character Dot Counter ( U 2407 A and U 2407 B ) to the address of the next dot in the character being refreshed. In Fast mode (when there is low demand for display time or the refresh rate is getting too slow), each character is completely refreshed. In Slow mode, the dots are refreshed at the rate of only one dot per each readout request.

When all the dots in a character have been refreshed, the $\overline{E O C H}$ (end-of-character) signal from Character Dot Position ROM U2408 tells U2410 that there are no more pixels to be refreshed in that character. $\overline{R O R E Q}$ is then unasserted to release control of the display system and $\bar{Q} E O C H$ (U2410, pin 18) is sent to the Readout Processor to tell it that the Dot Refresher is finished with the character.

The Dot Refresher also asserts the POS EN signal low (pin 19) when readout associated with any of the
traces is being displayed. That signal enables the Readout Position Enable Latch (U2403).

## Divider/Counter

The 8 MHz System Clock is divided down to 4 MHz by Divider/Counter U2409A for clocking the Readout Processor and to 2 MHz to clock the Dot Refresher (after inversion by U2417B). The 2 MHz signal also clocks U2409B, a second divider that produces the signals that cycle the Dot Refresher through its internal states.

## Readout Position Enable Latch

When the readouts must follow the Channel Vertical POSITION controls or the TRACE SEP control, the vertical position information must be added to the readout position. This job is done in the Vertical Position Switching circuitry (Diagram 2). The time of enabling and the readout position that is enabled is determined by the Readout Processor. The correct enabling data for the next field of characters to be displayed is latched into U2403 from the R0-R7 (bits $0-4$ only) bus by the POS STB signal (U2403, pin 11). See Table 3-27. When a field is being refreshed, the outputs of U2403 are enabled by the $\overline{\text { POS EN }}$ signal from the Dot Refresher, U2410 pin 19.

Table 3-27
Position Enable Bit Assignment

| b4 | b3 | b2 | b1 | b0 | Value |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\times$ | $\times$ | $\times$ | $\times$ | 0 | Disable CH 1 position current |
| x | x | x | x | 1 | Enable CH 1 position current |
| x | x | x | 0 | $\times$ | Disable CH 2 position current |
| x | $\times$ | x | 1 | $\times$ | Enable CH 2 position current |
| x | x | 0 | $\times$ | x | Disable CH 3 position current |
| x | x | 1 | $\times$ | x | Enable CH 3 position current |
| x | 0 | $\times$ | x | x | Disable CH 4 position current |
| x | 1 | x | x | x | Enable CH 4 position current |
| 0 | x | x | x | x | Disable Trace Sep current |
| 1 | x | x | x | x | Enable Trace Sep current |


#### Abstract

Readout DACs Vertical Character. and Dot position data bytes are converted to analog current for eventual application to the Vertical Delay Line by Vertical Readout DAC U2412. The vertical signal current is applied to both signal mixer multiplexers (U2414 and U2415). When fixed position text is displayed, the output mixer selects a fixed position value to mix with the horizontal output signal to define the readout position on the display. When positionable text is displayed (such as time cursors), the cursor position signal is mixed with the horizontal output signal. That summed signal then defines (vertically) where a character (dot) is displayed on the crt. Vertical Readout that follows the Channel Vertical POSITION controls (tracking cursors and associated text) has summed its position information in the Vertical Position Switching circuitry (Diagram 2).

Horizontal Character and Dot position data bytes are converted to analog current for application to the Horizontal Preamplifier (U802, Diagram 6) by Horizontal Readout DAC U2413. The horizontal signal current is applied to both signal mixer multiplexers (U2414 and U2415). When fixed position text is displayed, the output mixer selects a fixed position value to mix with the horizontal output signal to define the readout position on the display. When positionable characters are displayed (such as time cursors), the cursor position signal is mixed with the horizontal character position signal. That summed signal then defines (horizontally) where a character dot is displayed on the crt. None of the readout (text or cursors) is positionable using the Horizontal POSITION control.


## Field and Mixer Control Latch

Selection signals for switching the Readout Position Mixer multiplexers (U2414 and U2415) are latched into Field and Mixer Control Latch U2411 by the MIX STB output from the Readout Processor (U2400 pin 25). Three field selection bits used in addressing the Character Code RAM are also loaded from the data byte output from U2400 on the R0-R7 data bus. The MIX3-MIX0 bits select the combination of fixed, positionable, and character (dots) signals that are mixed to produce the required readout positions on the crt.

The Field signals (FLDO, FLD1, and FLD2) access the type of characters that are displayed (menus and readout labels, vertical cursors, or horizontal cursors). Each of the three fields contains space for 255 characters. Characters from each field are superimposable over the other field's characters in the display. The attributes implicitly affect the field specified by b0, b1, and b2 (b2 is always handled as if zero, even if not communicated as zero).

## Readout Position Mixers

The Readout Position Mixer (U2414, U2415) selects either fixed or cursor-position voltages to mix with the character signals to position them in the display. Selection is done by the MIXO-MIX3 signal levels set up by the Measurement Processor for the particular field of characters being displayed (see Table 3-28).

Table 3-28
Field and Mixer Attribute Bit Assignment

| MIX3 | MIX2 | MIX1 | MIX0 | NC | FLD2 | FLD1 | FLD0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| $x$ | $x$ | $x$ | $x$ | $x$ | b2 | b1 | b0 | Field number (0,1, or 2) |
| $x$ | $x$ | 0 | 0 | $x$ | $x$ | $x$ | $x$ | Route Horiz DAC to Horiz Ampl |
| $x$ | $x$ | 0 | 1 | $x$ | $x$ | $x$ | $x$ | Route Cursor0 to Horiz Amplifier |
| $x$ | $x$ | 1 | 0 | $x$ | $x$ | $x$ | $x$ | Route Cursor1 to Horiz Amplifier |
| $x$ | $x$ | 1 | 1 | $x$ | $x$ | $x$ | $x$ | Unassigned |
| 0 | 0 | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | Route Vert DAC to Vert Ampl |
| 0 | 1 | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | Route Vert DAC + Cursor0 to Vert Amplifier |
| 1 | 0 | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | Route Vert DAC + Cursor1 to Vert Amplifier |
| 1 | 0 | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | Route Horiz DAC to Vert Ampl |

The 2245A Readout Output Mixer allows three modes of display to present the text and vertical or horizontal cursors.

TEXT OUTPUT MODE. The vertical output displays vertical text information, locked to crt vertical screen position. The horizontal output displays horizontal text information, locked to ort horizontal screen position.

HORIZONTAL CURSOR MODE. The vertical output displays vertical text information, whose position is controlled by an analog cursor level control. The horizontal output displays horizontal text information, locked to crt horizontal screen position.

VERTICAL CURSOR MODE. The vertical output provides a ramp signal, locked to crt vertical screen position. The horizontal output matches the voltage of an analog cursor level control.

MIXER OPERATION. The readout system displays text in a pixel-type representation. For example, an underlined letter " $A$ "' may be represented as in Figure 3-9. Blackened spaces in the illustration denote a displayed pixel.


Figure 3-9. Character pixel arrangement.

For each character, one pixel at a time is displayed by driving the vertical and horizontal outputs to values representing the vertical and horizontal position of a pixel within a character and then unblanking the Z -Axis.

Multiplexers U2414 and U2415 are ganged electronic switches that mix current and voltage settings. Vertical Readout DAC U2412 (vertical text generator) provides an output current from pin 2 that is proportionate to the vertical position of the pixel being
displayed; the minimum output is 0 mA . Horizontal Readout DAC U2413 (horizontal text generator) provides an output current that is proportionate to the horizontal position of the pixel being displayed. Its minimum output is also 0 mA . The REF CURSOR and DELTA CURSOR levels are voltages that offset the text output for the type of cursor being displayed (vertical TIME cursors or horizontal VOLTS cursors). When straight text is to be displayed, dc levels for offsetting the vertical and horizontal text display outputs are added. Horizontal and vertical signals to be mixed for a particular readout are selected by the MIXO-3 outputs of latch U2411. The data is latched from the Readout Processor bus when MIX STB clock is generated by the Readout Processor.

## Output Buffers

The Output Buffers (U2416A and U2416D-vertical, and U2416B and U2416C-horizontal) are voltage follower circuits that mix the signals selected by the Readout Position Multiplexers and buffer them for application to the vertical delay line (RO VERT) and the Horizontal Preamplifier (RO HORIZ).

The voltage at U2416 pin 14 depends on two things: the current from U2414 pin 13, and the voltage at U2414 pin 3. The possible displays are given in Table 3-29:

The voltage at U2416 pin 8 depends on two things: the current from U2415 pin 13, and the voltage at U2415 pin 3. The possible conditions are shown is Table 3-30.

## SWITCH BOARD AND INTERFACE (Diagram 10)

The front-panel LEDs that backlight the switches and panel labels are schematically arranged in a matrix of eight rows and six columns. The front-panel switches are arranged in a matrix of 16 rows and six columns. Each LED and switch is connected to a distinct row/column intersection, with a column of LEDs and a column of switches being common and enabled by the same signal.

At intervals of about 2 ms , a column of LEDs is refreshed (turned on or off) and the status (open or closed) of the connected column of switches is read. All six columns of LEDs and the six columns of switches are completely refreshed and checked every 12 ms . The timing is fast enough to prevent flicker of the LEDs and to catch a push-button closure.

Table 3-29
Display Possibilities

| Readout Type | U2414-3 | U2414-13 |
| :--- | :--- | :---: |
| Stationary Text | 0.6 V | U2412 output |
| Horizontal Ref Cursor | REF CURSOR | U2412 output |
| Horizontal Delta Cursor | DELTA CURSOR | U2412 output |
| Vertical Ref Cursor | 0.6 V | U2413 output |
| Vertical Delta Cursor | 0.6 V | U2413 output |

Table 3-30
Possible Signal Conditions to U2416

| Readout Type | U2415-3 | U2415-13 |
| :--- | :---: | :---: |
| Stationary Text | 2.0 V | U2413 output |
| Horizontal Ref Cursor | 2.0 V | U2413 output |
| Horizontal Delta Cursor | 2.0 V | U2413 output |
| Vertical Ref Cursor | REF CURSOR | 0 mA |
| Vertical Delta Cursor | DELTA CURSOR | 0 mA |

## LED Refresh

Assume LED column ASO is being refreshed. First, the LED Cathode Register, U2524, is loaded with a data byte from the Measurement Processor. That byte defines the LEDs that are on for that column, and the outputs of Cathode Driver U2525 for the "on" LEDs are low. Then, a high on the DO bit of the Measurement Processor Data Bus is latched into LED Anode Register U2523 with the LED ANODE CLK signal. That high turns on the associated Darlington transistor (Q2506 for the ASO column), and the LEDs in that column that also have their cathodes low from U2525 are turned on.

## Switch Reading

At the same time the ASO LED column is refreshed, the connected ASO switch column is pulled high through CR2006. The switch status (low for open or high for closed) for the active switch column is
parallel loaded into the Switch Board Shift Registers (U2001 and U2002). This switch status data is then shifted out serially (by 15 SW BD SR SHIFT clocks) to the Measurement Processor on the SW BD DATA return line. The position of a high in the serial data stream, and knowing the active column, tells the Measurement Processor the switch in column ASO that is closed (the CH 1 VOLTS/DIV setting). Columns with push-button switches may or may not have a switch closed. A switch closure is interpreted by the Measurement Processor, and any new operating conditions needed (determined from the firmware routines called up to handle a particular switch closure) are set up.

At the next 2 ms interrupt, the Measurement Processor loads new data into Cathode Register U2524 to enable the LED rows, and the column is advanced to enable the A01 column for refresh and switch reading. The process described is continual while the oscilloscope is on.

Part of the Measurement Processor routine stores the new front-panel settings in the System RAM each time a change is made. At power on (after being turned off), the stored front-panel settings are recalled from the System RAM to return the oscilloscope to the same operating state that existed at power off (with some exceptions).

## Diagnostic

When the Measurement Processor is running the register checks during the DIAGNOSTIC, it can check the condition of registers U2001 and U2002. Serial data is placed on the ASO line from the DO bit of the Measurement Processor data bus. That data is serially shifted through the two registers to the SW BD DATA return line. The Measurement Processor compares the returned data stream with what was sent. A difference in the data bits shows an error; a correct comparison passes the test.

## ADC AND DAC SYSTEM (Diagram 11)

The ADC and DAC System permits the Measurement Processor to provide analog control voltages to the circuitry under its control and to find out certain analog voltage levels that it must have to do its control and measurement functions.

## Pot Multiplexer Latch

Latch U2313 latches data from the data bus (D0-D7) to control multiplexers U2308 and U2309 on this diagram and U506 on Diagram 7.

## Front-Panel Control Multiplexers

Multiplexers U2308 and U2309, controlled by the Measurement Processor via Pot Mux Latch U2313, select the front-panel control levels that are compared with the output of the D-to-A Converter (U2302). The result of that comparison is sent via signal line AD COMP to the Measurement Processor (U2501, Diagram 8).

## Input Data Latches

Binary data bytes to be converted to analog voltages are loaded into two latches (U2300 and U2301). Data Latch U2301 latches data to the DAC Multiplexer U2303 and U2302. Data Latch U2300 latches data to D-to-A Converter U2302.

## Digital-to-Analog Converter

The D-to-A Converter (U2302), using 12 data bits, can produce 4096 discrete output signal current levels from 0 to 2 mA . Signal current flows through R 2303 to the +2.5 V reference voltage. The resulting voltage drop across the resistor moves the voltage at pin 3 of voltage follower U2314 away from +2.5 V toward 0 V and below. When there is 0 mA output, the voltage at pin 3 is +2.5 V . At maximum output current, the voltage at pin 3 is -2.5 V . Voltage follower U2314 buffers the voltage and applies it to the input pin of analog multiplexer U2303, where it is directed to the control circuit selected by the Measurement Processsor.

A-TO-D CONVERSION. The output from U2314 is also applied to comparator U2306. When analog-todigital conversion is being done, the Measurement Processor drives the DAC to produce comparison voltage levels in a binary search pattern. The output of U2306 is monitored to determine the smallest DAC input change that will produce an output change from the comparator. That value is then used as the digital representation of the analog voltage applied to the other pin of the comparator from the output of Multiplexer U2308 or U2309. Signals on that multiplexed line are the front-panelpotentiometers wiper voltages and the probe-code levels.

## Sample-and-Hold Circuits

The analog voltages from the multiplexer U2303 remain stable only for the short period of time that the DAC is at a fixed output level. Control voltages to the analog circuitry must remain constant except for changes to the control settings. Those control voltages are held constant between refreshes by sample-and-hold circuits formed by a capacitor (to hold the voltage) and a voltage follower (to buffer the voltage held by capacitor). The voltage follower circuits are provided by the operational amplifiers of U2304 and U2305. Each of the hold voltages are protected from humidity degradation of the voltage follower's high-impedance input by an active guard shield on the circuit board. Extra noise filtering for two of the control voltages (REF DELAY and DELTA DELAY) is provided by using an RC pi-type filter input circuit to the voltage follower.

## Analog Control Auto Setup

The auto-setup circuitry presets many of the analog front-panel controls to predetermined settings. Pressing the AUTO SETUP button starts the setup function. Auto-ranging on the signal is part of the setup procedure not discussed here. However, as part of that setup procedure, the settings of TRACE SEP, CH $1-\mathrm{CH} 4$ POSITION, READOUT, and $A$ and

B INTEN are set to levels that provide a good starting point for making measurement setups. Those settings remain at the SNAP setting level until the front-panel potentiometer setting crosses the preset SNAP level. After that level is crossed, control is returned to the front-panel potentiometer.

When AUTO SETUP is pressed, the Measurement Processor loads the SNAPO - SNAP7 data bits into the SNAP latch, U2307, on the rising edge of $\overline{\text { SNAP CLK }}$ at pin 11. The latch is permanently enabled by the ground on pin 1, the enable input. The SNAP bits switch multiplexors U2311, U2310, and $U 2312$ to apply fixed analog levels to the frontpanel control output lines at J2304. The fixed control values remain switched in until the microprocessor determines the movement of a front-panel control has crossed the SNAP control level. At that time, the Measurement Processor resets the SNAP bit level to switch the multiplexor to return control to the frontpanel potentiometer. SNAP bits for the unchanged controls remain set to levels that hold the fixed voltages on the control lines.

## POWER SUPPLY (Diagram 12)

The Power Supply (Diagram 12) provides the various low-voltages needed to operate the 2245A and the high-voltage required by the cathode-ray tube (crt). The supply circuitry is arranged in the following functional blocks: AC Input, Primary Power Rectifier, Start-Up circuit, Preregulator Control circuit, Preregulator Power Switching circuit, Inverter Control circuit, Inverter Power Switching circuit, LowVoltage Secondary Supplies, and High-Voltage Supply (see Figure 3-10).

Ac power via the power cord is rectified and filtered by the Primary Power Rectifier to supply the dc voltage to Preregulator circuitry. The output voltage level from the Primary Power Rectifier depends on the ac supply voltage level and may vary between about 125 V and 350 V . This unregulated, filtered, dc voltage is supplied to the Preregulator Start-Up circuit and the Preregulator Switching circuit. The Preregulator Power Switching circuit supplies +44 Vdc output power to drive the Inverter Power Switching circuit.

The +44 V Preregulator output voltage is switched by the Inverter Power Switching circuit to produce an alternating current through the primary of the Inverter power transformer. The current source to the Inverter switching transistors is monitored and regulated by the Inverter Control circuit to maintain a
constant output voltage level across the transformer secondaries.

The Low-Voltage Secondary Supplies rectify and filter the low-voltage secondary ac voltages to provide the dc power requirements for the instrument. Two other secondary windings on the Inverter Power Transformer are used in the High-Voltage Supply, a high-voltage winding and a crt filament winding. Voltage from the high-voltage winding is further multiplied and converted to dc voltage for the crt anode, cathode, and intensity-grid voltages.

Both overvoltage and overcurrent protection are provided to protect the oscilloscope circuitry from further damage if a circuit component fails.

## Ac Input

Applied source voltage is input to the Primary Power Rectifier via surge protection circuitry and noise filtering circuitry. A sealed line filter (FL2201), L2207, L2208, C2214, C2213, C2216, C2215, R2260, R2227, and R2228 form a low-pass filter designed to prevent transmission of high-frequency noise signals either into or out of the instrument. Bleeder resistor R2215 across the input line filter drains off any charge retained by the capacitors in the input circuitry when the power is disconnected. Thermistor RT2201 prevents a sudden rush of input current into the rectifier and filter capacitor, C2202, when the power switch is turned on. The thermistor presents a relatively high resistance when cold, then quickly reduces to a low value when warmed up. Varistor VR2204 acts as a surge limiter to reduce the effects of any power line surges that may damage the input circuit components. The varistor is a voltage-sensitive device that quickly reduces its resistance value when its voltage limits are exceeded. Line fuse F2201 protects the instrument from additional damage in case of of a severe short in the power supply.

## Primary Power Rectifier

Rectification of the input ac source voltage is done by bridge rectifier CR2233. Simple capacitive filtering of the rectifier output is done by C2202. The filtered output voltage may range between about 125 Vdc and 350 Vdc , depending on the amplitude of the ac input voltage. A line trigger signal is picked off by T2206 for use when the Trigger SOURCE is set to LINE. Bleeder resistor R2256 drains off the charge on C2202 when the instrument is turned off.


Figure 3-10. Power Supply block diagram.

## Start-Up Circuit

The Start-Up circuit provides the operating supply voltage to the Preregulator. At power on, C2204 in the Start-Up circuit begins charging through R2203 and R2204 from, the output of the Primary Power Rectifier. When the voltage across C2204 reaches 20 V , the voltage at the base of Q2204 is about 6.8 V . This base voltage level causes Q2204 to conduct (there is a 6.2 V zener diode in the emitter path), and Q2211 also is then biased on. Positive feedback to the base of Q2204 (from the collector of Q2211 through R2220) then keeps both transistors on. The do voltage to U2201 (Vcc) for start up (and continued running after start up) is provided by the charge on C2204 via Q2211.

With U2201 on and drawing current from C2204, the voltage across C 2204 begins to fall. If the Preregulator output rises to +44 V before the voltage across C2204 falls to 10 V , then CR2202 becomes forward biased, and current pulses are supplied by a winding (pins 8 and 9) on T2203 to keep C2204 charged (and U2201 operating).

If the Preregulator output does not rise to +44 V within the time it takes to discharge C2204 below $10 \vee$ (about $1 / 10$ of a second), the voltage at the base of Q2204 will drop too low for the feedback voltage to keep it on. That will cause Q2211 to also shut off. The start-up cycle repeats when the voltage across C2204 again reaches 20 V (recharging from the output of the Primary Power Rectifier output via R2203 and R2204). Continued failure of the Preregulator to start up and the repeated attempts to do so is called the "Chirp" mode. Zener diode VR2206 prevents the voltage across C2204 from exceeding about 30 V if no start-up attempt occurs.

## Preregulator Control Circuit

The Preregulator Control IC, U2201, is a pulse-width modulator used to control the on time of Preregulator Switching FET Q2201. It contains an oscillator, comparators, voltage and current error amplifiers, and logic circuitry that controls its operation. The modulated output pulses drive switching transistor Q2201 through a buffer amplifier composed of Q2202 and Q2203. Pulse width (the time that FET Q2201 is on) is inversely proportional to the control voltage at pin 3 of U2201 (i.e., a lower voltage at pin 3 makes the pulse width wider to keep Q2201 on longer.

Pin 7 of U2201 is the IC ground reference, and it is tied directly to the $+44 \vee$ output voltage. Therefore, the Preregulator IC and the Start-Up circuitry
operating potentials "float" on the regulated output voltage (developed across C2203).

Pin 2 of U2201 is the current-summing node to the voltage-error amplifier. The error amplifier will try to keep the voltage on pin 2 equal to the voltage on pin 1 (the $+44 V$ supply voltage). The error amplifier maintains pin 2 at +44 V by raising (or lowering as necessary) the voltage at pin 3. This raises (or lowers) the voltage across C2203 so that less (or more) current will be drawn out of the currentsumming node.

The major current injected into the summing node is from the regulated 5 V output, from pin 12 of U2201, via R2212. That current is about 0.6 mA . The current through R2206 adds to the current shunted by the Preregulator Output Voltage Control transistor, Q2208, to produce about 0.6 mA to keep the current into and out of the summing node balanced. The actual current through R2206 is the output voltage ( +44 V across C 2203 ) divided by the resistance value of R2206 ( $100 \mathrm{k} \Omega$ ) or about 0.4 mA .

SOFT START. At the initial turn-on of the instrument, C2203 is discharged. If no action were taken to prevent it, the initial charging current to that capacitor would exceed safe limits. To avoid such a problem, a "soft start" of the charging path is done.

At turn-on, the +5 V output of U 2201 steps to +5 V immediately. $\mathrm{A}+5 \mathrm{~V}$ pulse is coupled to pin 4 of U2201 via C2207. This pin is the "dead time control" input, and when it is high, the dead time between switching pulses to Q2201 is increased to $100 \%$. Switching transistor Q2201 does not turn on, and no charging of C2203 occurs. Then, as C2207 charges, the voltage on pin 4 begins to decrease toward the ground reference value (on pin 7). This decreases the dead time, allowing increasingly wider conduction pulses to occur.

The on-time gradually increases until the charging current is limited by the internal current limit amplifier of U2201. At that point, the Preregulator is acting as a current source. When the voltage across C 2203 reaches +44 V , the voltage error amplifier starts to limit the output, and the Preregulator has reached its operating level and acts as a voltage source.

CURRENT LIMIT. The output current of the Preregulator switching FET, Q2201, is limited to a safe value. If the current exceeds 2.4 amperes, the voltage dropped across R2201 causes pin 14 of U2201 (one input of the current limit amplifier) to exceed the voltage on pin 13 of U2201 (the other input pin of the current limit amplifier). The output of the current limit amplifier then goes high, raising the voltage on pin 3 of U2201. Increased voltage on
pin 3 narrows the width of the turn-on pulses to switching FET Q2201 and limits the output current.

Usually, with a circuit failure, the excess loading remains, and the pulses remain narrow. The Preregulator Control IC then shuts down because the charge on C2204 is not maintained via the Preregulator supply winding on T2203, and the Preregulator goes into the chirp mode (continual shut down and restart attempts).

OVERVOLTAGE CROWBAR. If the output voltage across C2203 exceeds about +51 V , VR2201 in the crowbar circuit conducts. The gate of SCR Q2206 then rises; and, if the rise is enough, the SCR latches on. When on, Q2206 shorts out C2203, and the current limit circuit causes the switching pulses to Q2201 to become very narrow. Preregulator IC U2201 then shuts down (as described in the Current Limit discussion). The Preregulator will attempt a restart after about half a second, but will shut down again if the overvoltage condition continues (this is the "chirp" mode).

PREREGULATOR OUTPUT CONTROL. The voltage across the Inverter current source transistor, FET Q2214, is monitored by Q2208 (from the collector voltage of either Q2209 or Q2210). That voltage has to be maintained at the proper level to provide enough regulation room for the secondary supply voltages and still not dissipate more power than necessary in Q2214. If the voltage across Q2214 is too high, Q2209 is biased on harder and draws more current from the input summing node (pin 2 of U2201) of the voltage error amplifier in U2201, the Preregulator Control IC. The output of the error amplifier at pin 3 of U2201 then rises, and the width of the switching pulse to the Preregulator Switching circuit narrows to decrease the +44 V output.

The Inverter Control circuit (Q2212 and Q2213) senses the decreased voltage across the primary of the Inverter power transformer (T2204) and responds by driving Q2214, the Inverter currentsource transistor, harder; thereby decreasing the voltage across it.

Control response time in the feedback loop just described is long; but it does not need a fast response time, since the circuit only determines the power dissipation in Q2214. Compensation of the circuit to prevent oscillation is done by a low-pass filter ( 10 Hz cutoff) formed by C2238, R2205, and R2246.

## Preregulator Switching Circuit

The Preregulator Switching circuit provides the energy required to keep C2203 charged up to +44 V. Switching FET Q2201 is driven by the pulsewidth modulated output of the Preregulator IC (U2201) via a buffer amplifier circuit. The Preregulator IC controis the on-time to maintain the voltage across C2203 at +44 V .

For the following discussion of the switching circuit, assume that Q2201 is off, C2201 is charged to the rectified line voltage ( 160 V from the Primary Power Rectifier), and the +44 V supply is up and driving a circuit load.

When the Preregulator IC turns on Q2201, the drain of Q2201 is immediately clamped to 44 V . This forces $116 \mathrm{~V}(160 \mathrm{~V}-44 \mathrm{~V})$ across pins 6 and 7 of T2203. Current begins increasing linearly in that coil as Q2201 supplies current to the $+44 \vee$ supply. With the one end of C2201 clamped to +44 V , and C2201 being charged to +160 V , the other end of C2201 is pushed down with the anode of CR2201 going to $-116 \vee(44 \vee-160 \mathrm{~V})$. This places 116 V $(0-116 \mathrm{~V})$ across pins 1 and 2 of T2203 and current begins increasing linearly in that coil, also flowing through Q2201 to the +44 V supply. After a time determined by Preregulator IC U2201, the drive signal to Q2201 is switched low, and the switching FET is turned off.

The current flowing in both coils of T2203 must continue as the magnetic field collapses, but it cannot flow through Q2201. The only available path is through CR2201 (previously biased off). The polarity reversal of the voltage across T2203 that occurs forward biases CR2201, and permits the energy in the magnetic field to be released to the +44 V supply.

When CR2201 is forward biased its cathode is clamped to the +44 V supply level. With C2201 still charged to +160 V (the supply voltage), its positive end is pushed up to $204 \mathrm{~V}(44 \mathrm{~V}+160 \mathrm{~V})$. Now there is $-44 \mathrm{~V}(160 \mathrm{~V}-204 \mathrm{~V})$ across the coil of T2203 from pin 7 to pin 6 and $-44 \mathrm{~V}(0-44 \mathrm{~V})$ from pin 2 to pin 1 (see Figure 3-11). Since C2201 is in parallel with C2202 for dc voltages (coils are shorts to dc), the dc voltage across C2201 can change very little. The capacitance of C2201 is large enough that the charging and discharging currents do not have enough time to change the voltage across C2201 in normal operation.


Figure 3-11. Preregulator switching waveforms.
The two coils of T2203 need not be coupled magnetically for the circuit to operate. Both coils are wound on the same core for convenience. Transformer action is minimal because the waveforms impressed across both coils are nearly identical.

After a time controlled by the Preregulator IC (the dead time), the on-time cycle for Q2201 repeats. On-time depends on the line voltage level; a higher line voltage level means a shorter on-time of Q2201 is needed to maintain +44 V across C 2203 .

## Inverter Power Switching Circuit

The Inverter Power Switching circuit is composed of switching transistors Q2209 and Q2210, current source transistor Q2214, inverter power transformer T2204, base-drive transformer T2205, and associated components. Current supplied by the +44 volts output from the Preregulator circuit is alternately switched through each side of the center-tapped primary of T2204 to drive the loads on the secondary windings of the inverter transformer.

INVERTER STARTER. As the Preregulator turns on, the +44 V supply increases from 0 V . The increasing voltage forward biases CR2236 and charges C2248 through the base-emitter junctions of Q2209 and Q2210. Current is drawn through each side of T2204, from the center tap, as the transistors conduct. One of the two transistors will have a slightly higher gain than the other, and its collector voltage will decrease more than the other. The voltage difference across the primary of T2204 also appears across the primary winding of T2205, and a feedback voltage is induced in the secondary winding of T2204. The polarity of the transformer is such that
the conduction of the higher gain transistor is reinforced (positive feedback), and that transistor quickly saturates while the other is cut off. One end of the primary of T2204 is driven toward ground while the other end is opened. After about half a second, C2248 charges up, CR2236 becomes reverse biased, and that path for current through the conducting transistor is blocked.

If the Inverter Power Switching circuit stops, the Inverter Starter circuit will not restart it until C2248 is discharged. Furthermore, C2248 will not discharge until the +44 V supply falls.

INVERTER POWER SWITCHING. Switching is started by one or the other of either Q2209 or Q2210 conducting more that the other, and circuit action biases the other one off. Assume for this discussion that Q2210 is biased on and Q2214 is off. Current flows through current-source FET Q2214, ontransistor Q2210, and half of the primary of T2204 (pins 9 and 11). The voltage drop across currentsource transistor Q2214 holds the emitter voltage of Q2209 and Q2210 at 3 V . Voltage across pins 9 and 11 is therefore $41 \vee(44 \mathrm{~V}-3 \mathrm{~V})$.

Through autotransformer action, 41 V is induced in the other half of the primary winding of T2204 from pin 8 to the center-tap pin. That voltage adds to the 41 V from pins 9 to 11 to produce a potential of 82 volts across the primary of switching transformer T2205. Current rapidly ramps up through the primary of T2205 and induces a positive feedback base current in one-half of its center-tapped secondary that keeps Q2210 turned on. Current in the other half of the secondary biases on CR2227 to prevent a high reverse base-to-emitter voltage from being developed across Q2209.

After about $25 \mu \mathrm{~s}$, the current through the primary of T2205 saturates the magnetic core and the primary impedance of the transformer drops to a low value. When saturation occurs, the impedance presented by L2206 by comparison to that of T2205 is large, and most of the voltage applied from the secondary of T2204 is then dropped across L2206. The secondary voltage of T2205 drops to zero, and with no base-drive current to Q2210, that transistor switches off.

With both Q2209 and Q2210 off, the magnetic energy stored in the primary of T2205 and in L2206 causes current to flow in the primary of T2204, reversing the voltage polarity on this winding. The voltage reversal is not instantaneous because of the parasitic capacitance of the T2204 windings. When the reverse voltage gets high enough, base current flows to Q2204 and that transistor turns on. The inverter current flow cycle through T2204 then repeats but in the opposite direction to induce ac
current in the various secondary windings of the inverter power transformer.

INVERTER CONTROL LOOP. Whenever either Q2209 or Q2210 is on, the collector voltage of the on transistor forward biases either CR2205 (if Q2209 is on) or CR2204 (if Q2210 is on). Capacitor C2219 is then charged to nearly the same voltage that is applied to the center tap of the primary winding of Inverter Transformer T2204.

A resistive voltage divider formed by R2239, R2238, and potentiometer R2252 (+7.5 V ADJUST) applies a fraction of the voltage across C2219 to the base of Q2213 (one-half of a differential amplifier formed by Q2212 and Q2213). The voltage on the base of Q2213 is compared to a voltage on the base of Q2212 that is referenced back to the +44 V center tap voltage of T2204. If the collector voltage of the conducting inverter-switching transistor (Q2009 or Q2210) is not the correct level (about 3 V ), the gate voltage of current-source FET Q2214 will be raised or lowered as needed to correct the error.

## Low-Voltage Secondary Supplies

The low-voltage power supply circuitry on the pin 12 to pin 22 and pin 13 to pin 15 secondary windings of the Inverter power transformer consist of rectifier and filter components only. All the regulation is done by the Preregulator and Inverter Control circuitry in the primary side of the transformer. Both half-wave and full-wave rectifiers are used, and either simple capacitor or capacitive-input PI filter circuits are used. Rectifier and filter type used for each of the secondary voltages depends on the load requirement. A single 130 Vac output from pin 12 of T2204 supplies the drive to the Z-Axis dc restorer circuitry. Power for the blower fan is supplied by the -15 V power supply line.

The center-tapped secondary winding from pins 13 to 15 of $T 2204$ is used for the +5 V and -5 V supplies. Both are full-wave rectified and filtered using capacitive-input PI filters.

## High-Voltage Supply

The high-voltage power supply uses two secondary windings of T2204: one for high-voltage multiplier

U2230 and the other for the crt filament. Flying leads from the top of the transformer make the circuit connections into the high-voltage circuitry. The crt filament winding consists of a few turns of insulated wire.

The high-voltage winding attaches directly to the HV Multiplier. Outputs from HV Multiplier U2230 are the 13.7 kV to the crt anode via a high-voltageinsulated connecting lead and the -2.7 kV supplied to the crt cathode, focus grid, and intensity grid. The -2.7 kV supply is filtered by a two-section capacitive input RC filter. A neon lamp across the second section of the filter provides protection against arcing if there is a failure that can cause a large difference of potential to develop between the crt heater and cathode circuits.

## MAIN BOARD POWER DISTRIBUTION (Diagram 13)

The Main Board Power Distribution diagram schematically displays the distribution paths and decoupling circuits for the low voltages from the Power Supply. The supply and ground connections to the various integrated circuits in the instrument are also shown. Use this diagram to aid circuit tracing when trying to locate a power supply loading problem associated with the Main Board.

## PROCESSOR BOARD POWER DISTRIBUTION (Diagram 14)

The continuing power distribution from the Main Board to the top board (Processor Board, A16) is shown in the Processor Board Power Distribution schematic diagram. Use Diagram 14 to aid in locating power supply loading problems that are isolated to the Processor Board.

## INTERCONNECTION DIAGRAM (Diagram 15)

Circuit board interconnections with the plug, jack, pin numbers, and signal names shown are found in schematic Diagram 15. The diagram is useful in checking continuity of cable runs and signal paths from board to board through the instrument.

# PERFORMANCE CHECK PROCEDURE 

## INTRODUCTION

The Performance Check Procedure is used to verify the Performance Requirements listed in Table 1-1 and to help determine the need for readjustment. These checks may also be used as an acceptance test or as a troubleshooting aid.

You do not have to remove the wrap-around cabinet from the 2245A to do this procedure. All checks can be made with controls and connectors accessible from the outside.

## TEST EQUIPMENT REQUIRED

Table 4-1 lists the test equipment required for both the Performance Check Procedure in this section and the Adjustment Procedure in Section 5. Test equipment specifications described are the minimum necessary to provide accurate results. For test equipment operating information, refer to the appropriate test equipment instruction manual.

If the exact equipment given as an example in Table $4-1$ is not available, use the Minimum Specification column to determine if any other test equipment can be used for the check. When you use equipment other than that recommended, you may have to make some changes to the test setups.

## PERFORMANCE CHECK INTERVAL

To ensure instrument accuracy, check the performance of the 2245A after every 2000 hours of operation, or once each year if used infrequently. If the checks indicate a need for readjustment or repair, refer the instrument to a qualified service person.

## PREPARATION

This procedure is divided into subsections so that individual sections of the instrument may be checked whenever a complete Performance Check is not needed. An "Equipment Required" block at the beginning of each subsection lists the equipment from Table 4-1 that is needed to do the checks in that subsection.

The initial front-panel control settings at the beginning of each subsection prepare the instrument for the first step of the subsection. Do each of the steps in a subsection completely and in order, to ensure the correct control settings for steps that follow.

To ensure the performance accuracies given in Table 1-1, let the instrument warm up for 20 minutes and then run the SELF CAL MEASUREMENTS routine. To run the SELF CAL MEASUREMENTS routine:

Press the CH 1 and CHOP/ALT VERTICAL MODE buttons at the same time to display the SERVICE MENU. Underline and select SELF CAL MEASUREMENTS by pressing the ADD (down-arrow) button. Press the CH 2 (RUN) button to start the routine, then CH 4 (QUIT) button to return to the normal oscilloscope mode.

> NOTE

> Performance accuracies are ensured only when the SELF CAL MEASUREMENTS routine is done AFTER the 20-minute warmup.

Table 4-1
Test Equipment Required

| Item and Description | Minimum Specification | Use | Example of Test Equipment |
| :---: | :---: | :---: | :---: |
| Leveled Sine-Wave Generator | Frequency: 250 kHz to above 150 MHz . Output amplitude: variable from 10 mV to 5 V p-p. Output impedance: $50 \Omega$. Amplitude accuracy: constant within $1.5 \%$ of reference frequency to 100 MHz . | Vertical, horizontal, triggering, measurement bandwidth, and Z-Axis checks and adjustments. | TEKTRONIX SG 503 Leveled Sine-Wave Generator. ${ }^{\text {a }}$ |
| Calibration Generator | Standard-amplitude signal levels (dc and square wave): 5 mV to 50 V. Accuracy: $\pm 0.25 \%$. <br> High-amplitude signal levels: 1 V to 60 V . Repetition rate: 1 kHz . <br> Fast-rise signal level: 1 V . Repetition rate: 1 MHz . Rise time: 1 ns or less. Flatness: $\pm 0.5 \%$. | Signal source for gain and transient response checks and adjustments. | TEKTRONIX PG 506 Calibration Generator. ${ }^{\text {a }}$ |
| Time-Mark Generator | Marker outputs: 5 ns to 0.5 s. Marker accuracy: $\pm 0.1 \%$. Trigger output: 1 ms to $0.1 \mu \mathrm{~s}$, timecoincident with markers. | Horizontal checks and adjustments, display adjustment, and time cursor checks. | TEKTRONIX TG 501 Time-Mark Generator. ${ }^{\text {a }}$ |
| Function Generator | Range: less than 1 Hz to 1 kHz ; sinusoidal output; amplitude variable up to greater than 10 V p-p open circuit with dc offset adjust. | Low-frequency checks. | TEKTRONIX FG 502 Function Generator. ${ }^{\text {a }}$ |
| Coaxial Cable (2 required) | Impedance: $50 \Omega$. Length: 42 in. Connectors: BNC | Signal interconnection. | Tektronix Part Number 012-0057-01. |
| Precision Coaxial Cable | Impedance: $50 \Omega$. <br> Length: 36 in. <br> Connectors: BNC | Used with PG 506 Calibration Generator and SG 503 Sine-Wave Generator. | Tektronix Part Number 012-0482-00. |

$a_{\text {Requires }}$ a TM500-series power module.

Table 4-1 (cont)

| Item and Description | Minimum Specification | Use | Example of Test Equipment |
| :---: | :---: | :---: | :---: |
| Termination (2 required) | Impedance: $50 \Omega$. <br> Connectors: BNC. | Signal termination. | Tektronix Part Number 011-0049-01. |
| 10X Attenuator | Ratio: 10X. <br> Impedance: $50 \Omega$. <br> Connectors: BNC. | Triggering checks. | Tektronix Part Number 011-0059-02. |
| $2 \times$ Attenuator | Ratio: 2 X . <br> Impedance: $50 \Omega$. <br> Connectors: BNC. | Triggering checks. | Tektronix Part Number 011-0069-02. |
| Adapter | Connectors: BNC male-to-miniature-probe tip. | Signal interconnection. | Tektronix Part Number 013-0084-02. |
| Alignment Tool | Length: 1-in shaft. <br> Bit size: $3 / 32$ in. <br> Low capacitance; insulated. | Adjust TRACE ROTATION pot. Adjust variable capacitors and resistors. | Tektronix Part Number 003-0675-00. |
| Test Oscilloscope | Bandwidth: $20 \mathrm{MHz} .$ | Z-Axis response adjustment. | TEKTRONIX 2246A. |
| Dual-Input Coupler | Connectors: BNC female-to-dual-BNC male. | Signal interconnection. | Tektronix Part Number 067-0525-01. |
| T-Connector | Connectors, BNC. | Signal interconnection. | Tektronix Part Number 103-0030-00. |
| Precision Normalizer | Input resistance: $1 \mathrm{M} \Omega$ : Input capacitance: 20 pF . | Input capacitance adjustments. | Tektronix Part Number 067-1129-00. |
| TV Signal Generator | Provide composite TV video and line sync signals. | Check TV Trigger circuit. | Tektronix 067-0601-00. Calibration fixture with 067-5002-00 (525/60) and 067-5010-00 (1201/60) plug-ins. |
| Digital Multimeter (DMM) | Dc volts range: 0 to 140 V . Dc voltage accuracy: $\pm 0.15 \%$. $41 / 2$ digit display. | Power supply voltage checks and adjustments. | Tektronix DM 501A Digital Multimeter. ${ }^{\text {a }}$ |

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## DISPLAY

## Equipment Required (See Table 4-1)

Time-mark generator
$50 \Omega$ BNC coaxial cable
$50 \Omega$ BNC termination

## 1. TRACE ROTATION

a. Set:

READOUT (Intensity)
A INTEN
VERTICAL MODE
CH 1 VOLTS/DIV
CH 1 COUPLING
SCOPE BW
A/B SELECT
TRIGGER MODE
TRIGGER SOURCE
TRIGGER CPLG
TRIGGER SLOPE
TRIGGER HOLDOFF
TRIGGER LEVEL
Horizontal MODE
Horizontal POSITION
A SEC/DIV
CLEAR MEAS'MT

FOCUS
For a viewable readout
For a viewable
trace
CH 1
0.1 V

AC
Off
A Trigger
AUTO LEVEL
VERT
DC

- (positivegoing)
Min
12 o'clock
A
12 o'clock
$2 \mu \mathrm{~s}$
Press to remove measurement cursors.
For best defined display
b. Position trace vertically to the center graticule line.
c. CHECK-trace rotation control range is adequate to align trace with center graticule line using a small straight-bladed alignment tool.
d. ADJUST-trace parallel to center horizontal graticule line.

2. Geometry
a. Connect time-mark generator (TG 501) to CH 1 via a $50 \Omega$ BNC coaxial cable and a $50 \Omega$ BNC termination.
b. Set generator for $0.2 \mu \mathrm{~s}$ time markers.
c. Position the bottom of the CH 1 signal below the bottom graticule line.
d. CHECK-deviation of any vertical line within the center eight horizontal divisions does not exceed 0.1 division (half a minor division).
e. Set CH 1 COUPLING to GND.
f. Position trace slowly from the bottom graticule line to the top graticule line while making the following check.
g. CHECK—bowing or tilt of baseline trace doesn't exceed 0.1 division (half a minor division) within the eight vertical divisions.
h. Disconnect test signal from the 2245A.

## VERTICAL

```
Equipment Required (See Table 4-1)
    Leveled sine-wave generator
    Calibration generator
    Function generator
    50\Omega BNC coaxial cable
```

$50 \Omega$ precision BNC coaxial cable
$50 \Omega$ termination
Adapter BNC-male-to-miniature probe tip
Dual-input coupler

1. Input COUPLING Functional Check
a. Set:

READOUT (Intensity)
A INTEN
VERTICAL MODE
CH 1 and CH 2
VOLTS/DIV
CH 1 and CH 2
Input COUPLING
SCOPE BW
CH 2 INVERT
A/B SELECT
trigger mode
TRIGGER SOURCE
TRIGGER CPLG
TRIGGER SLOPE
TRIGGER LEVEL
TRIGGER HOLDOFF
Horizontal POSITION
Horizontal MODE
SEC/DIV
FOCUS
CLEAR MEAS'MT

For a viewable readout For a viewable trace
CH 1 and CH 2
1 V
DC
Off
Off
A TRIGGER
AUTO LEVEL VERT
DC - (positivegoing)
12 o'clock Min
12 o'clock
A
0.5 ms

For bestdefined display
Press to remove measurement cursors
b. Connect function generator (FG 502) sine-wave output to the CH 1 input via a $50 \Omega \mathrm{BNC}$ coaxial cable and a $50 \Omega$ BNC termination.
c. Set function generator output for 1 kHz sinewave signal of five divisions peak-to-peak with maximum positive dc offset.
d. Position the bottom of the signal to the center horizontal graticule line.
e. Set CH 1 Input COUPLING to $A C$.
f. CHECK-display is centered about the center horizontal graticule line.
g. Move the test signal to the CH 2 input.
h. Set CH 2 VERTICAL MODE to on (CH 1 off).
i. Repeat the procedure for CH 2.
j. Disconnect the test signal from the 2245A.
2. CH 1 and CH 2 VOLTS/DIV Trace Shift
a. Set:

CH 1 and CH 2
VERTICAL MODE On
CH 1 and CH 2
VOLTS/DIV 2 mV
CH 1 and CH 2
Input COUPLING
GND
b. Set VERTICAL MODE to CH 1 (CH 2 off).
c. Position trace to center horizontal graticule line.
d. Switch CH 1 VOLTS/DIV through all positions from 2 mV to 5 V .
e. CHECK-trace shift does not exceed 0.2 division between steps.
f. Set VERTICAL MODE to CH 2 (CH 1 off).
g. Position CH 2 trace to the center horizontal graticule line.
h. Switch CH 2 VOLTS/DIV through all positions from 2 mV to 5 V .
i. CHECK-trace shift does not exceed 0.2 division between steps.
3. CH 3 and CH 4 VOLTS/DIV Trace Shift
a. Set VERTICAL MODE to CH 3 (CH 2 off).
b. Position trace to the center horizontal graticule line.
c. Switch CH 3 VOLTS/DIV between 0.1 V and 0.5 V .
d. CHECK-trace shift does not exceed one division.
e. Set VERTICAL MODE to CH 4 (CH 3 off).
f. Position trace to the center horizontal graticule line.
g. Switch CH 4 VOLTSIDIV between 0.1 V and 0.5 V .
h. CHECK-trace shift does not exceed one division.
4. CH 1 and CH 2 VAR VOLTSIDIV Trace Shift
a. Set:
VERTICAL MODE
CH 1 (CH 4 off) CH 1 VOLTS/DIV
2 mV
b. Position trace to center graticule line.
c. Set CH 1 VAR VOLTS/DIV fully CCW (counterclockwise).
d. CHECK-trace shift does not exceed one division.
e. Set:

## CH 1 VAR VOLTSIDIV

VERTICAL MODE CH 2 VOLTS/DIV

Detent (calibrated) $\mathrm{CH} 2(\mathrm{CH} 1$ off) 2 mV
f. Position trace to center graticule line.
g. Set CH 2 VAR VOLTS/DIV fully CCW.
h. CHECK-trace shift does not exceed one division.
i. Set CH 2 VAR VOLTS/DIV to detent (calibrated) position.

## 5. CH 1 and CH 2 Input COUPLING Trace Shift

a. Position trace to center graticule line.
b. Set CH 2 Input COUPLING to DC.
c. CHECK-trace shift does not exceed 0.25 division.
d. Set:

VERTICAL MODE
CH 1 (CH 2 off)
CH 1 Input COUPLING GND
e. Position trace to center graticule line.
f. Set CH 1 input COUPLING to DC.
g. CHECK-trace shift does not exceed 0.25 division.

## 6. CH 2 INVERT Trace Shift

a. Set:
VERTICAL MODE
CH 2 ( CH 1 off)
CH 2 Input COUPLING GND
b. Position trace to center horizontal graticule line.
c. Set CH 2 INVERT On.
d. CHECK-trace shift does not exceed one division.
e. Set:

CH 2 INVERT Off
CH 2 Input COUPLING DC

## 7. CH 1 and CH 2 VAR VOLTS/DIV Range

a. Set VERTICAL MODE to CH 1 and CH 2.
b. Position CH 1 and CH 2 traces to the center horizontal graticule line.
c. Connect calibration generator (PG 506) Std Ampl output to the CH 1 input via $50 \Omega$ precision BNC coaxial cable. Set generator Std Ampl output to 50 mV .
d. Set:

CH 1 and CH 2 VOLTSIDIV

10 mV
CH 1 VAR VOLTS/DIV Fully CCW
e. CHECK-the signal amplitude is two divisions or less.
f. Set:
CH 1 VAR VOLTS/DIV
CH 1 VERTICAL MODE
Detent (calibrated) Off
g. Move the test signal to the CH 2 input.
h. Set CH 2 VAR VOLTS/DIV fully CCW.
i. Repeat the CHECK procedure for CH 2.
j. Set CH 2 VAR VOLTS/DIV to detent (calibrated) position.
8. Low-Frequency Linearity
a. Set:

| VERTICAL MODE | CH 1 |
| :--- | :--- |
| CH 1 VOLTSIDIV | 10 mV |
| SCOPE BW | $O \mathrm{On}$ |

b. Set calibration generator to Std Ampl output, 20 mV .
c. Move the test signal to the CH 1 input.
d. Position the top of the signal to top graticule line.
e. Check the signal amplitude is between 1.9 and 2.1 divisions.
f. Set bottom of the signal to bottom graticule line.
g. Check the signal amplitude is between 1.9 and 2.1 divisions.
h. Repeat the procedure for CH 2.
9. CH 1 and CH 2 Vertical Deflection Accuracy
a. Set CH 2 VOLTSIDIV to 2 mV .
b. Set calibration generator to Std Ampl output, 10 mV .
c. CHECK-all positions of the VOLTS/DIV settings for correct signal to graticule accuracy, using the settings in Table 4-2, Signal-to-Graticule Accuracy, for the checks.
d. Set calibration generator to Std Ampl output, 10 mV .
e. Move the test signal to the CH 1 input.
f. Set:

VERTICAL MODE
CH 1 VOLTS/DIV
CH 1 (CH 2 off) 2 mV
g. Repeat CHECK procedure for CH 1.

Table 4-2
Signal-to-Graticule Accuracy

| VOLTS/DIV <br> Setting | Std Ampl <br> Setting | Deflection Accy <br> (in divisions) |
| :---: | :---: | :---: |
| 2 mV | 10 mV | 4.90 to 5.10 |
| 5 mV | 20 mV | 3.92 to 4.08 |
| 10 mV | 50 mV | 4.90 to 5.10 |
| 20 mV | 100 mV | 4.90 to 5.10 |
| 50 mV | 200 mV | 3.92 to 4.08 |
| 0.1 V | 500 mV | 4.90 to 5.10 |
| 0.2 V | 1 V | 4.90 to 5.10 |
| 0.5 V | 2 V | 3.92 to 4.08 |
| 1 V | 5 V | 4.90 to 5.10 |
| 2 V | 10 V | 4.90 to 5.10 |
| 5 V | 10 V | 3.92 to 4.08 |

10. CH 3 and CH 4 Vertical Deflection Accuracy
a. Set:

VERTICAL MODE $\quad \mathrm{CH} 3$ and CH 4
CH 3 and CH 4 VOLTSIDIV
0.1 V
b. Position CH 3 and CH 4 traces to the second graticule line down from the center horizontal graticule line.
c. Move CH 1 test setup to the CH 3 input.
d. Set calibration generator to Std Ampl output, 0.5 V .
e. CHECK-the signal amplitude is between 4.90 and 5.10 divisions.
f. Move the test signal to the CH 4 input.
g. Set CH 3 VERTICAL MODE to Off.
h. Repeat CHECK for CH 4.
i. Set CH 3 and CH 4 VOLTSIDIV to 0.5 V .
j. Set calibration generator to Std Ampl output, 2 V .
k. CHECK-the signal amplitude is between 3.92 and 4.08 divisions.

1. Set CH 3 VERTICAL MODE On (CH 4 off).
m. Move the test signal to the CH 3 input.
n. Repeat CHECK procedure for CH 3.
o. Disconnect the test setup from the 2245 A.

## 11. ADD Mode and CH 2 INVERT Deflection Accuracy

a. Set:

| VERTICAL MODE | ADD (all others |
| :--- | :--- |
| off) |  |
| CH 1 and CH 2 VOLTS/DIV | 0.1 V |
| CH 1 and CH 2 input |  |
| COUPLING | DC |

b. Connect calibration generator Std Ampl output to the CH 1 and CH 2 inputs via $50 \Omega$ precision BNC coaxial cable and a BNC dual-input coupler.
c. Set the calibration generator to Std Ampl output, 0.2 V .
d. Position the ADD signal to the center of the crt graticule with the CH 1 and CH 2 POSITION controls.
e. CHECK-that the ADD signal amplitude is between 3.92 and 4.08 divisions.
f. Set CH 2 INVERT On.
h. CHECK-that the ADD signal amplitude is 0.08 division (less than half a minor graticule division) or less excluding trace width (sweep will free run).
g. Disconnect the test setup from the 2245A.

## 12. Vertical POSITION Range (all channels)

a. Set:

| A SEC/DIV | 0.1 ms |
| :--- | :--- |
| VERTICAL MODE | CH 1 On (ADD |
|  | off) |
| CH 1 VOLTS/DIV | 1 V |
| CH 2 INVERT | Off |
| SCOPE BW | Off |
| CH 1 and CH 2 Input |  |
| COUPLING | AC |

b. Connect leveled sine-wave generator (SG 503) output to the CH 1 and CH 2 inputs via a $50 \Omega$ BNC coaxial cable, a $50 \Omega$ BNC termination, and a BNC dual-input coupler.
c. Position trace to center horizontal graticule line.
d. Set leveled sine-wave generator output for twodivision signal at 50 kHz .
e. Set:

| CH 1 VOLTSIDIV | 0.1 V |
| :--- | :--- |
| CH | 1 |
|  | POSITION |
|  | (clockwise) |

f. CHECK-that the bottom of the waveform is at least one division above the center horizontal graticule line.
g. Set CH 1 POSITION fully CCW.
h. CHECK-that the top of the waveform is at least one division below the center horizontal graticule line.
i. Set:

| CH 1 POSITION | 12 o' $^{\prime}$ lock |
| :--- | :--- |
| VERTICAL MODE | $\mathrm{CH} 2(\mathrm{CH} 1$ off) |
| CH 2 POSITION | Fully CW |

j. CHECK-that the bottom of the waveform is at least one division above the center horizontal graticule line.
k. Set CH 2 POSITION fully CCW.
I. CHECK-that the top of the waveform is at least one division below the center horizontal graticule line.
m. Set CH 2 POSITION to 12 o'clock.
n. Move the BNC dual-input coupler from the CH 1 and CH 2 inputs to the CH 3 and CH 4 inputs.
o. Set:

VERTICAL MODE
CH 3 and CH 4
VOLTS/DIV
CH 3 POSITION

CH 3 (CH 2 off)
0.1 V

Fully CW
p. CHECK-that the bottom of the waveform is at least one division above the center graticule line.
q. Set CH 3 POSITION fully CCW.
r. CHECK-that the top of the waveform is at least one division below the center graticule line.
s. Set:

## CH 3 POSITION VERTICAL MODE

12 o'clock
CH 4 (CH 3 off)
t. Repeat the procedure for CH 4.
u. Set CH 4 POSITION to 12 o'clock.
v. Disconnect the test setup from the 2245A.
13. CH 1 to CH 2 Signal Delay Match
a. Set:

VERTICAL MODE
CH 1 and CH 2
Input COUPLING
CH 1 and CH 2
VOLTS/DIV 0.1 V
SEC/DIV
TRIGGER SOURCE
20 ns
CH 3
b. Superimpose the CH 1 and CH 2 traces at the $100 \%$ graticule marking.
c. Connect calibration generator (PG 506) fast rise, rising-edge signal to the CH 1 and CH 2 inputs via a $50 \Omega$ precision BNC coaxial cable, a $50 \Omega$ BNC termination, and a BNC dual-input coupler.
d. Connect calibration generator trig out signal to the CH 3 input via a $50 \Omega$ BNC coaxial cable and a $50 \Omega \mathrm{BNC}$ termination.
e. Set the calibration generator output for five divisions of signal amplitude at 1 MHz .
f. Position the rising edges of the superimposed waveforms horizontally to the center vertical graticule line.
g. Set X10 MAG On (for 2 ns/div sweep speed).
h. CHECK-that the leading edges of the two waveforms have less than 0.1 horizontal division separation at the center graticule line excluding trace width.

## 14. CH 1 to CH 4 Signal Delay Match

a. Set VERTICAL MODE to CH 1 and CH 4 (CH 2 off).
b. Move the CH 2 signal to the CH 4 input connector.
c. Superimpose the CH 4 waveform on the CH 1 waveform.
d. CHECK-that the leading edges of the two waveforms have less than 0.1 horizontal division separation at the center graticule line excluding trace width.

## 15. CH 3 to CH 4 Signal Delay Match

a. Set:

VERTICAL MODE
CH 3 and CH 4 (CH 1 off)
CH 2
b. Move the CH 1 signal to the CH 3 input and the CH 3 trigger signal to the CH 2 input.
c. Superimpose CH 3 and CH 4 waveforms at the center graticule line.
d. CHECK-that the leading edges of the two waveforms have less than 0.1 horizontal division separation at the center graticule line.
e. Disconnect the test setup.

## 16. CH 1 and CH 2 Vertical Bandwidth

a. Set:

| X10 MAG | Off |
| :--- | :--- |
| VERTICAL MODE | CH 1 (CH 3 and |
| SEC/DIV | CH 4 off) |
| CH 1 VOLTS/DIV | 0.1 ms |
| CH 1 and CH 2 Input | 2 mV |
| COUPLING |  |
| TRIGGER SOURCE | DC |
| Horizontal POSITION | VERT |
|  | 12 o'clock |

b. Connect leveled sine-wave generator (SG 503) output to the CH 1 input via a $50 \Omega$ precision BNC coaxial cable and a $50 \Omega$ BNC termination.
c. Set the leveled sine-wave generator output for a six-division signal amplitude at 50 kHz .
d. Set the generator Frequency Range and Frequency Variable controls for a 90 MHz output signal.
e. CHECK-the displayed signal amplitude is 4.2 divisions or more.
f. Repeat the frequency setup and CHECK procedure for VOLTS/DIV settings of 5 mV through 1 V , except perform CHECK at 100 MHz .
g. Move the test signal to the CH 2 input.
h. Set:

VERTICAL MODE
CH 2 (CH 1 off)
CH 2 VOLTS/DIV 2 mV
i. Repeat the complete Bandwidth check procedure for Channel 2.
17. CH 3 and CH 4 Vertical Bandwidth
a. Set:

```
VERTICAL MODE
CH 3 (CH 2 off)
CH 3 and CH 4 VOLTS/DIV
0.1 V
```

b. Connect leveled sine-wave generator (SG 503) output to the CH 3 input via a $50 \Omega$ precision BNC coaxial cable and a $50 \Omega$ BNC termination.
c. Set the generator output for a six-division signal display at 50 kHz .
d. Set the generator Frequency Range and Frequency Variable controls for a 100 MHz output frequency.
e. CHECK-that the signal display amplitude is 4.2 divisions or more.
f. Repeat the procedure for 0.5 VOLTS/DIV setting.
g. Move the test signal to the CH 4 input.
h. Set VERTICAL MODE to CH 4
i. Repeat the procedure for CH 4.
18. SCOPE BW (Bandwidth Limit) Accuracy
a. Set:
VERTICAL MODE
CH 1 (CH 4 off$)$
CH 1 VOLTS/DIV 10 mV
SCOPE BW
On
b. Move test signal from the CH 4 input to the CH 1 input.
c. Set leveled sine-wave generator (SG 503) output for a six-division signal amplitude at 50 kHz .
d. Set the leveled sine-wave generator Frequency Range and Frequency Variable controls to produce a signal display amplitude of 4.2 divisions.
e. CHECK-that the sine-wave generator output frequency is between 17 MHz and 23 MHz .
f. Disconnect the test setup.

## 19. Common-mode Rejection Ratio

a. Connect leveled sine-wave generator (SG 503) output to the CH 1 and CH 2 input connectors via a $50 \Omega$ precision BNC coaxial cable, a $50 \Omega$ BNC termination, and a BNC dual-input coupler.
b. Set the leveled $\sin e$-wave generator output for an eight-division signal-display amplitude at 50 kHz .
c. Set:

| ADD MODE | On |
| :--- | :--- |
| CH 2 VOLTSIDIV | 10 mV |
| CH 2 INVERT | On |
| CH 1 VERTICAL MODE | Off |
| SCOPE BW | Off |

d. Adjust CH 1 or CH 2 VAR VOLTS/DIV (as needed) for smallest signal amplitude.
e. Set the leveled sine-wave output frequency to 50 MHz .
f. Set:

## CH 1 VERTICAL MODE On ADD MODE <br> Off

g. Set the leveled sine-wave output amplitude for an eight-division display.
h. Set:

ADD MODE On
CH 1 Off
i. CHECK-the signal is less than 0.8 division in amplitude.
j. Disconnect the test setup.
20. Channel Isolation
a. Set:

CH 1 and CH 2 VERTICAL

| MODE | On (ADD off) |
| :--- | :--- |
| CH 2 INVERT | Off |
| CH 1, CH 2, CH 3, and |  |
| CH 4 VOLTS/DIV | 0.1 V |
| TRIGGER SOURCE | CH 1 |

b. Connect the leveled sine-wave generator (SG 503) output to the CH 1 input via a $50 \Omega$ precision BNC coaxial cable and a $50 \Omega$ BNC termination.
c. Set the leveled sine-wave generator (SG 503) output for a five-division signal display amplitude at 100 MHz .
d. Set $\mathrm{CH} 2, \mathrm{CH} 3$, and CH 4 VERTICAL MODE On (CH 1 off).
e. CHECK-display amplitude is 0.1 division or less, excluding trace width, on the $\mathrm{CH} 2, \mathrm{CH} 3$, and CH 4 traces.
f. Move sine-wave generator signal to the CH 2 input.
g. Set:
$\mathrm{CH} 1, \mathrm{CH} 3$, and CH 4 VERTICAL MODE TRIGGER SOURCE

On (CH 2 off) CH 2
h. CHECK-display amplitude is 0.1 division or less, excluding trace width, on the $\mathrm{CH} 1, \mathrm{CH} 3$, and CH 4 traces.
i. Move sine-wave generator signal to the CH 3 input.
j. Set:
$\mathrm{CH} 1, \mathrm{CH} 2$, and CH 4 VERTICAL MODE

On (CH 3 off) TRIGGER SOURCE CH 3
k. CHECK-display amplitude is 0.1 division or less, excluding trace width, on the $\mathrm{CH} 1, \mathrm{CH} 2$, and CH 4 traces.
I. Move sine-wave generator signal to the CH 4 input.
m. Set:
$\mathrm{CH} 1, \mathrm{CH} 2$, and CH 3 VERTICAL MODE

On (CH 4 off)
TRIGGER SOURCE
CH 4
n. CHECK-display amplitude is 0.1 division or less, excluding trace width, on the $\mathrm{CH} 1, \mathrm{CH} 2$, and CH 3 traces.
o. Disconnect the test setup.
21. AC-Coupled Lower -3 dB Point
a. Set:

| A SEC/DIV | 10 ms |
| :--- | :--- |
| VERTICAL MODE | CH 1 (all others |
|  | off) |
| TRIGGER SOURCE | VERT |
| TRIGGER MODE | NORM |
| TRIGGER HOLDOFF | Fully CW |

b. Connect function generator (FG 502) output to the CH 1 input via a $50 \Omega$ BNC coaxial cable and a $50 \Omega \mathrm{BNC}$ termination.
c. Set the function generator output controls to produce a six-division sine-wave display at 10 Hz (with no dc offset).
d. Set CH 1 Input COUPLING to AC .
e. CHECK-display amplitude is 4.2 divisions or more.
f. Set VERTICAL MODE to CH 2 (CH 1 off).
g. Repeat the procedure for CH 2 .
h. Disconnect the test equipment from the 2245A.
22. Vertical ALT and CHOP Modes
a. Set:

| VERTICAL MODE | $\begin{aligned} & \mathrm{CH} 1, \mathrm{CH} 2 \text {, } \\ & \mathrm{CH} 3, \mathrm{CH} 4 \mathrm{On} \end{aligned}$ |
| :---: | :---: |
| CHOP VERTICAL MODE | Off (ALT mode) |
| CH 1 and CH 2 |  |
| VOLTS/DIV | 10 mV |
| CH 3 and CH 4 |  |
| VOLTS/DIV | 0.1 V |
| CH 1 and CH 2 Input |  |
| COUPLING | DC |


| Horizontal MODE | A |
| :--- | :--- |
| SEC/DIV | 1 ms |
| TRIGGER MODE | AUTO LEVEL |

b. Position all traces for two divisions of separation with the CH 1 trace near the top; then in order down the graticule area with the CH 4 trace near the bottom.
c. Set SEC/DIV to 10 ms .
d. CHECK-that four traces are sweeping across the screen alternately.
e. Set CHOP VERTICAL MODE On.
f. CHECK-that four traces are sweeping across the screen simultaneously.
23. BEAM FIND Functional Check
a. Push BEAM FIND in and hold.
b. CHECK-the signal is visible and compressed fully within the graticule area as the horizontal and vertical position controls are rotated through their ranges.
c. Release the BEAM FIND button.
d. Set all Vertical and Horizontal POSITION controls at the 12 o'clock position.
24. A and B Trace Separation
a. Set:

| A SEC/DIV | 1 ms |
| :--- | :--- |
| VERTICAL MODE | CH 1 (others |
|  | off) |
| Horizontal MODE | ALT |
| B SEC/DIV | 0.5 ms |
| A/B SELECT | B |
| B Trigger MODE | RUNS AFTER |
| TRACE SEP | Fully CW |

b. Position the CH 1 trace below the center horizontal graticule line to display the separated B trace.
c. CHECK-for at least four divisions of upward trace separation between the B trace and the A trace.
d. Set TRACE SEP fully CCW.
e. Position the CH 1 trace above the center horizontal graticule line to display the separated $B$ trace.
f. CHECK-for at least four divisions downward trace separation of the $B$ trace from the A trace.

## TRIGGERING

Equipment Required (See Table 4-1)<br>Leveled sine-wave generator Function generator<br>$50 \Omega$ BNC coaxial cable 10X BNC attenuator<br>2 X BNC attenuator $50 \Omega$ BNC termination<br>Dual-input coupler TV signal generator

1. 500 Hz Trigger Sensitivity
a. Set:

READOUT (Intensity)
A INTEN
VERTICAL MODE
SCOPE BW
CH 1 and CH 2 Input COUPLING CH 1 VOLTS/DIV Horizontal MODE A SEC/DIV Horizontal POSITION A/B SELECT TRIGGER MODE TRIGGER SOURCE TRIGGER CPLG trigger slope

TRIGGER HOLDOFF FOCUS

CLEAR MEAS'MT

For a viewable readout For a viewable trace
CH 1
On
DC
0.1 V

A
2 ms
12 o'clock
A Trigger AUTO LEVEL VERT
AC

- (positivegoing)
Min
For bestdefined display
Press to remove measurement cursors.
b. Connect function generator (FG 502) output to the CH 1 input via a $50 \Omega \mathrm{BNC}$ coaxial cable and a $50 \Omega$ BNC termination.
c. Set function generator (FG 502) output to produce a 7.0 division sine-wave display at 500 Hz .
d. Add a $10 \times$ and a $2 \times$ BNC attenuator before the $50 \Omega$ BNC termination (for a 0.35 division display).


## NOTE

The TRIGGER LEVEL control may be used to obtain a stable display.
e. CHECK-that the display is stably triggered with DC, HF REJ, and AC Trigger CPLG; and that the display will not trigger on NOISE REJ or LF REJ Trigger CPLG.
f. Set:

| Horizontal MODE | B |
| :---: | :---: |
| TRIGGER CPLG | DC |
| A/B SELECT | B Trigger |
| TRIGGER MODE | NORM |
| tRigGer Source | VERT |
| TRIGGER SLOPE | - (positivegoing) |
| B SEC/DIV | 0.5 ms |
| DELAY Time | $? 0.000 \mathrm{~ms}$ (minimum delay time) |
| B INTEN | For viewable display |

It may be necessary to adjust the TRIGGER LEVEL control to obtain a display.
g. CHECK-that, using the Trigger LEVEL control, the display can be stably triggered in DC, HF REJ, and AC Trigger CPLG; and that the display cannot be triggered in NOISE REJ or LF REJ Trigger CPLG.
h. Disconnect the test setup from the CH 1 input.

## 2. 500 kHz Trigger Sensitivity

a. Set:
SCOPE BW
Horizontal MODE
A/B SELECT
Off
A SEC/DIV
A
A Trigger
$2 \mu s$
b. Connect leveled sine-wave generator (SG 503) output to the CH 1 input via a $50 \Omega \mathrm{BNC}$ coaxial cable and a $50 \Omega$ BNC termination.
c. Set leveled sine-wave generator output to produce a 7.0 division sine-wave display amplitude at 500 kHz .
d. Add a 10 X and a 2 X BNC attenuator before the $50 \Omega$ BNC termination (for a 0.35 division display amplitude).
e. CHECK—that the display cannot be triggered in either HF REJ of NOISE REJ CPLG.
f. Set:

| Horizontal MODE | B |
| :--- | :--- |
| A/B SELECT | B Trigger |
| B SEC/DIV | $1 \mu \mathrm{~s}$ |

g. CHECK-that the display cannot be triggered in HF REJ or NOISE REJ CPLG by adjusting the Trigger LEVEL control.
3. 25 MHz Trigger Sensitivity
a. Set:

| Horizontal MODE | A |
| :--- | :--- |
| A/B SELECT | A Trigger |
| TRIGGER CPLG | DC |
| A SEC/DIV | 50 ns |

b. Remove the 10X and 2 X BNC attenuators from the signal path.
c. Set leveled sine-wave generator output to produce a 7.0 division display amplitude at 25 MHz .
d. Add a 10X and a 2 X BNC attenuator before the $50 \Omega$ BNC termination.
e. CHECK-that the display is stably triggered in DC, LF REJ, and AC Trigger CPLG; the display is not triggered in NOISE REJ and HF REJ Trigger CPLG settings.
f. Set:

| TRIGGER CPLG | AC |
| :--- | :--- |
| Horizontal MODE | B |
| A/B SELECT | B Trigger |
| B SEC/DIV | 20 ns |

g. CHECK—that, using the Trigger LEVEL control, the display can be stably triggered in DC, LF REJ, and AC Trigger CPLG; the display cannot be triggered in NOISE REJ and HF REJ Trigger CPLG settings.
h. Set leveled sine-wave generator (SG 503) to produce a 1.4 division display at 25 MHz .
i. CHECK-that the display can be stably triggered with NOISE REJ Trigger CPLG but does not trigger with HF REJ CPLG.
j. Set:

| Horizontal MODE | A |
| :--- | :--- |
| A/B SELECT | A Trigger |

k. CHECK-that the display is stably triggered with NOISE REJ Trigger CPLG but does not trigger with HF REJ CPLG. (The Trigger LEVEL control may be adjusted to improve display stability in NOISE REJ CPLG.)
4. 150 MHz Trigger Sensitivity
a. Set:

TRIGGER MODE AUTO
TRIGGER CPLG
DC
b. Set leveled sine-wave generator to produce a 1.0 division display at 150 MHz .
c. CHECK-that the display is stably triggered in DC, LF REJ, and AC Trigger CPLG; the display is not triggered in NOISE REJ and HF REJ Trigger CPLG.
d. Set:

| Horizontal MODE | B |
| :--- | :--- |
| A/B SELECT | B Trigger |

e. CHECK-that, using the Trigger LEVEL control, the display can be stably triggered in DC, LF REJ, and AC Trigger CPLG; the display cannot be triggered in NOISE REJ and HF REJ Trigger CPLG.
f. Set:

Horizontal MODE
A VERTICAL MODE $\mathrm{CH} 2, \mathrm{CH} 3$, and CH 4 VOLTSIDIV A/B SELECT TRIGGER CPLG
$\mathrm{CH} 2(\mathrm{CH} 1$ off)
0.1 V

A Trigger
DC
g. Move test signal from CH 1 to the CH 2 input.
h. Set leveled sine-wave generator output to produce a 1.0 division display amplitude at 150 MHz .
i. CHECK-that a stable display can be obtained. (The Trigger LEVEL control may be adjusted to improve the display stability.)
j. Repeat the procedure for CH 3 and CH 4 (turn on the appropriate VERTICAL MODE and move the test signal as required).
k. Move test signal to the CH 1 input.
I. Set VERTICAL MODE to CH 1 (others off).
m . Remove the 2 X BNC attenuator from the test signal path.
n. Set leveled sine-wave generator output for a 2.2 division display amplitude at 100 MHz .
0. CHECK-that the display is stably triggered with NOISE REJ Trigger CPLG but is not triggered with HF REJ Trigger CPLG.
p. Set:

| TRIGGER CPLG | DC |
| :--- | :--- |
| Horizontal MODE | B |
| A/B SELECT | B Trigger |

q. Repeat 100 MHz NOISE REJ Trigger CPLG procedure for the B Trigger.
5. Single Sweep Mode
a. Set:

Horizontal MODE
A/B SELECT TRIGGER MODE

## A

$10 \mu \mathrm{~s}$
A Trigger
AUTO LEVEL
b. Remove the 10X BNC attenuator from the test signal path.
c. Set leveled sine-wave generator output to produce a 7.0 division display amplitude at 50 kHz .
d. Add a 10X and a 2 X BNC attenuator before the $50 \Omega$ BNC termination. (Display should stably trigger with AUTO LEVEL finding the correct trigger level setting.)
e. Set:
A TRIGGER MODE
NORM
CH 1 Input COUPLING GND
TRIGGER MODE
SGL SEQ
f. CHECK-that the Trigger READY LED turns on and remains on.
g. Set:
A INTEN
$3 / 4$ fully CW
CH 1 Input COUPLING
DC (see
CHECK below)
h. CHECK-that the TRIG'D LED flashes, and the READY LED turns off after a single sweep and readout display occurs when the Input COUPLING switches to DC.

## 6. Trigger LEVEL Control Range

a. Set:

TRIGGER MODE
AUTO (not AUTO LEVEL)
TRIGGER LEVEL A INTEN

Fully CCW
For a good viewing intensity
b. Remove 10 X and 2 X BNC attenuators from the test signal path.
c. Reduce leveled sine-wave generator output level until a stably triggered display is just obtainable.
d. Set TRIGGER LEVEL fully CW.
e. Set leveled sine-wave generator output for a stable display (if necessary).
f. Set CH 1 VOLTS/DIV to 1 V . .
g. CHECK-that the CH 1 signal display amplitude is four divisions or more (peak-to-peak). Note that the signal is not triggered.
h. Disconnect the test setup from the 2245A.
7. TV Field Trigger Sensitivity
a. Set:

| VERTICAL MODE | $\mathrm{CH} 2(\mathrm{CH} 1$ off) |
| :--- | :--- |
| CH 2 VOLTS/DIV | 2 V |
| SEC/DIV | 0.2 ms |
| TRIGGER SLOPE | 2oing) |
|  | gegative- |
| TRIGGER MODE | TV FIELD |

b. Connect TV signal generator negative-going sync pulse output to the CH 1 input via a $50 \Omega$ BNC cable.
c. Set CH 2 VAR VOLTS/DIV control for a 0.5 division composite sync signal.
d. CHECK—that a stable display is obtained.
e. Set:

CH 2 INVERT TRIGGER SLOPE

On
$\sim$ (positivegoing)
f. CHECK—that a stable display is obtained.
8. TV Line Trigger Sensitivity
a. Set:

SEC/DIV
TRIGGER MODE TRIGGER HOLDOFF
$20 \mu \mathrm{~s}$
TV LINE For a single triggered display
b. CHECK—that a stable display is obtained.
c. Set:
CH 2 INVERT
TRIGGER SLOPE
Off ㄴ (negativegoing)
d. CHECK-that a stable display is obtained.
e. Set CH 2 VAR VOLTS/DIV to detent position (calibrated).
f. Disconnect the TV signal generator from the 2245A.
9. Line Trigger Functional Check
a. Set:

| CH 2 VOLTS/DIV | 0.1 V (without <br> a $10 \times$ probe <br> attached) |
| :--- | :--- |
|  | DC |
| CH 2 Input COUPLING | 5 ms |
| A SEC/DIV | AUTO LEVEL |
| TRIGGER MODE | LINE |
| TRIGGER SOURCE | DC |

b. Connect a 10X probe to the CH 2 input connector.
c. CHECK-that the display can be triggered in both $\sim$ (positive-going) and $\neg$ (negative-going) slopes.
d. Disconnect the test setup.

## HORIZONTAL

```
Equipment Required (See Table 4-1)
    Time-mark generator
    50\Omega BNC coaxial cable
    50\Omega BNC termination
```


## 1. $A$ and $B$ Sweep Length

a. Set:

READOUT (Intensity)
A INTEN
VERTICAL MODE
CH 1 and CH 2
Input COUPLING
CH 1 VOLTS/DIV
Horizontal MODE
A SEC/DIV
Horizontal POSITION
A/B SELECT
TRIGGER MODE
trigger source
TRIGGER CPLG
TRIGGER SLOPE
TRIGGER HOLDOFF
TRIGGER LEVEL
CLEAR MEAS'MT

FOCUS

For a viewable readout
For a viewable trace
CH 1
DC
0.5 V

A
2 ms
12 o'clock
A Trigger
AUTO LEVEL
VERT
AC
$\sim$ (positivegoing)
Min
12 o'clock
Press to remove measurement cursors.
For bestdefined display
b. Connect time-mark generator (TG 501) to the CH 1 input via a $50 \Omega$ BNC coaxial cable and a $50 \Omega$ BNC termination.
c. Set generator for 2 ms time markers.
d. CHECK-sweep length of the A trace is greater than 10 divisions.
e. Set:

| Horizontal MODE | B |
| :--- | :--- |
| B SEC/DIV | 1 ms |
| A/B SELECT | B Trigger |
| TRIGGER MODE | RUNS AFTER |
| K OR DELAY Control | CCW to |
|  | the lowest |
|  | DELAY readout |
| B INTEN | value |
|  | For a visible |
|  | display |

f. CHECK-the Delay Time readout is 30.000 ms , and the B Sweep length is greater than 10 divisions.
2. Horizontal POSITION Range
a. Set:

| Horizontal MODE | A |
| :--- | :--- |
| Horizontal POSITION | Fully CW |

b. CHECK-that the start of trace positions past the center vertical graticule line.
c. Set Horizontal POSITION fully CCW.
d. CHECK-that the 11 th time marker is positioned to the left of the center vertical graticule line.
3. VAR SEC/DIV Range
a. Set:

| SEC/DIV | 1 ms |
| :--- | :--- |
| SEC/DIV VAR | Fully CCW |
| Horizontal POSITION | $120^{\prime}$ clock |

b. Set time-mark generator for 5 ms time markers.
c. CHECK-the time-marker spacing is equal to or less than two divisions.
d. Set SEC/DIV VAR fully CW (calibrated detent).
4. Magnifier Registration
a. Set X10 MAG on.
b. Position a time marker to the center vertical graticule line.
c. Set $\times 10$ MAG off.
d. CHECK-for less than 0.5 division horizontal trace shift.
5. $A$ and $B$ Timing Accuracy and Linearity
a. Set A SEC/DIV to 20 ns .
b. Set time-mark generator for 20 ns time markers.
c. Position the time marker peaks vertically to the center horizontal graticule line (allows use of the minor division graticule markings as an aid in making the accuracy checks).
d. Position the second time marker to the second vertical graticule line.
e. Repeat the procedure for all other SEC/DIV settings. Use Table 4-3, Settings for Timing Accuracy Checks, for the SEC/DIV and timemark generator settings.
f. Set SEC/DIV to 20 ns .
g. Set time-mark generator for 20 ns time markers.
h. Set:

| Horizontal MODE <br> B INTEN | B <br> For a viewable <br> display |
| :--- | :--- |
| Repeat the CHECK procedure for all the B <br> SEC/DIV settings. |  |

6. $A$ and $B$ Magnified Timing Accuracy and Linearity
a. Set time-mark generator for 5 ns time markers.
b. Set:

| Horizontal MODE | A |
| :--- | :--- |
| A SEC/DIV | 20 ns |
| Horizontal MODE | B |
| B SEC/DIV | 20 ns |
| X10 MAG | On (for $2 \mathrm{~ns} /$ |
|  | div sweep |
|  | speed) |
| CH 1 VOLTS/DIV | 0.5 V (use |
|  | 0.2 V for the |
|  | 5 ns time |
|  | markers if |
|  | necessary) |

## NOTE

In the following checks, for magnified SEC/ DIV settings between 2 ns and 20 ns , set the fifth or sixth time marker from the start of the sweep to the second vertical graticule line. For the SECIDIV settings between 50 ns and $50 \mathrm{~ms}(0.5 \mathrm{~ms}$ for $B$ Sweep), position the leading edge of the second time marker to the second graticule line.
C. Align the rising edge of the fifth or sixth time marker from the start of the sweep with the second vertical graticule line (center the display vertically).
d. CHECK-that the rising edge of the fourth displayed time marker crosses the center horizontal graticule line at between 8.27 divisions and 8.73 divisions.
e. CHECK—the linearity is within 0.1 division over any 2.5 divisions of the center eight divisions. Exclude any portion of the sweep past the 100th magnified division.
f. Set SEC/DIV to 5 ns .
g. Align the correct time marker to the second vertical graticule line (see NOTE above).
h. CHECK-that the tenth displayed time marker is within 0.24 division (left or right) of the tenth graticule line.

Table 4-3
Settings for Timing Accuracy Checks

| SEC/DIV Setting |  | Time-Mark Setting |  |
| :---: | :---: | :---: | :---: |
| Normal | X10 MAG | Normal | X10 MAG |
| $\begin{aligned} & 20 \mathrm{~ns} \\ & 50 \mathrm{~ns} \end{aligned}$ | $\begin{aligned} & 2 \mathrm{~ns} \\ & 5 \mathrm{~ns} \end{aligned}$ | 20 ns 50 ns | $\begin{aligned} & 5 \mathrm{~ns} \\ & 5 \mathrm{~ns} \end{aligned}$ |
| $0.1 \mu \mathrm{~s}$ | 10 ns | 0.1 ns | 10 ns |
| $0.2 \mu \mathrm{~s}$ | 20 ns | $0.2 \mu \mathrm{~s}$ | 20 ns |
| $0.5 \mu \mathrm{~s}$ | 50 ns | $0.5 \mu \mathrm{~s}$ | 50 ns |
| $1 \mu s$ | $0.1 \mu \mathrm{~s}$ | $1 \mu \mathrm{~s}$ | $0.1 \mu \mathrm{~s}$ |
| $2 \mu s$ | $0.2 \mu \mathrm{~s}$ | $2 \mu s$ | $0.2 \mu \mathrm{~s}$ |
| $5 \mu \mathrm{~s}$ | $0.5 \mu \mathrm{~s}$ | $5 \mu \mathrm{~s}$ | $0.5 \mu \mathrm{~s}$ |
| $10 \mu \mathrm{~s}$ | $1 \mu \mathrm{~s}$ | $10 \mu \mathrm{~s}$ | $1 \mu \mathrm{~s}$ |
| $20 \mu \mathrm{~s}$ | $2 \mu s$ | $20 \mu \mathrm{~s}$ | $2 \mu s$ |
| $50 \mu \mathrm{~s}$ | $5 \mu \mathrm{~s}$ | $50 \mu \mathrm{~s}$ | $5 \mu \mathrm{~s}$ |
| 0.1 ms | $10 \mu \mathrm{~s}$ | 0.1 ms | $10 \mu \mathrm{~s}$ |
| 0.2 ms | $20 \mu \mathrm{~s}$ | 0.2 ms | $20 \mu \mathrm{~s}$ |
| 0.5 ms | $50 \mu \mathrm{~s}$ | 0.5 ms | $50 \mu \mathrm{~s}$ |
| 1 ms | 0.1 ms | 1 ms | 0.1 ms |
| 2 ms | 0.2 ms | 2 ms | 0.2 ms |
| 5 ms | 0.5 ms | 5 ms | 0.5 ms |
| A Sweep only |  |  |  |
| 10 ms | 1 ms | 10 ms | 1 ms |
| 20 ms | 2 ms | 20 ms | 2 ms |
| 50 ms | 5 ms | 50 ms | 5 ms |
| 0.1 s | 10 ms | 0.1 s | 10 ms |
| 0.2 s | 20 ms | 0.2 s | 20 ms |
| 0.5 s | 50 ms | 0.5 s | 50 ms |

i. CHECK-that the linearity accuracy is 0.1 division over any two of the center eight divisions. (Exclude any portion of the sweep past the 100th magnified division for SEC/DIV settings of 5 ns through 20 ns .)
j. Repeat the timing and linearity checks for all SEC/DIV settings between 20 ns and 0.5 s . Use the SEC/DIV and Time Mark Generator X10 MAG settings given in Table 4-3.
k. Set:

Horizontal MODE SEC/DIV

A
2 ns (with $\times 10$ MAG on)

1. Set time-mark generator for 5 ns time markers.
m . Repeat the magnified accuracy and linearity checks for the A Sweep at all SEC/DIV settings.

## 7. Delay Time Jitter

a. Set:
$\times 10 \mathrm{MAG}$
A SEC/DIV
Horizontal MODE B SEC/DIV

Off
1 ms
ALT
$0.5 \mu \mathrm{~s}$
b. Set the time-mark generator for 1 ms time markers.
C. Position the intensified dot to the leading edge of the 10th time marker to display the rising edge on the $B$ Trace (using the $\leftarrow$ OR DELAY control).
d. Set:

Horizontal MODE
B INTEN

## B

Fully CW (maximum intensity)
d. CHECK—that the jitter on the leading edge does not exceed one division over a two-second interval. Disregard slow drift.
8. Delay Time Accuracy
a. Set:

| Horizontal MODE | ALT |
| :--- | :--- |
| B SEC/DIV | $10 \mu \mathrm{~s}$ |
| TRACE SEP | Fully CCW |
|  | (maximum <br> downward |
|  | position) <br> CH 1 POSITION <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br> To display both <br> and the B <br> and <br> Delayed Traces |

b. Position the first time marker on the ALT trace to first vertical graticule line (left-most edge).
c. Position the intensified dot to full left position (counterclockwise rotation of the $\vDash \leftarrow O R$ DELAY control).
d. CHECK -that the readout is $? 0.000 \mathrm{~ms}$.
e. Position the intensified zone to the second time marker and align the leading edge of the time marker displayed on the B Trace to the left-most (first) graticule line. Using the Readout Accuracy Limits given in Table 4-4, check the delay time accuracy.
f. Repeat the procedure for the third through 10th time markers.

## Table 4-4

Delay Time Accuracy

| Time Marker | Readout Accuracy Limits |
| :---: | :--- |
| 1st | $? 0.000 \mathrm{~ms}$ |
| 2nd | 0.975 ms to 1.025 ms |
| 3rd | 1.970 ms to 2.030 ms |
| 4th | 2.965 ms to 3.035 ms |
| 5th | 3.960 ms to 4.040 ms |
| 6th | 4.955 ms to 5.045 ms |
| 7th | 5.950 ms to 6.050 ms |
| 8th | 6.945 ms to 7.055 ms |
| 9th | 7.940 ms to 8.060 ms |
| 10th | 8.935 ms to 9.065 ms |

## 9. Delay Time Position Range

a. Set time-mark generator for 0.1 ms .
b. Set:
A SEC/DIV
1 ms
B SEC/DIV
$K$ OR DELAY control
$5 \mu \mathrm{~s}$
$? 0.000 \mathrm{~ms}$
c. CHECK-that the intensified dot is positioned at or before the second time marker.
d. Turn the $k$ OR DELAY control clockwise until the delay readout stops increasing (largest number).
e. CHECK-that the intensified dot is positioned at or after the 99th time marker (located at a Delay Time of 9.9 ms ).
f. Disconnect the time-mark generator from the 2245A.
10. X-Axis Gain Accuracy
a. Set:

| Horizontal MODE | X-Y |
| :--- | :--- |
| VERTICAL MODE | CH 2 (CH 1 off) |
| CH 1 and CH 2 |  |
| VOLTS/DIV | 10 mV |
| CH 1 Input COUPLING | DC |
| CH 2 Input COUPLING | GND |

b. Connect calibration generator Std Ampl output to the CH 1 and CH 2 inputs via a $50 \Omega$ precision BNC coaxial cable and a BNC dual-input coupler.
c. Set calibration generator for Std Ampl output, 50 mV .
d. CHECK-X-Axis amplitude is between 4.85 and 5.15 horizontal divisions.
e. Disconnect calibration generator.

## 11. X-Y Phase Difference

a. Set:

| HORIZONTAL MODE | A |
| :--- | :--- |
| VERTICAL MODE | CH 1 (CH 2 off) |
| CH 1 input COUPLING | DC |

b. Connect leveled sine-wave generator output to the CH 1 input via a $50 \Omega \mathrm{BNC}$ coaxial cable and a $50 \Omega \mathrm{BNC}$ termination.
c. Set leveled sine-wave generator output for six divisions of signal display amplitude at 50 kHz .
d. Set:

| Horizontal MODE | $X-Y$ |
| :--- | :--- |
| CH 1 Input COUPLING | GND |

e. Position dot to graticule center.
f. Set CH 1 Input COUPLING to DC.
g. CHECK-ellipse opening at the center is 0.3 division or less, measured horizontally.
12. X-Axis Bandwidth
a. Set VERTICAL MODE to CH 2 (CH 1 off).
b. Set leveled sine-wave generator output frequency to 3 MHz .
c. CHECK-X-Axis display is 4.2 horizontal divisions or more.
d. Disconnect the test equipment from the 2245 A .

## MEASUREMENT CURSORS

```
Equipment Required (See Table 4-1)
    Time mark generator Calibration generator
    50\Omega BNC coaxial cable 50\Omega BNC termination
```

1. $K$ SEC $\rightarrow 1$ and $k 1$ SEC $\rightarrow$ Cursor Accuracy
a. Set:

READOUT (Intensity)
A INTEN
VERTICAL MODE
CH 1 VOLTS/DIV
CH 1 and CH 2
Input COUPLING
CH 2 INVERT
SCOPE BW
Horizontal MODE
A SEC/DIV
A/B SELECT
TRIGGER MODE
TRIGGER CPLG
TRIGGER SOURCE
TRIGGER SLOPE
TRIGGER HOLDOFF
FOCUS

For a viewable readout
For a viewable trace
CH 1
0.5 V

DC
Off
Off
A
1 ms
A Trigger
AUTO LEVEL
DC
VERT
I (positivegoing)
Min
For best defined display
b. Connect time-mark generator (TG 501) output via a $50 \Omega$ BNC coaxial cable and a $50 \Omega$ BNC termination to the CH 1 input.
c. Set time-mark generator for 1 ms time markers.
d. Position first time marker horizontally to the first vertical graticule line (left-most edge of the graticule).
e. Press TIME MEASUREMENTS button to display the $K-$ SEC $\rightarrow \mid$ cursors.
f. Position the reference cursor to the first time marker and the delta cursor to the second time marker.
g. CHECK-that the readout is 0.975 ms to 1.025 ms .
h. Press the $1 /$ TIME MEASUREMENTS button to display the $\leqslant 1 /$ SEC $\rightarrow$ cursors.
i. CHECK-that the readout is 0.975 kHz to 1.025 kHz .
j. Position the delta cursor to align with the 11 th time mark.
k. CHECK-that the readout is 99.7 Hz to 100.7 Hz .

1. Press the TIME button to display the $K$ SEC $\rightarrow$ I cursors.
m . CHECK-that the readout is between 9.930 ms and 10.070 ms .
2. $\leftarrow$ VOLTS $\rightarrow$ Cursor Accuracy
a. Set:
CH 1 VOLTS/DIV
0.1 V
SEC/DIV
0.5 ms
b. Connect calibration generator (PG 506) output to the CH 1 input via a $50 \Omega$ precision BNC coaxial cable.
c. Set the calibration generator to Std Ampl, 0.5 V .
d. Position bottom of the signal to the second horizontal graticule line from the bottom.
e. Press the CURSOR VOLTS button to display the $\leftarrow$ VOLTS $\rightarrow \mid$ cursors.
f. Position the reference cursor to the bottom of the signal and the delta cursor to the top of the signal (both cursors move with the $k$ OR DELAY control).
g. CHECK-that the readout is between 0.495 V to 0.505 V .
h. Disconnect calibration generator.

# EXTERNAL Z-AXIS, PROBE ADJUST AND AUTO SETUP FUNCTIONS 

\author{

Equipment Required (See Table 4-1) <br> | Calibration Generator | BNC T-connector |
| :--- | :--- |
| Two $50 \Omega$ BNC coaxial cable | Test ocsilloscope |
| $50 \Omega$ precision BNC coaxial cable | with a $10 X$ probe |

}

1. Check External Z-Axis Input
a. Set:

READOUT (Intensity)
A INTEN
VERTICAL MODE
CH 1 VOLTS/DIV
CH 2 INVERT
SCOPE BW
CH 1 Input COUPLING
Horizontal MODE
A SEC/DIV
Horizontal POSITION
A/B SELECT
TRIGGER MODE
TRIGGER CPLG
trigger source
TRIGGER SLOPE
TRIGGER HOLDOFF
FOCUS

For a viewable readout
For a viewable trace
CH 1
1 V
Off
Off
DC
A
0.5 ms

12 o'clock
A Trigger
AUTO LEVEL
DC
VERT
$\Gamma$ (positive-
going)
Min
For best defined display
b. Connect calibration generator (PG 506) Std Ampl output to the CH 1 and the EXT Z-AXIS inputs via a $50 \Omega$ precision BNC coaxial cable, a BNC T-connector, and two $50 \Omega$ BNC coaxial cables. Set generator to Std Ampl output, 5 V .
c. CHECK-waveform display intensity has noticeable modulation at 3.8 V or less.
d. Disconnect the test equipment from the 2245A.
2. PROBE ADJUST Output
a. Set:

| CH 1 VOLTS/DIV | 10 mV |
| :--- | :--- |
| SEC/DIV | 0.2 ms |

b. Connect a 10 X probe to the CH 1 input connector and connect the probe tip to the 2245A PROBE ADJUST output. (When using Tektronix coded probes, the readout changes to . 1 V. )
c. CHECK-For a 5-division vertical display of PROBE ADJUST square-wave signal (squarewave period is typically 1 ms , within $25 \%$ ).
3. AUTO SETUP Functional Check
a. Set:

| CH 1 COUPLING | GND |
| :--- | :--- |
| CH 1 VOLTS/DIV | 2 mV |
| A SEC/DIV | 20 ns |

b. Press the AUTO SETUP button.
c. Check that the Probe Adjust waveform is stably displayed on the upper half of the crt.

# ADJUSTMENT PROCEDURE 

# IMPORTANT-PLEASE READ BEFORE USING THIS PROCEDURE 

## PURPOSE

This Adjustment Procedure returns the instrument to conformance with the Performance Requirements as listed in the specification tables in Section 1. Adjustments should be done only after the checks in the Performance Check Procedure (Section 4) have indicated a need for readjustment of the instrument.

## TEST EQUIPMENT REQUIRED

The test equipment listed in Table 4-1 (Section 4) is required to complete the Adjustment Procedure in this section and the Performance Check Procedure in Section 4. Test equipment specifications described in Table 4-1 are the minimum necessary to provide accurate results; you must use equipment that meets or exceeds these specifications. Detailed operating instructions for test equipment are not given in this procedure; if more operating information is required, refer to the appropriate test equipment instruction manual.

When equipment other than that recommended is used, control settings given for the test setup may have to be changed. If the exact item of equipment given as an example in Table 4-1 is not available, first check the "Use" column to verify use of the item. Then use the "Minimum Specification" column to decide whether other available test equipment can be used.

## LIMITS AND TOLERANCES

The limits and tolerances stated in this procedure are instrument specifications only if they are listed in the Performance Requirements column of Table 1-1, Electrical Characteristics. Tolerances given apply only to the instrument under adjustment and do not include test equipment error. Adjustments must be made at an ambient temperature between $+20^{\circ} \mathrm{C}$
and $+30^{\circ} \mathrm{C}$, and the instrument must have had a warm-up period of at least 20 minutes.

## PARTIAL PROCEDURES

This procedure is divided into subsections to permit adjustment of individual sections of the instrument (except the Power Supply) whenever a complete readjustment is not required. For example, if only the Vertical section fails to meet the Performance Requirements (or has had repairs made or components replaced), it can be readjusted with little or no effect on other sections of the instrument. However, if the Power Supply section has undergone repairs or adjustments that change the absolute value of any of the supply voltages, a complete readjustment of the instrument is required.

At the beginning of each subsection is a list of the initial front-panel control settings required to prepare the instrument for Step 1 in that subsection. Each succeeding step within a subsection should then be done completely and in the sequence given to ensure that control settings will be correct for steps that follow.

## INTERNAL ADJUSTMENTS AND ADJUSTMENT INTERACTION

Do not preset any internal controls, since that may make it necessary to recheck or readjust a major portion of the instrument when only a partial check or adjustment might otherwise have been required. To avoid unnecessary checks and adjustments, change an internal control setting only when a Performance Characteristic cannot be met with the original setting. When independently changing the setting of any internal control, always check Table $5-1$ for possible interacting adjustments that might be required.

Table 5-1
Adjustment Interactions


The use of Table 5-1 is particularly important if only a partial procedure is done or if a circuit requires readjustment due to a component replacement. To use this table, first find the adjustment that was made (extreme left column). Then move to the right, across the row, until you come to a darkened square. From the darkened square, move up the table to find the affected adjustment at the heading of that column. Check the accuracy of this adjustment by using the Performance Check Procedure in Section 4. Then, if necessary, make a readjustment.

Specific interactions are called out within some adjustment steps to indicate that the adjustments must be repeated until no further improvement is noted.

## PREPARATION FOR ADJUSTMENT

It is necessary to remove the cabinet to do the Adjustment Procedure. See the cabinet removal instructions in the Maintenance section of this manual.

All test equipment items required to do the complete Adjustment Procedure are described in Table 4-1 at the beginning of Section 4, Performance Check Procedure. The specific items of equipment needed to do each subsection in this procedure are listed at the beginning of that subsection.

Connect the test equipment and the 2245A to an appropriate ac-power source and allow 20 minutes warmup before making any adjustments.

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# POWER SUPPLY, DISPLAY, AND Z-AXIS 

## Equipment Required (See Table 4-1):

Digital multimeter (DMM) $\quad 50 \Omega$ coaxial cable
Leveled sine-wave generator
$50 \Omega$ termination
Test oscilloscope w/10X probe
at the back of this manual for test points and adjustment locations.

## INITIAL CONTROL SETTINGS

Set:

| VERTICAL MODE | CH 1 |
| :--- | :--- |
| CH 1 COUPLING | DC |
| VOLTSIDIV | 0.1 V |
| VERTICAL POSITION |  |
| Controls | $120^{\prime}$ clock |
| HORIZONTAL MODE | A |
| A/B SELECT | A |
| SEC/DIV | 0.1 ms |
| TRIGGER LEVEL | $120^{\prime}$ clock |
| HOLDOFF | Min (CCW) |
| SLOPE | - |
| TRIGGER MODE | AUTO LEVEL |
| TRIGGER SOURCE | CH 1 |
| TRIGGER COUPLING | DC |
| MEASUREMENTS | OFF |
| A INTEN | $10 o^{\prime}$ clock |
| READOUT | $120^{\prime}$ clock |
| FOCUS | For well-defined |
|  | display |
| SCALE ILLUM | Fully CCW |

## PROCEDURE

## 1. Power Supply DC Levels (R2252)

a. Connect a digital multimeter (DMM) negative lead to chassis ground. Connect the positive
lead to the first test point listed in Table 5-2 (all test points on J1204, Main board).
b. CHECK-Voltage reading is within the range given in Table 5-2.
c. Move DMM positive lead to each of the other supply voltages in Table 5-2 and check that voltage ranges are within limits.

## NOTE

If all supply voltages are within the limits given in Table 5-2, it is not necessary to adjust the power supply. If voltages are not within limits, you will have to adjust the +7.5 V supply, recheck the other voltages, and continue with a complete readjustment of the instrument.
d. Connect a digital multimeter (DMM) negative lead to chassis ground and positive lead to $+7.5 \vee$ test point (J2104-8).
e. ADJUST-+7.5 $\vee$ Adj (R2252) for $+7.5 \vee$ and check that all supply voltages in Table 5-2 are within limits. The +7.5 V Adjustment is accessible through the right side frame.
f. Disconnect digital multimeter.

Table 5-2
Power Supply Voltage Limits

| Nominal <br> Supply <br> Voltage | Test Point <br> ( + lead) | Limits <br> $\left(0^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right)$ <br> Min Max |
| :---: | :---: | :---: |
| +130 V | $\mathrm{~J} 1204-11$ | +127 to +135 |
| +58 V | $\mathrm{~J} 1204-10$ | +55.7 to +59.2 |
| +15 V | $\mathrm{~J} 1204-7$ | +14.6 to +15.6 |
| +7.5 V | $\mathrm{~J} 1204-8$ | +7.4 to +7.6 |
| +5.0 V | $\mathrm{~J} 1204-1,2$ | +5.0 to +5.3 |
| -5.0 V | $\mathrm{~J} 1204-5$ | -5.1 to -5.4 |
| -7.5 V | $\mathrm{~J} 1204-9$ | -7.4 to -7.8 |
| -15 V | $\mathrm{~J} 1204-6$ | -15.5 to -16.6 |

2. Grid Bias (R2719)
a. Set:

| HORIZ MODE | X-Y |
| :--- | :--- |
| CH 1 VOLTS/DIV | $5 V$ |
| CH 1 COUPLING | GND |
| SCOPE BW | On |
| A INTEN | Fully CCW (off) |
| B INTEN | Fully CCW (off) |
| READOUT (Intensity) | Fully CCW (off) |
| SCALE ILLUM | Fully CCW (off) |

b. ADJUST-Grid Bias (R2719) for a visible dot.
c. Position dot just off center screen with vertical or horizontal POSITION controls.
d. Set FOCUS control for a well-defined dot.
e. ADJUST-Grid Bias (R2719) so that dot is no longer visible.

## 3. Astigmatism (R2788)

a. Set:

| HORIZ MODE | A |
| :--- | :--- |
| A INTEN | $10 o^{\prime}$ clock |
| READOUT (Intensity) | $120^{\prime}$ clock |
| SEC/DIV | $5 \mu \mathrm{~s}$ |
| VAR SEC/DIV | Detent (fully CW) |
| CH 1 VOLTS/DIV | 10 mV |
| CH 1 COUPLING | DC |

b. Connect leveled sine-wave generator output to the CH 1 input connector via a $50 \Omega \mathrm{BNC}$ coaxial cable and a $50 \Omega$ BNC termination. Set for a 5 -division display at 50 kHz .
c. ADJUST-Astigmatism (R2788) together with front-panel FOCUS control for best overall resolution of the sine-wave display.
d. DISCONNECT-Leveled sine-wave generator.

## 4. Trace Rotation

a. Set CH 1 COUPLING to GND.
b. Position trace to center horizontal graticule line and beginning of trace to first vertical graticule line.
c. ADJUST-TRACE ROTATION (front panel) to align trace parallel with center horizontal graticule line.
5. Geometry (R2784)
a. Set:

| CH 1 VOLTS/DIV | 0.1 V |
| :--- | :--- |
| CH 1 COUPLING | DC |
| SEC/DIV | $50 \mu \mathrm{~s}$ |
| READOUT (intensity) | Fully CCW (off) |

b. Connect the time-mark generator to CH 1 via a $50 \Omega$ cable and a $50 \Omega$ termination. Display $10 \mu \mathrm{~s}$ time markers.
c. Position base trace below bottom graticule line.
d. ADJUST-Geometry (R2784) for minimum bowing of time markers across the full graticule area. Vertical bowing of time marker across screen should be no more than 0.1 division.
e. Disconnect time-mark generator.

## 6. Z-Axis Response (C2704)

a. Set:

| READOUT (Intensity) | $120^{\prime}$ 'clock |
| :--- | :--- |
| SEC/DIV | $5 \mu s$ |
| READOUT (Intensity) | Fully CCW (off) |

b. Connect test oscilloscope with 10X probe to R2718 (either side).
c. ADJUST-Z-Axis Response (C2704) for flattest response possible of the signal displayed by the test scope.
d. Disconnect test oscilloscope.
7. Readout Jitter (R724)
a. Set:
READOUT (intensity)
12 o'clock SEC/DIV 10 ms CH 1 COUPLING DC A INTEN Fully CCW (off)
b. Connect calibration generator to CH 1 input via $50 \Omega$ precision coaxial cable. Set generator for STD AMPL and 1 volt.
c. ADJUST-Readout Jitter (R724) for the least amount of jitter or sway in the readout.
d. Disconnect calibration generator.

## VERTICAL

## Equipment Required (See Table 4-1):

Calibration generator (PG 506)
Leveled sine-wave generator
$50 \Omega$ precision coaxial cable
$50 \Omega$ termination
Precision normalizer ( 20 pF )

See adjustment locations
at the back of this manual for test points and adjustment locations.

## INITIAL CONTROL SETTINGS

## Set:

| VERTICAL MODE | CH 1 and CH 2 |
| :--- | :--- |
| INPUT COUPLING | DC |
| VOLTS/DIV | 0.1 V |
| VERTICAL POSITION |  |
| COntrols | 12 o' $^{\prime}$ clock |
| HORIZONTAL MODE | A |
| A/B SELECT | A |
| SEC/DIV | 0.1 ms |
| TRIGGER LEVEL | $120^{\prime}$ clock |
| HOLDOFF | Min (CCW) |
| SLOPE | - |
| TRIGGER MODE | AUTO LEVEL |
| TRIGGER SOURCE | VERT |
| TRIGGER COUPLING | DC |
| MEASUREMENTS | OFF |
| A INTEN | 10 o'clock |
| READOUT | 12 o'clock |
| FOCUS | For well-defined |
|  | display |
| SCALE ILLUM | Fully CCW |

## PROCEDURE

1. Vertical Output Gain (R703) and Readout Vertical Centering (R260)
a. Run ADJUST VERTICAL OUTPUT routine.

Select the SERVICE MENU by pressing the CH 1 and CHOP/ALT VERTICAL MODE buttons at the same
time. Press the ADD (down-arrow button) four times to underline INTERNAL SETTINGS MENU, then press CH 2 (SELECT) button. Press ADD (down-arrow) button twice to underline ADJUST VERTICAL OUTPUT, then press CH 2 (RUN) button.

## NOTE

For this adjustment, the 2245A must be placed in the "normal" operating position to avoid incorrect alignment due to the effects of the earth's magnetic field.
b. ADJUST-Vertical Output Gain (R703) and Readout Vertical Centering (R260) alternately until dashed lines produced by the diagnostics are aligned with dotted lines on the graticule.
c. To end the ADJUST VERTICAL OUTPUT routine, either press the CLEAR MEAS'MT button or press CH 1 (END) and then press CH 4 (QUIT).
2. CH 1 Step Balance (R12)
a. Set:

| VERTICAL MODE | CH 1 (CH 2 off) |
| :--- | :--- |
| CH 1 COUPLING | GND |
| SCOPE BW | On |

b. Position trace to center horizontal graticule line.
c. ADJUST-CH 1 Step Balance (R12) so the trace does not move vertically while switching CH 1 VOLTS/DIV switch from 10 mV to 50 mV .

## 3. CH 2 Step Balance (R22)

a. Set:

## VERTICAL MODE CH 2 COUPLING <br> CH 2 (CH 1 off) GND

b. Position trace to center of graticule.
c. ADJUST-CH 2 Step Balance (R22) so that trace does not move vertically while switching CH 2 VOLTS/DIV switch from 10 mV to 50 mV .
4. CH 3 Step Balance (R141)
a. Set VERTICAL MODE to CH 3 ( CH 2 off).
b. Position trace to center of graticule.
c. ADJUST-CH 3 Step Balance (R141) so that trace does not move vertically while switching CH 3 VOLTS/DIV switch from $0.1 \vee$ to 0.5 V .
5. CH 4 Step Balance (R161)
a. Set VERTICAL MODE to $\mathrm{CH} 4(\mathrm{CH} 3$ off).
b. Position trace to center of graticule.
c. ADJUST-CH 4 Step Balance (R161) so that trace does not move vertically while switching CH 4 VOLTS/DiV switch from 0.1 V to 0.5 V .
6. CH $1 \mathrm{MF} / \mathrm{LF}$ Gain (R13) and Compensation (C1)
a. Set:

$$
\begin{array}{ll}
\text { VERTICAL MODE } & \text { CH } 1 \text { (CH } 4 \mathrm{off}) \\
\text { CH } 1 \text { VOLTS/DIV } & 50 \mathrm{mV} \\
\text { CH } 1 \text { COUPLING } & \text { DC } \\
\text { SEC/DIV } & 50 \mu \mathrm{~s}
\end{array}
$$

b. Connect calibration generator to CH 1 input via $50 \Omega \mathrm{BNC}$ coaxial cable and $50 \Omega$ BNC termination. Set generator for High Amplitude. Set Period to 10 kHz and adjust Pulse Amplitude for a 5-division display.
c. ADJUST-CH 1 MF/LF Gain (R13) and Compensation (C1) for the flattest response.
7. CH 1 Input Capacitance (C114)
a. Set:

CH 1 VOLTS/DIV
SEC/DIV
10 mV
0.2 ms
b. Add precision normalizer between termination and CH 1 input connector. Set calibration generator Period to 1 kHz and adjust Pulse Amplitude for a 5-division display.
c. ADJUST-CH 1 Input Capacitance (C114) for best flat top.
d. Remove precision normalizer from the input cable.
8. CH 1 Input Compensation X 10 (C11)
a. Set:

```
CH }1\mathrm{ VOLTS/DIV
0.1 V
SEC/DIV }50\mu\textrm{s
```

b. Set calibration generator Period to 10 kHz and adjust Pulse Amplitude for a 5-division display.
c. ADJUST-CH 1 Input Compensation X10 (C11) for flattest response.
9. CH 1 Input Compensation $\times 100$ (C10)
a. Set $\mathrm{CH} 1 \mathrm{VOLTS} / \mathrm{DIV}$ to 1 V .
b. Set calibration generator amplitude for a 5division display.
c. ADJUST-CH 1 Input Compensation X100 (C10) for flattest response.
10. CH 1 Gain (R211)
a. Set calibration generator to Standard Amplitude and Amplitude to 50 mV . Remove $50 \Omega$ termination from input cable.
b. Set:

c. ADJUST-CH 1 Gain (R211) for exactly 5 divisions display amplitude.
11. CH 2 MF/LF Gain (R23) and Compensation (C2)
a. Set:

| VERTICAL MODE | CH 2 (CH 1 off) |
| :--- | :--- |
| CH 2 VOLTS/DIV | 50 mV |
| CH 2 COUPLING | DC |
| SEC/DIV | $50 \mu \mathrm{~s}$ |
|  |  |
| Move calibration generator signal to CH 2 input. <br> Add $50 \Omega$ termination. |  |

b. Move calibration generator signal to CH 2 input. Add $50 \Omega$ termination.
c. Set calibration generator for High Amplitude. Set Period to 10 kHz and adjust Pulse Amplitude for a 5-division display.
d. ADJUST-CH 2 MF/LF Gain (R23) and Compensation (C2) for flattest response.
12. CH 2 Input Capacitance (C124)
a. Set:

| CH 2 VOLTS/DIV | 10 mV |
| :--- | :--- |
| SEC/DIV | 0.2 ms |

b. Add precision normalizer between termination and CH 2 input connector. Set calibration generator Period to 1 kHz and adjust Pulse Amplitude for a 5-division display.
c. ADJUST-CH 1 Input Capacitance (C124) for best flat top.
d. Remove precision normalizer from the input cable.
13. CH 2 Input Compensation X 10 (C21)
a. Set:

| CH 2 VOLTS/DIV | 0.1 V |
| :--- | :--- |
| SEC/DIV | $50 \mu \mathrm{~s}$ |

b. Set calibration generator Period to 10 kHz and adjust Pulse amplitude for a 5-division display.
c. ADJUST-CH 2 Input Compensation X10 (C21) for flattest response.
14. CH 2 Input Compensation $\times 100$ (C20)
a. Set $\mathrm{CH} 2 \mathrm{VOLTS} / \mathrm{DIV}$ to 1 V .
b. Set calibration generator amplitude for a 5division display.
c. ADJUST-CH 2 input Compensation X100 (C20) for flattest response.
15. CH 2 Gain (R221)
a. Set calibration generator to Standard Amplitude and Amplitude to 50 mV . Remove $50 \Omega$ termination from the input cable.
b. Set:

| CH 2 VOLTS/DIV | 10 mV |
| :--- | :--- |
| SEC/DIV | 0.2 ms |

c. ADJUST-CH 2 Gain (R221) for exactly 5 divisions display amplitude.
16. CH 3 MF/LF Compensation (C134)
a. Set:
VERTICAL MODE
CH 3 (CH 2 off)
CH 3 VOLTS/DIV SEC/DIV
0.1 V
$50 \mu \mathrm{~s}$
b. Move calibration generator signal to CH 3 input. Add $50 \Omega$ termination.
c. Set calibration generator for High Amplitude. Set Period to 10 kHz and adjust Pulse Amplitude for a 5-division display.
d. ADJUST-CH 3 MF/LF Compensation (C134) for flattest response.
17. CH 3 Gain (R231)
a. Set:
CH 3 VOLTS/DIV
0.5 V
SEC/DIV

$$
2 \mathrm{~ms}
$$

b. Set calibration generator for Standard Amplitude. Set amplitude to 2 V . Remove $50 \Omega$ termination.
c. ADJUST-CH 3 Gain (R231) for exactly 4 divisions display amplitude.
18. CH 4 MF/LF Compensation (C154)
a. Set:
VERTICAL MODE
CH 4 (CH 3 off)
CH 4 VOLTS/DIV
0.1 V
SEC/DIV
$50 \mu \mathrm{~s}$
b. Move calibration generator signal to CH 4 input. Add $50 \Omega$ termination.
c. Set calibration generator for High Amplitude. Set Period to 10 kHz and adjust Pulse Amplitude for a 5 -division display.
d. ADJUST-CH 4 MF/LF Compensation (C154) for flattest response.
19. CH 4 Gain (R241)
a. Set:
CH 4 VOLTS/DIV
0.5 V
SEC/DIV
0.2 ms
b. Set calibration generator for Standard Amplitude. Set amplitude to 2 V . Remove $50 \Omega$ termination.
c. ADJUST-CH 4 Gain (R241) for exactly 4 divisions display amplitude.
d. Disconnect calibration generator from CH 4.
e. Run the SELF CAL MEASUREMENTS routine (see "Self Characterization" near the end of this section).
20. Delay-Line HF Compensation (R272, R273, R275, C274, C273)
a. Set

VERTICAL MODE
CH 1 VOLTS/DIV
SEC/DIV
SCOPE BW

CH 1 (CH 4 off)
50 mV
20 ns
Off
b. Connect calibration generator positive-going Fast Rise Output to the CH 1 input via a $50 \Omega$ precision coaxial cable and a $50 \Omega$ termination.
c. Set calibration generator for Fast Rise at 1 MHz and adjust Pulse Amplitude for a 5-division display.
d. Position the top of display to the center horizontal graticule line.
e. ADJUST-Delay-Line HF Compensations (R272, R273, R275) for flattest response and (C274, C273) for sharpest front corner with minimum overshoot. Figure 5-1 shows the area of the waveform affected by each adjustment.


Figure 5-1. Areas of waveform affected by HF compensation adjustments.
21. CH 3 HF Compensation (C138)
a. Set:
VERTICAL MODE
CH 3 (CH 1 off)
CH 3 VOLTS/DIV
0.5 V
b. Move calibration generator signal to CH 3 . Set Pulse Amplitude to maximum to obtain about a 2.5-division display.
c. ADJUST-CH 3 HF Compensation (C138) for flattest response.
22. CH 4 HF Compensation (C158)
a. Set:
VERTICAL MODE
CH 4 VOLTS/DIV
CH 4 (CH 3 off) 0.5 V
b. Move calibration generator signal to CH 4.
c. ADJUST-CH 4 HF Compensation (C158) for flattest response.
d. Disconnect calibration generator.
23. CH 1 and CH2 Bandwidth Check
a. Set:
VERTICAL MODE
CH 1 (CH 4 off)
CH 1 VOLTSIDIV
2 mV SEC/DIV
0.1 ms
b. Connect leveled sine-wave generator output to the CH 1 input via a $50 \Omega$ precision coaxial cable and a $50 \Omega \mathrm{BNC}$ termination.
c. Set leveled sine-wave generator output for a six-division signal amplitude at 50 kHz .
d. Set the generator Frequency Range and Frequency Variable controls for an 80 MHz output signal.
e. CHECK-the displayed signal amplitude does not drop below 4.2 divisions as the frequency is increased to 90 MHz .
f. Repeat the frequency setup and CHECK procedure for VOLTS/DIV settings of 5 mV through 1 V , except perform CHECK at 100 MHz .

## NOTE

When checking bandwidth at a VOLTSIDIV setting of 1 V , use 5 divisions at 50 kHz and check for 3.5 divisions or more at 100 MHz .
g. Move the test signal to the CH 2 input.
h. Set
VERTICAL MODE
CH 2 (CH 1 off)
CH 2 VOLTS/DIV 2 mV
i. Repeat the complete bandwidth check procedure for Channel 2.
24. CH 3 and CH 4 Bandwidth Check
a. Set:

VERTICAL MODE
CH 3 (CH 2 off)
CH 3 VOLTSIDIV 0.1 V
b. Move the leveled sine-wave generator signal to the CH 3 input.
c. Set the generator output for a six-division signal display at 50 kHz .
d. Set the generator Frequency Range and Frequency Variable controls for a 90 MHz output frequency.
e. CHECK-signal display amplitude does not drop below 4.2 divisions as the frequency is increased to 100 MHz .
f. Repeat the procedure for 0.5 VOLTS/DIV setting.
g. Move the test signal to the CH 4 input.
h. Set:

VERTICAL MODE $\quad \mathrm{CH} 4$ (CH 3 off) CH 4 VOLTS/DIV 0.1 V
i. Repeat the procedure for CH 4.
j. Disconnect leveled sine-wave generator.

## HORIZONTAL

```
Equipment Required (See Table 4-1):
```

Time-mark generator
Calibration generator
$50 \Omega$ coaxial cable
$50 \Omega$ termination
at the back of this manual for test points and adjustment locations.

## INITIAL CONTROL SETTINGS

Set:

VERTICAL MODE
INPUT COUPLING
VOLTS/DIV
VERTICAL POSITION Controls
HORIZONTAL MODE A/B SELECT
SEC/DIV
TRIGGER LEVEL
HOLDOFF
SLOPE
TRIGGER MODE
TRIGGER SOURCE
TRIGGER COUPLING
MEASUREMENTS
A INTEN
READOUT
FOCUS
SCALE ILLUM

CH 1 and CH 2 (CH 4 off)
DC
0.1 V

12 o'clock
A
A
0.1 ms

12 o'clock
Min (CCW)
-
AUTO LEVEL
VERT
DC
OFF
10 o'clock
12 o'clock
For well-defined display
Fully CCW

## PROCEDURE

1. Horizontal X 1 Gain (Timing) (R826)
a. Set:

VERTICAL MODE
CH 1 VOLTS/DIV

CH 1 (CH 2 off)
0.5 V
b. Connect time-mark generator to CH 1 input via $50 \Omega$ BNC coaxial cable and $50 \Omega$ BNC termination. Set generator for 0.1 ms time markers.
c. Position display to center of screen.
d. ADJUST-Horizontal 1X Gain (R826) for one time marker per division over the center 8 divisions.
2. Horizontal $\times 10$ Gain (Timing) (R825)
a. Set $\times 10$ MAG to $O N$.
b. Set time-mark generator for $10 \mu \mathrm{~s}$ time markers.
c. Position display to center of screen.
d. ADJUST-Horizontal X10 Gain (R825) for one time marker per division over the center 8 divisions.
3. Readout Horizontal Gain (R823) and MAG Registration (R809)
a. Set:

X10 MAG
Off SEC/DIV 1 ms A INTEN CeW (off)
b. Press the TIME MEASUREMENTS button.
c. Rotate the $k$ OR DELAY control counterclockwise and the $\rightarrow 1$ control clockwise until cursors stop moving.
d. ADJUST-MAG Registration (R809) and Readout Horizontal Gain (R823) alternately until the reference cursor, lines up exactly with the left graticule line and the delta cursor lines up exactly with the right graticule line.
e. Press CLEAR MEAS'MT button to remove cursors from screen.
f. Set:
SEC/DIV
$20 \mu \mathrm{~s}$
A INTEN
10 o'clock
g. Set time-mark generator for 0.1 ms time markers.
h. Position rising edge of middle time marker to the center vertical graticule line.
i. Set X10 MAG to On.
j. INTERACTION-between MAG Registration and horizontal positioning of the time cursors. Check for less than 0.5 division shift of time-marker rising edge between MAG off and MAG on. If not within 0.5 division, recheck the accuracy of R809 and R823 adjustments; readjust if necessary.
4. A 20 ns Timing (C314)
a. Set:

| X10 MAG | Off |
| :--- | :--- |
| SEC/DIV | 20 ns |

b. Set time-mark generator for 20 ns time markers.
c. ADJUST-A 20 ns Timing (C314) for one time marker per division over the center 8 divisions.
5. B 20 ns Timing (C329)
a. Set:

| HORIZONTAL MODE | B |
| :--- | :--- |
| B SEC/DIV | 20 ns |
| B INTEN | 10 o'clock |

b. Set the time-mark generator for 20 ns time markers.
c. ADJUST-B 20 ns Timing (C329) for one time marker per division over the center 8 divisions.
6. 2 ns Timing (C807, C814)
a. Set:

| HORIZONTAL MODE | A |
| :--- | :--- |
| X10 MAG | On |
| CH 1 | 50 mV |
| CH 1 COUPLING | AC |

b. Set time-mark generator for 5 ns time marks.
c. ADJUST-2 ns Timing (C807, C814) for 1 cycle for each 2.5 divisions over the center 8 divisions. See Figure 5-2. Use the vertical transition of the sine wave instead of the peaks for better accuracy.
d. INTERACTION-between C807 and C814. Readjust as necessary to make the timing at $2.5,5$, and 7.5 divisions within +/-0.2 division (1 minor division).
e. Disconnect time-mark generator.


Figure 5-2. 2 ns Timing.
7. $X$ Gain (R827)
a. Set:

X10 MAG
Horizontal MODE VERTICAL MODE
CH 1 VOLTS/DIV

## Off

$X-Y$
CH 2 (CH 1 off) 10 mV
b. Connect calibration generator to CH 1 input via a $50 \Omega$ coaxial cable. Set generator for Standard Amplitude. Set Amplitude to 50 mV .
c. ADJUST-X Gain (R827) for 5 divisions of horizontal signal.
d. Disconnect calibration generator.

## SELF CHARACTERIZATION

## PROCEDURE

## 1. Self Characterization

a. Run the SELF CAL MEASUREMENTS routine. Press both the CH 1 and CHOP/ALT VERTICAL MODE buttons to display the SERVICE MENU. Press ADD (down-arrow) button three times to underline SELF CAL MEASUREMENTS. Press CH 2 (RUN) to start the routine.
b. Run MAKE FACTORY SETTINGS routine. Press ADD (down-arrow) to select INTERNAL SETTINGS MENU. Press CH 2 (SELECT) and then press ADD (down-arrow) to underline MAKE FACTORY SETTINGS. Press CH 2 (RUN) to start the routine. When done, press CH 4 (QUIT) or CLEAR MEAS'MT to return to normal oscilloscope mode.

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## MAINTENANCE

This section of the manual contains information on static-sensitive components, preventive maintenance, troubleshooting, and corrective maintenance. General information regarding the care and handling of semiconductor devices is provided in "Static-Sensitive Components," and routine cleaning and inspection are covered in "Preventive

Maintenance." Internal testing capabilities and diagnostic test routines are included in the "Troubleshooting" subsection. The "Corrective Maintenance" part of this section includes circuit board removal procedures, maintenance aids, and soldering techniques.

## STATIC-SENSITIVE COMPONENTS

The following precautions apply when performing any maintenance involving internal access to the instrument.

$\{$ CAUTION\}<br>Static discharge can damage any semiconductor component in this instrument.

This instrument contains electrical components that are susceptible to damage from static discharge. Table 6-1 lists the relative susceptibility of various classes of semiconductors. Static voltages of 1 kV to 30 kV are common in unprotected environments.

When performing maintenance, observe the following precautions to avoid component damage:

1. Minimize handling of static-sensitive components.
2. Transport and store static-sensitive components or assemblies in their original containers or on a metal rail. Label any package that contains static-sensitive components or assemblies.
3. Discharge the static voltage from your body by wearing a grounded antistatic wrist strap while handling these components. Servicing staticsensitive components or assemblies should be performed only at a static-free work station by qualified service personnel.

Table 6-1
Relative Susceptibility to Static-Discharge Damage

| Semiconductor Classes | Relative <br> Susceptibility <br> Levels $^{\text {a }}$ |
| :--- | :---: |
| MOS or CMOS microcircuits or <br> discretes, or linear microcircuits <br> with MOS inputs <br> (Most Sensitive) | 1 |
| ECL | 2 |
| Schottky signal diodes | 3 |
| Schottky TTL | 4 |
| High-frequency bipolar <br> transistors | 5 |
| JFET | 6 |
| Linear microcircuits | 7 |
| Low-power Schottky TTL | 8 |
| TTL <br> (Least Sensitive) | 9 |

${ }^{\text {a }}$ Voltage equivalent for levels (voltage discharged from a 100-pF capacitor through a resistance of 100 ) :

| $1=100$ to $500 \vee$ | $6=600$ to $800 \vee$ |
| :--- | :--- |
| $2=200$ to $500 \vee$ | $7=400$ to $1000 \vee$ (est) |
| $3=250 \vee$ | $8=900 \vee$ |
| $4=500 \vee$ | $9=1200 \vee$ |
| $5=400$ to $600 \vee$ |  |

4. Keep anything capable of generating or holding a static charge off the work station surface.
5. Keep the component leads shorted together whenever possible.
6. Pick up components by their bodies, never by their leads.
7. Do not slide the components over any surface.
8. Avoid handling components in areas that have a floor or work-surface covering capable of generating a static charge.
9. Use a soldering iron that is connected to earth ground.
10. Use only approved antistatic, vacuum-type desoldering tools for component removal.

## PREVENTIVE MAINTENANCE

## INTRODUCTION

Preventive maintenance consists of cleaning, inspection, and checking instrument performance. Preventive maintenance on a regular basis may prevent instrument malfunction and improve instrument reliability. The required frequency of maintenance depends on the severity of the environment in which the instrument is used. A good time to do preventive maintenance is just before instrument adjustment.

## INSPECTION AND CLEANING

Inspect and clean the 2245A as often as operating conditions require. Accumulation of dirt in the instrument can cause overheating and component breakdown. Dirt on components acts as an insulating blanket, preventing efficient heat dissipation. It also provides an electrical conduction path that could result in instrument failure, especially under highhumidity conditions


Do not use chemical cleaning agents which might damage the plastics used in this instrument. Use a nonresidue-type cleaner, preferably isopropyl alcohol or a solution of $1 \%$ mild detergent and $99 \%$ water. Before using any other type of cleaner, consult your Tektronix Service Center or representative.

## Exterior

INSPECTION. Inspect the external portions of the instrument for damage, wear, and missing parts; use Table 6-2 as a guide. Instruments that appear to have been dropped or otherwise abused should be checked thoroughly to verify correct operation and performance. Deficiencies that could cause personal injury or could lead to further instrument damage should be repaired immediately.

Do not allow moisture to get inside the instru-
ment during external cleaning. Use only
enough liquid to dampen the cloth or
applicator.

CLEANING. Loose dust on the outside of the instrument can be removed with a soft cloth or small softbristle brush. The brush is particularly useful on and around the controls and connectors. Remove remaining dirt with a soft cloth dampened in a mild detergent-and-water solution. Do not use abrasive cleaners.

Clean the light filters and the crt face with a soft lintfree cloth dampened with either isopropyl alcohol or a mild detergent-and-water solution.

## Interior

To clean or inspect the inside of the instrument, first refer to the Removal and Replacement Instructions in the Corrective Maintenance part of this section.

Table 6-2
External Inspection Checklist

| Item | Inspect For | Repair Action |
| :--- | :--- | :--- |
| Cabinet, Front Panel, and <br> Cover | Cracks, scratches, deformations, <br> damaged hardware or gaskets. | Touch up paint scratches and <br> replace defective components. |
| Front-panel controls | Missing, damaged, or loose knobs, <br> buttons, and controls. | Repair or replace missing or <br> defective items. |
| Connectors | Broken shells, cracked insulation, <br> and deformed contacts. Dirt in <br> connectors. | Replace defective parts. Clean or <br> wash out dirt. |
| Carrying Handle | Correct operation. | Replace defective parts. |
| Accessories | Missing items or parts of items, <br> bent pins, broken or frayed cables, <br> and damaged connectors. | Replace damaged or missing items, <br> frayed cables, and defective <br> parts. |

Table 6-3
Internal Inspection Checklist

| Item | Inspect For | Repair Action |
| :--- | :--- | :--- |
| Circuit Boards | Loose, broken, or corroded solder <br> connections. Burned circuit boards. <br> Burned, broken, or cracked <br> circuit-run plating. | Clean solder corrosion with an <br> eraser and flush with isopropyl <br> alcohol. Resolder defective con- <br> nections. Determine cause of <br> burned items and repair. Repair <br> defective circuit runs. |
| Resistors | Burned, cracked, broken, or <br> blistered. | Replace defective resistors. Check <br> for cause of burned component <br> and repair as necessary. |
| Solder Connections | Cold solder or rosin joints. | Resolder joint and clean with <br> isopropyl alcohol. |
| Capacitors | Damaged or leaking cases. <br> Corroded solder on leads or <br> terminals. | Replace defective capacitors, Clean <br> solder connections and flush with <br> isopropyl alcohol. |
| Semiconductors | Loosely inserted in sockets. <br> Distorted pins. | Firmly seat loose semiconductors. <br> Remove devices having distorted <br> pins. Carefully straighten pins (as <br> required to fit the socket), using |
| long-nose pliers, and reinsert |  |  |
| firmly. Ensure that straightening |  |  |
| action does not crack the pins, |  |  |
| causing them to break. |  |  |,

INSPECTION. Inspect the internal parts of the 2245A for damage and wear, using Table 6-3 as a guide. Repair any problems found immediately. The repair method for most visible defects is obvious, but take particular care if heat-damaged components are found. Since overheating usually indicates other trouble in the instrument, the cause of overheating must be found and corrected to prevent further damage.

If any electrical component is replaced, do a Performance Check for the affected circuit and for other closely related circuits (see Section 4 for the Performance Check). If repair or replacement work is done on any of the power supplies, do a complete Performance Check and, if so indicated, an instrument readjustment (see Section 5 for Adjustment Procedure).


To prevent damage from electrical arcing, ensure that circuit boards and components are dry before applying power to the instrument.

CLEANING. To clean the interior, blow off dust with dry, low-pressure air (approximately 9 psi). Remove any remaining dust with a soft brush or a cloth dampened with a solution of mild detergent and water. A cotton-tipped applicator is useful for cleaning in narrow spaces and on circuit boards. If these methods do not remove all the dust or dirt, the instrument may be spray washed using a solution of $1 \%$ mild detergent and $99 \%$ water as follows:

1. Remove covers and shields to reach parts to be cleaned (see Removal and Replacement Instructions).
2. Spray wash dirty parts with the detergent-andwater solution; then use clean water to thoroughly rinse them.
3. Dry all parts with low-pressure air.
4. Dry all components and assemblies in an oven or drying compartment using low-temperature $\left(125^{\circ} \mathrm{F}\right.$ to $150^{\circ} \mathrm{F}$ ) circulating air.

SWITCH CONTACTS. Switch contacts are permanently treated when assembled. Neither cleaning nor other preventive maintenance is necessary, unless the switch board is replaced or the switch assembly has remained disassembled for a long time.

## LUBRICATION

A regular lubrication program for the instrument is not necessary. Most of the potentiometers used in this instrument are permanently sealed and generally do not require periodic lubrication. The backs of the front-panel knob guides have been lubricated when assembled and will require lubrication again only when the front-panel assembly is replaced. Rotary switches are installed with proper lubrication when assembled and will require lubrication only when the rotor is replaced.

## SEMICONDUCTOR CHECKS

Periodic checks of the transistors and other semiconductors in the oscilloscope are not recommended. The best check of semiconductor performance is actual operation in the instrument.

## PERIODIC READJUSTMENT

To ensure accurate measurements, check the performance of this instrument every 2000 hours of operation or, if used infrequently, once each year. If you replace any components, it may be necessary to readjust the affected circuits.

Complete performance check instructions are given in Section 4 of this manual; adjustment instructions are given in Section 5. The Performance Check Procedure can be helpful in localizing certain troubles in the instrument. In some cases, minor problems may be revealed or corrected by readjustment. If only a partial adjustment is performed, see Table 5-1 (the interaction chart) for possible adjustment interaction with other circuits.

## TROUBLESHOOTING

## INTRODUCTION

Preventive maintenance done on a regular basis should reveal most potential problems before an instrument malfunctions. However, should troubleshooting be needed, the following information will help to locate a fault. In addition, the Theory of Operation and the Diagrams sections of this manual may be helpful while troubleshooting.

## TROUBLESHOOTING AIDS

## Diagnostic Firmware

This instrument contains built-in diagnostic routines that can aid in localizing failures. An automatic power-up self test checks the system RAM and ROM and readout interface circuitry. If a failure is detected, this information is presented in either of two ways: a flashing code display on the Trigger LEDs or, if the instrument is capable of presenting a readout, error messages in the crt display. In addition to the power-on testing, various diagnostic routines can be run from the service mode using the SERVICE MENU. (See Internal Testing Capabilities in this subsection for the details.)

## Schematic Diagrams

Complete schematic diagrams are located on tabbed foldout pages in the Diagrams section. Portions of circuitry mounted on each circuit board are enclosed by heavy black lines. The assembly number and name(s) of the circuit(s) are shown near the top or the bottom edge of each diagram.

Functional blocks on schematic diagrams are outlined with a wide gray line. Components within the outlined area perform the function designated by the block label. The Theory of Operation uses these functional block names when describing circuit operation as an aid in cross-referencing between the circuit description and the schematic diagrams.

Component numbers and electrical values of components in this instrument are shown on the schematic diagrams. Refer to the first page of the Diagrams section for the reference designators and symbols used to identify components. Important voltages and waveform reference numbers (enclosed in hexagonal-shaped boxes) are also shown on each diagram. Waveform illustrations are
located adjacent to their respective schematic diagram.

## Circuit Board Illustrations

Circuit board illustrations showing the physical location of each component are provided for use with the schematic diagrams. Each board illustration is found in the Diagrams section on the back of a foldout page, preceding the first related schematic diagram.

The locations of waveform test points are marked on the circuit board illustrations with hexagonal outlined numbers corresponding to the waveform numbers on both the schematic diagram and the waveform illustrations.

## Circuit Board Locations

The location of a circuit board within the instrument is shown on the foldout page along with the circuit board illustration.

## Circuit Board Interconnections

A circuit board interconnection diagram (schematic Diagram 15) is provided in the Diagrams section to aid in tracing a signal path or power source between boards. All wire, plug, and jack numbers are shown along with their associated wire or pin numbers and signal names.

## Power Distribution

Two power distribution diagrams (schematic Diagrams 13 and 14) are provided to aid in troubleshooting power supply problems. These diagrams show the components that the various voltages are applied to and the jumper connections and decoupling components used to apply the power to those circuits. Excessive loading on a power supply by a circuit fault may be isolated by disconnecting the appropriate jumpers.

## Grid Coordinate System

Each schematic diagram and circuit board illustration has a grid border along its left and top edges. A table located next to each schematic diagram lists the grid coordinates of each component shown in that diagram. To aid in physically locating components on the circuit board, the table also lists the
grid coordinates of each component in the circuit board illustration.

Near each circuit board illustration is an alphanumeric listing of all components mounted on that board. The second column in each listing identifies the schematic diagram in which each component can be found. These component-locator tables are especially useful when more than one schematic diagram is associated with a particular circuit board.

## Component Color Coding

Information regarding color codes and markings of resistors and capacitors is located in the colorcoding illustration (Figure 9-1) at the beginning of the Diagrams section.

RESISTOR COLOR CODE. Resistors used in this instrument are carbon-film, composition, or precision metal-film types. They are usually color coded with the EIA color code; however, some metal-film type resistors may have the value printed on the body. The color code is interpreted starting with the stripe nearest to one end of the resistor. Composition resistors have four stripes; these represent two significant digits, a multiplier, and a tolerance value. Metal-film resistors have five stripes representing three significant digits, a multiplier, and a tolerance value.

CAPACITOR MARKINGS. Capacitance values of common disc capacitors and small electrolytics are marked on the side of the capacitor body. White ceramic capacitors are color coded in picofarads, using a modified EIA code.

Dipped tantalum capacitors are color coded in microfarads. The color dot indicates both the positive lead and the voltage rating. Since these capacitors are easily destroyed by reversed or excessive voltage, be careful to observe the polarity and voltage rating when replacing them.

DIODE COLOR CODE. The cathode end of each glass-encased diode is indicated by either a stripe, a series of stripes, or a dot. For most diodes marked with a series of stripes, the color combination of the stripes identifies three digits of the Tektronix Part Number, using the resistor color-code system. The cathode and anode ends of a metalencased diode may be identified by the diode symbol marked on its body.

## Semiconductor Lead Configurations

Figure 9-2 in the Diagrams section shows the lead configurations for semiconductor devices used in the instrument. These lead configurations and case styles are typical of those used at completion of the instrument design. Vendor changes and performance improvement changes may result in changes of case styles or lead configurations. If the device in question does not appear to match the configuration shown in Figure 9-2, examine the associated circuitry or consult a manufacturer's data sheet.

## Multipin Connections

This instrument uses two types of cable connectors. The main type is an etched-circuit ribbon cable with pin connectors crimped directly to the end of the cable. The number one pin is indicated by a mark on the ribbon cable. The other type of connector is a plastic holder containing connectors crimped to the ends of individual wires. Orientation, where important, is indicated by a triangle (arrow).

## TROUBLESHOOTING EQUIPMENT

The equipment listed in Table 4-1 of this manual, or equivalent equipment, may be useful when troubleshooting this instrument.

## TROUBLESHOOTING TECHNIQUES

The following procedure is arranged in an order that enables checking simple trouble possibilities before requiring more extensive troubleshooting. The first two steps use diagnostic routines built into the operating system of the instrument.

The next four procedures are check steps that ensure proper control settings, connections, operation, and adjustment. If the trouble is not located by these checks, the remaining steps will aid in locating the defective component. When the defective component is located, replace it by using the appropriate replacement procedure given under Corrective Maintenance in this section.

[^8]
## 1. Power-up Tests

When the instrument power is applied, self tests are automatically run to verify proper operation of the system RAM and ROM and readout interface circuitry. If the power-up test fails, failure codes appear in the Trigger Mode LEDs to identify the general location of the fault. (See Power-Up Testing later in this section for failure-code information.)

## 2. Diagnostic Routines

Various diagnostic routines can be run from the service mode. The routines can be run at any time by displaying the SERVICE MENU and selecting the desired item from the menu using front panel pushbuttons.

Entry into the SERVICE MENU and its uses are explained in the Diagnostic Routines discussion later in this section.

## 3. Check Control Settings

Incorrect control settings can give a false indication of instrument malfunction. If there is any question about the correct function or operation of any control, refer to the Operating Information in the 2245A Operators Manual

## 4. Check Associated Equipment

Before proceeding, ensure that any equipment used with the 2245A is operating correctly. Verify that input signals are properly connected and that the interconnecting cables are not defective. Check that the ac-power-source voltage to all equipment is correct.

## 5. Visual Check

## WARNING

To avoid electrical shock, disconnect the instrument from the ac power source before making a visual inspection of the internal circuitry.

Look for broken connections or wires, damaged components, semiconductors not firmly mounted, damaged circuit boards, or other clues to the cause of an instrument malfunction.

## 6. Check Instrument Performance and Adjustment

Check the performance of either those circuits where you suspect trouble or the entire instrument. An apparent trouble may be the result of misadjustment. The complete performance check is given in Section 4 of this manual, and adjustment instructions are given in Section 5.

## 7. Isolate Trouble to a Circuit

To isolate problems, use any symptoms noticed when checking the instrument's operation to help localize the trouble to a particular circuit. For example, if the vertical deflection is incorrect on all channels, the problem is most likely from the delay line driver to the vertical output; if deflection is bad only on one channel, the problem is from the attenuator of that channel to the input of the delay line driver. The detailed block diagram shown in the foldout section may be used as an aid in determining signal flow and control line dependency for correct circuit operation. Refer to the troubleshooting hints given in Table 6-6 for diagnostic routine failures. Troubleshooting hints by diagram are given immediately following Table 6-6, and Table 6-9 may be used to aid in locating a problem in the measurement system.

## 8. Check Power Supplies

## WARNING

For safety reasons, an isolation transformer must be used between the ac power main and the instrument's ac power input whenever troubleshooting is done with the cabinet removed. This is especially important when working in the Preregulator and Inverter Power Supply sections of the instrument.

When trouble symptoms appear in more than one circuit, first check the power supplies; then check the affected circuits by taking voltage and waveform readings. Check first for the correct output voltage of each individual supply. These voltages are measured between J1204 (interface connector between power supply and main board) and ground (J1204 pin 4 or 8). See the associated circuit board illustration and Table 6-4.

Voltages levels may be measured either with a DMM or with an oscilloscope. Voltage ripple amplitudes must be measured using an oscilloscope. Use a 1 X probe with as short a ground lead as possible to minimize stray pickup.

## NOTE

Use 20 MHz bandwidth limiting on the test oscilloscope. A higher bandwidth may produce higher observed ripple levels.

If the power-supply voltages and ripple are within the listed ranges in Table 6-4, the supply can be assumed to be working correctly. If they are outside the range, the supply may be either misadjusted, operating incorrectly, or excessively loaded. The power supply adjustment procedure is given in the Power Supply, Display, and Z-Axis subsection of Section 5 (the Adjustment Procedure).

A defective component elsewhere in the instrument can create the appearance of a power-supply problem and may also affect the operation of other circuits. Use the power distribution diagrams (schematic Diagrams 13 and 14 in the foldouts) to aid in localizing a loading problem to a particular circuit.

## 9. Check Circuit Board Interconnections

After the trouble has been isolated to a particular circuit, again check for loose or broken connections, improperly seated semiconductors, and heat-damaged components.

## 10. Check Voltages and Waveforms

Often the defective component can be located by checking circuit voltages or waveforms. Typical voltages are listed on the schematic diagrams. Waveforms indicated on the schematic diagrams by hexagonal-outlined numbers are shown adjacent to the diagrams. Waveform test points are shown in the circuit board illustrations.

## NOTE

Voltages and waveforms indicated on the schematic diagrams are not absolute and may vary slightly between instruments. To establish operating conditions similar to those used to obtain these readings, see the Voltage and Waveform Setup Conditions preceding the waveform illustrations in the Diagrams section.

Note the recommended test equipment, front-panel control settings, voltage and waveform conditions, and cable-connection instructions. Any special control settings required to obtain a given waveform are noted under the waveform illustration. Volts/Div and Sec/Div settings of the test oscilloscope for a waveform are indicated in the waveform illustration.

Table 6-4
Power Supply Voltage and Ripple Limits

| Nominal Supply Voltage | $\begin{aligned} & \text { Test Point } \\ & (+ \text { lead }) \end{aligned}$ | $\begin{gathered} \text { Limits } \\ \left(0^{\circ} \mathrm{C} \text { to } 50^{\circ} \mathrm{C}\right) \end{gathered}$ |  | P-P Ripple ${ }^{\text {a }}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | $60-150 \mathrm{~Hz}$ | $20-40 \mathrm{kHz}$ |
| $+130$ | J1204-11 | +127 | +135 | 70 mV | 70 mV |
| +58 | J1204-10 | +55 | +59 | 40 mV | 120 mV |
| +15 | J1204-7 | +14.6 | +15.6 | 8 mV | 4 mV |
| +7.5 | J1204-8 | +7.4 | +7.6 | 8 mV | 4 mV |
| +5.0 | J1204-1,2 | +5.0 | +5.3 | 30 mV | 20 mV |
| -5.0 | J1204-5 | -5.1 | -5.4 | 4 mV | 4 mV |
| -7.5 | J1204-9 | -7.4 | -7.8 | 4 mV | 4 mV |
| -15 unreg | J1204-6 | -15.5 | -16.6 | $10 \mathrm{~m}, \mathrm{~V}$ | 100 mV |

[^9]
## 11. Check Individual Components

## WARNING

To avoid electric shock, always disconnect the instrument from the ac power source before removing or replacing components.

The following procedures describe methods of checking individual components. Two-lead components that are soldered in place are most accurately checked by first disconnecting one end from the circuit board. This isolates the measurement from the effects of the surrounding circuitry. See Figure 9-1 for component value identification and Figure 9-2 for semiconductor lead configurations.
When checking semiconductors, observe the
static-sensitivity precautions given at the
beginning of this section.

TRANSISTORS. A good check of a transistor is actual performance under operating conditions. A transistor can most effectively be checked by substituting a known-good component. However, be sure that circuit conditions are not such that a replacement transistor might also be damaged. If substitute transistors are not available, use a dynamic-type transistor checker for testing. Statictype transistor checkers are not recommended, since they do not check operation under simulated operating conditions.

When troubleshooting transistors in the circuit with a voltmeter, measure both the emitter-to-base and emitter-to-collector voltages to determine whether they are consistent with normal circuit voltages. Voltages across a transistor may vary with the type of device and its circuit function.

Some of these voltages are predictable. The emitter-to-base voltage for a conducting silicon
transistor will normally range from 0.6 V to 0.8 V . The emitter-to-collector voltage for a saturated transistor is about 0.2 V . Because these values are small, the best way to check them is by connecting a sensitive voltmeter across the junction rather than comparing two voltages taken with respect to ground. If the former method is used, both leads of the voltmeter must be isolated from ground.

If voltage values measured are less that those just given, either the device is shorted or no current is flowing in the external circuit. If values exceed the emitter-to-base values given, either the junction is reverse biased or the device is defective. Voltages exceeding those given for typical emitter-tocollector values could indicate either a nonsaturated device operating normally or a defective (opencircuited) transistor. If the device is conducting, voltage will be developed across the resistors in series with it; if open, no voltage will be developed across the resistors unless current is being supplied by a parallel path.



#### Abstract

When checking emitter-to-base junctions, do not use an ohmmeter range that has a high internal current. High current may damage the transistor. Reverse biasing the emitter-to-base junction with a high current may degrade the current-transfer ratio (Beta) of the transistor.


A transistor emitter-to-base junction also can be checked for an open or shorted condition by measuring the resistance between terminals with an ohmmeter set to a range having a low internal source current, such as the $R \times 1 \mathrm{k} \Omega$ range. The junction resistance should be very high in one direction and much lower when the meter leads are reversed.

When troubleshooting a field-effect transistor (FET), the voltage across its elements can be checked in the same manner as previously described for other transistors. However, remember that in the normal depletion mode of operation, the gate-to-source junction is reverse biased; in the enhanced mode, the junction is forward biased.

INTEGRATED CIRCUITS. An integrated circuit (IC) can be checked with a voltmeter, test oscilloscope, or by direct substitution. A good understanding of circuit operation is essential when troubleshooting a circuit having IC components. Use care when checking voltages and waveforms around the IC so that adjacent leads are not shorted together. An IC test clip provides a convenient means of clipping a test probe to an IC.

When checking a diode, do not use an ohmmeter scale that has a high internal current. High current may damage a diode. Checks on diodes can be performed in much the same manner as those on transistor emitter-to-base junctions.

DIODES. A diode can be checked for either an open or a shorted condition by measuring the resistance between terminals with an ohmmeter set to a range having a low internal source current, such as the $R X$ $1 \mathrm{k} \Omega$ range. The diode resistance should be very high in one direction and much lower when the meter leads are reversed.

Silicon diodes should have 0.6 V to 0.8 V across their junctions when conducting; Schottky diodes about 0.2 V to 0.4 V . Higher readings indicate that they are either reverse biased or defective, depending on polarity.

RESISTORS. Check resistors with an ohmmeter. Refer to the Replaceable Electrical Parts list for the tolerances of resistors used in this instrument. A resistor normally does not require replacement unless its measured value varies widely from its specified value and tolerance.

INDUCTORS. Check for open inductors by checking continuity with an ohmmeter. Shorted or partially shorted inductors can usually be found by checking the waveform response when high-frequency signals are passed through the circuit.

CAPACITORS. A leaky or shorted capacitor can best be detected by checking resistance with an ohmmeter set to one of the highest ranges. Do not exceed the voltage rating of the capacitor. The resistance reading should be high after the capacitor is charged to the output voltage of the ohmmeter. An open capacitor can be detected with a capaci-
tance meter or by checking whether the capacitor passes ac signals.

## 12. Repair and Adjust the Circuit

If any defective parts are located, follow the replacement procedures given under Corrective Maintenance in this section. After any electrical component has been replaced, the performance of that circuit and any other closely related circuit should be checked. Since the power supplies affect all circuits, performance of the entire instrument should be checked if work has been done on the power supplies. Readjustment of the affected circuitry may be necessary. Refer to the Performance Check Procedure and the Adjustment Procedure, (sections 4 and 5) and to Table 5-1 (Adjustment Interactions).

## INTERNAL TESTING CAPABILITIES

The diagnostics built into the 2245A permit the technician to test much of the digital circuitry and the digital-to-analog interface. The following text describes the testing capabilities of the Measurement Processor and the firmware controlled circuitry.

## Power-Up Testing

The systems shown in Figure 6-1 are tested at power-on. Failure codes appear in the Trigger MODE LEDs, with ON being shown as " $x$ " and OFF as " $O$ " in the figure. In the event of a display failure where error messages cannot be displayed on the crt, the codes indicate a failure area to begin troubleshooting.


Figure 6-1. Power-on test failure codes.

Power-up tests performed are:

1. RAM diagnostics-failures indicated by flashing AUTO LEVEL lamp. Three diagnostics are run on all locations in the RAM:
a. Store and read 00.
b. Store and read FF.
c. Store and read pseudo-random pattern.
2. ROM diagnostics-failures indicated by flashing AUTO lamp. Tests all of ROM, except for ROM header. Runs proprietary version of CRCC test.
3. Readout interface diagnostics-failures indicated by flashing NORM lamp. Performs a marchingone test around the loop from D7-DO to R7-RO and back.

## SERVICE MODE

The service mode driver menu is accessed by pressing the CH 1 and CHOP/ALT Vertical MODE buttons at the same time. The main SERVICE MENU will be displayed as shown in Figure 6-2. Each service menu display has two parts; the part to the left is the service menu, and the part to the right is the modifier menu.


6557-97
Figure 6-2. Main SERVICE MENU.

Each service menu has a title and a number of selectable items in the menu. The title appears in the top line of the crt display, and the selectable items appear under the title, indented (see Figure 6-2). Menu choices that are names of sub-menus have a following slash (/), and when one is underlined, the word "SELECT" appears in the modifier menu list. When a choice with sub-menus is selected, the sub-menu choices are displayed on the left side of the screen with the name of the selected sub-menu displayed in the top line.

A menu choice that has no following slash is an executable service routine. The routine may be run by underlining it and pressing the CH 2 button (corresponding to the RUN label that appears in the modifier menu list). Executable servicing selections are: diagnostics that return either a pass message or a fail message along with service data; one-shot exercisers that carry out some service and immediately return to the menu; or regular exercisers that carry out a service while continuously displaying service data.

An underlined service-menu choice is available for selection. To select a menu item, use the CH 1 or ADD buttons corresponding to the up-arrow and down-arrow symbols to move the underline up or down in the SERVICE MENU. When the underline is below the menu title in the top line, pressing the CH 1 (up-arrow) button returns to the preceding menu containing that sub-menu (an up-menu operation).

Pressing CH 4 (QUIT) any time the choice is displayed will cause the scope to return to normal oscilloscope mode. If a service routine is operating that has an END menu selection displayed, pressing CH 1 (END) exits the routine and returns to the selection menu (where QUIT is displayed). Routines that run once return to the selection menu when finished.

The diagnostic tests in the SERVICE MENU may be run with a conditional setting that determines how many times the routine is done. The conditional MODE setting menu choice appears in the modifier menu when the DIAGNOSE choice in the SERVICE MENU is underlined (see Figure 6-3). One of the following mode types will be displayed:
ONCE, CONTINUOUS, UNTIL PASS, or UNTIL FAIL

Change the mode type displayed in the bottom line by pressing the CHOP/ALT (MODE) button. When ONCE is the mode, the diagnostic is run once, and
the result is displayed. When CONTINUOUS is the mode, the diagnostics are run continuously. When UNTIL PASS is the mode, the diagnostics are run until they pass. When UNTIL FAIL is the mode, the diagnostics are run until they fail. In order to stop a diagnostic that is looping in the CONTINUOUS, UNTIL PASS, or UNTIL FAIL mode, press the CH 1 (HALT) button. The diagnostic will stop and display the current status. When the status is displayed, press CH 1 (END) to return to the SERVICE MENU choices.


Figure 6-3. SERVICE MENU with DIAGNOSE choice selected.

## Service Routines

Descriptions of the available service routines are given in Table 6-5. The complete SERVICE MENU has this structure:

```
SERVICE MENU/
    DIAGNOSE
    CONFIGURE
    SELF CAL MEASUREMENTS
    INTERNAL SETTINGS MENU/
        MAKE FACTORY SETTINGS
        ADJUST VERTICAL OUTPUT
    EXERCISER MENU/
        FRONT PANEL MENU/
            EXERCISE POTS
            EXERCISE LEDS
            EXERCISE SWITCHES
        PROC BOARD MENU/
            A TO D MENU/
                EXERCISE DACS
                    EXERCISE PORTS
            READOUT MENU/
                SHOW READOUT ROM HEADER
                    EXERCISE RO INTERFACE
            SHOW SYSTEM ROM HEADER
            EXERCISE TIME REF
            SHOW AUTO RESTARTS
        MAIN BOARD MENU/
            SHIFT REGISTER MENU/
                EXERCISE SR O
                    EXERCISE SR 1
                    EXERCISE SR 2
            EXERCISE VOLT REF
```

Table 6-5
SERVICE MENU Selections

| Menu Item | Action |
| :---: | :---: |
| DIAGNOSE | Runs all diagnostics in sequence, stopping at the first failed diagnostic. (See Table 6-6 for a diagnostic test failure troubleshooting guide.) <br> Diagnostics are: <br> RO (readout) INTERFACE <br> ROM RAM <br> SLIC CONTROL REG <br> SHIFT REGISTERS (in SR2, SRO, SR1, SR3 order) <br> DAC <br> TRIGGERS |
| CONFIGURE | Configures the scope-mode operation of the instrument according to the users' wishes. Configuration is done by answering a yes/no question. The question is: <br> KEEP READOUT ON IN SGL SEQ? Selecting YES causes the readout to be on constantly when in SGL SEQ trigger mode. <br> Selecting NO causes the readout to flash on for a brief period after the signal display sequence has finished. |

Table 6-5 (cont)
SERVICE MENU Selections

| Menu Item | Action |
| :---: | :---: |
| SELF CAL MEASUREMENTS | Self characterizes the gain and offset errors in the vertical system and time base so that they may be compensated for in the measurements. This should be run only after instrument is warmed up properly, although if desired, it can be used to compensate for an unusual operating temperature. |
| MAKE FACTORY SETTINGS | Resets the front panel settings to those shipped with the instrument. Used to produce a known setup condition. The following is a partial list of settings: |
| ADJUST VERTICAL OUTPUT | Used to adjust the vertical output gain and centering (see Adjustment Procedure in Section 5). |
| EXERCISE POTS | Shows the name of the latest digitized potentiometer moved, along with its hexadecimal value (from FF to OO). Starts by showing the HORIZ POSITION and its value until another pot is adjusted. Pressing CH 1 (END) exits the exerciser. |
| EXERCISE LEDS | Uses the delay control to select a single LED, turn it on, and display its circuit number. The exerciser is used to check for adjacent-row or adjacent-column shorts in the front panel board and for inoperative LEDs. Pressing CH 1 (END) exits the excerciser. |
| EXERCISE SWITCHES | Shows the circuit number of the latest momentary-contact button pressed, or the name and position of the latest rotary switch turned. Pressing CH 1 (END) exits the exerciser. |
| EXERCISE DACS | Attaches the DAC (U2302, Diagram 11) to a single sample-and-hold channel (through U2303), and outputs a sawtooth waveform to that channel. Select the channel by pressing CHOP/ALT (STEP). This excerciser may be used to trace a sample-hold value through the system, with the DAC system operating in a non-multiplexed mode. Pressing CH 1 (END) exits the exerciser. |

Table 6-5 (cont)
SERVICE MENU Selections

| Menu Item | Action |
| :---: | :---: |
| EXERCISE PORTS | Continuously does analog-to-digital conversion on a single A-to-D port. Select the port by pressing CHOP/ALT (STEP). The exerciser may be used to trace a single potentiometer wiper value or probe code value through the system by operating the A-to-D converter in a non-multiplexed mode. Pressing CH 1 (END) exits the exerciser. |
| SHOW READOUT ROM HEADER | Shows the Readout ROM part number (U2408, Diagram 9) and its expected and actual checksum. |
| EXERCISE RO INTERFACE | Continuously echos a marching-bit value across the readout interface. This exerciser may be used to check the integrity of the Measurement-Processor-to-Readout-Processor communication system. Pressing CH 1 (END) exits the exerciser. |
| SHOW SYSTEM ROM HEADER | Shows the system ROM part numbers (U2519, Diagram 8) and checksums of the installed firmware version. |
| EXERCISE TIME REF | Steps through the timing frequencies used to characterize the horizontal timing accuracy. Calibration periods are shown in the following table. |
| SHOW AUTO RESTARTS | Shows the address being executed if a software error occurs that causes execution out of normal memory space. This is for factory use only and is of no use in field servicing of the instrument. If an address is ever displayed when SHOW AUTO RESTART is run, record the address displayed and report it to a service center; the error address is cleared from memory when SHOW AUTO RESTARTS is exited. |
| EXERCISE SR 0 | Shifts alternate zeros and ones through Shift Register 0 (U171, U172, and U173, Diagram 1). This shift register sets Attenuator and Input Coupling relay positions and Vertical Preamplifier gain settings. |
| EXERCISE SR 1 | Shifts alternate zeros and ones through Shift Register 1 (U302 and U303, Diagram 5; U1103, Diagram 3). This shift register sets sweep speeds and auxiliary trigger settings (TV Trigger, Scope Bandwidth, X10 magnification, and $X-Y$ Mode). |
| EXERCISE SR 2 | Shift alternate zeros and ones through Shift Register 2 (U502, Diagram 4). |

Table 6-5 (cont)
SERVICE MENU Selections

| Menu Item |  |  |
| :---: | :---: | :---: |
| EXERCISE VOLT REF | Steps through all settings of the Voltage Reference Generator (U931, Diagram 7) that are used to calibrate the Volts Measurement system. For each setting, Channels 1 and 2 are placed into the gain configuration ( 2 mV through 50 mV ) that uses that setting. The voltage select lines (VOLTS CAL 2-0) may be checked for activity, and the generated VOLTS CAL SIGNAL may be measured to check its values. |  |
|  | VOLTSIDIV | Cal voltage |
|  | 2 mv | 10 mv |
|  | 5 mv | 25 mv |
|  | 10 mv | 50 mv |
|  | 20 mv | 100 mv |
|  | 50 mv | 250 mv |

## DIAGNOSE Tests

The complete DIAGNOSE routine may be called up by the service technician as needed to aid in
troubleshooting the instrument. Testing routines and troubleshooting information for use in the event of a failed test are given in Table 6-6.

Table 6-6
dIAGNOSE ROUTINES

| Error Label | Path, Devices Tested, and Troubleshooting Actions |
| :---: | :---: |
| INTERFACE ERROR | Measurement Processor to Readout Processor Communications. <br> This test rotates a 1 through the byte on the bus lines. The difference between WROTE and READ indicates which bit is stuck. |
|  | Devices to troubleshoot: <br> U2401, U2402, U2417C and D, and bus lines between Measurement Processor and Readout Processor. <br> Check U2501 pin 29 for enabling signal to U2402, and U2400 pin 22 for clock. |

Table 6-6 (cont) dIAGNOSE ROUTINES

| Error Label | Path, Devices Tested, and Troubleshooting Actions |
| :---: | :---: |
| RAM ERROR | Writes and reads test bytes from the Readout RAM (U2406). <br> The difference between WROTE and READ data indicates a stuck bit. |
| RO ROM | PART NUM (Tektronix Part Number without dashes). EXPECTED CHECKSUM (hex number, 2 characters). ACTUAL CHECKSUM (hex number, 2 characters). <br> NOTE <br> Readout ROM is internal to the Readout Processor, U2400; a failure of this test may mean a bad Readout Processor. |
| REG SR 2 | Front Panel Potentiometer Multiplexer data path check. WROTE (hex data written, 1 character). <br> READ (hex data read, 1 character). <br> Device Tested: U502, Diagram 4. |
|  | Troubleshooting checks: <br> Check pin 11 for correct clock. Check pin 2 for data. Check pin 12 for multiplexer output. |
| REG SR 0 | Attenuator and Preamplifier data path check. <br> WROTE <br> (hex data written, 6 characters). <br> READ <br> (hex data read,, 6 characters). <br> Devices Tested: U171, U172, and U173 on Diagram 1. <br> NOTE <br> U171 and U172 have +15 V clocks and data; U173 has +5 $V$ clocks and data. |
|  | Troubleshooting checks: <br> Check pin 3 of each device for correct clock. <br> Check pin 9 of each device for marching bit pattern. <br> Attenuator relay latches are driven and a clacking sound is heard. |

Table 6-6 (cont) DIAGNOSE ROUTINES

| Error Label | Path, devices tested, and troubleshooting actions |
| :---: | :---: |
| REG SR 1 | Sweeps and Auxiliary Trigger data path check. <br> Devices Tested: <br> U302 and U303 on Diagram 3; U1103 on Diagram 3. Clock and data levels for U302 and U303 are +15 V; they are +5 V for U1103. |
|  | Troubleshooting checks: <br> Check pin 3 of each device for correct clock. Check pin 9 of each device for marching bit pattern. |
| REG SR 3 | Switch board data path check. <br> WROTE (hex data written, 4 characters). <br> READ (hex data read, 4 characters). <br> NOTE <br> There is no exerciser for SR 3, but it is included in "DIAGNOSE." <br> Devices Tested: U2001 and U2002, Diagram 10. |
|  | Troubleshooting Checks: <br> Check pin 10 for serial data in. Check pin 9 for serial data out. Check pin 2 for clock. |
| DAC ERROR 0 | The A-to-D system, Diagram 11, is not working correctly. Ground level was digitized out of the specified error limits. |
|  | Devices to troubleshoot: <br> U2515 and U2517, Diagram 8; U2306, U2302, U2300, U2313, and U2314, Diagram 11; U506, Diagram 7 |

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Table 6-6 (cont)
DIAGNOSE ROUTINES

| Error Label | Path, Devices Tested, and Troubleshooting Actions |
| :---: | :---: |
| (TRIGGERS) | The trigger diagnostic partially checks the Trigger SOURCE, Trigger CPLG, and Trigger SLOPE circuitry. |
|  | Error Messages: <br> TIME SIGNAL TOO SMALL <br> AT A Trigger <br> A Trigger circuitry failed amplitude test. <br> TIME SIGNAL TOO SMALL <br> AT B Trigger <br> B Trigger circuitry failed amplitude test. <br> NO A Trigger FOR TIME <br> CAL SIGNAL <br> (2 digit code, see table) <br> Trigger never occurred. |
|  | Time Base <br> Cal Signal Code <br> $128 \mu \mathrm{~s}$ 0 <br> 8.192 ms 1 <br> $256 \mu \mathrm{~s}$ 2 <br> 4.096 ms 3 <br> 2.048 ms 4 <br> $512 \mu \mathrm{~s}$ 5 <br> 32.768 ms 6 <br> 1.024 ms 7 <br> $64 \mu \mathrm{~s}$ 13 <br> $32 \mu \mathrm{~s}$ 14 <br> Check U421, U431, U1106A, and associated circuitry, Diagram 3. <br> SLIC (Display Logic IC, U600) and FLIC (Trigger Logic IC, U602) gate outputs and level shifters, Diagram 4. |

## TROUBLESHOOTING HINTS BY DIAGRAM

## VERTICAL SELF CAL-Checks Cursor and Preamplifier Outputs

The circuitry listed below must be operational for Vertical SELF CAL to work. Troubleshoot these circuits if voltage measurements are not correct.

1. DAC system (U2303, U2304, and U2305, Diagram 11).
2. Trigger Level Comparators (U431 and U421, Diagram 3).
3. VERT COMP feedback (U702, Diagram 2).
4. ECL-to-CMOS translators (Q604, Q605, Q606, Q607, Q602, and Q603) between U600 and U602 (Diagram 4).
5. Data to Measurement Processor (data bus and bus transceivers, Diagram 8):
6. VOLTS CAL signal (U931, Diagram 7).
7. Vertical Preamps (U210, U220, U230, and U240), Delay Line Drivers (Q250, Q251, Q252, and Q253), and Vertical Position Switching circuitry (U203, U801B, U201, U202, U280, Q284 and Q285, Diagram 2).

## HORIZONTAL SELF CAL-Checks Sweep Timing

1. Put the oscilloscope into Self Cal and check at U421A pin 4 (Diagram 3) for changing width calibration signals.
2. Run the "EXERCISE TIME REF" exerciser and check for correct TB CAL signal at U421A pin 4, Diagram 3 (see Table 6-5).

## Schematic Diagram 1-VERTICAL INPUTS

1. Run DIAGNOSE to check for shift register failure.
2. Run the shift register exerciser for Shift Register 0. Check for clock, data, and strobe signals. Check the shift register outputs.

NOTE
The outputs of U171 and U172 are at 15 V ; the outputs from U173 are at 5 V .
3. Check the outputs of the relay driver transistor arrays (U174 and U175). When a transistor is blown in one of the arrays, the usual symptom is 8 V on its output.
4. Go to a known setup and check the outputs for correct levels (see the circuit description in Section 3). The MAKE FACTORY SETTINGS selection under INTERNAL SETTINGS of the SERVICE MENU provides known control states.
5. Check relay contacts.
6. Follow the signal path and check for correct signal and gains. Put in a known signal for each attenuator setting and check at the Vertical Preamplifier inputs to determine if the signal path is ok. The front panel boards and the attenuator shield have to be removed to gain access to the solder side of the Main board.
7. Check the channel input buffer amplifier (U112 or U122) output if the vertical deflection of either channel 1 or channel 2 is defective. If the buffer amplifier output is held at -6 V or a strange sawtooth signal is present, replace that buffer amplifier.
8. Check gains and offsets of the CH 3 or CH 4 input buffers (Q131 or Q151).

Schematic Diagram 2-VERTICAL PREAMPLIFIERS, DELAY LINE DRIVERS and OUTPUT

Perform the following troubleshooting checks with no signal input.

1. Check both inputs of the delay line. If offset on either side, troubleshoot the offsetting side. Inputs to the bases of Q250 and Q251 should be at +7.5 V .
2. Differential voltage across the delay line should be $0 \vee \pm 0.5 \mathrm{~V}$.
3. Check signal gain through the Preamplifier ICs (U210, U220, U230, and U240). Gain is $10 \mathrm{mV} /$ division of input signal.
4. Check INVERT operation.
5. Check the operation of U260 if the inputs to delay line driver are not at 7.5 V . This operational amplifier is the bias stabilization circuit that compares the average dc level to +7.5 and moves the emitters (and therefore the bases) of Q250 and Q251 to return the inputs to 7.5 V .

## WARNING

Vertical output transistors Q701 and Q702 run extremely hot (in excess of $100^{\circ} \mathrm{C}$ ). Use care when probing in those areas to not touch the heat sinks or cases with bare fingers.

WARNING

The vertical output amplifier runs hot. DO NOT touch it with bare fingers.


The metal tab on top of the vertical output amplifier IC (U701) is NOT ground. Do not connect a ground lead to it. Doing so may cause the IC to fail and usually causes R733 from pin 14 of $U 701$ to the -5 V supply to open.
6. A common mechanical failure is lead breakage on R708. If the resistor pack is moved excessively, the leads will break. The resistor pack will then have to be replaced.

## NOTE

The heat sinks on Q701 and Q702 may be removed for short periods of time to permit access for a test probe around the close-in circuitry. DO NOT leave them off for extended periods. Check that they are on all the way when replaced.
7. If the heat sinks on the output transistors shake loose, the plastic grommet inserted in the top of the heat sink prevents the sink from touching the metal cabinet. If the grommet is left out, the metal cabinet may come in contact with the heat sink; and the transistor, the vertical output amplifier IC, and R733 will usually fail. If the heat sinks are removed during maintenance, they must fit tightly when replaced and the grommet must be checked.

## NOTE

The cases of Q701 and Q702 are the base leads of the transistors, not the collector as is usual for a TO5 case. Also, the tab marks the collector lead, not the emitter.
8. The vertical outputs to the crt may be momentarily shorted together to check for offsets in the crt. (This should center the vertical trace.)
9. The output at pins 6 and 7 of U701 may be shorted together to check for offsets in the Vertical Preamplifier. (This should bring the trace to within $\pm 0.5$ division of center.)
10. Pins 18 and 19 of $\cup 701$ may be shorted together to check for offsets from the delay line. (This should bring the trace to within $\pm 1.5$ divisions of center.)
11. Shorting the bases of Q701 and Q702 together usually causes the vertical output circuit to oscillate.
12. Check the center lead of R708 for a voltage of about +60 V , and a common-mode voltage difference (between the two deflection plates) of about $0 \vee$ (when pins 6 and 7 of U701 are shorted together).
13. Check the operation of Vertical Comparator U702 by running SELF CAL. (The Vertical

Comparator circuit is enabled only during a vertical Self Cal.)

## Schematic Diagram 4-DISPLAY AND TRIGGER LOGIC AND PROCESSOR INTERFACE

1. Put the oscilloscope into A Horizontal Display mode with CH 1 and CH 2 Vertical modes on.
2. Check U600 vertical enables ( CH 1 EN , pin 39; $\mathrm{CH} 2 \mathrm{EN}, \mathrm{pin} 38$ ).
3. Probe U600 A TRIG selects (ATS 0, pin 31; ATS 1, pin 32; ATS 2, pin 33; A SLOPE, pin 30) and B TRIG selects (BTS 0, pin 27; BTS 1, pin 28; BTS 2, pin 29; B SLOPE, pin 26) while making trigger source and slope changes on the front panel. (Probe the A select lines for A trigger changes and the $B$ select lines for $B$ trigger changes.)
4. Check the 10 MHz clock at U600 pin 1 and U600 power sources. Check the 1 kHz clock at pin 2.
5. Check communication lines ( $\overline{\mathrm{SLIC} R D}$, pin 8; SLIC WR, pin 3; ADDRO through ADDR3, pins 4 through 7, respectively; and MB DATA, pin 9) for activity while making front-panel trigger mode changes.
6. Check THO line, pin 17. Signal should go to a logic high then low again for every new frontpanel setup condition, such as changing trigger mode, vertical mode, etc.
7. Check TDI, U600, pin 10, for a CMOS-level switching signal.
8. Check TDO, U602, pin 30, for an ECL-level switching signal.
9. Check the A TRIG signal at U602 pin 7.
10. Check the A GATE signal at U602 pin 14. Vary the Holdoff control to see if the spacing between each A GATE pulse changes.
11. Check the Holdoff oscillator output at $\cup 600$ pin 15. Vary the HOLDOFF control to see if the width of the oscillator pulses varies.

## Schematic Diagram 5-A AND B SWEEPS AND DELAY COMPARATORS

1. Check that the baseline voltage (level that is present during holdoff after retrace) of the A and $B$ ramp signals is $-2 V$. (The baseline level is referenced to the output of U309B and controlled by Q302, Q303, and Q304 for the

A sweep and Q315, Q316, and Q317 for the B sweep).
2. Check the Sweep End Comparators, U316, for correct output. The sweep should end at a maximum of 2.5 V . Check the outputs (pin 15 for the A Sweep and pin 2 for the B Sweep) for about 3.8 $V$ (the middle of ECL transitions).
3. Place the oscilloscope in delay and delta delay and check the Delay Time Comparators for correct outputs (DLY END 1 and DLY END 0).
4. Check U301 for correct switching and delay level transfer. Vary the Delay Time and the Delta Delay time and check for smooth signal change at pins 12 and 13 of U301C. If not correct, troubleshoot DAC system or front panel controls.
5. Run diagnostics to check for Shift Register 1 (U302 and U303) failure.
6. Exercise SR 1 and check switching of U307, U308, U310, and U311.

## Schematic Diagram 6-HORIZONTAL OUTPUT AMPLIFIER

1. Turn off the READOUT and check the ramps for equal (but opposite) waveforms on each plate. (Run MAKE FACTORY SETTINGS under the INTERNAL SETTINGS MENU in the SERVICE MENU.)

## \{CAUTION\}

DO NOT short the horizontal output leads together or to ground. This will cause the output amplifier FETs to fail.
2. The MOSFET output transistors (Q801 and Q802, left plate; Q805 and Q806, right plate) run hot. If either side is cold, it is defective.
3. If output is all the way to one side or the other, check U801A and the common-mode feedback. This circuit is supposed to keep the outputs at about 70 V average to ground.

## NOTE

Pins 12 and 13 of 4802 may be shorted together to determine if the unbalance is before or after the horizontal preamplifier (U802). DO NOT short to ground.
4. Check the A RAMP and B RAMP input signals (A Horizontal mode for A RAMP and B Horizontal mode for $B$ RAMP). They start at -2 V and ramp up to about +2.5 V .
5. Check the RO HORIZ input for correct waveform.
6. Check for the $X$ AXIS input signal on pin 7 of U802 in $X-Y$ mode (a signal must be applied to the CH 1 input).
7. Check at the junction of R855 and R854 (the common-mode bias point of Q810 and Q809) for 9.5 V .
8. Check at the junction of R846 and R852 (the common-mode source voltage of Q802 and Q805) for 15 V .
9. Check at the junction of R845 and R847 (the common-mode collector voltage of emitter followers Q803 and Q807) for 24 V .
10. Check the HDO and HD1 signals to U802 (see Table 6-7 for display states).
11. The horizontal preamplifier, U802, runs warm to the touch, but not hot.

Table 6-7
Horizontal Display State Logic

| HDO | HD1 | Display |
| :---: | :---: | :--- |
| 0 | 0 | Readout |
| 0 | 1 | A Sweep |
| 1 | 0 | B Sweep |
| 1 | 1 | $X-Y$ |

## Schematic Diagram 7-Z-AXIS, CRT, PROBE ADJUST, AND CONTROL MUX

1. Turn off the Readout (READOUT control fully CCW) and test the node between CR2703 and C2711 for correct Z-Axis waveform. Vary INTEN to check operation. (Readout signals add confusion to the waveforms.)
2. Check for correct auto-focus operation at the junction of CR2715 and the collector of Q2712. Circuit action is exactly opposite of the Z-Axis to obtain focus tracking.
3. Parts replaced in the CRT High Voltage circuit and Z-Axis are safety controlled parts.

Replacements need to be exact. The power supply is capable of delivering more that 15 watts at high voltages.

## Schematic Diagram 8-MEASUREMENT PROCESSOR

1. Check U2501, pin 57 for a RESET condition. Processor will be in permanent reset condition if RESET is high. Check that RESET goes high then low again at power on.
2. Check SYS RESET at U2506C pin 8.
3. Check that U 2502 pin 5 is low when RESET is high. (This signal prevents random RAM writes on power-up and power-down when the processor is being reset.)
4. Check the 8 MHz clock (CLK 8 M ) at U2501 pin 56.
5. Check address decoding. Use a data analyzer or word recognizer probe set up to recognize the address that produces a selected enabling strobe from the address-decoding circuitry. Observe that the strobe is produced when the correct address is output by the Measurement Processor. The easiest way to generate most addresses during normal operation is to change a front-panel setting. See Table 6-8 for the addresses.

## Schematic Diagram 9-READOUT SYSTEM

1. Run EXERCISE POTS (under the EXERCISER and FRONT PANEL menus) and check the digitized front panel pots for proper operation. The name of the exercised pot is displayed in the readout along with its current hexadecimal value. The value range from at or near 00 to at or near FF and the displayed value should change smoothly as the pot is rotated. EXERCISE POTS always displays the HORIZ POSITION pot when first called.
2. Check Readout Request pulse ( $\overline{\mathrm{RO} \text { REQ, U2410 }}$ pin 14).
3. Check Readout Blanking signal ( $\overline{\text { RO BLANK, }}$ U2410 pin 16).
4. Check activity of Readout Processor (U2400).
5. Check outputs of Vertical and Horizontal Readout DACs (U2412 and U2413, respectively).
6. Check outputs of Vertical and Horizontal Readout Mixers (U2416A and U2416B, respectively) and multiplexers (U2414 and U2415, respectively).

## Schematic Diagram 10-SWITCH BOARD AND INTERFACE

1. Run the EXERCISE SWITCHES exerciser and check each of the front panel switches for correct operation. The circuit number of the latest switch pressed is displayed in the readout.
2. Run the EXERCISE LEDS exerciser and check that each of the front panel LEDS may be turned on. The circuit number of the lighted LED is displayed in the readout.

## Schematic Diagram 12-POWER SUPPLY

## WARNING

For safety reasons, an isolation transformer must be connected whenever troubleshooting is done in the Preregulator and Inverter Power Supply sections of the instrument.

1. If the fuse blows, check that Q2201 is not shorted. (If a variac is available, slowly increase the line voltage from 0 V until the voltage across C 2202 is about 40 V . If the same voltage is across C2203, Q2201 is probably shorted.)
2. If the Preregulator fails to come up ( 44 V not present across C2203):
a. Check $+D C$ at the output of the line rectifier bridge (across C2202) for approximately (Vacrms $\times 1.414$ ).
b. Check the Start-up circuit. The voltage across C2204 should ramp up to about 20 V , at which point Q2204 and Q2211 turn on to supply voltage to pin 10 of U2201.
c. Check the Preregulator circuit. Voltage pulses with a repetition rate of about $25 \mu \mathrm{~s}$ should be present on pin 8 of U2201 whenever supply voltage is present on pin 10.
3. If the power supply is in the chirp mode (continually restarting and shutting down), excessive loading of the +44 V supply is probable.

Table 6-8
Measurement Processor I/O Memory Map

| $\stackrel{\text { Address range }(\mathrm{A} 19-\mathrm{A} 0)}{\stackrel{\text { Binary }}{ } \xrightarrow{\text { A }} 1}$ |  |  |  |  | Signal name and description | Signal source |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0110 | 0000 | 0000 | 0xXX | XXXX | LED CATH CLK -Latches cathode data to Front-Panel LEDs. | U2501 pin 25 (Diagram 8) |
| 0110 | 0000 | 0000 | 1XXX | XXXX | LED ANODE CLK-Latches anode data to Front-Panel LEDs. | U2501 pin 27 (Diagram 8) |
| 0110 | 0000 | 0001 | OXXX | XXXX | $\overline{\text { RO BUF WR -Latches Readout }}$ Processor control datas. | U2501 pin 28 (Diagram 8) |
| 0110 | 0000 | 0001 | 1XXX | XXXX | $\overline{\text { RO BUF RD-Enables Readout RAM }}$ data onto bus D0-D7 (used for diagnostics only). | U2501 pin 29 (Diagram 8) |
| 0110 | 0000 | 0010 | 0xxx | X000 | $\overline{\text { DAC LSB CLK-Latches the least sig- }}$ nificant byte of data to the D-to-A Converter. | U2517 pin 15 (Diagram 8) |
| 0110 | 0000 | 0010 | OXXX | X001 | $\overline{\text { DAC MSB CLK }}$-Latches the most significant byte of data to the D-to-A Converter. | U2517 pin 14 (Diagram 8) |
| 0110 | 0000 | 0010 | OXXX | $\times 010$ | $\overline{\text { POT MUX CLK }}$-Latches channel selection code for pot multiplexer. | U2517 pin 13 <br> (Diagram 8) |
| 0110 | 0000 | 0010 | 0XXX | X010 | SNAP CLK -Selects whether control of $\mathrm{CH} 1-\mathrm{CH} 4$ POSITION, TRACE SEP, A INTEN, B INTEN, and READOUT are controlled by front-panel pots or fixed resistor dividers. | U2517 pin 12 (Diagram 8) |
| 100x | xxxx | XXXX | xxxx | $\times 000$ | $\overline{\text { MB CNTL WR }}$ - Write enables Processor Interface circuitry (Diagram 4). | U2518 pin 15 (Diagram 8) |
| 100X | 0000 | XXXX | XXXX | $\times 000$ | Sets BEAM FIND (U503 pin 7) high ON. | U503 pin 7 (Diagram 4) |
| 100x | XXXX | XXXX | XXXX | $\times 001$ | $\overline{S W}$ BD SR LOAD -Loads column data into switch board registers. | U2518 pin 14 (Diagram 8) |
| 100X | XXXX | XXXX | XXXX | $\times 010$ | SW BD SR SHIFT -Shifts data in switch board registers to the SW BD DATA signal line. | U2518 pin 13 <br> (Diagram 8) |
| 100X | XXXX | XXXX | XXXX | X011 | SLIC WR -Write to SLIC, U600 Diagram 4. | U2518 pin 12 <br> (Diagram 8) |

Table 6-8 (cont)
Measurement Processor 1/O Memory Map

| Address range (A19 - AO) |  |  |  |  | Signal name and description | Signal source |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 100x | XXXX | XXXX | XXXX | $\times 100$ | FLIC WR -Write to FLIC, U602 Diagram 4. | U2518 pin 11 <br> (Diagram 8) |
| 100x | 0001 | XXXX | XXXX | $\times 000$ | SR 0 CLK-Clock Shift Register 0. | U606F pin 12 <br> (Diagram 4) |
| 100x | 0010 | XXXX | XXXX | X000 | SR 1 CLK-Clock Shift Register 1. | U606B pin 4 (Diagram 4) |
| 100x | 0011 | XXXX | XXXX | $\times 000$ | Sets BEAM FIND (503 pin 7) low (OFF). | U503 pin 7 (Diagram 4) |
| 100x | 0011 | XXXX | XXXX | $\times 000$ | Sets MSEL (U602 pin 29) Iow (delta or long delay). | U503 pin 13 (Diagram 4) |
| 100x | 0100 | XXXX | XXXX | X000 | Sets MSEL (U602 pin 29) high reference or short delay). | U503 pin 13 (Diagram 4) |
| 100x | 0101 | XXXX | XXXX | $\times 000$ | Sets SR DATA signal line low. | U606C pin 6 (Diagram 4) |
| 100x | 0110 | XXXX | XXXX | $\times 000$ | Sets SR DATA signal line high. | U606C pin 6 (Diagram 4) |
| 100x | 0111 | XXXX | XXXX | X000 | Places SR 2 in shift mode (U502 pin 10, Diagram 4). | U2512 pin 5 (Diagram 8) |
| 100x | $1 \times X X$ | XXXX | XXXX | $\times 000$ | A places SR 2 in load mode (U502 pin 10, Diagram 4). | U2512 pin 5 <br> (Diagram 8) |
| 100x | 1111 | XXXX | XXXX | X011 | $\overline{\text { TRIG CLK }}$-Loads coupling data to triggers. | U600 pin 19 (Diagram 4) |
| 1010 | XXXX | XXXX | XXXX | XXXX | Chip enable for Measurement Processor RAM (U2521 pin 20). | U2501 pin 36 (Diagram 8) |

## WARNING

To avoid electrical shock, always disconnect the instrument from the ac power source before removing or replacing components.
a. Check that Q2209 and/or Q2210 are not shorted. Open W2201 and connect the positive lead of an ohmmeter to either collector and the negative lead to the emitters. Readings of less than $100 \Omega$ indicate a probable short. If a short is found, it will be necessary to unsolder one of the collector leads to determine which transistor is shorted. Reconnect W2201 when done.
b. Check the secondary supplies for excessive loading. Measure from each supply to ground using an ohmmeter at a low range (one that will forward bias diodes, usually around the $1 \mathrm{k} \Omega$ range). Use the following as a guideline:

|  | Nominal Resistance <br> Supply |
| :---: | :---: |
| +5 V | 100 |
| -5 V | 50 |
| -15 V | 500 |
| +15 V | 400 |
| +7.5 V | 150 |
| -7.5 V | 180 |
| +58 V | 7500 |
| +130 V | 9000 |

## TROUBLESHOOTING MEASUREMENT ERRORS

When certain measurement malfunctions occur, the symptoms usually indicate the circuit components that may be causing the problems. Verify all the following conditions, and then use Table 6-9 for locating the source of measurement-error problems.

## Conditions:

All vertical channels can be successfully displayed and positioned independently.

The $A$ and $B$ sweeps both free-run and trigger successfully.

Both A and B Trigger COUPLING and SOURCE operate properly.

Normal-appearing readout text and cursors can be displayed.

Measurement value accuracy is the accuracy of number displayed in top line of readout on the crt.

Measurement cursor accuracy is the accuracy of the match between cursor position and the measurement value.

Table 6-9
Measurement Error Troubleshooting Hints

| Circuit <br> Problem | Symptoms |
| :--- | :--- |
|  | VERTICAL INPUTS (Schematic Diagram 1) |
| Ground relay stuck in <br> signal position | Test: Use "EXERCISE VOLT REF." Check that the ground relay is in <br> ground position. |
| Defective X10, X100, <br> X1, X2, X5 Relays <br> and Attenuators | Gross value problems for affected channel for volts measurement. |
|  | Test: Check channel accuracy at all VOLTS/DIV settings. |
| RO FREEZE line stuck <br> high (U173-11) | Gross cursor problems for volts measurement. |

Table 6-9, (cont)
Measurement Error Troubleshooting Hints

| Circuit <br> Problem | Symptoms |
| :--- | :--- | :--- |
| VERTICAL PREAMP AND OUTPUT AMPLIFIER (Schematic Diagram 2) |  |

Table 6-9, (cont)
Measurement Error Troubleshooting Hints

| Circuit Problem | Symptoms |
| :---: | :---: |
| B Trig Source Multiplexer (U431A) | "SEARCH RETURNED BAD VALUE AT . . ." on time measurements (unless stuck in LINE SOURCE). |
|  | Test: Set B Trigger SOURCE to VERT. For each channet, display only that channel and check that the signal applied to the displayed channel appears at U431 pin 25. |
| BW FULL B line (U1103-14) | Test: Should be CMOS low when SCOPE BW button is lit. <br> Should be CMOS high when SCOPE BW button is not lit; use ALT Horizontal MODE with B CPLG set to DC. |
| B Trig <br> (U431C) | "SEARCH RETURNED BAD VALUE AT . . ." on time measurements. |
| VERT COMP EN line stuck high (U1103-7) | See notes on "VERT COMP" (schematic diagram 2). |
|  | Test: $\overline{\text { VERT COMP EN }}$ should be at CMOS high in normal use. Run "SELF CAL" and check that VERT COMP EN goes to a CMOS low. |
| LINE/TIME BASE CAL signal Mux stuck in LINE position (U1106A) | "RETURNED BAD SEARCH VALUE AT . . ." from "SELF CAL" for time measurements. |
|  | Test: Run "EXERCISE TIME REF" diagnostic and check the output of U1106A (pin 1) for changing signal. |
| DISPLAY AND TRIGGER LOGIC AND PROCESSOR INTERFACE (Schematic Diagram 4) |  |
| MB RETURN line (U502-12) | See notes on VERT COMP (schematic diagram 2). |
| MP DLY SEL line (U503-13) or MP DLY SEL Interface (U602) | "SEARCH RETURNED BAD VALUE AT $5 \mu \mathrm{~s}$ " on time measurements. |
|  | Test: Turn all measurements off. Use the A Horizontal MODE. The MP DLY SEL signal should be at a TTL high. |
| SR DATA line (U606C-6) | Effects are the same as those caused by malfunctions in SR 0 and SR 1. |
|  | Test: The A Sweep rate changes when SEC/DIV knob is rotated in the A Horizontal MODE. |
| SR 0 CLK line (U606F-12) | Effects are the same as those caused by malfunctions in SR 0. |
|  | Test: Channel 1 sensitivity changes when CH 1 VOLTS/DIV knob is rotated. |

Table 6-9, (cont)
Measurement Error Troubleshooting Hints

| Circuit Problem | Symptoms |
| :---: | :---: |
| SR 1 CLK line (U606B-4) | Effects same as those caused by malfunctions in SR 1. |
|  | Test: Check that the A Sweep rate changes when SEC/DIV knob is rotated in the A Horizontal MODE. |
| SR 1 CLK TTL line (U501-13) | Effects same as those caused by malfunctions in auxiliary section of SR 1 (U1103, diagram 3). |
|  | Test: HF noise in trace reduces when SCOPE BW button is lit and increases when not lit. |
| Processor-to-DisplaySequencer Interface (U600) | Gross effects on all voltage and time measurements. |
|  | Test: Run DIAGNOSE and note results of SLIC CONTROL REG test. Set the A Trigger MODE to NORM; check that the ATS 0-2 signal lines (pins 31-33) change when the A Trigger SOURCE is changed. |
| TDO Level Shifter (U603, Q603, Q602) | Same as Processor-to-Display-Sequencer Interface problem. |
|  | Test: Using NORM mode for both triggers, VERT source for both triggers, and CH 1 only displayed; apply a four-division, squarewave signal to the CH 1 input. <br> In the A Horizontal mode, check that the TRIG'D LED light goes off and the sweep stops running with the Trigger LEVEL control at full CW rotation. <br> Change to AUTO mode for A trigger; check that sweep free-runs with the Trigger LEVEL control at full CW rotation. <br> Check that the TRIG'D LED can be lit and the sweep can be triggered when the Trigger LEVEL is set to within the signal limits. Keep the A Sweep triggered for the next check. <br> In B Horizontal mode, check that the TRIG'D LED goes off, and the sweep stops running with the Trigger LEVEL control set at full CW rotation. <br> Check that the TRIG'D LED can be lit and the sweep made to trigger when Trigger LEVEL is set to within the signal limits. <br> Change to RUNS AFTER Mode for the B Trigger. Check that the B Sweep free-runs. |

Table 6-9, (cont)
Measurement Error Troubleshooting Hints

| Circuit Problem | Symptoms |
| :---: | :---: |
| DLY SEL line stuck low (U602-32) | "SEARCH RETURNED BAD VALUE AT $5 \mu \mathrm{~s}$ " for "SELF CAL" on time measurements. <br> Test: Use settings given in previous test. Set the first delay zone to the start of the sweep with $k$ control. Check that the second delay zone can be positioned over the entire sweep length with the $\rightarrow$ control. |
| DLY SEL line stuck high (U602-32) | "SEARCH RETURNED BAD VALUE AT 0.1 ms " for "SELF CAL" on time measurements. |
|  | Test: Use settings given in previous test. Set the first delay zone to the start of the sweep with $k$ control. Check that the second delay zone can be positioned over the entire sweep length with the $\rightarrow$ control. |
| ATS 0-2 (U600, pins 31-33) A Trig Source Multiplexer | See notes on "A Trig Source Multiplexer" (schematic diagram 3). |
| BTS 0-2 (U600, pins 27-29) B Trig Source Multiplexer | See notes on "B Trig Source Multiplexer" (schematic diagram 3). |
| $\overline{\text { TRIG CLK }}$ line (U600-19) | See notes on "A Trig Cplg Multiplexer" (schematic diagram 3). |
| A AND B SWEEP AND DELAY COMPARATORS (Schematic Diagram 5) |  |
| DLY END 0 line stuck low or high (U315-15) | "SEARCH RETURNED BAD VALUE AT $5 \mu \mathrm{~s}$ " for "SELF CAL" on time measurements. |
|  | Test: Run the $k$ TIME $\rightarrow$ measurement in ALT Horizontal Mode with the A SEC/DIV at $1 \mathrm{~ms} / \mathrm{div}$ and the B SEC/DIV at $0.1 \mathrm{~ms} / \mathrm{div}$. Check that the first delay zone can be positioned over the length of sweep using the $k$ control. |
| Ref/Delta Delay Muxes stuck (U301A \& C) | See notes on DLY SEL (schematic diagram 4). |
| A Sweep Control circuit (U302 \& U303) | "SEARCH RETURNED BAD VALUE AT (affected SEC/DIV setting)" for <br> "SELF CAL" on time measurements. |
|  | Test: Use "EXERCISE VOLT REF" diagnostic. |

Table 6-9, (cont)
Measurement Error Troubleshooting Hints

| Circuit Problem | Symptoms |
| :---: | :---: |
| VOLT CAL 0-2 (U302 \& U303) | Gross value problems with volts measurement. |
|  | Test: Use "EXERCISE VOLT REF" diagnostic. |
| Z-AXIS, CRT, PROBE ADJUST, AND CONTROL MUX (Schematic Diagram 7) |  |
| VOLT CAL line (U931-3) | Gross value problems with volts measurement. |
|  | Test: Use "EXERCISE VOLT REF" diagnostic. |
| MEASUREMENT PROCESSOR (Schematic Diagram 8) |  |
| TB CAL line (U2501-22) | "SEARCH FAILED AT SWEEP SPEED . . ." in "SELF CAL" on time measurements. |
|  | Test: Use "EXERCISE TIME REF" diagnostic. <br> Check that TB CAL signal is correct and signal path is intact to U421A pin 4 (diagram 3) through U1106A. |
| $\begin{aligned} & \text { SLIC WR } \\ & (\mathrm{U} 2518-12) \\ & \hline \end{aligned}$ | See notes on "Processor-to-Display-Sequencer Interface" (schematic diagram 4). |
| $\begin{aligned} & \hline \overline{\text { SLIC RD }} \\ & \text { (U2503C-8) } \end{aligned}$ | See notes on "Processor-to-Display-Sequencer Interface" (schematic diagram 4). |
| $\begin{aligned} & \overline{\text { FLIC WR }} \\ & \text { (U2518-11) } \end{aligned}$ | See notes and tests on "TDO Level Shifter" (schematic diagram 4). |
| MB DATA (U2515-11) | See notes on "Processor-to-Display-Sequencer Interface" (schematic diagram 4). |
| Field \& Mixer Control Latch or Readout Position Mixer stuck (U2411, U2414, U2415) | Gross cursor problems with volts measurement. |
|  | Test: Run $k$ VOLTS $\rightarrow$ CURSOR Measurement mode with only CH 1 displayed. <br> Check that cursors move the CH 1 position control. <br> Check that $k$ cursor moves with $k$ control and $\rightarrow$ cursor moves with $\rightarrow$ control. <br> Check that top and bottom line of readout do not move with any position control. |

Table 6-9, (cont)
Measurement Error Troubleshooting Hints

| Circuit Problem | Symptoms |
| :---: | :---: |
| ADC, DAC SYSTEM (Schematic Diagram 11) |  |
| A TRIG LVL (U2304C-8) | See notes for A Trig (schematic diagram 3). |
|  | Test: Select A trigger, set A Trigger MODE to NORM. <br> Check that A TRIG LVL can be set to any value from -2.5 to +2.5 volts using the Trigger LEVEL control. |
| B REF TRIG LVL$(U 23048-7)$ (U2304B-7) | See notes for "B Trig" (schematic diagram 3). |
|  | Test: Select B trigger, set B Trigger MODE to NORM, and select B Horizontal MODE. |
| $\begin{aligned} & \text { REF DLY } \\ & \text { (U2305C-8) } \end{aligned}$ | "RETURNED BAD SEARCH VALUE AT . . ." for "SELF CAL" on time measurements. |
|  | Test: Run $\vDash \leftarrow$ TIME $\rightarrow$ measurement in ALT Horizontal mode; A at $1 \mathrm{~ms} / \mathrm{div}$, B at $0.1 \mathrm{~ms} / \mathrm{div}$. <br> Check that first delay zone can be positioned over length of sweep with the $k$ control. |
| $\begin{aligned} & \text { DELTA DELAY } \\ & (\mathrm{U} 2305 \mathrm{~B}-7) \end{aligned}$ | "RETURNED BAD SEARCH VALUE AT . . ." for "SELF CAL" on on time measurements. |
|  | Test: Use the preceding REF DLY settings, and set first delay zone to start of sweep with $k$ control. <br> Check that second delay zone can be positioned over length of sweep with $\rightarrow 1$ control. |
| REF CURSOR <br> (U2304D-14) | Gross value problems with volts measurement. |
|  | Test: Run $\Vdash$ VOLTS $\rightarrow 1$ CURSOR Measurement Mode. <br> Check that $k$ cursor can be positioned $\pm 15$ divisions around the trace ground. |
| DELTA CURSOR (U2304A-1) | Gross value problems with volts measurement. |
|  | Test: Run $\mathfrak{k}$ VOLTS $\rightarrow$ CURSOR Measurement Mode. <br> Check that $\rightarrow$ cursor can be positioned $\pm 15$ divisions around the trace ground level. |

## CORRECTIVE MAINTENANCE

## INTRODUCTION

Corrective maintenance consists of component replacement and instrument repair. This part of the manual describes special techniques and procedures that are needed to replace components in this instrument. If it is necessary to ship your instrument to a Tektronix Service Center for repair or service, refer to the Repackaging for Shipment information in this section.

## MAINTENANCE PRECAUTIONS

To reduce the possibility of personal injury or instrument damage, observe the following precautions.

1. Disconnect the instrument from the ac-power source before removing or installing components.
2. Verify that the line-rectifier filter capacitors are discharged prior to performing any servicing.
3. Use care not to interconnect instrument grounds which may be at different potentials (cross grounding).
4. When soldering on circuit boards or small insulated wires, use only a 15-watt, pencil-type soldering iron.


Do not exceed 9 in-lb of torque when tightening the 6-32 screws.
5. Use care not to overtighten screws into chassis. Threads that have been formed directly into aluminum components can be stripped out. If this occurs, use a 6-32 nut to secure the screw.

## WARNING

Portions of the power supply are floating at the ac line voltage level and pose a shock hazard if not isolated from ground
6. Use an isolation transformer to supply power to the 2245A if you troubleshoot in the power supply with power applied to the instrument.

## OBTAINING REPLACEMENT PARTS

Electrical and mechanical replacement parts can be obtained through your local Tektronix Field Office or representative. However, many of the standard electronic components may be obtained from a local commercial source. Before purchasing or ordering a part from a source other than Tektronix, Inc., please check the Replaceable Electrical Parts list for the proper value, rating, tolerance, and description.

## NOTE

> The physical size and shape of a component may affect instrument performance, particularly at high frequencies. Always use directreplacement components, unless it is known that a substitute will not degrade instrument performance. Parts in the ort high-voltage and Z-Axis circuits are safety-controlledUSE EXACT REPLACEMENTS in these circuits.

## Special Parts

In addition to the standard electronic components, some special parts are used in the 2245A. These components are manufactured or selected by Tektronix, Inc. to meet specific performance requirements, or are manufactured for Tektronix, Inc. in accordance with our specifications. The various manufacturers can be identified by referring to the Cross Index-Manufacturer's Code number to Manufacturer at the beginning of the Replaceable Electrical Parts list (Section 8). Most of the mechanical parts in this instrument are manufactured by Tektronix, Inc. Order all special parts directly from your local Tektronix Field Office or representative.

## Ordering Parts

When ordering replacement parts from Tektronix, lnc., be sure to include all of the following information:

1. Instrument type (include modification or option numbers).
2. Instrument serial number.
3. A description of the part (if electrical, include its full circuit component number).
4. Tektronix part number.

## REPACKAGING FOR SHIPMENT

Save the original carton and packing material for reuse if the instrument should have to be reshipped on a commercial transport carrier. If the original materials are unfit or not available, repackage the instrument as follows:

1. Use a corrugated cardboard shipping carton with a test strength of at least 275 pounds and with an inside dimension at least six inches greater than the instrument dimensions.
2. If instrument is being shipped to a Tektronix Service Center, enclose the following information: the owner's address, name and phone number of a contact person, type and serial number of the instrument, reason for returning, and a complete description of the service required.
3. Completely wrap the instrument with polyethylene sheeting or equivalent to protect the outside finish and prevent entry of foreign materials into the instrument.
4. Cushion the instrument on all sides, using three inches of padding material or urethane foam
tightly packed between the carton and the instrument.
5. Seal the shipping carton with an industrial stapler or strapping tape.
6. Mark the address of the Tektronix Service Center and also your own return address on the shipping carton.

## MAINTENANCE AIDS

The maintenance aids listed in Table 6-10 include items required for performing most of the maintenance procedures in this instrument. Equivalent products may be substituted for the examples given if their characteristics are similar.

## INTERCONNECTIONS

Several types of mating connectors are used for the interconnecting cable pins. The following information gives the replacement procedures for the various connectors:

## End-Lead Pin Connectors

Pin connectors used to connect the wires to the interconnect pins are factory assembled. They consist of machine-inserted pin connectors mounted in plastic holders. If the connectors are faulty, the entire wire assembly should be replaced.

## Ribbon-Cable Connectors

The etch-ribbon cables have the connector pins crimped onto the wire runs. If the connectors are defective, the entire ribbon cable assembly must be replaced.

Table 6-10
Maintenance Aids

| Description | Specification | Usage | Example |
| :---: | :---: | :---: | :---: |
| Soldering Iron | 15 to 25 W . | General soldering and unsoldering. | Antex Precision Model C. |
| Torx Screwdriver Tips and Handle | Torx tips: \#T7, \#T9, \#T10, \#T15, and \#T20. <br> Handle: $1 / 4$ inch hex drive. | Assembly and disassembly. | Tektronix Part Numbers: <br> Handles: <br> $81 / 2 \mathrm{in}$. 003-0293-00 <br> 3 1/2 in. 003-0445-00 |
| Nutdrivers | 1/4 inch, 5/16 inch, 1/2 inch, and 9/16 inch. | Assembly and disassembly. | Xcelite \#8, \#10, \#16 and \#18. |
| Open-end Wrench | 9/16 inch and $1 / 2$ inch. | Channel Input and Ext Trig BNC Connectors | Tektronix Part Numbers: $\begin{aligned} & 9 / 16) \text { 003-0502-00 } \\ & 1 / 2) \text { 003-0822-00 } \end{aligned}$ |
| Hex Wrenches | 0.050 inch, $1 / 16$ inch. | Assembly and disassembly. | Allen wrenches. |
| Long-nose Pliers |  | Component removal and replacement. | Diamalloy Model LN55-3. |
| Diagonal Cutters |  | Component removal and replacement. | Diamalloy Model M554-3. |
| Vacuum Solder Extractor. | No Static Charge Retention. | Unsoldering static sensitive devices and components on multilayer boards. | Pace Model PC-10. |
| Contact Cleaner | No-Noise. ${ }^{(8)}$ | Switch and pot cleaning. | Tektronix Part Number 006-0442-02. |
| Pin-replacement Kit |  | Replace circuit board connector pins. | Tektronix Part Number 040-0542-01. |
| IC-removal Tool |  | Removing DIP IC packages. | Augat T114-1. |
| Isopropyl Alcohol | Reagent grade. | Cleaning attenuator and front-panel assemblies. | 2-Isopropanol. |
| Isolation Transformer |  | Isolate the instrument from the ac power source for safety. | Tektronix Part Number 006-5953-00. |
| 1X Probe |  | Power supply ripple check. | TEKTRONIX P6101A. |

## LITHIUM BATTERY (B2501)

The lithium battery used to supply backup power to the System RAM should last for at least 3 years. However, when it becomes necessary to replace the battery, be sure to observe the following general warning about disposal of lithium batteries.

## WARNING

To avoid personal injury, observe proper procedures for handling and disposal of lithium batteries. Improper handling may cause fire, explosion, or severe burns. Do not recharge, crush, disassemble, heat the battery above $212^{\circ} \mathrm{F}\left(100^{\circ} \mathrm{C}\right)$, incinerate, or expose contents of the battery to water. Dispose of battery in accordance with local, state, and national regulations.

Typically, small quantities (less than 20) can be safely disposed of with ordinary garbage n a sanitary landfill. Larger quantities must ze sent by surface transport to a hazardou's vaste disposal facility. The batteries should be individually packaged to prevent shorting and packed in a sturdy container that is clearly labeled "Lithium Batteries-DO NOT OPEN."

## TRANSISTORS AND INTEGRATED CIRCUITS

Transistors and integrated circuits should not be replaced unless they are actually defective. If one is removed from its socket or unsoldered from the circuit board during routine maintenance, return it to its original board location. Unnecessary replacement or transposing of semiconductor devices may affect the adjustment of the instrument. When a semiconductor is replaced, check the performance of any circuit that may be affected.

Any replacement component should be of the original type or a direct replacement. Bend component leads to fit their circuit board holes, and cut the leads to the same length as the original component. See Figure 9-2 in the Diagrams section for the semiconductor lead-configurations.

> After replacing a power transistor, check that the collector is not shorted to the chassis before applying power to the instrument.

To remove socketed dual-in-line packaged (DIP) integrated circuits, pull slowly and evenly on both ends of the device. Avoid disengaging one end of the integrated circuit from the socket before the other, since this may damage the pins.

To remove a soldered DIP IC when it is going to be replaced, clip all the leads of the device and remove the leads from the circuit board one at a time. If the device must be removed intact for possible reinstaliation, do not heat adjacent conductors consecutively. Apply heat to pins at alternate sides and ends of the IC as solder is removed. Allow a moment for the circuit board to cool before proceeding to the next pin.

## SOLDERING TECHNIQUES

The reliability and accuracy of this instrument can be maintained only if proper soldering techniques are used to remove or replace parts. General soldering techniques that apply to maintenance of any precision electronic equipment should be used when working on this instrument.

## WARNING

To avoid an electrical-shock hazard, observe the following precautions before attempting any soldering: turn the instrument off, disconnect it from the ac power source, and wait at least three minutes for the line-rectifier filter capacitors to discharge.

Use rosin-core wire solder containing 63\% tin and $37 \%$ lead. Contact your local Tektronix Field Office or representative to obtain the names of approved solder types.

When soldering on circuit boards or small insulated wires, use only a 15-watt, pencil-type soldering iron. A higher wattage soldering iron may cause etched circuit conductors to separate from the board base material and melt the insulation on small wires. Always keep the soldering-iron tip properly tinned to ensure the best heat transfer from the tip to the solder joint. Apply only enough solder to make a firm joint. After soldering, clean the area around
the solder connection with an approved fluxremoving solvent (such as isopropyl alcohol) and allow it to air dry.

Only an experienced maintenance person, proficient in the use of vacuum-type desoldering equipment should attempt repair of any circuit board in this instrument. Many integrated circuits are static sensitive and may be damaged by solder extractors that generate static charges. Perform work involving static-sensitive devices only at a staticfree work station while wearing a grounded antistatic wrist strap. Use only an antistatic vacuum-type solder extractor approved by a Tektronix Service Center.

## \{CAUTION\}

Attempts to unsolder, remove, and resolder leads from the component side of a circuit board may cause damage to the reverse side of the circuit board. The following techniques should be used to replace a component on a circuit board:

1. Touch the vacuum desoldering tool tip to the lead at the solder connection. Never place the tip directly on the board; doing so may damage the board.

## NOTE

Some components are difficult to remove from the circuit board due to a bend placed in the component leads during machine insertion. To make removal of machine-inserted components easier, straighten the component leads on the reverse side of the circuit board.
2. When removing a multipin component, especially an IC, do not heat adjacent pins consecutively. Apply heat to the pins at alternate sides and ends of the IC as solder is removed. Allow a moment for the circuit board to cool before proceeding to the next pin.

Excessive heat can cause the etched circuit conductors to separate from the circuit board. Never allow the solder extractor tip to remain at one place on the board for more than three seconds. Solder wick, springactuated or squeeze-bulb solder suckers, and heat blocks (for desoldering multipin components) must not be used. Damage caused by poor soldering techniques can void the instrument warranty.
3. Bend the leads of the replacement component to fit the holes in the circuit board. If the component is replaced while the board is installed in the instrument, cut the leads so they protrude only a small amount through the reverse side of the circuit board. Excess lead length may cause shorting to other conductive parts.
4. Insert the leads into the holes of the board so that the replacement component is positioned the same as the original component. Most components should be firmly seated against the circuit board.
5. Touch the soldering iron tip to the connection and apply enough solder to make a firm solder joint. Do not move the component while the solder hardens.
6. Cut off any excess lead protruding through the circuit board (if not clipped to the correct length in step 3).
7. Clean the area around the solder connection with an approved flux-removing solvent. Be careful not to remove any of the printed information from the circuit board.

## REMOVAL AND REPLACEMENT INSTRUCTIONS

## WARNING

To avoid electrical shock, disconnect the instrument from the power input source before removing or replacing any component or assembly.

The exploded-view drawings in the Replaceable Mechanical Parts list may be helpful during removal
and reinstallation of individual components or subassemblies. Circuit board and component locations are shown in the Diagrams section.

Read these instructions before attempting to remove or install any components.

## Cabinet

To remove the cabinet:

1. Unplug the power cord from its rear-panel connector.
2. Place the instrument face down on a clean, flat surface.
3. Remove the Torx-head screw from the right side near the rear of the cabinet.
4. Remove the plastic rear cover, held with four Torx-head screws.
5. Slide the cabinet housing up and off the instrument.

## WARNING

Potentially dangerous voltages exist at several points throughout this instrument. If it is operated with the cabinet removed, do not touch exposed connections or components. Before replacing parts or cleaning, disconnect the ac-power source from the instrument and check that the line-rectifier filter capacitors have discharged. Also, check the low voltages at the Power-Supply/MainBoard interface connector (J1024). If any of the supply-voltage or line-voltage filter capacitors remain charged for more that 20 seconds, discharge them to ground through a $1 \mathrm{k} \Omega, 5$ - or 6 -watt resistor.

To install the cabinet:
6. Carefully slide the cabinet housing over the rear of the instrument. Be careful not to snag any of the folded ribbon cables. Make sure the cabinet housing slides between the plastic front-panel housing and the instrument chassis.
7. Install the rear panel. Secure it with four \#15 Torx-head screws.
8. Install a Torx-head screw in the right side of the cabinet.

## Crt Removal and Replacement

## WARNING

Use care when handling a crt. Breaking the crt can cause high-velocity scattering of glass fragments. Protective clothing and safety glasses or safety face shield should be worn. Avoid striking the crt on any object which might cause it to crack or implode. When storing a crt, either place it in a protective carton or set it face down on a smooth surface in a protected location with a soft mat under the faceplate.

To remove the crt:

## WARNING

To avoid electrical shock, carefully discharge the crt anode lead directly to the metal chassis. To avoid static-discharge damage to electronic components, do not allow the anode lead to discharge into the adjacent circuitry.

1. Disconnect the high-voltage anode lead. Pull the anode-lead coupler apart slowly and carefully. DO NOT touch the exposed connector pin as it is withdrawn from coupler socket. Discharge the exposed anode pin to the metal chassis only. A hole is provided in the left side of the power supply chassis for the purpose of holding the end of the lead to prevent a recharge while it is disconnected.
2. Unplug the trace rotation cable (P27) from the Main board.
3. Unplug the two vertical and the two horizontal deflection leads from the crt neck. Grasp each lead connector with long-nosed pliers and pull it straight away from the crt neck pins. Be careful not to bend the neck pins.
4. Remove the crt implosion shield and bezel frame (held with two screws at the lower side).
5. Place your left hand on the crt neck shield and your right hand over the crt face. Move the crt assembly forward to unplug the crt from its socket and carefully withdraw it from the instrument while ensuring that the crt anode lead clears all obstructions. Do not hold the crt assembly by the shield only.
6. If it is necessary remove the metal shield from crt, carefully slide the shield to the rear of the crt. Be careful not to damage the neck pins.

To install the crt:
7. Install the metal shield over the neck of the crt. Make sure that the plastic grommet is in place over the front of the shield. Align the neck pins with the shield holes.
8. Check that the graticule scale-illumination light pipe is in place at bottom front of crt opening. Also make sure that the four crt corner cushions are in place in the crt opening of the subpanel.
9. Carefully guide the crt, anode lead, and trace rotation cable into the instrument. Line up the crt base pins with base socket. Make sure that the ground clip above the rear of the crt shield goes outside of the shield. Hold in on the rear of the base socket with one hand and push on the face of the crt with the other hand to completely seat the crt base pins. If the crt will not go in all the way, check for bent pins. DO NOT FORCE this connection!
10. Connect the trace rotation cable (P27) to the Main board.
11. Connect the vertical and horizontal deflection leads to the crt neck pins. The horizontal deflection leads (going to bottom pins) should be crossed.
12. Connect the high-voltage anode lead.
13. Install the crt implosion shield and frame using two $7 / 8 \mathrm{in}$. Torx-head screws.
14. Check that the graticule illumination light bulbs are in place in the light pipe at the bottom of the crt.

## BNC Connectors (Vertical Inputs)

To replace BNC Connectors:

1. Remove the Main board (see Main board removal procedure).

## NOTE

Do not disconnect the ends of the delay line from board as indicated in the Main board removal procedure. It is not necessary for replacing the input BNC connectors.
2. Using a 9/16 open-end wrench, remove and replace the defective BNC connector(s).
3. Replace the Main board (see Main board installation procedure).

## A16 Processor Board

To remove the Processor board:

1. Unplug ribbon cables J2501, J18pin, J17pin, and J25pin from the the processor board. To aid the release of the ribbon-cable pins from connector, slide a thin-shafted, flat-bladed screwdriver between the ribbon cable (near the connector) and the etched-circuit board and pry gently upward.
2. Remove the six Torx-head attaching screws (one at each corner and two in the middle).
3. Unplug J2501 (17-pin) from the Potentiometer board and lift the Processor board out of the instrument.

To install the Processor board:

## $\{$ CAUTION $\}$ <br> \&~NMNN

Do not exceed $9 \mathrm{in-l} / \mathrm{l}$ of torque when tightening the 6-32 screws that hold the circuit board to the chassis. Damage to the circuit board and/or screw threads may result if the screws are overtightened.
4. Position the board to align the screw holes and install the six Torx-head attaching screws (two, $5 / 8 \mathrm{in}$. screws in the center and one, 7/16 in. screw at each corner).
5. Plug in ribbon cables J20pin, J17pin, J18pin, J17pin, and J25pin. Press the ribbon cable pins firmly into the connector holes.

## A18 Power Supply Board

To remove the Power Supply board:

1. Remove the Processor board (see Processor board removal procedure).

## WARNING

To avoid electrical shock, carefully discharge the crt anode lead directly to the metal chassis. To avoid static-discharge damage to electronic components, do not allow the anode lead to discharge into the adjacent circuitry.
2. Disconnect the high-voltage anode lead. Pull the anode-lead coupler apart slowly and carefully. DO NOT touch the exposed connector pin as it is withdrawn from coupler socket. Discharge the exposed anode pin to the metal chassis only. A hole is provided in the left side of the power supply chassis for the purpose of holding the end of the lead to prevent a recharge while it is disconnected.
3. Remove the eight screws holding the power supply housing shield and remove the shield.
4. Disconnect the connectors from J2208 and J 2225 and the two wires from ac-line filter. (Note the color stripes on the wires to the line filter for reinstallation.)
5. Pull the HV connector through the grommet in the power supply housing.
6. Set the POWER switch in the OFF (out) position.

## \{CAUTION\}

The POWER switch must be in the OFF position to safely remove the shaft from the shaft of the switch in the following step. Pulling the shaft off with the POWER switch on may damage the switch shaft and spring assembly.
7. Remove the power-switch-extension shaft. Snap the extension shaft off the transitional pivot assembly, then pull the shaft off the switch.
8. Remove the six screws that hold down the Power Supply board.
9. Unplug the Power Supply board from the Main board interface connector. Grasp the two heat sinks near the center of the board, one with each hand, and pull up to disconnect the interface connection.
10. Lift the front of Power Supply board and withdraw the board from the power-supply housing.

To install the Power Supply board:
11. Place the Power Supply board into power-supply housing. First, guide the fuse holder into the rear panel, then lower the front end of the board until the board interface pins touch the interface connector.
12. Plug the interface pins into the interface connector. With the Power Supply board against the rear panel, pull up on the large electrolytic capacitor (near the center of the board) with one hand and push down on HV multiplier module (at front of board) with the other hand. This action tends to align the pins with the connector. At the same time you will have to move the board around slightly so that the pins will easily slide into the connector holes. DO NOT FORCE this connection, otherwise you may bend the pins.

## $\{$ CAUTION\} EMUTOS

Do not exceed 9 in-lb of torque when tightening the 6-32 screws that hold the circuit board to the chassis. Damage to the circuit board or screw threads may result if the screws are overtightened.
13. Secure the circuit board with six screws.
14. Install the power-switch-extension shaft. Snap the shaft onto the switch, then onto the transitional pivot assembly.
15. Insert the high-voltage lead through the power-supply-housing grommet and snap the connector shell into the clamp at the front of the power-supply housing.
16. Connect the leads to J2208, J2225, and the ac-line filter (observe the color coding noted when the filter leads were disconnected).
17. Install the power-supply-housing shield with eight screws.
18. Connect the crt anode lead to the HV connector.
19. Install the Processor board (see Processor board installation instructions).

## Potentiometer/Switch board Assembly

To remove the Potentiometer/Switch board assembly:

1. Unplug ribbon-cable connector P2501 from the Processor board and unplug ribbon-cable connector P2105 from the Potentiometer board.
2. Remove the CH 1 and CH 2 VOLTSIDIV VAR knobs and the SEC/DIV VAR knob. (A 1/16 in. hexagonal wrench is needed for the set screws).
3. Pull out all the remaining front-panel knobs to the right of the crt. Grasp the knobs firmly and pull straight out from the front panel.
4. Pull out on the four captive plastic snap fasteners on the back of the Switch board that hold the Switch board assembly to the front panel (not those that hold the Potentiometer board to the Switch board). Use long-nose pliers as necessary to reach the fasteners.
5. Unclip the high-voltage connector from the front of the power-supply housing. Remove the plastic retaining clip from the housing (it is pressed in). Move the high-voltage connector to the top of the power-supply housing to make room for removing the Potentiometer/Switch board.
6. Move the Potentiometer/Switch board assembly back away from the front panel and lift it out of the instrument.

To separate the A12 Potentiometer board from the Switch board:
7. Pull out on the three snap fasteners that hold the Potentiometer board to the Switch board.
8. Separate the Potentiometer board from the Switch board.
9. If necessary, unplug the VAR control shafts from their potentiometers.

To install the Potentiometer board:
10. Set the three snap fasteners on the board in the released (out) position.
11. Plug the three VAR control shafts onto the VAR potentiometers.
12. Set the Potentiometer board in place over the Switch board and press in on the snap fasteners.

To install the Potentiometer/Switch board assembly:
13. Set the four snap fasteners (on the Switch board) in the released (out) position.
14. Guide the Potentiometer/Switch board assembly into place behind the front panel and press in on the snap fasteners.
15. Install the control knobs. Push knobs in while rotating slightly until they align with the shaft and snap in place. The two knobs without a positionindicator rib go on the $k$ and $\rightarrow$ control shafts.
16. Install the three VAR control knobs, using $1 / 16$ in. allen wrench. Make sure that VAR controls are in the detent (fully CW ) position, then rotate the knobs so that the VAR label is horizontal before tightening the set screws.
17. Install the high-voltage connector clip to the front side of the power-supply housing and snap the connector shell into it.
18. Connect ribbon cable J2105 to the Potentiometer board and P2501 to the Processor board. Position the connector pins in the socket holes and push them fully into place.

A10 Main Board

## NOTE

This procedure is intended for the complete replacement of the Main board. All repairs and component replacements '(except BNC connectors) can be done without completely removing the Main board. When replacing BNC connectors, use the BNC Connector replacement procedure previously given in this section.

To remove the Main board:

1. Remove the crt (see crt removal procedure).
2. Pull out and remove the five crt-display control knobs.
3. Remove the Processor board (see Processor board removal procedure).
4. Remove the shield from the power-supply housing (held with eight screws).
5. Unplug the three-wire cable from J2208 on the Power Supply board. Pull the cable and connector through the plastic grommet.
6. Release the crt socket from its holder on the rear panel. First pull off clear plastic socket retainer, then push the socket out the rear enough to turn it sideways and push it through to the inside of the instrument.
7. Remove the Potentiometer/Switch board assembly (see Potentiometer/Switch board assembly removal procedure).
8. Remove the top and bottom attenuator shields. The bottom shield is held with five screws and the top shield is held with one remaining screw. See Figure 6-4.

## NOTE

If the Main board is being removed to replace or repair a component (such as a BNC connector), it is not necessary to disconnect the delay line from the board as indicated in the following step.
9. Unsolder the main delay-line wires from both sides of board (see Figures 6-4 and 6-5).
10. Unclip the delay line from both sides of the board and from the two clips at the lower side of the rear panel. Remove the two clips from the rear panel.
11. Remove the ten screws that hold the Main board to the chassis. Back out the three screws going through the rear panel enough to allow removal of Main board. See Figure 6-4.
12. Pull the three ribbon cables through to the bottom of the instrument.
13. Lift the back of Main board enough to disconnect interface connection between Main board and Power Supply board.
14. Slide the Main board back away from the front panel to completely remove the board from the instrument.

To install the Main board:
15. Guide the BNC connectors at front of the Main board into the holes in the front panel. Make sure that you guide the PROBE ADJUST jack into the front panel as well as the BNC connectors.
16. Lower the rear of Main board while guiding the interface connector onto the power supply interface pins. DO NOT FORCE this connection; the pins may bend. Make sure that the grommet holding the crt and power supply wires is in place between the board and the rear panel.

Do not exceed 9 in-lb of torque when tightening the 6-32 screws that hold the circuit board to the chassis. Damage to the circuit board or screw threads may result if the screws are overtightened.
17. Secure the Main board with ten screws. See Figure 6-4.
18. Solder both ends of delay line to Main board. Be sure to observe the polarity of the leads. See Figures $6-4$ and $6-5$. Press the ends of delay line into the clips on board.
19. Snap the two plastic clips into the lower edge of the rear panel and snap the delay line into them.
20. Connect the three-wire cable from the crtsocket cable assembly to J 2208 on the Power Supply board.
21. Install the shield on the power-supply housing (eight screws).
22. Install the inside attenuator shield (secure with one screw). Then install the outside attenuator shield (secure with five screws).
23. Install the Potentiometer/Switch board assembly (see Potentiometer/Switch board assembly installation procedure).
24. Install the Processor board.


Figure 6-4. Main board removal.


Figure 6-5. Delay-line connections to top of Main board.
25. Dress the two ribbon cables to the top of the instrument. Connect them to the Processor and Potentiometer boards.
26. Install the crt socket. Turn the socket sideways and push it through the crt-socket holder in the rear panel.
27. Install the crt (see crt installation procedure).

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## OPTIONS

## INTRODUCTION

This section contains a general description of the instrument options available at the time of publication. Additional information about instrument options can be obtained either by consulting the current Tektronix Product Catalog or by contacting your local Tektronix Field Office or representative.

## INTERNATIONAL POWER CORDS

Instruments are shipped with the detachable powercord option ordered by the customer. Descriptive information about the international power-cord options is provided in Section 2 "Preparation for Use.' ' The following list describes the power cords available for the 2245A.

| Standard | North American 120 V, $60 \mathrm{~Hz}, 74 \mathrm{in}$. |
| :---: | :---: |
| Option A1 | Universal Euro 220 V , $50 \mathrm{~Hz}, 2.5 \mathrm{~m}$ |
| Option A2 | $\begin{aligned} & \text { UK } 240 \mathrm{~V}, 50 \mathrm{~Hz} \text {, } \\ & 2.5 \mathrm{~m} \end{aligned}$ |
| Option A3 | Australian 240 V , $50 \mathrm{~Hz}, 2.5 \mathrm{~m}$ |
| Option A4 | North American $220 \mathrm{~V}, 50 \mathrm{~Hz}, 2.5 \mathrm{~m}$ |
| Option A5 | Switzerland 220 V , $50 \mathrm{~Hz}, 2.5 \mathrm{~m}$ |

## OPTION 1R <br> RACKMOUNTED INSTRUMENT

When the 2245A Portable Oscilloscope is ordered with Option 1R, it is shipped in a configuration that permits easy installation into a 19 -inch-wide equipment rack. Also, an optional rackmounting kit may be ordered to convert the standard 2245A to a rackmounted instrument. Installation instructions for rackmounting are provided in the documentation supplied with the rackmounting kit and the 1R Option.

This Document is a complete Scan from the original Tektronix manual
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High quality line of technical Manuals in PDF
mailto : Qservice@otenet.gr


# REPLACEABLE ELECTRICAL PARTS 

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

## LIST OF ASSEMBLIES

A list of assemblies can be found at the beginning of the Electrical Parts List. The assemblies are listed in numerical order. When the complete component number of a part is known, this list will identify the assembly in which the part is located.

## CROSS INDEX-MFR. CODE NUMBER TO MANUFACTURER

The Mfr. Code Number to Manufacturer index for the Electrical Parts List is located immediately after this page. The Cross Index provides codes, names and addresses of manufacturers of components listed in the Electrical Parts List.

ABBREVIATIONS<br>Abbreviations conform to American National Standard Y1.1.

## COMPONENT NUMBER (column one of the Electrical Parts List)

A numbering method has been used to identify assemblies, subassemblies and parts. Examples of this numbering method and typical expansions are illustrated by the following:

Example a. component number


Read: Resistor 1234 of Assembly 23


Read: Resistor 1234 of Subassembly 2 of Assembly 23

Only the circuit number will appear on the diagrams and circuit board illustrations. Each diagram and circuit board illustration is clearly marked with the assembly number. Assembly numbers are also marked on the mechanical exploded views located in the Mechanical Parts List. The component number is obtained by adding the assembly number prefix to the circuit number.

The Electrical Parts List is divided and arranged by assemblies in numerical sequence (e.g., assembly A1 with its subassemblies and parts, precedes assembly A2 with its subassemblies and parts).

Chassis-mounted parts have no assembly number prefix and are located at the end of the Electrical Parts List.

## TEKTRONIX PART NO. (column two of the Electrical Parts List)

Indicates part number to be used when ordering replacement part from Tektronix.

## SERIAL/MODEL NO. (columns three and four of the Electrical Parts List)

Column three (3) indicates the serial number at which the part was first used. Column four (4) indicates the serial number at which the part was removed. No serial number entered indicates part is good for all serial numbers.

## NAME \& DESCRIPTION (column five of the Electrical Parts List)

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

## MFR. CODE (column six of the Electrical Parts List)

Indicates the code number of the actual manufacturer of the part. (Code to name and address cross reference can be found immediately after this page.)

## MFR. PART NUMBER (column seven of the Electrical Parts List)

Indicates actual manufacturers part number

## CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 00779 | AMP INC | 2800 FULLING MILL <br> PO BOX 3608 | HARRISBURG PA 17105 |
| 01121 | ALLEN-BRADLEY CO | 1201 SOUTH 2ND ST | MILWȦUKEE WI 53204-2410 |
| 01295 | TEXAS INSTRUMENTS INC SEMICONDUCTOR GROUP | 13500 N CENTRAL EXP PO BOX 655012 | DALLAS TX 75265 |
| 02735 | RCA CORP <br> SOLID STATE DIVISION | ROUTE 202 | SOMERVILLE NJ 08876 |
| 03508 | GENERAL ELECTRIC CO SEMI-CONDUCTOR PRODUCTS DEPT | W GENESEE ST | AUBURN NY 13021 |
| 04099 | CAPCO INC | 1328 WINTERS AVE PO BOX 1028 | GRAND JUNCTION CO 81502 |
| 04222 | AVX CERAMICS DIV OF AVX CORP | 19TH AVE SOUTH P O BOX 867 | MYRTLE BEACH SC 29577 |
| 04713 | MOTOROLA INC SEMICONDICTOR PRODUCTS SECTOR | 5005 E MCDOWELL RD | PHOENIX AZ 85008-4229 |
| 05245 | CORCOM INC | 1600 WINCHESTER RD | LIBERTYVILLE IL 60048-1267 |
| 05397 | UNION CARBIDE CORP MATERIALS SYSTEMS DIV | 11901 MADISON AVE | CLEVELAND OH 44101 |
| 05828 | GENERAL INSTRUMENT CORP GOVERNMENT SYSTEMS DIV | 600 W JOHN ST | HICKSVILLE NY 11802 |
| 06665 | PRECISION MONOLITHICS INC SUB OF BOURNS INC | 1500 SPACE PARK DR | SANTA CLARA CA 95050 |
| 07263 | FAIRCHILD SEMICONDUCTOR CORP <br> NORTH AMERICAN SALES <br> SUB OF SCHLLMBERGER LTD MS 118 | 10400 RIDGEVIEW CT | CUPERTINO CAW CA 95014 |
| 08806 | GENERAL ELECTRIC CO MINIATURE LAMP PRODUCTS DEPT | NELA PK | CLEVELAND OH 44112 |
| 09922 | BURNDY CORP | RICHARDS AVE | NORWALK CT 06852 |
| 11236 | CTS CORP <br> BERNE DIV <br> THICK FILM PRODUCTS GROUP | 406 PARR ROAD | BERNE IN 46711-9506 |
| 12954 | MICROSEMI CORP - SCOTTSDALE | 8700 E THOMAS RD P O BOX 1390 | SCOTTSDALE AZ 85252 |
| 13511 | AMPHENOL CADRE DIV BUNKER RAMO CORP |  | LOS gatos CA |
| 14433 | ITT SEMICONDUCTORS DIV |  | WEST PALM BEACH FL |
| 14552 | MICROSEMI CROP | 2830 S FAIRVIEW ST | SANTA ANA CA 92704-5948 |
| 15238 | ITT SEMICONDLCTORS <br> A DIVISION OF INTERNATIONAL <br> TELEPHONE AND TELEGRAPH CORP | $\begin{aligned} & 500 \text { BROADWAY } \\ & \text { P O BOX } 168 \end{aligned}$ | LAWRENCE MA 01841-3002 |
| 15454 | AMETEK INC RODAN DIV | 2905 BLUE STAR ST | ANAHEIM CA 92806-2510 |
| 19613 | MINNESOTA MINING AND MFG CO <br> TEXTOOL PRODUCTS DEPT <br> ELECTRONIC PRODUCT DIV | 1410 E PIONEER DR | IRVING TX 75061-7847 |
| 19701 | MEPCO/CENTRALAB <br> A NORTH AMERICAN PHILIPS CO | P 0 B0X 760 | MINERAL WELLS TX 76067-0760 |
| 20932 | KYOCERA INTERNATIONAL INC | 11620 SORRENTO VALLEY RD PO BOS 81543 PLANT NO 1 | SAN DIEGO CA 92121 |
| 24546 | CORNING GLASS WORKS | 550 HIGH ST | BRADFORD PA 16701-3737 |
| 24931 | SPECIALTY CONNECTOR CO INC | 2100 EARLYWOOD DR PO BOX 547 | FRANKLIN IN 46131 |
| 27014 | NATIONAL SEMICONDUCTOR CORP | 2900 SEMICONDUCTOR DR | SANTA CLARA CA 95051-0606 |
| 31918 | ITT SCHADOW INC | 8081 WALLACE RD | EDEN PRAIRIE MN 55344-2224 |
| 32997 | BOURNS INC TRIMPOT DIV | 1200 COLUMBIA AVE | RIVERSIDE CA 92507-2114 |
| 34649 | INTEL CORP | 3065 BOWERS AVE | SANTA CLARA CA 95051 |
| 50434 | HEWLETT-PACKARD CO OPTOELECTRONICS DIV | 370 W TRIMBLE RD | SAN JOSE CA 95131 |
| 51406 | MURATA ERIE NORTH AMERICA INC georgia operations | 2200 LAKE PARK DR | SMYRNA GA 30080 |
| $\begin{aligned} & 51642 \\ & 52763 \end{aligned}$ | CENTRE ENGINEERING INC STETTNER ELECTRONICS INC | 2820 e COLLEGE AVE 6135 AIRWAYS BLVD PO BOX 21947 | STATE COLLEGE PA 16801-7515 CHATTANOOGA TN 37421-2970 |
| 52769 | SPRAGUE-GOODMAN ELECTRONICS INC | 134 FULTON AVE | GARDEN CITY PARK NY 11040-5352 |
| 54473 | MATSUSHITA ELECTRIC CORP OF AMERICA | ONE PANASONIC WAY PO BOX 1501 | SECAUCUS NJ 07094-2917 |

## CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

Mfr.

| Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 54583 | TDK ELECTRONICS CORP | 12 HARBOR PARK DR | PORT WASHINGTON NY 11550 |
| 54937 | DE YOUNG MANUFACTURING INC | 12920 NE 125TH WAY | KIRKLAND, WA 98034-7716 |
| 55112 | WESTLAKE CAPACITORS INC | 5334 STERLING CENTER DRIVE | WESTLAKE VILLAGE CA 91361 |
| 55680 | NICHICON / AMERICA/ CORP | 927 E STATE PKY | SCHAUMBURG IL 60195-4526 |
| 56289 | SPRAGUE ELECTRIC CO WORLD HEADQUARTERS | 92 HAYDEN AVE | LEXINGTON MA 02173-7929 |
| 57668 | R-OHM CORP | 16931 MILLIKEN AVE | IRVINE CA 92713 |
| 61529 | AROMAT CORP | 250 SHEFFIELD ST | MOUNTAINSIDE NJ 07092-2303 |
| 71400 | BUSSMANN | 114 OLD STATE RD | ST LOUIS MO 63178 |
|  | DIV OF COOPER INDUSTRIES INC | PO BOX 14460 |  |
| 71590 | MEPCO/CENTRALAB INC <br> A NORTH AMERICAN PHILIPS CO | $\begin{aligned} & \text { HWY } 20 \mathrm{~W} \\ & \text { P O BOX } 858 \end{aligned}$ | FORT DODGE IA 50501 |
| 75042 | TRW INC <br> TRW ELECTRONIC COMPONENTS <br> IRC FIXED RESISTORS PHILADELPHIA DIV | 401 N BROAD ST | PHILADELPHIA PA 19108-1001 |
| 80009 | TEKTRONIX INC | 14150 SW KARL BRAUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 91637 | DALE ELECTRONICS INC | 2064 12TH AVE PO BOX 609 | COLUMBUS NE 68601-3632 |
| 96733 | SFE TECHNOLOGIES | 1501 FIRST ST | SAN FERNANDO CA 91340-2707 |
| D5243 | ROEDERSTEIN E SPEZIALFABRIK FUER KONDENSATOREN GMBN | LUDMILLASTRASSE 23-25 | 8300 LANDSHUT GERMANY |
| TK0020 | UNITED CHEMI-CON INC | 1128 LEXINGTON AVE | ROCHESTER NY 14606 |
| TK0213 | TOPTRON CORP | TOKYO | JAPAN |
| TK0273 | MITEL SEMICONDUCTOR INC | 18 AIRPORT BLVD | BROMONT QUE CAN JOE 1 LO |
| TK0510 | PANASONIC COMPANY <br> DIV OF MATSUSHITA ELECTRIC CORP | ONE PANASONIC WAY | SECAUCUS NJ 07094 |
| TK0515 | WORLD PRODUCTS INC | $\begin{aligned} & 19678 \text { 8TH ST E } \\ & \text { PO OBX } 517 \end{aligned}$ | SONOMA CA 95476-3803 |
| TK0961 | NEC ELECTRONICS USA INC ElECTRON DIV | 401 ELLIS ST PO OBX 7241 | MOUNTAIN VIEW CA 94039 |
| TK1015 | MUSASHI WORKS OF HITACHI LTD | $\begin{aligned} & 1450 \text { JOSUI HON-CHO } \\ & \text { KODAIRA-SHI } \end{aligned}$ | TOKYO JAPAN |
| TK1016 | TOSHIBA AMERICA INC ELECTRONIC COMPONENTS DIV BUSINESS SECTOR | 2692 DOW AVE | TUSTIN CA 92680 |
| TK1424 | MARCON AMERICA CORP | 700 LANDWEHR RD | NORTHBROOK IL 60062 |
| TK1441 | GFS MANUFACTURING INC | 6 PROGRESS DR BOX 517 | DOVER NH 03820 |
| TK1450 | TOKYO COSMOS ELECTRIC CO LTD | 2-268 SOBUDAI ZAWA | KANAGAWA 228 JAPAN |
| TK1573 | WILHELM WESTERMAN | PO BOX 2345 AUGUSTA-ANLAGE 56 | 6800 MANNHEIM 1 WEST GERMANY |
| TK1689 | AROMAT CORP | 10400 N TANTAU AVE | CUPERTINO CA 95014-0708 |
| TK2051 | MARSHALL INDUSTRIES | 8333 S.W. CIRRUS DR. | BEAVERTON, OR 97005 |
| TK2058 | TDK CORPORATION OF AMERICA | 2254 N. FIRST ST. | SAN JOSE, CA. 95131 |


| Camponent No. | Tektronix <br> Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A8 | 670-9783-01 |  | CIRCUIT BD ASSY:CRT CONTROL | 80009 | 670-9783-01 |
| A10 | 671-0532-01 |  | CIRCUIT BD ASSY:MAIN | 80009 | 671-0532-01 |
| A12 | 670-9402-01 |  | CIRCUIT BD ASSY:POTENTIOMETER | 80009 | 670-9402-01 |
| A14 | 670-9934-00 |  | CIRCUIT BD ASSY:SWITCH | 80009 | 670-9934-00 |
| A16 | 671-0314-00 |  | CIRCUIT BD ASSY:PROCESSOR | 80009 | 671-0314-00 |
| A18 | 670-9398-03 |  | CIRCUIT BD ASSY:LV POWER SUPPLY,A18 | 80009 | 670-9398-03 |


| Camponent Mo. | Tektronix Part 10. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A8 | 670-9783-01 |  | CIRCUIT BD ASSY:CRT CONTROL | 80009 | 670-9783-01 |
| A8P8 | 131-4038-00 |  | CONN,RCPT, ELEC:HDR, $1 \times 8, \mathrm{RTANG}, 0.1$ SPACING | 00779 | 640453-8 |
| A8R901 | 311-2344-00 |  | RES, VAR, NONWW:CKT BD,4.7K OHM, 20\%,1.25W | 71590 | BA17140001 |
| A8R902 | -311-2344-00 |  | RES, VAR, NONWW:CKT BD, 4.7 K OHM, $20 \%$, 1.25 W | 71590 | BA17140001 |
| A8R903 | 311-2344-00 |  | RES, VAR, NONWW:CKT BD, 4.7 K OHM, $20 \%, 1.25 \mathrm{~W}$ | 71590 | BA17140001 |
| A8R905 | 311-2344-00 |  | RES, VAR, NONWW:CKT B0,4.7K OHM,20\%, 1.25W | 71590 | BA17140001 |


| Camponent No. | Tektronix Part No . | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10 | 671-0532-01 |  | CIRCUIT BD ASSY:MAIN | 80009 | 671-0532-01 |
| A10AT117 | 307-2135-00 |  | RES NTWK, FXD, FI:ATTENUATOR DIP PKG | 80009 | 307-2135-00 |
| A10AT127 | 307-2135-00 |  | RES NTWK, FXD, FI:ATTENUATOR DIP PKG | 80009 | 307-2135-00 |
| A10C101 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C102 | 281-0909-00 |  | CAP, FXD, CER DI :0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C103 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C104 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C105 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C106 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C107 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C108 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C111 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C112 | 283-0414-01 |  | CAP, FXD, CER DI $00.022 \mathrm{UF}, 20 \%, 500 \mathrm{~V}$ | 80009 | 283-0414-01 |
| A10C113 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C114 | 281-0214-00 |  | CAP, VAR,CER DI:0.6-3PF, 400 V | 52763 | 313613-140 |
| A10C121 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C122 | 283-0414-01 |  | CAP, FXD, CER DI:0.022UF, $20 \%, 500 \mathrm{~V}$ | 80009 | 283-0414-01 |
| A10C123 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C124 | 281-0214-00 |  | CAP, VAR, CER DI: $0.6-3 \mathrm{PF}, 400 \mathrm{~V}$ | 52763 | 313613-140 |
| A10C125 | 281-0770-00 |  | CAP,FXD,CER DI:1000PF, $20 \%, 100 \mathrm{~V}$ | 04222 | MA101C102MAA |
| A10C126 | 281-0770-00 |  | CAP, FXD, CER DI:1000PF, $20 \%$,100V | 04222 | MA101C102MAA |
| A10C131 | 281-0909-00 |  | CAP,FXD,CER DI: 0.022 UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C132 | 281-0938-00 |  | CAP, FXD, CER DI: $20 \mathrm{PF}, 2 \%, 500 \mathrm{~V}$ | 96733 | R3900 |
| A10C133 | 281-0799-00 |  | CAP,FXD,CER DI:62PF, $2 \%, 100 \mathrm{~V}$ | 04222 | MA101A620GAA |
| A10C134 | 281-0306-00 |  | CAP, VAR,CER, DI:3.3-20PF | 52769 | GKU 18000 |
| A10C135 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C136 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C137 | 281-0797-00 |  | CAP, FXD, CER DI:15PF, $10 \%, 100 \mathrm{~V}$ | 04222 | SA106A150KAA |
| A10C138 | 281-0315-00 |  | CAP, VAR,CER DI:2.8-10PF | 52769 | GKU 10000 |
| A10C139 | 281-0797-00 |  | CAP, FXD, CER DI:15PF, $10 \%, 100 \mathrm{~V}$ | 04222 | SA106A150KAA |
| A10C140 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10UF, 20\%, 50V | TK0020 | KMC50VB1ORM5 $\times 11 \mathrm{~F}$ |
| Al0C151 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| Al0C152 | 281-0938-00 |  | CAP, FXD, CER DI: $20 \mathrm{PF}, 2 \%$, 500 V | 96733 | R3900 |
| A10C153 | 281-0799-00 |  | CAP, FXD, CER DI:62PF, 2\%,100V | 04222 | MA101A620GAA |
| Al0C154 | 281-0306-00 |  | CAP, VAR, CER, DI:3.3-20PF | 52769 | GKU 18000 |
| A10C155 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C156 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C157 | 281-0797-00 |  | CAP, FXD, CER DI: $15 \mathrm{PF}, 10 \%, 100 \mathrm{~V}$ | 04222 | SA106A150KAA |
| A10C158 | 281-0315-00 |  | CAP, VAR,CER DI:2.8-10PF | 52769 | GKU 10000 |
| A10C159 | 281-0797-00 |  | CAP, FXD, CER DI:15PF, $10 \%, 100 \mathrm{~V}$ | 04222 | SA106A150KAA |
| A10C171 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10 UF, $20 \%$, 50 V | TK0020 | KMC50VB1ORM5X11F |
| A10C172 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C173 | 281-0772-00 |  | CAP, FXD, CER DI: $4700 \mathrm{PF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA2O1C472KAA |
| A10C180 | 290-0944-01 |  | CAP, FXD, ELCTLT:220UF,20\%,10V | 55880 | UVX1C221MPA1TA |
| A10C181 | 290-0944-01 |  | CAP, FXD, ELCTLT:220UF,20\%,10V | 55680 | UVXIC221MPA1TA |
| AlOC190 | 281-0797-00 |  | CAP, FXD, CER DI:15PF, $10 \%$, 100V | 04222 | SA106A150KAA |
| A10C191 | 281-0797-00 |  | CAP, FXD, CER DI:15PF, $10 \%$,100V | 04222 | SA106A150KAA |
| A10C201 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%$, 50 V | TK0020 | KMC50VB10PM5X11F |
| A10C202 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | TK0020 | KMC50VB1ORM5X11F |
| A10C203 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10UF, 20\%,50V | TK0020 | KMC50VB1ORM5X11F |
| Al0C204 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10UF, $20 \%$, 50V | TK0020 | KMC50VB1ORM5X11F |
| Al0C205 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C206 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C210 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C211 | 281-0759-00 |  | CAP, FXD, CER DI:22PF, $10 \%, 100 \mathrm{~V}$ | 04222 | MA101A22OKAA |
| A10C212 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C213 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C214 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |


| Component No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10C215 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%$, 50 V | TK0020 | KMC50V810RM5X11F |
| A10C216 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C217 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C218 | 281-0775-01 |  | CAP, FXD, CER DI: $0.1 \mathrm{UF}, 20 \%$,50V | 04222 | SA105E104MAA |
| A10C219 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C220 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C221 | 281-0759-00 |  | CAP, FXD, CER DI :22PF, 10\%,100V | 04222 | MA101A220KAA |
| A10C222 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C223 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C224 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C225 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%$, 50 V | TK0020 | KMC50VB10RM5X11F |
| A10C228 | 281-0775-01 |  | CAP, FXD,CER DI: $0.1 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 04222 | SA105E104MAA |
| A10C229 | 281-0909-00 |  | CAP, FXD, CER DI: 0.022 UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C232 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C233 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C234 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C235 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%$, 50 V | TK0020 | KMC50VB10RM5X11F |
| A10C238 | 281-0775-01 |  | CAP, FXD, CER DI:0.1UF,20\%,50V | 04222 | SA105E104MAA |
| A10C239 | 281-0909-00 |  | CAP, FXD, CER DI: 0.022 UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C242 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C243 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C244 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C245 | 290-0974-01 |  | CAP, FXD, ELCTLT:10UF, 20\%,50V | TK0020 | KMC50VB10RM5X11F |
| A10C248 | 281-0775-01 |  | CAP, FXD, CER DI:0.1UF, $20 \%$, 50 V | 04222 | SA105E104MAA |
| A10C249 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| Al0C258 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10UF,20\%,50V | TK0020 | KMC50VB10RM5X11F |
| Al0C265 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C268 | 281-0770-00 |  | CAP, FXD, CER DI: $1000 \mathrm{PF}, 20 \%, 100 \mathrm{~V}$ | 04222 | MA101C102MAA |
| A10C271 | 281-0798-00 |  | CAP, FXD, CER DI: 51 PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A10C272 | 281-0819-00 |  | CAP, FXD,CER DI:33 PF, 5\%, 50V | 04222 | GC105A330 |
| A10C273 | 281-0307-00 |  | CAP, VAR, CER, DI :3-8-25PF | 52769 | GKU 25000 |
| A10C274 | 281-0305-00 |  | CAP, VAR,CER,DI:1.5-4.0PF | 52769 | GKU 4R000 |
| A10C275 | 281-0872-00 |  | CAP, FXD,CER DI: $91 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MC101A910J |
| A10C282 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C283 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C297 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C298 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C301 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C302 | 281-0770-00 |  | CAP, FXD, CER DI: $1000 \mathrm{PF}, 20 \%, 100 \mathrm{~V}$ | 04222 | MA101C102MAA |
| A10C303 | 290-0183-00 |  | CAP, FXD, ELCTLT: 1UF, $10 \%$, 35 V | 05397 | T3228105K035AS |
| A10C304 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C305 | 290-0183-00 |  | CAP, FXD, ELCTLT: 1UF, $10 \%$, 35 V | 05397 | T3228105K035AS |
| A10C306 | 290-0183-00 |  | CAP, FXD, ELCTLT: 1 UF, 10\%, 35V | 05397 | T3228105K035AS |
| A10C307 | 295-0198-00 |  | CAP SET, MATCHED: (1), 10.0UF, 1.5\%,25V/ (1)0.1UF, $1.5 \%, 35 \mathrm{~V} /(1) 0.0099 \mathrm{FF}, 1.5 \%, 50 \mathrm{~V}$ (LOCATIONS A,B,C) | 80009 | 295-0198-00 |
| A10C308 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C309 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C310 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C311 | 281-0798-00 |  | CAP, FXD, CER DI: 51PF, $1 \%$, 100 V | 04222 | MA101A510GAA |
| A10C312 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| Al0C313 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C314 | 281-0307-00 |  | CAP, VAR, CER,DI:3-8-25PF | 52769 | GKU 25000 |
| A10C315 | 281-0798-00 |  | CAP, FXD, CER DI: 51 PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA10IA510GAA |
| A10C316 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C317 | 281-0909-00 |  | CAP, FXD, CER DI: 0.022 UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| Al0C318 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C319 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |


| Component No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10C320 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C321 | 281-0798-00 |  | CAP, FXD, CER DI:51PF, 1\%, 100 V | 04222 | MA101A510GAA |
| A10C326 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C329 | 281-0307-00 |  | CAP, VAR, CER, DI:3-8-25PF | 52769 | GKU 25000 |
| A10C330 | 281-0799-00 |  | CAP, FXD, CER DI: $62 P \mathrm{PF}, 2 \%, 100 \mathrm{~V}$ | 04222 | MA101A620GAA |
| A10C337 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C338 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C339 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C351 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C421 | 281-0773-00 |  | CAP, FXO, CER DI: $0.01 \mathrm{UF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA201C103KAA |
| A10C422 | 281-0861-00 |  | CAP, FXD, CER DI: $270 \mathrm{PF}, 5 \%$, 50 V | 54583 | MA12COG1H271J |
| A10C423 | 281-0864-00 |  | CAP, FXD,CER DI:430PF,5\%,100V | 54583 | MA12COE2A431J |
| A10C424 | 290-0183-00 |  | CAP, FXD, ELCTLT: $1 \mathrm{UF}, 10 \%$, 35 V | 05397 | T3228105K035AS |
| A10C425 | 281-0820-00 |  | CAP, FXD, CER DI: $680 \mathrm{PF}, 10 \%$, 50 V | 04222 | MA105C651KAA |
| A10C426 | 281-0864-00 |  | CAP, FXD, CER DI: 430 PF, $5 \%, 100 \mathrm{~V}$ | 54583 | MA12COG2A431J |
| A10C432 | 281-0767-00 |  | CAP, FXD, CER DI : $330 \mathrm{PF}, 20 \%, 100 \mathrm{~V}$ | 04222 | MA1 O6C331MAA |
| A10C444 | 281-0765-00 |  | CAP, FXD, CER DI: $100 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C445 | 290-0183-00 |  | CAP, FXD, ELCTLT: $1 \mathrm{UF}, 10 \%$, 35 V | 05397 | T3228105K035AS |
| A10C447 | 281-0770-00 |  | CAP, FXD, CER DI: $1000 \mathrm{PF}, 20 \%, 100 \mathrm{~V}$ | 04222 | MA10IC102MAA |
| A10C451 | 281-0773-00 |  | CAP, FXD, CER DI: 0.01 UF, $10 \%, 100 \mathrm{~V}$ | 04222 | MA201C103KAA |
| A10C452 | 281-0861-00 |  | CAP, FXD, CER DI:270PF,5\%,50V | 54583 | MA12COG1H271J |
| A10C453 | 281-0864-00 |  | CAP, FXD, CER DI: 430 PF, $5 \%, 100 \mathrm{~V}$ | 54583 | MA12C0G2A431J |
| A10C454 | 290-0183-00 |  | CAP, FXD, ELCTLT: 1UF, $10 \%$, 35V | 05397 | T3228105K035AS |
| A10C455 | 281-0820-00 |  | CAP, FXD,CER DI:680 PF, $10 \%$,50V | 04222 | MA105C651KAA |
| A10C462 | 281-0864-00 |  | CAP, FXD, CER DI:430PF, $5 \%, 100 \mathrm{~V}$ | 54583 | MA12COG2A431J |
| A10C463 | 281-0813-00 |  | CAP,FXD, CER DI : 0.047UF, $20 \%$, 50V | 05397 | C412C473M5V2CA |
| A10C474 | 281-0776-00 |  | CAP,FXD, CER DI:120PF, $5 \%, 100 \mathrm{~V}$ | 20932 | 401E0100AD121J |
| A10C475 | 290-0183-00 |  | CAP, FXD, ELCTLT:1UF, 10\%,35V | 05397 | T3228105K035AS |
| A10C477 | 281-0770-00 |  | CAP, FXD, CER DI:1000PF, $20 \%, 100 \mathrm{~V}$ | 04222 | MA101C102MAA |
| A10C481 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| Al0C482 | 281-0909-00 |  | CAP,FXD,CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C483 | 281-0820-00 |  | CAP, FXD,CER DI: $680 \mathrm{PF}, 10 \%$,50V | 04222 | MA105C651KAA |
| A10C484 | 281-0765-00 |  | CAP, FXD, CER DI:100PF, $5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C485 | 281-0765-00 |  | CAP, FXD, CER DI: $100 \mathrm{PF}, 5 \%$, 100 V | 04222 | MA1O1A101JAA |
| Al0C486 | 281-0765-00 |  | CAP, FXD, CER DI: $100 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C487 | 281-0765-00 |  | CAP, FXD, CER DI:100PF, $5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C488 | 281-0765-00 |  | CAP, FXD, CER DI:100PF, $5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C489 | 281-0765-00 |  | CAP, FXD, CER DI:100PF, $5 \%, 100 \mathrm{~V}$ | 04222 | MAIO1A101JAA |
| Al0C491 | 281-0819-00 |  | CAP, FXD, CER DI: $33 \mathrm{PF}, 5 \%$, 50V | 04222 | GC105A330 J |
| A10C492 | 281-0819-00 |  | CAP, FXD,CER DI:33 PF,5\%,50V | 04222 | GC105A330J |
| A10C493 | 281-0819-00 |  | CAP, FXD,CER DI: $33 \mathrm{PF}, 5 \%$, 50V | 04222 | GC105A330] |
| A10C494 | 281-0819-00 |  | CAP, FXD,CER DI:33 PF, 5\%,50V | 04222 | GC105A330J |
| A10C501 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C502 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C503 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C505 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C600 | 281-0861-00 |  | CAP, FXD, CER OI:270PF,5\%,50V | 54583 | MA12COG1-271J |
| A10C601 | 281-0861-00 |  | CAP, FXD, CER DI: $270 \mathrm{PF}, 5 \%$,50V | 54583 | MA12COG1-271J |
| A10C602 | 281-0819-00 |  | CAP, FXD, CER DI: $33 \mathrm{PF}, 5 \%$, 50V | 04222 | GC105A330J |
| A10C603 | 281-0819-00 |  | CAP, FXD, CER DI:33 PF,5\%,50V | 04222 | GC105A330J |
| A10C604 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C605 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MAr2X7R1H223M-T |
| A10C606 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C607 | 281-0765-00 |  | CAP, FXD, CER DI: $100 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C608 | 281-0765-00 |  | CAP, FXD, CER DI: $100 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C609 | 281-0909-00 |  | CAP, FXO, CER DI:0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C610 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C611 | 281-0810-00 |  | CAP, FXD, CER DI:5.6PF,+/-0.5PF,100V | 04222 | MA101A5R60AA |


| Camponent No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10C612 | 281-0810-00 |  | CAP, FXD, CER DI: $5.6 \mathrm{PF},+/-0.5 \mathrm{PF}, 100 \mathrm{~V}$ | 04222 | MA101A5R6DAA |
| A10C613 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C701 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C702 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C703 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C704 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C705 | 283-0057-00 |  | CAP, FXD, CER DI: $0.14 \mathrm{~F},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C706 | 281-0893-00 |  | CAP,FXD,CER DI:4.7PF,+/-0.5PF,100V | 04222 | MA101A4R7DAA |
| A10C707 | 281-0798-00 |  | CAP,FXD,CER DI:51PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A10C708 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C711 | 283-0201-01 |  | CAP, FXD, CER DI:27PF, 10\%,50V | 51642 | ADVISE |
| A10C712 | 283-0201-01 |  | CAP, FXD, CER DI: $27 \mathrm{PF}, 10 \%$, 50 V | 51642 | ADVISE |
| A10C801 | 283-0057-00 |  | CAP, FXD, CER DI: 0.1 UF, $+80-20 \%$, 200V | 04222 | SR306E1042AA |
| A10C802 | 283-0057-00 |  | CAP, FXD, CER DI: $0.14 \mathrm{UF},+80-20 \%$, 200V | 04222 | SR306E1042AA |
| A10C803 | 281-0707-00 |  | CAP, FXD, CER DI :15000PF, 20\%, 200V | 20932 | 402EM200AD153K |
| Al0C804 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$,50V | 54583 | MA12X7R1H223M-T |
| A10C805 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C806 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C807 | 281-0064-00 |  | CAP, VAR, PLASTIC: 0. 25-1.5PF,600V | 52769 | ER-530-013 |
| A10C808 | 281-0765-00 |  | CAP, FXD, CER DI : $100 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MA101A101JAA |
| A10C809 | 283-0057-00 |  | CAP, FXD, CER DI: $0.14 \mathrm{~F},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C810 | 281-0707-00 |  | CAP, FXD, CER DI: $15000 \mathrm{PF}, 20 \%$, 200V | 20932 | 402EM200AD153K |
| A10C811 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A10C814 | 281-0064-00 |  | CAP, VAR, PLASTIC:0.25-1.5PF,600V | 52769 | ER-530-013 |
| A10C815 | 281-0909-00 |  | CAP, FXD,CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C816 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C817 | 290-1198-00 |  | CAP, FXO, ELCTLT: 100UF,20\%, 10VAC | 80009 | 290-1198-00 |
| A10C818 | 283-0057-00 |  | CAP, FXD, CER DI: $0.1 \mathrm{UF},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C819 | 281-0765-00 |  | CAP, FXD, CER DI:100PF,5\%,100V | 04222 | MA101A101JAA |
| A10c901 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C902 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C903 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UFF}, 20 \%$,50V | TK0020 | KMC50VB10RM5X11F |
| A10c904 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | TK0020 | KMC50VB10RM5 $\times 11 \mathrm{~F}$ |
| A10C910 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C935 | 285-1339-00 |  | CAP, FXD, MTLZD:0.022UF, 10\%,63V | 55112 | 185/0.022/K63AAA |
| A10C1001 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10 UF , 20\%, 50V | TK0020 | KMC50VB10RM5X11F |
| A10C1002 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10 UF , 20\%, 50V | TK0020 | KMC50VB10RM5×11F |
| A10C1003 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{LF}, 20 \%$, 50V | TK0020 | KMC50VB10RM5X11F |
| A10C1004 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C1005 | 281-0909-00 |  | CAP, FXD, CER DI :0.022UF, 20\%, 50V | 54583 | MA12X7R1H223M-T |
| A10C1006 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C1101 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1-223M-T |
| A10C1102 | 290-0183-00 |  | CAP, FXD, ELCTLT: 1UF, 10\%, 35V | 05397 | T3228105K035AS |
| A10C1103 | 290-0183-00 |  | CAP, FXD, ELCTLT: 1UF, 10\%,35V | 05397 | T3228105K035AS |
| A10C1105 | 290-0974-01 |  | CAP, FXD, ELCTLT: $10 \mathrm{UF}, 20 \%$,50V | TK0020 | KMC50VB10RM5X11F |
| A10C1106 | 281-0820-00 |  | CAP, FXD, CER DI: $680 \mathrm{PF}, 10 \%$, 50 V | 04222 | MA105C651KAA |
| A10C1107 | 281-0765-00 |  | CAP, FXD, CER DI: $100 \mathrm{PF}, 5 \%$, 100V | 04222 | MA101A101JAA |
| Al0C1110 | 281-0799-00 |  | CAP, FXD, CER DI: $62 P \mathrm{PF}, \mathrm{Z} \mathrm{\%}, 100 \mathrm{~V}$ | 04222 | mal01A620gAA |
| A10C1111 | 281-0799-00 |  | CAP, FXD, CER DI: 62PF, $2 \%, 100 \mathrm{~V}$ | 04222 | MA101A620GAA |
| A10C1114 | 290-0974-01 |  | CAP, FXD, ELCTLT: 10UF, 20\%,50V | TK0020 | KMC50VB1ORM5X11F |
| AlOC1130 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H22314-T |
| A10C1154 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| Al0C1155 | 281-0909-00 |  | CAP, FXD, CER DI : $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| Al0C1158 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C1159 | 281-0909-00 |  | CAP, FXD, CER DI: $0.0224 \mathrm{~F}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12×7R1H223M-T |
| A10C2701 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C2702 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| Al0C2703 | 281-0909-00 |  | CAP, FXD, CER DI :0.022UF,20\%,50V | 54583 | MA12X7R1H223M-T |


| Component No. | Tektronix <br> Part No. | Serial/Assenbly No. Effective Dscont | Nare \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10C2704 | 281-0064-00 |  | CAP, VAR, PLASTIC:0.25-1.5PF,600V | 52769 | ER-530-013 |
| A10C2705 | 281-0771-00 |  | CAP, FXD, CER DI: $2200 \mathrm{PF}, 20 \%$, 200V | 04222 | SA106E222MAA |
| A10C2706 | 281-0893-00 |  | CAP, FXD, CER DI:4.7PF, +/-0.5PF,100V | 04222 | MA101A4R7DAA |
| A10C2707 | 281-0893-00 |  | CAP, FXD, CER DI:4.7PF,+/-0.5PF,100V | 04222 | MA101A4R7DAA |
| A10C2708 | 283-0057-00 |  | CAP, FXD, CER DI: 0.1 UF, $+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C2709 | 283-0057-00 |  | CAP, FXD, CER DI: $0.1 \mathrm{UF},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C2710 | 283-0057-00 |  | CAP, FXD, CER DI: 0.1 UF, $+80-20 \%$, 200 V | 04222 | SR306E104ZAA |
| A10C2711 | 285-1184-01 |  | CAP, FXD,MTLZD: 0.01 UF, $20 \%$, 4KV | 56289 | 430P103X040 |
| A10C2712 | 285-1040-00 |  | CAP, FXD, PLASTIC:1200PF, $10 \%, 4000 \mathrm{~V}$ | 04099 | TEK-17A |
| A10C2713 | 281-0771-00 |  | CAP, FXD, CER DI: 2200PF, 20\%,200V | 04222 | SA106E222MAA |
| A10C2715 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A10C2716 | 281-0771-00 |  | CAP, FXD,CER DI:2200PF, $20 \%, 200 \mathrm{~V}$ | 04222 | SA106E222MAA |
| A10C2717 | 283-0057-00 |  | CAP, FXD, CER DI: $0.1 \mathrm{UF},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C2719 | 285-1184-01 |  | CAP, FXD,MTLZD: $0.01 \mathrm{UF}, 20 \%$, 4KV | 56289 | 430P103X040 |
| A10C2720 | 285-1040-00 |  | CAP, FXD, PLASTIC: $1200 \mathrm{PF}, 10 \%, 4000 \mathrm{~V}$ | 04099 | TEK-17A |
| A10C2721 | 281-0771-00 |  | CAP, FXD, CER DI: $2200 \mathrm{PF}, 20 \%, 200 \mathrm{~V}$ | 04222 | SA106E222MAA |
| A10C2723 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A10C2724 | 285-1184-01 |  | CAP, FXD, MTLZD: $0.01 \mathrm{UF}, 20 \%, 4 \mathrm{KV}$ | 56289 | 430P103×040 |
| A10C2758 | 285-1184-01 |  | CAP, FXD, MTLZD: 0.01 UF , 20\%, 4KV | 56289 | 430P103X040 |
| A10C2759 | 281-0759-00 |  | CAP, FXD, CER DI:Z2PF, $10 \%, 100 \mathrm{~V}$ | 04222 | MA101A220KAA |
| A10C2783 | 283-0057-00 |  | CAP,FXD, CER DI:0.1UF,+80-20\%, 200V | 04222 | SR306E104ZAA |
| A10C2784 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A10C2785 | 283-0057-00 |  | CAP, FXD, CER DI: $0.1 \mathrm{UF},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10CR131 | 152-0246-00 |  | SEMICOND DVC, DI:SW, SI, 40V, 200MA, DO-7 | 14433 | WG1537TK |
| A10CR151 | 152-0246-00 |  | SEMICOND DVC, DI: SW, SI, $40 \mathrm{~V}, 200 \mathrm{NA}, 00-7$ | 14433 | WG1537TK |
| A10CR171 | 152-0141-02 |  | SEMICOND DVC,DI:SW,SI, 30V,150MA,30V,00-35 | 03508 | DA2527 (1N4152) |
| A10CR201 | 152-0141-02 |  | SEMICOND DVC,DI:SW, SI, 30V,150MA, 30V, 00-35 | 03508 | DA2527 (1N4152) |
| A10CR202 | 152-0141-02 |  | SEMICOND DVC, DI:SW, SI, 30V,150M4, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR260 | 152-0066-00 |  | SEMICOND DVC, DI:RECT,SI,400V,1A, D0-41 | 05828 | GP10G-020 |
| A10CR261 | 152-0066-00 |  | SEMICOND DVC, DI:RECT,SI, 400V, 1A, D0-41 | 05828 | GP10G-020 |
| A10CR301 | 152-0141-02 |  | SEMICOND DVC,DI:SW, SI, 30V,150MA, 30V,D0-35 | 03508 | DA2527 (1N4152) |
| A10CR432 | 152-0246-00 |  | SEMICOND DVC, DI:SW, SI, 40V, 200MA,00-7 | 14433 | WG1537TK |
| A10CR462 | 152-0246-00 |  | SEMICOND DVC, DI:SW,SI, 40V, 200MA, D0-7 | 14433 | WG1537TK |
| A10CR603 | 152-0141-02 |  | SEMICOND DVC, DI: SW, SI, 30V, 150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR801 | 152-0141-02 |  | SEMICOND DVC, DI:SW, SI, 30V,150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR802 | 152-0061-00 |  | SEMICOND DVC, DI :SW, SI, 175V,0.1A,D0-35 | 07263 | FDH2181 |
| A10CR819 | 152-0061-00 |  | SEMICOND DVC, DI:SW, SI, 175V, 0.1A, 00-35 | 07263 | FDH2161 |
| A10CR935 | 152-0141-02 |  | SEMICOND DVC, DI:SW, SI, 30V,150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR936 | 152-0141-02 |  | SEMICOND DVC, DI:SW, SI, 30V,150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR1001 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V,150MA, 30V,00-35 | 03508 | DA2527 (1N4152) |
| A10CR1002 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V,150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR1003 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V, 150MA, 30V, DO-35 | 03508 | DA2527 (1N4152) |
| A10CR1004 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V, 150MA, 30V, 00-35 | 03508 | DA2527 (1N4152) |
| A10CR1005 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V,150MA,30V,D0-35 | 03508 | DA2527 (1N4152) |
| Al0CR2701 | 152-0400-00 |  | SEMICOND DVC, DI: RECT, SI, 400V,1A | 04713 | SR1977K |
| Al0CR2702 | 152-0400-00 |  | SEMICOND OVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A10CR2703 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| Al0CR2704 | 152-0400-00 |  | SEMICOND DVC, DI :RECT, SI, 400V,1A | 04713 | SR1977K |
| A10CR2705 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V,150MA, 30V,00-35 | 03508 | DA2527 (1N4152) |
| A10CR2707 | 152-0141-02 |  | SEMICOND DVC, DI :SW, SI, 30V,150NA,30V,D0-35 | 03508 | DA2527 (1N4152) |
| A10CR2713 | 152-0141-02 |  | SEMICOND DVC, DI : SW, SI, 30V,150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR2714 | 152-0400-00 |  | SEMICOND DVC, DI :RECT, SI, 400V,1A | 04713 | SR1977K |
| A10CR2715 | 152-0400-00 |  | SEMICOND DVC, DI: RECT, SI, 400V,1A | 04713 | SR1977K |
| A10CR2716 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A10CR2717 | 152-0400-00 |  | SEMICOND DVC, DI:RECT,SI, 400V,1A | 04713 | SR1977K |
| AlOCR2718 | 152-0400-00 |  | SEMICOND DVC, DI: RECT, SI, 400V, 1A | 04713 | SR1977K |
| A100L22 | 119-2119-01 |  | DELAY LINE, ELEC: | 80009 | 119-2119-01 |
| A1005901 | 150-0146-00 |  | LAMP, INCANO:14V,80MA, $73 E$, WEDGE BASE | 08806 | 73E |


| Component No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A100S902 | 150-0146-00 |  | LAMP, INCAND:14V, $80 \mathrm{MA}, 73 \mathrm{E}$, WEDGE BASE | 08806 | 73E |
| A1005903 | 150-0146-00 |  | LAMP, INCAND:14V,80MA,73E, WEDGE BASE | 08806 | 73E |
| A100S2701 | 150-0035-00 |  | LAMP,GLOW:90V MAX, 0.3MA, AID-T,WIRE LD | TK0213 | JH005/3011JA |
| A100S2702 | 1'50-0035-00 |  | LAMP, GLOW:90V MAX, 0.3MA,AID-T,WIRE LD | TK0213 | JH005/3011JA |
| A100S2703 | 150-0035-00 |  | LAMP, GLOW:90V MAX, 0.3MA,AID-T,WIRE LD | TK0213 | JH005/3011JA |
| A10DS2704 | 150-0035-00 |  | LAMP,GLOW:90V MAX, 0.3MA,AID-T,WIRE LD | TK0213 | JH005/3011JA |
| A10J11 | 131-3731-00 |  | CONN, RCPT, ELEC: BNC, MALE | 24931 | 28JR377-1 |
| A10J12 | 131-3731-00 |  | CONN, RCPT, ELEC: BNC, MALE | 24931 | 28JR377-1 |
| A10J13 | 131-3731-00 |  | CONN, RCPT, ELEC: BNC, MALE | 24931 | 28JR377-1 |
| A10J14 | 131-3731-00 |  | CONN, RCPT, ELEC: BNC, MALE | 24931 | 28JR377-1 |
| A10J15 | 131-3464-00 |  | CONTACT, ELEC:BRASS | 80009 | 131-3464-00 |
| A10,3927 | 131-3486-00 |  | CONN,RCPT, ELEC:HEADER,RTANG, 2 POS, 0.1 SP | 00779 | 640452-2 |
| A10J1204 | 131-3638-00 |  | CONN, RCPT, ELEC: HEADER, 13 CIRCUIT, 0.156 SP | 80009 | 131-3638-00 |
| A10K100 | 148-0174-00 |  | RELAY,ARMATURE:1 FORM C,12VDC | TK1689 | DS1EM-DC 12V |
| A1OK101 | 148-0174-00 |  | RELAY, ARMATLRE: 1 FORM C, 12VDC | TK1689 | DS1EM-DC 12V |
| A10K102 | 148-0173-01 |  | RELAY, ARMATURE: 12VDC | TK1689 | RK1EDC12V |
| A10K103 | 148-0173-01 |  | RELAY, ARMATURE: 12VDC | TK1689 | RKIEDC12V |
| A10K104 | 148-0174-00 |  | RELAY,ARMATURE: 1 FORM C,12VDC | TK1689 | DS1EM-DC 12V |
| A10K105 | 148-0174-00 |  | RELAY, ARMATURE: 1 FORM C,12VDC | TK1689 | DSIEM-DC 12V |
| A10K107 | 148-0174-00 |  | RELAY, ARMATURE:1 FORM C,12VDC | TK1689 | OS1EM-DC 12V |
| A10K108 | 148-0174-00 |  | RELAY, ARMATURE: 1 FORM C,12VDC | TK1689 | DS1EM-DC 12V |
| AlOK109 | 148-0173-01 |  | RELAY, ARMATURE:12VDC | TK1689 | RK1EDC12V |
| A10K110 | 148-0173-01 |  | RELAY, ARMATURE:12VDC | TK1689 | RK1EDC12V |
| A10K111 | 148-0174-00 |  | RELAY, ARMATURE: 1 FORM C,12VDC | TK1689 | DS1EM-DC 12V |
| A10K112 | 148-0174-00 |  | RELAY, ARMATURE: 1 FORM C, 12VDC | TK1689 | DS1EM-DC 12V |
| A10L101 | 108-1319-00 |  | INDUCTOR, FIXED: $33 \mathrm{UH}, 10 \%, 1.8 \mathrm{~A}$ | 54583 | TSL1110-330K 1R8 |
| A10L102 | 108-1319-00 |  | INDUCTOR, FIXED: $33 \mathrm{UH}, 10 \%, 1,8 \mathrm{~A}$ | 54583 | TSL1110-330K 1R8 |
| A10L130 | 108-0682-00 |  | COIL, RF:FIXED,61NH | 80009 | 108-0682-00 |
| A10L140 | 108-0682-00 |  | COIL, RF: FIXED, 61NH | 80009 | 108-0682-00 |
| A10_201 | 108-1319-00 |  | INDUCTOR, FIXED:33UH, $10 \%, 1.8 \mathrm{~A}$ | 54583 | TSL1110-330K 1 R8 |
| A10L216 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L217 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L426 | 108-1281-00 |  | COIL, RF: FXD, 2.24H,10\% | 54583 | SP0305-2R2K |
| A10L432 | 108-1341-00 |  | COIL, RF: FXD, 180NH, 10\%, 0.1 OHM,1100MA | 80009 | 108-1341-00 |
| A10L445 | 108-1339-00 |  | COIL, RF:FXD,330NH | 80009 | 108-1339-00 |
| A10L446 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L462 | 108-1341-00 |  | COIL, RF: FXD, 180NH, 10\%, 0.1 OHM,1100MA | 80009 | 108-1341-00 |
| A10L475 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L476 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L701 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L702 | 108-1339-00 |  | COIL, RF: FXD, 330NH | 80009 | 108-1339-00 |
| A10L703 | 120-1688-00 |  | TRANSFORMER,RF:TAPPED INDUCTOR | TK1441 | 86-504-1 |
| A10L704 | 120-1688-00 |  | TRANSFORMER,RF:TAPPED INDUCTOR | TK1441 | 86-504-1 |
| A100131 | 151-1042-00 |  | SEMICOND DVC SE:FET,SI,TO-92 (LOCATION A AND B) | 04713 | SPF627M2 |
| A100151 | 151-1042-00 |  | SEMICOND DVC SE:FET,SI,TO-92 (LOCATION A AND B) | 04713 | SPF627M2 |
| A100171 | 151-0164-00 |  | TRANSISTOR:PNP,SI, T0-92 | 04713 | 2N2907A |
| A100250 | 151-0712-00 |  | TRANSISTOR:PNP, SI, T0-92 | 04713 | SPS8223 |
| A100251 | 151-0712-00 |  | TRANSISTOR: PNP, SI, T0-92 | 04713 | SPS8223 |
| A100252 | 151-0271-05 |  | TRANSISTOR: PNP, SI, 30MA, 2GHZ, TO-92 | 80009 | 151-0271-05 |
| A10Q253 | 151-0271-05 |  | TRANSISTOR:PNP, SI, 30MA, 2GHZ, T0-92 | 80009 | 151-0271-05 |
| A100284 | 151-0192-05 |  | TRANSISTOR:NPN, SI, T0=92 | 04713 | ORDER BY DESCR |
| A10Q285 | 151-0192-05 |  | TRANSISTOR:NPN, SI, T0=92 | 04713 | ORDER BY DESCR |
| Al0Q301 | 151-0254-03 |  | TRANSISTOR:DARLINGTON,NPN,SI | TK1016 | MPSA14, TPE2 |
| A10Q302 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100303 | 151-0188-00 |  | TRANSISTOR:PNP, SI , TO-92 | 80009 | 151-0188-00 |
| A100304 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER, 625,T0-92 | 80009 | 151-0830-00 |


| Companent Ho. | Tektronix Part Ho. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A100305 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER, 625,T0-92 | 80009 | 151-0830-00 |
| A100306 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER, 625,T0-92 | 80009 | 151-0830-00 |
| A100307 | 151-0829-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0829-00 |
| A100308 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER, 625, T0-92 | 80009 | 151-0830-00 |
| A100309 | 151-0830-00 |  | TRANSISTOR:NPN, SI , AMPLIFIER, 625, T0-92 | 80009 | 151-0830-00 |
| A100310 | 151-1042-00 |  | SEMICOND DVC SE:FET,SI,TO-92 (LOCATIONS A AND B) | 04713 | SPF627M2 |
| A100311 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A10Q312 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100313 | 151-0736-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0736-00 |
| A10Q315 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| Al0Q316 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100317 | 151-0830-00 |  | TRANSISTOR:NPN,SI, AMPLIFIER, 625, T0-92 | 80009 | 151-0830-00 |
| A100318 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER, 625, T0-92 | 80009 | 151-0830-00 |
| Al00320 | 151-0829-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0829-00 |
| A100321 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER,625,T0-92 | 80009 | 151-0830-00 |
| A100322 | 151-0830-00 |  | TRANSISTOR:NPN, SI, AMPLIFIER, 625, T0-92 | 80009 | 151-0830-00 |
| A100323 | 151-1042-00 |  | SEMICOND DVC SE:FET,SI,TO-92 (LOCATIONS A AND B) | 04713 | SPF627M2 |
| A100325 | 151-0188-00 |  | TRANSISTOR:PNP, SI, TO-92 | 80009 | 151-0188-00 |
| A100326 | 151-0736-00 |  | TRANSISTOR:NPN, SI, TO-92 | 80009 | 151-0736-00 |
| A10Q328 | 151-0829-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0829-00 |
| A100329 | 151-0829-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0829-00 |
| A100330 | 151-0829-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0829-00 |
| A100331 | 151-0829-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0829-00 |
| A100332 | 151-0736-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0736-00 |
| A100333 | 151-0736-00 |  | TRANSISTOR:NPN, SI , TO-92 | 80009 | 151-0736-00 |
| A100440 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100444 | 151-0190-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0190-00 |
| A100470 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100474 | 151-0190-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0190-00 |
| A100480 | 151-0188-00 |  | TRANSISTOR:PNP,SI, T0-92 | 80009 | 151-0188-00 |
| A100600 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100601 | 151-0424-00 |  | TRANSISTOR:NPN, SI, T0-92 | 04713 | SPS8246 |
| A100602 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100603 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| Al0Q604 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A100605 | 151-0188-00 |  | TRANSISTOR: PNP, SI , T0-92 | 80009 | 151-0188-00 |
| A100606 | 151-0188-00 |  | TRANSISTOR: PNP, SI , T0-92 | 80009 | 151-0188-00 |
| A100607 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A109608 | 151-0190-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0190-00 |
| A100701 | 151-0846-00 |  | TRANSISTOR:NPN, SI, 5W, T0-39 | 80009 | 151-0846-00 |
| A100702 | 151-0846-00 |  | TRANSISTOR: NPN, SI, 5W, T0-39 | 80009 | 151-0846-00 |
| A100703 | 151-0190-00 |  | TRANSISTOR:NPN, SI, TO-92 | 80009 | 151-0190-00 |
| A100704 | 151-0190-00 |  | TRANSISTOR:NPN, SI, TO-92 | 80009 | 151-0190-00 |
| A100801 | 151-1212-00 |  | TRANSISTOR:MOSFET, VOWOS, P-CHAN, TO-39 | 80009 | 151-1212-00 |
| Al0Q802 | 151-1211-00 |  | TRANSISTOR:MOSFET, VONOS, N-CHAN, TO-39 | 80009 | 151-1211-00 |
| A100803 | 151-0736-00 |  | TRANSISTOR: NPN, SI, TO-92 | 80009 | 151-0736-00 |
| A100804 | 151-0712-00 |  | TRANSISTOR: PNP, SI, TO-92 | 04713 | SPS8223 |
| Al0Q805 | 151-1211-00 |  | TRANSISTOR:MOSFET, VDMOS, N-CHAN, TO-39 | 80009 | 151-1211-00 |
| A109806 | 151-1212-00 |  | TRANSISTOR:MOSFET, VDMOS, P-CHAN, TO-39 | 80009 | 151-1212-00 |
| A100807 | 151-0164-00 |  | TRANSISTOR: PNP, SI, TO-92 | 04713 | 2N2907A |
| A100808 | 151-0711-00 |  | TRANSISTOR: NPN, SI, T0-92B | 80009 | 151-0711-00 |
| A109809 | 151-0711-00 |  | TRANSISTOR:NPN, SI, T0-92B | 80009 | 151-0711-00 |
| Al00810 | 151-0711-00 |  | TRANSISTOR:NPN, SI, T0-92B | 80009 | 151-0711-00 |
| A10Q905 | 151-0622-00 |  | TRANSISTOR:PNP, SI, 40V, 1A, T0-226AE/237 | 04713 | SPS8956(MPSW51A) |
| A109907 | 151-0622-00 |  | TRANSISTOR: PNP, SI, 40V, 1A, TO-226AE/237 | 04713 | SPS8956(MPSW51A) |
| A109908 | 151-0622-00 |  | TRANSISTOR: PNP, SI, 40V, 1A, T0-226AE/237 | 04713 | SPS8956(MPSW51A) |


| Comporent No. | Tektronix Part No. | Serial/Assenbly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No . |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A1001001 | 151-0424-00 |  | TRANSISTOR:NPN,SI, T0-92 | 04713 | SPS8246 |
| A1001002 | 151-0424-00 |  | TRANSISTOR:NPN, SI, T0-92 | 04713 | SPS8246 |
| A1001003 | 151-0424-00 |  | TRANSISTOR:NPN, SI, T0-92 | 04713 | SPS8246 |
| A1001004 | 151-0424-00 |  | TRANSISTOR:NPN, SI, T0-92 | 04713 | SPS8246 |
| A1001005 | 151-0216-04 |  | TRANSISTOR:PNP, SI, T0-92 | 04713 | SPS8803RL |
| A1001101 | 151-0216-04 |  | TRANSISTOR:PNP, SI, T0-92 | 04713 | SPS8803RL |
| A10Q1102 | 151-0192-05 |  | TRANSISTOR:NPN, SI, $\mathrm{TO}=92$ | 04713 | ORDER BY DESCR |
| A1001103 | 151-0216-04 |  | TRANSISTOR:PNP, SI, T0-92 | 04713 | SPS8803RL |
| A1001104 | 151-0192-05 |  | TRANSISTOR:NPN, SI, T0=92 | 04713 | ORDER BY DESCR |
| A1001105 | 151-0216-04 |  | TRANSISTOR: PNP, SI, TO-92 | 04713 | SPS8803RL |
| A1001106 | 151-0192-05 |  | TRANSISTOR:NPN, SI, T0=92 | 04713 | ORDER BY DESCR |
| A1002701 | 151-0164-00 |  | TRANSISTOR: PNP, SI, T0-92 | 04713 | 2N2907A |
| A1002702 | 151-0164-00 |  | TRANSISTOR:PNP, SI, T0-92 | 04713 | 2N2907A |
| A1002703 | 151-0736-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0736-00 |
| A1002704 | 151-0736-00 |  | TRANSISTOR: NPN, SI, T0-92 | 80009 | 151-0736-00 |
| A1002705 | 151-0192-05 |  | TRANSISTOR:NPN, SI, TO=92 | 04713 | ORDER BY DESCR |
| A1002706 | 151-0190-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0190-00 |
| A10Q2707 | 151-0190-00 |  | TRANSISTOR:NPN,SI, T0-92 | 80009 | 151-0190-00 |
| A1002708 | 151-0188-00 |  | TRANSISTOR:PNP,SI, T0-92 | 80009 | 151-0188-00 |
| A1092709 | 151-0188-00 |  | TRANSISTOR:PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A10Q2711 | 151-0199-00 |  | TRANSISTOR:PNP, SI, T0-92 | 27014 | ST65057 |
| A10Q2712 | 151-0347-02 |  | TRANSISTOR:NPN, SI, T0-92 | 56289 | CT7916 |
| A10Q2713 | 151-0350-00 |  | TRANSISTOR:PNP,SI, T0-92 | 04713 | SPS6700 |
| Al0Q2715 | 151-0190-00 |  | TRANSISTOR:NPN, S1, T0-92 | 80009 | 151-0190-00 |
| A10R101 | 313-1822-00 |  | RES, FXD, FILM: 8.2K, OHM, 5\%, 0.2W | 57668 | TR20JE 08K2 |
| A10R102 | 313-1822-00 |  | RES, FXD, FILM: $8.2 \mathrm{~K}, 0 \mathrm{HM}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 08K2 |
| A10R103 | 313-1822-00 |  | RES, FXD, FILM: $8.2 \mathrm{~K}, 0 \mathrm{HM}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 08K2 |
| Al0R104 | 313-1822-00 |  | RES, FXD, FILM:8.2K, OHM, 5\%,0.2W | 57668 | TR20JE 08K2 |
| AlOR105 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR20JEIOKO |
| Al0R106 | 313-1103-00 |  | RES, FXD,FILM:10K OHM, 5\%, 0.2W | 57688 | TR20JE10K0 |
| A10R107 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| Al0R108 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| Al0R111 | 315-0620-00 |  | RES, FXD, FILM: 62 OHM, 5\%, 0.25W | 19701 | 5043CX63R00J |
| AlOR113 | 313-1200-00 |  | RES, FXD, FILM:20 OHM, 5\%,0.2W | 57668 | TR20JE20E |
| Al0R114 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10EO |
| A10R115 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 75E0 |
| AlOR121 | 315-0620-00 |  | RES, FXD, FILM: 62 OHM, 5\%, 0.25W | 19701 | $50430 \times 63 \mathrm{R00J}$ |
| A10R123 | 313-1200-00 |  | RES, FXD, FILM: 20 OHM, 5\%, 0.2W | 57668 | TR20JE20E |
| AlOR124 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%,0.2W | 57668 | TR20JE10E0 |
| A10R125 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, $0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 75E0 |
| A10R131 | 315-0390-00 |  | RES, FXD, FILM: 39 OHM, 5\%, 0.25W | 57668 | NTR25J-E39E0 |
| A10R132 | 322-3443-00 |  | RES, FXD, FILM: $402 \mathrm{~K} 0 \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 91637 | CCF50G40202F |
| A10R133 | 322-3443-00 |  | RES, FXD, FILM: 402 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 91637 | CCF50G40202F |
| AIOR134 | 322-3414-00 |  | RES, FXD, FILM: $200 \mathrm{~K} 0 \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 91637 | CCF50G20002F |
| A10R135 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10E0 |
| A10R136 | 322-3284-00 |  | RES, FXD,FILM:8.87K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 8K87 |
| A10R137 | 322-3217-00 |  | RES, FXD,FILM:1.78K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 1 K78 |
| A10R138 | 322-3210-00 |  | RES, FXD, FILM: 1.5 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 1 K50 |
| A10R139 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 75E0 |
| A10R140 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 75E0 |
| AlOR141 | 311-2224-00 |  | RES, VAR, NONWW: TRMR, $20 \mathrm{OHM}, 20 \%, 0.5 \mathrm{~W}$ LINEAR | TK1450 | GFO6UT |
| A10R142 | 322-3056-00 |  | RES, FXD, FILM: 37.4 OHM, 1\%, 0.2W, TC=TO | 80009 | 322-3056-00 |
| A10R151 | 315-0390-00 |  | RES, FXD, FILM: 39 OHM, 5\%, 0.25W | 57668 | NTR25J-E39E0 |
| A1OR152 | 322-3443-00 |  | RES, FXD, FILM: 402 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 91637 | CCF50G40202F |
| A10R153 | 322-3443-00 |  | RES, FXD, FILM: 402 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 91637 | CCF50G40202F |
| A10R154 | 322-3414-00 |  | RES, FXD, FILM: 200 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 91637 | CCF50G20002F |
| A10R155 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%,0.2W | 57668 | TR2OJE10E0 |
| A10R156 | 322-3284-00 |  | RES, FXD, FILM:8.87K OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 8K87 |


| Component No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10R157 | 322-3217-00 |  | RES, FXD, FILM: 1.78 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 1K78 |
| A10R158 | 322-3210-00 |  | RES, FXD, FILM: 1.5 K OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 1 K50 |
| A10R159 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, 0.2W, TC=TO. | 57668 | CRB20 FXE 75E0 |
| A10R160 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, $0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 75E0 |
| A10R161 | 311-2224-00 |  | RES, VAR, NONWW: TRMR, 20 OHM, $20 \%$, 0.5 W LINEAR | TK1450 | GF06UT |
| A10R162 | 322-3056-00 |  | RES, FXD, FILM: 37.4 OHM, 1\%, 0.2W, TC=TO | 80009 | 322-3056-00 |
| A10R171 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 470E |
| A10R175 | 313-1204-00 |  | RES, FXD, FILM:200K, 5\%,0.2W | 57668 | TR20JE 200K |
| A10R176 | 313-1103-00 |  | RES, FXD,FILM:10K OHM, 5\%,0.2W | 57668 | TR20JE10K0 |
| A10R177 | 313-1472-00 |  | RES, FXD,FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| A10R178 | 313-1472-00 |  | RES, FXD,FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| A10R179 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM , 5\%, 0.2W | 57668 | TR20JE10K0 |
| A10R180 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R181 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R182 | 308-0058-00 |  | RES, FXD, WW: $1.50 \mathrm{HM}, 10 \%$, 1W | 75042 | BW-20-1R500K |
| A10R201 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 1 K00 |
| A10R202 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 1K00 |
| A10R203 | 322-3193-00 |  | RES, FXD, FILM 1 K OHM, $1 \%, 0.2 \mathrm{H}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 1 K00 |
| A10R204 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 1 K00 |
| A10R205 | 322-3150-00 |  | RES, FXD, FILM: 357 OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 357E |
| Al0R206 | 322-3236-00 |  | RES, FXD, FILM:2.8K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 2 K 80 |
| A10R207 | 322-3150-00 |  | RES, FXD, FILM: 357 OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 357E |
| A10R208 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10EO |
| A10R209 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.2W | 57668 | TR20JT68 510E |
| A10R210 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM , 5\%, 0.2W | 57668 | TR2OJE 330E |
| A10R211 | 311-2329-00 |  | RES, VAR, NONWW: TRIMMER, 5 K OHM, $10 \%$ | 32997 | 3386R-EA5-502 |
| A10R212 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.2W | 57668 | TR20JT68 510E |
| A10R213 | 313-1243-00 |  | RES, FXD, FILM:24K OHM, 5\%, 0.2 W | 80009 | 313-1243-00 |
| A10R214 | 322-3285-00 |  | RES, FXD,FILM: $9.09 \mathrm{~K} O \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 9K09 |
| A10R215 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 820E |
| A10R218 | 322-3237-00 |  | RES, FXD, FILM: $2.87 \mathrm{~K} O H M, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 80009 | 322-3237-00 |
| A10R219 | 313-1104-00 |  | RES, FXD,FILM:100K OHM, 5\%,0.2W | 57668 | TR20JE100K |
| A10R220 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM, 5\%, 0.2W | 57668 | TR20JE 330E |
| A10R221 | 311-2329-00 |  | RES, VAR, NONWW : TRIMMER, 5 K OHM, $10 \%$ | 32997 | 3386R-EA5-502 |
| A10R222 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.2W | 57668 | TR20JT68 510E |
| A10R223 | 313-1243-00 |  | RES, FXD, FILM:24K OHM, $5 \%, 0.2 \mathrm{~W}$ | 80009 | 313-1243-00 |
| A10R224 | 322-3285-00 |  | RES, FXD, FILM:9.09K OHM, 1\%,0.2W, TC=TO | 57668 | CRB2O FXE 9K09 |
| A10R225 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A10R226 | 313-1027-00 |  | RES, FXD, FILM:2.7 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 02E7 |
| A10R227 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A10R228 | 322-3237-00 |  | RES, FXD, FILM: $2.87 \mathrm{~K} O \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 80009 | 322-3237-00 |
| Al0R229 | 313-1104-00 |  | RES, FXD, FILM: 100 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| A10R230 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 330E |
| A10R231 | 311-2329-00 |  | RES, VAR, NONWW: TRIMMER, 5 K OHM, 10\% | 32997 | 3386R-EA5-502 |
| A10R232 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.2W | 57668 | TR20.JT68 510E |
| Al0R233 | 313-1243-00 |  | RES, FXD, FILM: 24 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 80009 | 313-1243-00 |
| AlOR234 | 322-3285-00 |  | RES, FXD, FILM: $9.09 \mathrm{~K} 01 \mathrm{M}, 1 \%, 0.2 \mathrm{~W}$, TC=T0 | 57668 | CRB20 FXE 9K09 |
| A10R235 | 322-3237-00 |  | RES, FXD, FILM: $2.87 \mathrm{~K} O H \mathrm{M}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 80009 | 322-3237-00 |
| A10R238 | 313-1100-00 |  | RES, FXD, FILM 10 OHM , 5\%, 0.2W | 57668 | TR20JE10E0 |
| Al0R240 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM, 5\%, 0.2W | 57688 | TR20JE 330E |
| A10R241 | 311-2329-00 |  | RES, VAR, NONWW: TRIMMER, 5K OHM, 10\% | 32997 | 3386R-EA5-502 |
| A10R242 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJT68 510E |
| A10R243 | 313-1243-00 |  | RES, FXD, FILM: 24 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 80009 | 313-1243-00 |
| A10R244 | 322-3285-00 |  | RES, FXD, FILM: 9.09 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 9K09 |
| A10R245 | 313-1027-00 |  | RES, FXD, FILM:2.7 OHM, 5\%, 0.2W | 57668 | TR2̈OJE O2E7 |
| Al0R248 | 322-3237-00 |  | RES, FXD, FILM: 2.87 K OHM, 1\%, 0. $2 \mathrm{~W}, \mathrm{TC}=$ TO | 80009 | 322-3237-00 |
| Al0R250 | 307-0792-00 |  | RES NTWK, FXD, FI: 7,82 OHM, $2 \%, 0.15 \mathrm{~W}$ EACH | 11236 | 750-81-R82 |
| A10R251 | 307-0792-00 |  | RES NTWK, FXD, FI: 7,82 OHM, $2 \%, 0.15 \mathrm{~W}$ EACH | 11236 | 750-81-R82 |


| Component No. | Tektronix <br> Part No. | Serial/Assenbly No. Effective Dscont. | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10R254 | 322-3318-00 |  | RES, FXD, FILM:20K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 20KO |
| Al0R255 | 322-3318-00 |  | RES, FXD, FILM:20K OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 20K0 |
| Al0R256 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| Al0R260 | 311-2234-00 |  | RES, VAR, NONWW: TRMR, 5 K OHM, $20 \%$, 0.5 W LINEAR | TK1450 | GFO日UT 5K |
| Al0R261 | 313-1243-00 |  | RES, FXD, FILM: 24 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 80009 | 313-1243-00 |
| Al0R262 | 322-3083-00 |  | RES, FXD, FILM: 71.5 OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 7155 |
| A10R263 | 322-3083-00 |  | RES, FXD, FILM: 71.5 OHM, 1\%, 0, 2W, TC=T0 | 57668 | CRB20 FXE 71E5 |
| A10R264 | 322-3083-00 |  | RES, FXD, FILM: 71.5 OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 71 E5 |
| A10R265 | 322-3083-00 |  | RES, FXD, FILM: 71.5 OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 71E5 |
| A10R266 | 313-1302-00 |  | RES, FXD, FILM: 3 K OHM, 5\%,0.2W | 57668 | TR2OJE 03K0 |
| A10R267 | 322-3164-00 |  | RES, FXD, FILM: 499 OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 499E |
| A10R268 | 322-3158-00 |  | RES, FXD, FILM: 432 OHM, 1\%, O.2W, TC=TO | 57668 | CRB2D FXE 432 |
| A10R269 | 322-3158-00 |  | RES, FXD, FILM: 432 OHM, 1\%, 0.2W, TC= T0 | 57668 | CRB2D FXE 432 |
| A10R270 | 313-1751-00 |  | RES, FXD, FILM: 750 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 750E |
| A10R271 | 313-1912-00 |  | RES, FXD, FILM:9.1K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20 FXE 9.1K |
| A10R272 | 311-2232-00 |  | RES, VAR, NONWW: TRMR,2K OHM, $20 \%, 0.5 \mathrm{~W}$ LINEAR | TK1450 | GFOGUT 2K |
| A10R273 | 311-2230-00 |  | RES, VAR, NONWW:TRMR, 500 OHM, $20 \%, 0.50$ LINEAR | TK1450 | GF06UT 500 |
| A10R274 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10E0 |
| A10R275 | 311-2227-00 |  | RES, VAR, NONWW: TRMR, 100 OHM, $20 \%, 0.5 W$ LINEAR | TK1450 | GFOEUT 100 |
| A10R276 | 322-3213-00 |  | RES, FXD, FILM: 1.62 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 1 K62 |
| A10R277 | 322-3213-00 |  | RES, FXD, FILM:1.62K OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 1K62 |
| A10R278 | 322-3141-00 |  | RES, FXD, FILM: 287 OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 287E |
| A10R279 | 322-3141-00 |  | RES, FXD, FILM: 287 OHM, 1\%, 0.2W, TC= TO | 57668 | CRB20 FXE 287E |
| A10R280 | 322-3098-00 |  | RES, FXD, FILM: 102 OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 102E |
| Al0R281 | 322-3098-00 |  | RES, FXD, FILM: 102 OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 102E |
| A10R282 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10E0 |
| A10R283 | 313-1100-00 |  | , RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR2OJE10E0 |
| A10R284 | 313-1393-00 |  | RES, FXD, FILM:39K OHM, 5\%, 0.2W | 57668 | TR20JE 39K |
| A10R285 | 313-1393-00 |  | RES, FXD, FILM: 39 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 39K |
| Al0R286 | 322-3097-00 |  | RES, FXD, FILM: 100 OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 100E |
| A10R287 | 322-3097-00 |  | RES, FXD, FILM: 100 OHM, 1\%, 0.2W, TC= TO | 57668 | CRB20 FXE 100E |
| A10R288 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, 1\%,0.2W, TC=TO | 57668 | CRB2O FXE 1 K00 |
| A10R289 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 1 K00 |
| Al0R290 | 322-3123-00 |  | RES, FXD, FILM: 187 OHM, $1 \%, 0.2 \mathrm{~W}$, TC= $=$ TO | 57668 | CRB20 FXE 187 E |
| A10R291 | 322-3123-00 |  | RES, FXD, FILM: 187 OHM, 1\%,0.2W, TC $=$ TO | 57668 | CRB20 FXE 187E |
| A10R292 | 313-1752-00 |  | RES, FXD, FILM: 7.5 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE O7K5 |
| A10R293 | 313-1752-00 |  | RES, FXD, FILM 7.5 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 07K5 |
| A10R294 | 313-1202-00 |  | RES, FXD, FILM:2K OHM, 5\%, 0.2W | 57668 | TR2OJEO2KO |
| A10R295 | 313-1302-00 |  | RES, FXD, FILM:3K OHM, 5\%,0.2W | 57668 | TR20JE 03K0 |
| A10R296 | 322-3117-00 |  | RES, FXD, FILM: 162 OHM, 1\%,0.2W, TC=T0 | 57668 | CRB 20 FXE 162E |
| A10R297 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM , 5\%,0.2W | 57668 | TR20JE10ED |
| A10R298 | 313-1027-00 |  | RES, FXD, FILM:2.7 OHM, 5\%, 0.2W | 57668 | TR20JE 02E7 |
| A10R301 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJEOIKO |
| A10R302 | 313-1027-00 |  | RES, FXD, FILM:2.7 OHM, 5\%, 0.2 W | 57668 | TR20JE 02E7 |
| A10R303 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| A10R304 | 313-1470-00 |  | RES, FXD, FILM: 47 OHM, 5\%, 0.2W | 57668 | TR20JE 47E |
| A10R305 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM $, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R306 | 313-1051-00 |  | RES, FXD, FILM:5.1 OHM , 5\%, 0.2W | 57668 | TR20JT68 05E1 |
| A10R307 | 322-3328-02 |  | RES, FXD, FILM: 25.5 K OHM, $0.5 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T2 | 57668 | CRB20 DYE 25K5 |
| A10R308 | 322-3319-02 |  | RES, FXD, FILM: 20.5 K OHM, $0.5 \%, 0.2 \mathrm{~W}, \mathrm{TC}=\mathrm{T} 2$ | 57668 | CRB20 DYE 20K5 |
| A10R309 | 322-3289-00 |  | RES, FXD, FILM: $10 \mathrm{~K} 0 \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 10K0 |
| A10R310 | 313-1473-00 |  | RES, FXD, FILM: 47 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 47K |
| A10R311 | 322-3269-02 |  | RES, FXD, FILM:6.19K OHM, 0. $2 \mathrm{~W}, 5 \%$ | 57668 | CRB DYE GK19 |
| A10R312 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%,0.2W | 57668 | TR2OJE10E0 |
| A10R313 | 307-2132-00 |  | RES NTWK, FXD, FI:REF VOLTAGE DIVIDER | 80009 | 307-2132-00 |
| A10R314 | 322-3333-02 |  | RES, FXD, FILM: 28.7 K OHM, 0.2W, $5 \%$ | 57668 | CRB20 DYE 28K7 |
| A10R315 | 313-1470-00 |  | RES, FXD, FILM: 47 OHM, 5\%,0.2W | 57668 | TR20JE 47E |
| A10R316 | 313-1270-00 |  | RES, FXD, FILM: 27 OHM 5\%,0.2W | 57668 | TR20JT68 27E |



| Component No. | Tektronix <br> Part No. | Serial/Assembly No. Effective Dscont | Mane \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10R377 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, 1\%, O.2W, TC=T0 | 57668 | CRB2O FXE 1K00 |
| A10R378 | 313-1820-00 |  | RES, FXD, FILM: 82 OHM, 5\%,0.2W | 57668 | TR20JE 82E |
| A10R379 | 322-3193-00 |  | RES, FXD,FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 1 KOO |
| A10R380 | 313-1820-00 |  | RES, FXD, FILM: 82 OHM, 5\%, 0.2W | 57668 | TR20JE 82E |
| A10R381 | 313-1270-00 |  | RES, FXD, FILM: 27 OHM 5\%,0.2W | 57668 | TR20JT68 27E |
| A10R382 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 1 K00 |
| A10R383 | 313-1161-00 |  | RES, FXD, FILM: 160 OHM, 5\%, 0.2W | 57668 | TR20JE160E |
| A10R384 | 313-1512-00 |  | RES, FXD, FILM: 5.1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| A10R385 | 313-1162-00 |  | RES, FXD, FILM:1.6K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT681K6 |
| A10R386 | 313-1162-00 |  | RES, FXD, FILM:1.6K OHM, 5\%,0.2W | 57668 | TR20JT681K6 |
| A10R387 | 313-1820-00 |  | RES, FXD, FILM: 82 OHM, 5\%,0.2W | 57668 | TR20JE 82E |
| A10R388 | 313-1820-00 |  | RES, FXD, FILM: 82 OHM, 5\%, 0. 2 W | 57668 | TR20JE 82E |
| A10R390 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR2OJE10E0 |
| A10R391 | 313-1203-00 |  | RES, FXD, FILM: 20K OHM, 5\%, 0.2W | 57668 | TR20JE20K |
| A10R392 | 313-1514-00 |  | RES, FXD, FILM: 510 K OHM, 5\%, 0.2 W | 57668 | TR20JE 510K |
| A10R393 | 313-1471-00 |  | RES, FXD, FILM: 470 OHMM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 470E |
| A10R394 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM , 5\%, 0.2W | 57668 | TR20JE 470E |
| A10R395 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%,0.2W | 57668 | TR2OJEO1KO |
| A10R396 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR20JE01KO |
| A10R410 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R411 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%,0.2W | 57668 | TR20JE100E |
| Al0R412 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| Al0R413 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| AlOR414 | 313-1511-00 |  | RES, FXD,FILM:510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R415 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R416 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| Al0R417 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| Al0R420 | 313-1271-00 |  | RES, FXD, FILM:270 OHM, 5\%, 0.2 W | 57668 | TR20JE 270E |
| Al0R421 | 322-3279-00 |  | RES, FXD, FILM 7.87 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 7K87 |
| A10R422 | 322-3279-00 |  | RES, FXD, FILM: 7.87 K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 7K87 |
| A10R423 | 322-3279-00 |  | RES, FXD, FILM: 7.87 K OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 7K87 |
| A10R424 | 322-3279-00 |  | RES, FXD, FILM: 7.87 K OHM, 1\%,0.2W, TC=TO | 57668 | CRB20 FXE 7K87 |
| A10R425 | 313-1750-00 |  | RES, FXD, FILM: 75 OHM, 5\%, 0. 2 W | 57668 | TR20JE 75E |
| A10R426 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R430 | 313-1271-00 |  | RES, FXD, FILM: 270 OHM, 5\%, 0.2W | 57668 | TR20JE 270E |
| AlOR431 | 313-1750-00 |  | RES, FXD, FILM 75 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 75E |
| A10R432 | 322-3074-00 |  | RES, FXD, FILM: 57.6 OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 80009 | 322-3074-00 |
| A10R440 | 313-1104-00 |  | RES, FXD, FILM: 100 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| A10R441 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A10R442 | 313-1562-00 |  | RES, FXD, FILM: 5.6 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 05K6 |
| AlOR443 | 313-1562-00 |  | RES, FXD, FILM 5.6 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 05K6 |
| A10R444 | 313-1561-00 |  | RES, FXD, FILM: 560 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 560E |
| AIOR445 | 322-3143-00 |  | RES, FXD, FILM: 301 OHM, 1\%, 0. $2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 301E |
| A10R446 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM, 5\%, 0.2W | 57668 | TR20JE 330E |
| A10R447 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 1K00 |
| Al0R448 | 322-3251-00 |  | RES, FXD, FILM $4.4 .02 \mathrm{~K} 01 \mathrm{M}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB2O FXE 4K02 |
| A10R449 | 313-1392-00 |  | RES, FXD, FILM:3.9K OHM, 5\%,0.2W | 57668 | TR20JE 03K9 |
| A10R450 | 313-1271-00 |  | RES, FXD, FILM: 270 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 270E |
| A10R451 | 322-3279-00 |  | RES, FXD, FILM: 7.87 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 7K87 |
| A10R452 | 322-3279-00 |  | RES, FXD, FILM: $7.87 \mathrm{~K} O \mathrm{MM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 7K87 |
| Al0R453 | 322-3279-00 |  | RES, FXD, FILM: $7.87 \mathrm{~K} O H \mathrm{M}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 7K87 |
| A10R454 | 322-3279-00 |  | RES, FXD, FILM $7.87 \mathrm{~K} 0 \mathrm{OM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 7K87 |
| A10R455 | 311-2230-00 |  | RES, VAR, NONWW: TRMR, 500 OHM, 20\%, 0.50 LINEAR | TK1450 | GFOSUT 500 |
| A10R456 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE10K0 |
| Al0R460 | 313-1271-00 |  | RES, FXD, FILM:270 OHM, 5\%, 0.2 W | 57668 | TR20JE 270E |
| Al0R461 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R462 | 322-3074-00 |  | RES, FXD, FILM: 57.6 OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 80009 | 322-3074-00 |
| Al0R463 | 313-1120-00 |  | RES, FXD, FILM: 12 OHM, 5\%,0.2W | 57668 | TR20JE12E0 |


| Component No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10R470 | 313-1104-00 |  | RES, FXD, FILM: 100 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| A10R471 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A10R472 | 313-1562-00 |  | RES, FXD, FILM: 5.6 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 05K6 |
| A10R473 | 313-1562-00 |  | RES, FXD, FILM: 5.6 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 05K6 |
| A10R474 | 313-1561-00 |  | RES, FXD, FILM: 560 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 560E |
| A10R475 | 322-3143-00 |  | RES, FXD, FILM: 301 OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 301E |
| A10R476 | 313-1392-00 |  | RES, FXD, FILM:3.9K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 03K9 |
| A10R477 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 1 KOO |
| A10R478 | 322-3251-00 |  | RES, FXD, FILM: 4.02 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 4K02 |
| A10R481 | 313-1051-00 |  | RES, FXD, FILM: 5.1 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 05E1 |
| A10R483 | 313-1151-00 |  | RES, FXO, FILM: 150 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE150E |
| A10R484 | 313-1202-00 |  | RES, FXD, FILM: 2 K OHM, 5\%, 0.2 W | 57668 | TR20JEO2K0 |
| A10R485 | 313-1392-00 |  | RES, FXD, FILM: 3.9 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 03K9 |
| A10R486 | 313-1512-00 |  | RES, FXD, FILM: 5.1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 5K1 |
| A10R487 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 330E |
| A10R490 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R491 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R492 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.2W | 57668 | TR20JT68 510E |
| A10R493 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R494 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R495 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM , 5\%, 0.2W | 57668 | TR20JT68 510E |
| A10R496 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R497 | 313-1511-00 |  | RES, FXD,FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R498 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.2W | 57668 | TR20JT68 510E |
| A10R501 | 307-0446-00 |  | RES NTWK, FXD, FI: 10 K OHM, 20\%, (9)RES | 11236 | 750-101-R10K |
| A10R502 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2 W | 57668 | TR20JE10K0 |
| A10R503 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| Al0R504 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM $5 \%$, 0.2 W | 57668 | TR20JE100E |
| Al0R505 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR2OJE10K0 |
| A10R506 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR20JE10K0 |
| A10R507 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM , 5\%, 0.2W | 57668 | TR20JE10KO |
| A10R508 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| Al0R510 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A10R512 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR2OJE10KO |
| Al0R601 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JEO1KO |
| Al0R602 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, 1\%, $0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 1K00 |
| A10R603 | 322-3193-00 |  | RES, FXX, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 1 K00 |
| Al0R604 | 322-3231-00 |  | RES, FXD,FILM:2.49K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 2K49 |
| Al0R605 | 322-3193-00 |  | RES, FXD, FILM: 1 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 1 K00 |
| A10R606 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR20JE01K0 |
| A10R607 | 313-1510-00 |  | RES, FXD, FILM: 51 OHM, 5\%, 0.2W | 80009 | 313-1510-00 |
| A10R609 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R610 | 313-1391-00 |  | RES, FXD, FILM:390 OHM, 5\%, 0.2W | 57668 | TR20JE 390E |
| A10R611 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100E |
| A10R612 | 313-1391-00 |  | RES, FXD, FILM:390 OHM, 5\%, 0.2W | 57868 | TR20JE 390E |
| A10R613 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R614 | 313-1391-00 |  | RES, FXD, FILM: 390 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 390E |
| A10R615 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 470E |
| A10R616 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM, 5\%, 0.2W | 57668 | TR20JE 470E |
| A10R617 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM, 5\%, 0.2W | 57668 | TR20JE 470E |
| A10R618 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, 5\%, 0.2W | 57668 | TR20JE 820E |
| A10R619 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, 5\%,0.2W | 57668 | TR2OJE 820E |
| A10R620 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, 5\%,0.2W | 57668 | TR20JE 820E |
| A10R621 | 313-1302-00 |  | RES, FXD, FILM:3K OHM, 5\%, 0. 2 W | 57668 | TR2OJE 03K0 |
| A10R622 | 313-1302-00 |  | RES, FXD, FILM:3K OHM, 5\%, 0.2W | 57668 | TRZOJE 03KO |
| A10R623 | 313-1302-00 |  | RES, FXD, FILM:3K OHM, 5\%, 0. 2 W | 57668 | TR2OJE 03K0 |
| A10R624 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0. 2 W | 57668 | TR2OJE01K0 |
| A10R625 | 313-1221-00 |  | RES, FXD,FILM:220 OHM, 5\%,0.2W | 57668 | TR20JE220E |


| Component No. | Tektronix Part No. | Serial/Assembly Mo. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
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| A10R626 | 313-1390-00 |  | RES, FXD, FILM: 39 OHM, 5\%,0.2W | 57668 | TR20JE 39E |
| A10R627 | 313-1390-00 |  | RES, FXD, FILM: 39 OHM, 5\%, 0.2W | 57668 | TR20JE 39E |
| A10R628 | 307-0503-00 |  | RES NTWK, FXD, FI: (9) $510 \mathrm{OHM}, 20 \%, 0.125 \mathrm{~W}$ | 11236 | 750-101-R510 |
| A10R630 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10KO |
| A10R631 | 313-1102-00 |  | RES, FXD, FILM:1K OHM, 5\%, 0.2 W | 57668 | TR20JE01K0 |
| A10R636 | 313-1273-00 |  | RES, FXD,FILM: 27 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 27 K |
| A10R637 | 313-1822-00 |  | RES, FXD, FILM 8.8 K, 0 OM $, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 08K2 |
| A10R638 | 313-1753-00 |  | RES, FXD, FILM: 75 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 75K |
| A10R639 | 313-1512-00 |  | RES, FXD, FILM $: 5.1 \mathrm{~K} 0 \mathrm{HM}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| A10R640 | 313-1512-00 |  | RES, FXD, FILM 5.5 .1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| Al OR641 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 820E |
| A10R642 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, 5\%, 0.2W | 57668 | TR20JE 820E |
| A10R643 | 313-1562-00 |  | RES, FXD, FILM: 5.6 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 05K6 |
| A10R644 | 313-1562-00 |  | RES, FXD, FILM 5.5 KK OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 05K6 |
| A10R645 | 313-1562-00 |  | RES, FXD, FILM 5.5 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 05K6 |
| A10R646 | 313-1562-00 |  | RES, FXD, FILM: 5.6 K OHM $, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 05K6 |
| A10R647 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM, 5\%, 0.2W | 57668 | TR20JE 820E |
| A10R648 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 470E |
| A10R649 | 313-1302-00 |  | RES, FXD, FILM 3 K OHM, 5\%, 0.2 W | 57668 | TR20JE O3K0 |
| A10R650 | 313-1751-00 |  | RES, FXD, FILM: 750 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 750E |
| A10R651 | 313-1331-00 |  | RES, FXD, FILM:330 OHM, 5\%, 0.2W | 57668 | TR20JE 330E |
| A10R652 | 313-1331-00 |  | RES, FXD, FILM: 330 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 330E |
| A10R653 | 313-1471-00 |  | RES, FXD, FILM: 470 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 470E |
| A10R654 | 313-1302-00 |  | RES, FXD, FILM 3 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 03K0 |
| A10R655 | 313-1821-00 |  | RES, FXD, FILM: 820 OHM , 5\%, 0.2W | 57668 | TR20JE 820E |
| A10R656 | 313-1621-00 |  | RES, FXD, FILM:620 OHM, 5\%,0.2W | 57668 | TR20JE 620E |
| A10R657 | 313-1621-00 |  | RES, FXD, FILM:620 OHM, 5\%,0.2W | 57668 | TR20JE 620E |
| A10R658 | 313-1302-00 |  | RES, FXD, FILM 3 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 03K0 |
| A10R659 | 313-1302-00 |  | RES, FXD, FILM:3K OHM, 5\%, O.2W | 57668 | TR2OJE 03K0 |
| A10R662 | 313-1393-00 |  | RES, FXD, FILM:39K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 39K |
| A10R663 | 313-1393-00 |  | RES, FXD, FILM: 39 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 39K |
| A10R664 | 313-1393-00 |  | RES, FXD, FILM:39K OHM, 5\%,0.2W | 57668 | TR2OJE 39K |
| A10R665 | 313-1393-00 |  | RES, FXD, FILM: 39 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 39K |
| A10R666 | 313-1393-00 |  | RES, FXD, FILM: 39 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57688 | TR2OJE 39K |
| A10R669 | 313-1511-00 |  | RES, FXD, FILM:510 OHM, 5\%, 0.2W | 57668 | TR2OJT68 510E |
| A10R670 | 313-1511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 510E |
| A10R671 | 313-1180-00 |  | RES, FXD, FILM: 18 OHM, 5\%, 0. 2 W | 80009 | 313-1180-00 |
| A10R672 | 313-1333-00 |  | RES, FXD, FILM: 33 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 33K |
| A10R701 | 322-3226-00 |  | RES, FXD, FILM: $2.21 \mathrm{~K} 0 \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 2K21 |
| A10R702 | 313-1222-00 |  | RES, FXD, FILM 22.2 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 02K2 |
| A10R703 | 311-2230-00 |  | RES, VAR, NONWW: TRMR, 500 OHM, 20\%, 0.50 LINEAR | TK1450 | GF06UT 500 |
| A10R706 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 75E0 |
| A10R707 | 322-3085-00 |  | RES, FXD, FILM: 75 OHM, 1\%, 0. $2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 75E0 |
| A10R708 | 307-2130-00 |  | RES NTWK, FXD, FI: DUAL LOAD RESISTOR | 80009 | 307-2130-00 |
| A10R709 | 313-1027-00 |  | RES, FXD, FILM: 2.7 OHM, $5 \%$, 0.2W | 57668 | TR2OJE 02E7 |
| A10R710 | 313-1134-00 |  | RES, FXD, FILM: 130 K OHM $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 130K |
| A10R711 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%,0.2W | 57668 | TR2OJE10EO |
| A10R712 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0. W | 57868 | TR20JE10E0 |
| A10R715 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JEIOKO |
| A10R716 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A10R717 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01K0 |
| A10R718 | 313-1102-00 |  | RES, FXD, FILM:1K OHM, 5\%,0.2W | 57868 | TR20JE01K0 |
| A10R719 | 313-1200-00 |  | RES, FXD, FILM: 20 OHM , 5\%, 0.2 W | 57668 | TR20JE20E |
| A10R720 | 313-1200-00 |  | RES, FXD, FILM: 20 OHM, 5\%, 0.2 W | 57668 | TR2OJE20E |
| A10R721 | 313-1134-00 |  | RES, FXD, FILM: 130 K OHM $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 130K |
| A10R722 | 313-1134-00 |  | RES, FXD, FILM: 130 K OHM $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 130K |
| A10R723 | 313-1027-00 |  | RES, FXD, FILM: 2.7 OHM, 5\%, 0.2W | 57668 | TR2OJE 02E7 |
| A10R724 | 311-2234-00 |  | RES, VAR, NONWW: TRMR, 5K OHM, 20\%,0.5W LINEAR | TK1450 | GFO6UT 5K |



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| Component No. | Tektronix Part No. | Serial/Assenbly Mo. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
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| A10R907 | 313-1120-00 |  | RES, FXD, FILM: 12 OHM, 5\%,0.2W | 57668 | TR2OJE12EO |
| A10R908 | 313-1120-00 |  | RES, FXD, FILM: 12 OHM, 5\%,0.2W | 57668 | TR20JE12EO |
| Al0R909 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%,0.2W | 57668 | TR20JE100E |
| A10R910 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R911 | 311-1239-00 |  | RES, VAR, NONWW:TRMR, 2.5K OHM, 0.5W | 32997 | 3386X-T07-252 |
| A10R915 | 322-3289-00 |  | RES, FXD, FILM: 10K OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 10 KO |
| A10R916 | 322-3289-00 |  | RES, FXD, FILM: 10 K OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 10K0 |
| A10R920 | 311-2228-00 |  | RES, VAR, NONWW: TRMR, 200 OHM, $20 \%$, 0.5 W LINEAR | TK1450 | GFO6UT B200 OHM |
| A10R921 | 307-2131-00 |  | RES NTWK, FXD, FI: PRECESION VOLTAGE DIVIDER | 80009 | 307-2131-00 |
| A10R922 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A10R923 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A10R924 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A10R930 | 313-1751-00 |  | RES, FXD, FILM: 750 OHM, $5 \%$, 0.2W | 57668 | TR20JE 750E |
| A10R931 | 322-3193-02 |  | RES, FXD, FILM: 1 K OHM, $0.5 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T2 | 57668 | CRB2O DYE 1 K00 |
| A10R932 | 322-3239-03 |  | RES, FXD, FILM:3.01K OHM, 0.25\%, 0.2W, TC $=$ T2 | 57668 | CRB20 CYE 3K01 |
| A10R933 | 313-1272-00 |  | RES, FXD, FILM:2.7K OHM, 5\%,0.2W | 57668 | TR20JE O2K7 |
| A10R934 | 313-1122-00 |  | RES, FXD, FILM:1.2K OHM, 5\%,0.2W | 57668 | TR2OJE01K2 |
| A10R935 | 313-1223-00 |  | RES, FXD, FILM: 22 K, OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 22K |
| A10R936 | 322-3489-02 |  | RES, FXD, FILM:3.52K OHM, 0.2W, 5\% | 57668 | CRB20 DYE 3K52 |
| A10R937 | 322-3126-02 |  | RES, FXD, FILM: 200 OHM, $0.5 \%, 0.2 \mathrm{~W}, \mathrm{TC}=\mathrm{T} 2$ | 80009 | 322-3126-02 |
| A10R938 | 313-1752-00 |  | RES, FXD, FILM: 7.5 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 07K5 |
| A10R939 | 313-1152-00 |  | RES, FXD, FILM: 1.5 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K5 |
| A10R940 | 313-1122-00 |  | RES, FXD, FILM:1.2K OHM, 5\%,0.2W | 57668 | TR20JE01K2 |
| AlOR1001 | 322-3232-00 |  | RES, FXD, FILM: 2.55 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 80009 | 322-3232-00 |
| A10R1002 | 322-3232-00 |  | RES, FXD, FILM: 2.55 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 80009 | 322-3232-00 |
| A10R1003 | 313-1512-00 |  | RES, FXD, FILM: 5.1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| A10R1004 | 322-3232-00 |  | RES, FXD, FILM:2.55K OHM, 1\%,0.2W, TC=TO | 80009 | 322-3232-00 |
| A10R1005 | 322-3251-00 |  | RES, FXD, FILM: 4.02K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 4K02 |
| A10R1006 | 322-3184-00 |  | RES, FXD, FILM: 806 OHM, 1\%, $0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 806E |
| A10R1007 | 322-3251-00 |  | RES, FXD, FILM:4.02K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 4K02 |
| Al0R1008 | 322-3184-00 |  | RES, FXD, FILM: 806 OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 806E |
| AlOR1009 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE1OKO |
| A10R1010 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, 5\%, 0.2W | 57668 | TR20JE10K0 |
| A10R1020 | 313-1272-00 |  | RES, FXD, FILM:2.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 02K7 |
| A10R1021 | 313-1512-00 |  | RES, FXD, FILM: 5.1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| A10R1022 | 313-1272-00 |  | RES, FXD, FILM: 2.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 02K7 |
| A10R1023 | 313-1512-00 |  | RES, FXD, FILM: 5.1 K OHM $, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 5K1 |
| A10R1024 | 313-1272-00 |  | RES, FXD, FILM: $2,7 \mathrm{~K}$ OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 02K7 |
| A10R1025 | 313-1512-00 |  | RES, FXD, FILM: 5.1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| Al0R1026 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10E0 |
| A10R1027 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57688 | TR2OJEIOEO |
| A10R1028 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJE01KO |
| A10R1101 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR2OJE10EO |
| Al0R1102 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0. 2 W | 57668 | TR20JE10E0 |
| A10R1103 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJEOIKO |
| A10R1104 | 313-1682-00 |  | RES, FXD,FILM:6.8K OHM, 5\%,0.2W | 57668 | TR20JE 06K8 |
| A10R1110 | 313-1682-00 |  | RES, FXD,FILM:6.8K OHM,5\%,0.2W | 57668 | TR2OJE 06K8 |
| A10R1111 | 313-1303-00 |  | RES, FXD, FILM:30K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 30K |
| A1OR1112 | 313-1302-00 |  | RES, FXD, FILM: 3 K OHM, 5\%, 0.2W | 57668 | TR2OJE O3K0 |
| A10R1113 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100E |
| A10R1114 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A10R1115 | 313-1682-00 |  | RES, FXD, FILM:6.8K OHM,5\%, 0.2 W | 57868 | TR20JE 06K8 |
| A10R1116 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJEOIK0 |
| A10R1117 | 313-1162-00 |  | RES, FXD, FILM: 1. 6K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT681K6 |
| A10R1118 | 313-1751-00 |  | RES, FXD, FILM: 750 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 750E |
| A10R1120 | 313-1682-00 |  | RES, FXD, FILM: 6.8 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 06K8 |
| A10R1121 | 313-1303-00 |  | RES, FXD, FILM: $30 \mathrm{~K} 0 \mathrm{HM}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 30K |
| Al0R1122 | 313-1302-00 |  | RES, FXD, FILM:3K OHM, $5 \%$, 0.2W | 57668 | TR20JE 03K0 |



| Component No. | Tektronix <br> Part No. | Serial/Assembly No. Effective Dscont | Mame \& Description | Mfr. Code | Mfr. Part Ho. |
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| A10R2740 | 315-0750-00 |  | RES, FXD, FILM: 75 OHM , 5\%, 0.25W | 57668 | NTR25J-E75E0 |
| A10R2741 | 315-0472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.25 W | 57668 | NTR25J-E04K7 |
| A10R2742 | 315-0244-00 |  | RES, FXD, FILM: 240 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX240K0J |
| A10R2743 | 315-0122-00 |  | RES, FXD, FILM 1.1 .2 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E01K2 |
| A10R2745 | 315-0102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.25 W | 57668 | NTR25JE01K0 |
| A10R2750 | 315-0511-00 |  | RES, FXD, FILM: 510 OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX510R0J |
| A10R2751 | 315-0625-00 |  | RES, FXD, FILM: $6.2 \mathrm{M} \mathrm{OHM}, 5 \%, 0.25 \mathrm{~W}$ | 01121 | CB6255 |
| A10R2758 | 311-1933-00 |  | RES, VAR, NONWW: PNL, 5M OHM, 10\%, 0.5W | 01121 | 23M909 |
| Al0R2760 | 307-2173-00 |  | RES NTWK, FXD, FI:HIGH VOLTAGE, FINISHED | 80009 | 307-2173-00 |
| A10R2765 | 322-3188-00 |  | RES, FXD, FILM: 887 OHM, 1\%, 0.2W, TC=T0 | 57668 | CRB20 FXE 887E |
| Al0R2783 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A10R2784 | 311-2239-00 |  | RES, VAR, NONWW: TRMR, 100K OHM, 20\%,0.5W LINEAR | TK1450 | GFOEUT 100K |
| A10R2785 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01K0 |
| A10R2786 | 313-1823-00 |  | RES, FXD, FILM:82K OHM, 5\%, 0.2W | 57668 | TR2OJE 82K |
| A10R2787 | 313-1363-00 |  | RES, FXD, FILM: 36 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR203E 36K |
| A10R2788 | 311-2239-00 |  | RES, VAR, NONWW: TRMR, 100K OHM, 20\%, 0.5W LINEAR | TK1450 | GF06UT 100K |
| A10R2789 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%,0.2W | 57668 | TR20JE01K0 |
| A10R2795 | 322-3268-00 |  | RES, FXD, FILM: 6.04 K OHM, $1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE GK04 |
| A10R2796 | 313-1100-00 |  | RES, FXD, FILM: 10 OHM, 5\%, 0.2W | 57668 | TR20JE10EO |
| A10U112 | 165-2232-00 |  | MICROCKT,LINEAR:BUFFER AMPLIFIER | 80009 | 165-2232-00 |
| A10U122 | 165-2232-00 |  | MICROCKT,LINEAR:BUFFER AMPLIFIER | 80009 | 165-2232-00 |
| A10U171 | 156-0796-00 |  | MICROCKT, DGTL: 8 STG SHF \& STORE BUS RGTR | 02735 | CD4094BF |
| A10U172 | 156-0796-00 |  | MICROCKT,DGTL: 8 STG SHF \& STORE BUS RGTR | 02735 | CD4094BF |
| A10U173 | 156-0796-00 |  | MICROCKT, DGTL: 8 STG SHF \& STORE BUS RGTR | 02735 | CD4094BF |
| A10U174 | 156-1190-00 |  | MICROCKT, LINEAR: 7 XSTR | 02735 | CA3082-98 |
| A10U175 | 156-1190-00 |  | MICROCKT,LINEAR:7 XSTR | 02735 | CA3082-98 |
| A10U201 | 156-2571-00 |  | MICROCKT, DGTL:HCMOS, ANALOG MUX, TRIPLE | 80009 | 156-2571-00 |
| A10U202 | 156-2571-00 |  | MICROCKT, DGTL: HCMOS, ANALOG MUX, TRIPLE | 80009 | 156-2571-00 |
| A10U203 | 156-2667-00 |  | MICROCKT, LINEAR:QUAD LOW PWR,OPERATIONAL AM PLIFIERS MC3403,14 DIP,MI | 80009 | 156-2667-00 |
| A10U210 | 234-0238-20 |  | QUICK CHIP: VERTICAL PREAMP, PACKAGE IC | 80009 | 234-0238-20 |
| A10U220 | 234-0238-20 |  | QUICK CHIP:VERTICAL PREAMP, PACKAGE IC | 80009 | 234-0238-20 |
| AlOU230 | 234-0238-20 |  | QUICK CHIP:VERTICAL PREAMP, PACKAGE IC | 80009 | 234-0238-20 |
| A10U240 | 234-0238-20 |  | QUICK CHIP:VERTICAL PREAMP, PACKAGE IC | 80009 | 234-0238-20 |
| A10U260 | 156-0067-01 |  | MICROCKT,LINEAR:OPNL AMPL, CHECKED | 04713 | MC1741CP1DS |
| A10U280 | 156-1349-00 |  | MICROCKT,LINEAR:DUAL INDEP DIFF AMPL | 02735 | CA3054-98 |
| A10U301 | 156-2571-00 |  | MICROCKT, DGTL: HCMOS, ANALOG MUX, TRIPLE | 80009 | 156-2571-00 |
| A10U302 | 156-0796-00 |  | MICROCKT, OGTL: 8 STG SHF \& STORE BUS RGTR | 02735 | CD4094BF |
| A10U303 | 156-0796-00 |  | MICROCKT, DGTL:8 STG SHF \& STORE BUS RGTR | 02735 | CD4094BF |
| A10U304 | 156-2873-00 |  | MICROCKT,LINEAR:DUAL BIFET,OPNL AMPL | 80009 | 156-2873-00 |
| A10U307 | 156-0514-00 |  | MICROCKT, DGTL:CMOS, DIFF 4-CHANNEL MUX | 02735 | CD4052BF-98 |
| A10U308 | 156-0514-00 |  | MICROCKT, DGTL:CMOS, DIFF 4-CHANNEL MUX | 02735 | CD4052BF-98 |
| A10U309 | 156-0158-07 |  | MICROCKT, LINEAR:DUAL OPNL AMPL, SCREENED | 01295 | MC1458JG4 |
| A10U310 | 156-0514-00 |  | MICROCKT, DGTL:CMOS,DIFF 4-CHANNEL MUX | 02735 | CD4052BF-98 |
| A10U311 | 156-0514-00 |  | MICROCKT, DGTL:CMOS, DIFF 4-CHANNEL MUX | 02735 | CD4052BF-98 |
| A10U313 | 156-1349-00 |  | MICROCKT,LINEAR:DUAL INDEP DIFF AMPL | 02735 | CA3054-98 |
| A10U315 | 156-1640-00 |  | MICROCKT, OGTL: ECL, TPL LINE RCVR | 04713 | MC1OH116(L OR P) |
| A10U316 | 156-0308-00 |  | MICROCKT, DGTL:ECL, QUAD DIFF LINE RCVR | 04713 | MC10115L OR P |
| A10U421 | 234-0239-20 |  | QUICK CHIP: TRIGGER, IC PACKAGE | 80009 | 234-0239-20 |
| A10U431 | 234-0239-20 |  | QUICK CHIP: TRIGGER, IC PACKAGE | 80009 | 234-0239-20 |
| A10U441 | 156-2027-00 |  | MICROCKT, DGTL:CMOS, HEX INVERTER | 27014 | MM74HCO4N |
| A10U501 | 156-0469-00 |  | MICROCKT,DGTL:3-LINE TO 8-LINE DECODER | 01295 | SN74LS138N |
| A10U502 | 156-0768-01 |  | MICROCKT, DGTL:BIDIRECT UNIV SR, SCREENED | 01295 | SN74LS194ANP3 |
| A10U503 | 156-0804-00 |  | MICROCKT, DGTL:QUADRUPLE S-R LATCH | 04713 | 74LS279(N OR J) |
| A10U506 | 156-0513-00 |  | MICROCKT, DGTL:CMOS, 8-CHANNEL MUX | 04713 | MC14051BCL |
| A10U600 | 156-2655-00 |  | MICROCKT, DGTL:SEMI CUST, STD CELL, SLOW LGC | 80009 | 156-2655-00 |
| A10U601 | 156-1126-00 |  | MICROCKT, LINEAR:VOLTAGE COMPARATOR | 01295 | LM311P |
| A10U602 | 156-2654-00 |  | MICROCKT, DGTL: ECL, SEMI CUSTOM,FAST LOGIC | 80009 | 156-2654-00 |


| Component Mo. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10U603 | 156-0631-00 |  | MICROCKT, DGTL: ECL, QUAD 2 INPUT OR/MOR GATE | 04713 | MC10101(L OR P) |
| A10U604 | 156-0860-00 |  | MICROCKT, DGTL: ECL, TRIPLE LINE RECEIVER | 04713 | MC10116L |
| A10U606 | 156-0140-00 |  | MICROCKT, DGTL:TTL, HEX BUFFER/DRIVER | 01295 | SN7417N |
| A104701 | 155-0322-00 |  | MICROCKT, LINEAR:VERTICAL OUTPUT AMPLIFIER | 80009 | 155-0322-00 |
| A10U702 | 156-1126-00 |  | MICROCKT,LINEAR:VOLTAGE COMPARATOR | 01295 | LM311P |
| A10U801 | 156-0158-07 |  | MICROCKT,LINEAR:DUAL OPNL AMPL,SCREENED | 01295 | MC1458.JG4 |
| A10U802 | 234-0401-21 |  | QUICK CHIP:GPS HORIZ PREAMP | 80009 | 234-0401-21 |
| A104901 | 156-2702-00 |  | MICROCKT,LINEAR:OUAL OP AMP, HIGH OUT CRNT | 80009 | 156-2702-00 |
| A104930 | 156-0158-07 |  | MICROCKT, LINEAR:DUAL OPNL AMPL, SCREENED | 01295 | MC1458.JG4 |
| A10U931 | 156-2605-00 |  | MICROCKT, DGTL:HCMOS, ANALOG MUX, 8 CHANNEL | 80009 | 156-2605-00 |
| A10U932 | 156-1173-00 |  | MICROCKT,LINEAR:VOLTAGE REFERENCE | 04713 | MC1403UDS |
| A10U1001 | 156-0495-00 |  | MICROCKT, LINEAR:OPNL AMPL | 01295 | LM324N |
| A10U1101 | 156-2873-00 |  | MICROCKT,LINEAR:DUAL BIFET, OPNL AMPL | 80009 | 156-2873-00 |
| A10U1102 | 156-1225-00 |  | MICROCKT, LINEAR:DUAL COMPARATOR | 01295 | LM393P |
| A10U1103 | 156-0796-00 |  | MICROCKT,DGTL:8 STG SHF \& STORE BUS RGTR | 02735 | CD4094BF |
| Al0U1104 | 156-0515-00 |  | MICROCKT, DGTL:CMOS, TRIPLE 2-CHAN MLX | 02735 | CD4053BF |
| A10U1106 | 156-0515-00 |  | MICROCKT, DGTL: CMOS, TRIPLE 2-CHAN MLX | 02735 | CD4053BF |
| A10VR301 | 152-0437-00 |  | SEMICOND DVC, DI:ZEN, SI, $8.2 \mathrm{~V}, 2 \%, 0.4 \mathrm{~W}, \mathrm{DO}-7$ | 04713 | SZG14RL |
| A10VR302 | 152-0437-00 |  | SEMICOND DVC, DI: ZEN, SI, 8.2V,2\%, 0.4W, 00-7 | 04713 | SZG14RL |
| A10VR303 | 152-0437-00 |  | SEMICOND DVC, DI: $2 \mathrm{EN}, \mathrm{SI}, 8.2 \mathrm{~V}, 2 \%, 0.4 \mathrm{~W}, \mathrm{DO}-7$ | 04713 | SZG14RL |
| A10VR304 | 152-0437-00 |  | SEMICOND DVC, DI:ZEN, SI, 8. $2 \mathrm{~V}, 2 \%, 0.4 \mathrm{~W}, \mathrm{DO}-7$ | 04713 | SZG14RL |
| A10VR308 | 152-0127-00 |  | SEMICOND DVC, DI:ZEN, SI, 7.5V,5\%, 0.4W, DO-7 | 14433 | 25347 (1N958B) |
| Al0VR309 | 152-0166-00 |  | SEMICOND DVC, DI:ZEN, SI, 6. 2V, 5\%, 400MW, DO-7 | 04713 | SZ11738RL |
| A10VR310 | 152-0166-00 |  | SEMICOND DVC,DI:ZEN, SI, 6.2V,5\%,400NW, DO-7 | 04713 | SZ11738RL |
| A10VR311 | 152-0168-00 |  | SEMICOND DVC, OI :ZEN, SI , 12V, $5 \%, 0.4 \mathrm{~W}$, D0-763B | 14552 | TD331689 |
| A10VR312 | 152-0168-00 |  | SEMICOND DVC, DI :ZEN, SI, 12V,5\%,0,4W, D0-763B | 14552 | T0331689 |
| A10VR801 | 152-0243-00 |  | SEMICOND DVC, DI:ZEN, SI ,15V, 5\%,0.4W, D0-7 | 04713 | SZ13203 (1N965B) |
| A10VR802 | 152-0265-00 |  | SEMICOND DVC, DI :ZEN, SI , 24V, 5\%,0.4W | 14552 | TD3810986 |
| A10VR2701 | 152-0306-00 |  | SEMICOND DVC, DI:ZEN,SI, $9.1 \mathrm{~V}, 5 \%, 0.4 \mathrm{~W}, 00-7$ | 12954 | $1 \mathrm{N960B}$ |
| A10W3 | 175-9903-00 |  | CA ASSY, SP, ELEC:25,27 AWG,6.4 L | 80009 | 175-9903-00 |
| A10w9 | 198-5523-00 |  | WIRE SET, ELEC:SOCKET ASSY CRT | 80009 | 198-5523-00 |
| Al0W17 | 196-3069-00 |  | LEAD, ELECTRICAL:22 AWG,5.0 L,9-N | 80009 | 196-3069-00 |
| A10W18 | 196-3069-00 |  | LEAD, ELECTRICAL:22 AMG,5.0 L,9-N | 80009 | 196-3069-00 |
| A10W19 | 196-3069-00 |  | LEAD, ELECTRICAL:22 AWG, $5.0 \mathrm{~L}, 9-\mathrm{N}$ | 80009 | 196-3069-00 |
| A10W20 | 196-3069-00 |  | LEAD, ELECTRICAL:22 AWG,5.0 L,9-N | 80009 | 196-3069-00 |
| A10W100 | 131-0566-00 |  | BUS, CONDUCTOR:DIMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W101 | 131-0566-00 |  | BUS, CONDUCTOR:DUMY RES $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W102 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| Al0W103 | 131-0566-00 |  | BUS, CONOUCTOR:OUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W200 | 131-0566-00 |  | BUS,CONDUCTOR:DUWY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W201 | 131-0566-00 |  | BUS,CONDUCTOR:DUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W202 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W203 | 131-0566-00 |  | BUS, CONDUCTOR: DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| Al0W205 | 131-0566-00 |  | BUS,CONDUCTOR:DLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW206 | 131-0566-00 |  | BUS,CONDUCTOR:DUMYY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W207 | 131-0566-00 |  | BUS,CONDUCTOR: DLMYY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W208 | 131-0566-00 |  | BUS,CONDUCTOR: DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W209 | 131-0566-00 |  | BUS, CONDUCTOR:DUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W210 | 131-0566-00 |  | BUS,CONDUCTOR: DIMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| AlOW223 | 131-0566-00 |  | BUS,CONDUCTOR:DUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W231 | 131-0566-00 |  | BUS,CONDUCTOR:DLMMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W232 | 131-0566-00 |  | BUS, CONDUCTOR:DUMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA. 07 |
| A10W235 | 131-0566-00 |  | BUS,CONDUCTOR: DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W304 | 131-0566-00 |  | BUS, CONDUCTOR: OUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W305 | 131-0586-00 |  | BUS,CONDUCTOR: DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | ONA 07 |
| AlOW401 | 131-0566-00 |  | BUS, CONDUCTOR: DUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W403 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |


| Component No. | Tektronix Part No. | Serial/Assenbly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10W404 | 131-0566-00 |  | BUS, CONDUCTOR:DIMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W405 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W406 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W407 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W408 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W410 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W411 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W412 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W413 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W414 | 131-0566-00 |  | BUS, CONDUCTOR:OUMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W415 | 174-0733-00 |  | CA ASSY, SP, ELEC:4,26 AWG,4.5 L,RIBBON | 80009 | 174-0733-00 |
| A10W416 | 174-0732-00 |  | CA ASSY, SP, ELEC:4,26 AWG,3.0 L,RIBBON | 80009 | 174-0732-00 |
| A10W505 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W510 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W511 | 174-1041-00 |  | CA ASSY, SP, ELEC:18 COND, 8.5 L,RIBBON | 80009 | 174-1041-00 |
| A10W512 | 174-1039-00 |  | CA ASSY, SP, ELEC:12 COND,11.3 L,RIBBON | 80009 | 174-1039-00 |
| A10W603 | 131-0566-00 |  | BUS, CONDUCTOR:OUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W604 | 131-0566-00 |  | BUS,CONDUCTOR:DIMMY RES 0.094 OD X 0.225 L . | 24546 | OMA 07 |
| A10W605 | 131-0566-00 |  | BUS, CONDUCTOR: DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W610 | 131-0566-00 |  | BUS, CONDUCTOR:DUMNY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| AlOW611 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W612 | 131-0566-00 |  | BUS, CONDUCTOR:DUMYY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W802 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| Al0W805 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W806 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| Al0W807 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W808 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W810 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W811 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W815 | 131-0566-00 |  | BUS,CONDUCTOR:DLMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W906 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| Al0W1000 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1010 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1101 | 131-0566-00 |  | BUS, CONDUCTOR:OLMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W1102 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1103 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W1104 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1105 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1106 | 131-0566-00 |  | BUS, CONDUCTOR:DUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1107 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1120 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1200 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1201 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1202 | 131-0566-00 |  | BUS, CONOUCTOR: DUMMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1204 | 131-0566-00 |  | BUS, CONOUCTOR:DUMYY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1205 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1209 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES 0.094 OD X 0.225 L | 24546 | OMA 07 |
| A10W1210 | 131-0566-00 |  | BUS,CONDUCTOR:DUMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1216 | 131-0566-00 |  | BUS, CONDUCTOR: DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1217 | 131-0566-00 |  | BUS, CONOUCTOR:DUMMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1218 | 131-0566-00 |  | BUS, CONDUCTOR:DUMY RES $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1221 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OHA 07 |
| A10W1222 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1223 | 131-0566-00 |  | BUS, CONDUCTOR:DIMNY RES 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1231 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1237 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1247 | 131-0566-00 |  | BUS,CONDUCTOR:DUMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |


| Camponent No. | Tektronix <br> Part Ho. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A10W1248 | 131-0566-00 |  | BUS, CONDUCTOR: DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1249 | 131-0566-00 |  | BUS, CONDUCTOR:DLMAY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1250 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1251 | 131-0566-00 |  | BUS, CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1252 | 131-0566-00 |  | BUS, CONDUCTOR:DLMMY RES, 0.094 OD $\times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1255 | 131-0566-00 |  | BUS,CONDUCTOR:DLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10W1277 | 131-0566-00 |  | BUS,CONDUCTOR:DUMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| AlOW1288 | 131-0566-00 |  | BUS, CONDUCTOR: DIMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| Al0W2701 | 131-0566-00 |  | BUS, CONDUCTOR: DLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |
| A10Y600 | 119-2051-00 |  | RESONATOR, CER: 10 MHZ | 51406 | CSA 10:00. Mx11 |


| Camponent №. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A12 | 670-9402-01 |  | CIRCUIT BD ASSY:POTENTIOMETER | 80009 | 670-9402-01 |
| A1232105 | 131-3626-00 |  | CONN,RCPT, ELEC:SIP STRIP RCPT 17 POSITION | 00779 | 643649-1 |
| A12R2101 | 311-2343-00 |  | RES, VAR, NONWW:CKT BD,5K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0119 |
| A12R2102 | '311-2345-00 |  | RES, VAR,NONWW:CKT BD 5K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0117 |
| A12R2103 | 311-2343-00 |  | RES, VAR, NONWW:CKT BD, 5K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0119 |
| A12R2104 | 311-2345-00 |  | RES, VAR, NONWW:CKT BD 5 K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0117 |
| A12R2105 | 311-2345-00 |  | RES, VAR,NONWW:CKT BD 5 K OHM, $20 \%$, 0.5W | 32997 | $91 Z 1$ Z245EA0117 |
| A12R2106 | 311-2345-00 |  | RES, VAR, NONWW:CKT BD $5 \mathrm{~K} 0 \mathrm{HM}, 20 \%, 0.5 \mathrm{~W}$ | 32997 | 91Z1A245EA0117 |
| A12R2107 | 311-2343-00 |  | RES, VAR, NONWW:CKT BD, 5 K OHM, $20 \%, 0.5 \mathrm{~W}$ | 32997 | 91Z1AZ45EA0119 |
| A12R2108 | 311-2345-00 |  | RES, VAR,NONWW:CKT BD 5 K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0117 |
| A12R2109 | 311-2345-00 |  | RES, VAR, NONWW:CKT BD $5 \mathrm{~K} 0 \mathrm{MM}, 20 \%, 0.5 \mathrm{~W}$ | 32997 | 91Z1AZ45EA0117 |
| A12R2110 | 311-2345-00 |  | RES, VAR, NONWW:CKT BD 5 K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0117 |
| A12R2111 | 311-2181-00 |  | RES, VAR, NONWW: LINEAR, 5 K OHM, 30\%, 0.25 W | 32997 | 91Z2D-Z45-EA0020 |
| A12R2112 | 311-2345-00 |  | RES,VAR, NONWW:CKT BD 5K OHM, 20\%,0.5W | 32997 | 91Z1AZ45EA0117 |
| A12R2113 | 311-2181-00 |  | RES, VAR, NONWW:LINEAR, $5 \mathrm{~K} \mathrm{OHM}, 30 \%, 0.25 \mathrm{~W}$ | 32997 | 9122D-Z45-EA0020 |



| Companent Ho. | Tektronix Part No . | Serial/Assenbly No. Effective Dscont | Mame \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A16 | 671-0314-00 |  | CIRCUIT BD ASSY:PROCESSOR | 80009 | 671-0314-00 |
| A16B2501 | 146-0055-00 |  | BATTERY, DRY:3.0V, 1200 MAH,LITHIUM | TK0510 | BR-2/3A-E2P |
| A16C2300 | 281-0759-00 |  | CAP, FXD, CER DI:22PF, $10 \%, 100 \mathrm{~V}$ | 04222 | MA101A220KAA |
| A16C2301 | 285-1300-01 |  | CAP, FXD, MTLZD:0.1UF, $10 \%$, 63V | 55112 | 185/0.1/K/63/ABA |
| A16C2302 | 285-1300-01 |  | CAP, FXD,MTLZD:0.1UF, 10\%,63V | 55112 | 185/0.1/K/63/ABA |
| A16C2303 | 285-1300-01 |  | CAP, FXD,MTLZD:0.1UF, $10 \%$, 63V | 55112 | 185/0.1/K/63/ABA |
| A16C2304 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A16C2305 | 285-1300-01 |  | CAP, FXD, MTLZD:0.1UF,10\%,63V | 55112 | 185/0.1/K/63/ABA |
| A16C2306 | 285-1300-01 |  | CAP, FXD, MTLZD:0.1UF, $10 \%$, 63V | 55112 | 185/0.1/K/63/ABA |
| A16C2307 | 285-1301-01 |  | CAP, FXD,MTLZD:0.47UF, 10\%,50V | 55112 | 1850.47K50ABB |
| A16C2308 | 285-1348-00 |  | CAP, FXD,MTLZD: $0.22 \mathrm{UF}, 10 \%$, 63V | TK1573 | ORDER BY DESCR |
| A16C2309 | 285-1301-01 |  | CAP, FXD,MTLZD: $0.47 \mathrm{UF}, 10 \%$, 50 V | 55112 | 1850.47K50ABB |
| A16C2310 | 285-1348-00 |  | CAP, FXD,MTLZ0:0.22UF, 10\%, 63 V | TK1573 | ORDER BY DESCR |
| A16C2311 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2312 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A16C2313 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A16C2314 | 281-0775-01 |  | CAP, FXD, CER DI:0.1UF,20\%,50V | 04222 | SA105E104MAA |
| A16C2315 | 281-0775-01 |  | CAP, FXD, CER DI:0.1UF, $20 \%$, 50V | 04222 | SA105E104MAA |
| A16C2316 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2317 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2318 | 281-0809-00 |  | CAP, FXD,CER DI: $200 \mathrm{PF}, 5 \%, 100 \mathrm{~V}$ | 04222 | MA101A201JAA |
| A16C2319 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2320 | 281-0798-00 |  | CAP, FXD, CER DI:51PF, 1\%,100V | 04222 | MA101A510GAA |
| A16C2321 | 281-0909-00 |  | CAP, FXD, CER DI: 0.022 UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2322 | 281-0798-00 |  | CAP, FXD, CER DI: $51 \mathrm{PF}, 1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A16C2323 | 281-0798-00 |  | CAP, FXD,CER DI:51PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A16C2324 | 285-1300-01 |  | CAP, FXD, MTLZD:0.1UF, $10 \%$, 63V | 55112 | 185/0.1/K/63/ABA |
| A16C2401 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2402 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2403 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2404 | 281-0909-00 |  | CAP, FXD, CER DI: 0.022 UF, $20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| Al6C2405 | 281-0909-00 |  | CAP, FXD,CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A16C2406 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2407 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2408 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2409 | 281-0909-00 |  | CAP, FXD, CER DI :0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2410 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2411 | 281-0809-00 |  | CAP, FXD,CER DI:200 PF,5\%, 100V | 04222 | MA101A201JAA |
| A16C2412 | 281-0809-00 |  | CAP, FXD,CER DI: $200 \mathrm{PF}, 5 \%$, 100V | 04222 | MA101A201JAA |
| A16C2415 | 281-0775-01 |  | CAP, FXD, CER DI: 0.1 UF, $20 \%$, 50 V | 04222 | SA105E104MAA |
| A16C2416 | 281-0798-00 |  | CAP, FXD, CER DI:51PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A16C2417 | 281-0798-00 |  | CAP, FXD, CER DI:51PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A16C2418 | 281-0798-00 |  | CAP, FXD, CER DI: 51 PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MAIO1A5IOGAA |
| A16C2419 | 281-0798-00 |  | CAP, FXD, CER DI: 51 PF, $1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A16C2420 | 281-0798-00 |  | CAP, FXD, CER DI: $51 \mathrm{PF}, 1 \%, 100 \mathrm{~V}$ | 04222 | MA101A510GAA |
| A16C2501 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| Al6C2502 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2503 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A16C2504 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, 20\%,50V | 54583 | MA12X7R1H223M-T |
| A16C2505 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2506 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2507 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2508 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 54583 | MA12X7R1H223M-T |
| A16C2509 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2510 | 281-0909-00 |  | CAP, FXD, CER DI: $0.022 \mathrm{UF}, 20 \%$, 50V | 54583 | MA12X7R1H223M-T |
| A16C2511 | 281-0909-00 |  | CAP, FXD, CER DI:0.022UF, $20 \%$, 50 V | 54583 | MA12X7R1H223M-T |
| A16C2514 | 281-0759-00 |  | CAP, FXD, CER DI: $22 \mathrm{PF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA101A220KAA |
| A16C2515 | 281-0759-00 |  | CAP, FXD, CER DI: $22 \mathrm{PF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA101A22OKAA |



| Camponent No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A16R2316 | 322-3231-00 |  | RES, FXD, FILM:2.49K OHM, 1\%,0.2W, TC $=$ T0 | 57668 | CRB20 FXE 2K49 |
| Al6R2317 | 322-3231-00 |  | RES, FXD, FILM:2.49K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 2 K 49 |
| A16R2318 | 322-3238-00 |  | RES, FXD, FILM:2.94K OHM, 1\%,0.2W, TC=T0 | 57668 | CRB20 FXE 2 K 94 |
| Al6R2319 | '313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2320 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2321 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| A16R2322 | 313-1472-00 |  | RES,FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2323 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2324 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2325 | 307-0499-00 |  | RES, FXD, FILM: $9,100 \mathrm{~K}$ OHM, $5 \%, 0.125 \mathrm{~W}$ | 11236 | 750-101-R100K |
| A16R2326 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2327 | 313-1472-00 |  | RES,FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2328 | 313-1472-00 |  | RES, FXO, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2329 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2330 | 313-1472-00 |  | RES, FXD, FILM 4.4 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2331 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%,0.2W | 57668 | TR20JE 04K7 |
| A16R2332 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%, 0.2W | 57668 | TR20JE22E |
| A16R2333 | 313-1220-00 |  | RES, FXD, FILM:22 OHM, 5\%, 0.2W | 57668 | TR20JE22E |
| A16R2334 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%, 0.2W | 57668 | TR20JE22E |
| A16R2335 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%,0.2W | 57668 | TR20JE22E |
| A16R2336 | 313-1220-00 |  | RES, FXD, FILM:22 OHM, 5\%,0.2W | 57668 | TR20JE22E |
| A16R2337 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR2OJE 04K7 |
| Al6R2338 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%,0.2W | 57668 | TR20JE 04K7 |
| A16R2339 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 04K7 |
| Al6R2340 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE O4K7 |
| Al6R2341 | 313-1472-00 |  | RES,FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE O4K7 |
| Al6R2342 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| Al6R2343 | 313-1472-00 |  | RES,FXD,FILM:4.7K OHM, 5\%,0.2W | 57668 | TR20JE 04K7 |
| A16R2344 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2345 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%$, 0.2 W | 57668 | TR20JE 04K7 |
| Al6R2346 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%,0.2W | 57668 | TR2OJE O4K7 |
| A16R2347 | 313-1472-00 |  | RES, FXD. FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2348 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57688 | TR20JE 04K7 |
| A16R2349 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2350 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| A16R2351 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 04K7 |
| A16R2352 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2353 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| A16R2354 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2355 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%,0.2W | 57668 | TR2OJE01K0 |
| A16R2356 | 313-1102-00 |  | RES, FXD, FILM:1K OHM, 5\%,0.2W | 57668 | TR20JE01K0 |
| A16R2357 | 313-1102-00 |  | RES, FXD, FILM:1K OHM, 5\%,0.2W | 57668 | TR20JE01K0 |
| Al6R2400 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| A16R2401 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| Al6R2402 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%,0.2W | 57668 | TR20JE 04K7 |
| Al6R2404 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2405 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A16R2406 | 322-3220-00 |  | RES, FXD, FILM 1.91 K OHM, 1\%,0.2W, TC= ${ }^{\text {c }}$ | 80009 | 322-3220-00 |
| A16R2407 | 322-3176-00 |  | RES, FXD, FILM: 665 OHM, 1\%, O.2W, TC=T0 | 91637 | CCF50-2 |
| A16R2408 | 322-3172-00 |  | RES, FXD, FILM: 604 OHM, 1\%, 0.2W, TC=TO | 57668 | CRB20 FXE 604E |
| Al6R2409 | 322-3220-00 |  | RES, FXD, FILM 1.91 K OHM, 1\%,0.2W, TC=TO | 80009 | 322-3220-00 |
| Al6R2410 | 322-3172-00 |  | RES, FXD, FILM: $604 \mathrm{OHM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 604E |
| Al6R2411 | 322-3220-00 |  | RES, FXD, FILM $1.1 .91 \mathrm{~K} O H M, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 80009 | 322-3220-00 |
| Al6R2412 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR20JE01K0 |
| A16R2413 | 322-3202-00 |  | RES, FXD, FILM $1.124 \mathrm{~K} O H M, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB2O FXE 1K24 |
| A16R2414 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| Al6R2415 | 322-3202-00 |  | RES, FXD, FILM $1.124 \mathrm{~K} O H M, 1 \%, 0.2 \mathrm{~W}$, TC= 0 | 57668 | CRB20 FXE 1K24 |
| Al6R2416 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%,0.2W | 57668 | TR2OJEOIKO |


| Component Al . | Tektronix Part Mo. | Serial/Assenbly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A16R2417 | 322-3202-00 |  | RES, FXD, FILM $1.1 .24 \mathrm{~K} 0 \mathrm{MM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ T0 | 57668 | CRB20 FXE 1K24 |
| A16R2418 | 322-3077-00 |  | RES, FXD, FILM:61.9 OHM, 1\%,0.2W, TC= $=10$ | 80009 | 322-3077-00 |
| Al6R2419 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100E |
| A16R2420 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0,2W | 57668 | TR20JE100E |
| A16R2421 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 04K7 |
| A16R2501 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A16R2502 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%, 0.2W | 57668 | TR20JE 04K7 |
| Al6R2503 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, 5\%, 0.2 W | 57668 | TR20JE 620E |
| Al6R2504 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, 5\%,0.2W | 57668 | TR20JE 04K7 |
| Al6R2505 | 313-1621-00 |  | RES, FXD,FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 620E |
| A16R2506 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM,5\%, 0.2 W | 57668 | TR20JE 620E |
| Al6R2508 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| Al6R2509 | 313-1102-00 |  | RES, FXD, FILM: IK OHM $, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01KO |
| Al6R2510 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01K0 |
| Al6R2511 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0. 2 W | 57668 | TR20JE01K0 |
| Al6R2512 | 313-1472-00 |  | RES, FXD, FILM:4.7K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| A16R2513 | 313-1472-00 |  | RES, FXD, FILM: 4.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 04K7 |
| Al6R2514 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| Al6R2515 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, 5\%, 0.2 W | 57668 | TR20JE 620E |
| Al6R2516 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, 5\%,0.2W | 57668 | TR20JE 620E |
| A16R2517 | 313-1621-00 |  | RES, FXD, FILM: $620 \mathrm{OHM}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A16R2518 | 313-1102-00 |  | RES, FXD, FILM: IK OHM, 5\%, 0.2W | 57668 | TR2OJE01K0 |
| Al6R2519 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A16R2520 | 307-0499-00 |  | RES, FXD, FILM: $9,100 \mathrm{~K}$ OHM, $5 \%, 0.125 \mathrm{~W}$ | 11236 | 750-101-R100K |
| Al6R2521 | 307-0499-00 |  | REs, FXD, FILM: $9,100 \mathrm{~K}$ OHM, $5 \%, 0.125 \mathrm{~W}$ | 11236 | 750-101-R100K |
| A16R2522 | 307-0499-00 |  | RES, FXD, FILM: $9,100 \mathrm{~K}$ OHM, $5 \%, 0.125 \mathrm{~W}$ | 11236 | 750-101-R100K |
| A16R2523 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| A16R2524 | 313-1102-00 |  | RES, FXD, FILM:1K OHM,5\%,0.2W | 57668 | TR2OJEO1K0 |
| A16R2526 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A16R2527 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, 5\%,0.2W | 57668 | TR20JE 620E |
| A16R2528 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 620E |
| A16R2529 | 313-1621-00 |  | RES, FXD, FILM: 620 OHM, 5\%, 0.2W | 57668 | TR20JE 620E |
| A16R2531 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01K0 |
| Al6R2532 | 313-1102-00 |  | RES, FXD, FILM:1K OHM, 5\%,0.2W | 57668 | TR20JE01K0 |
| A16R2533 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%,0.2W | 57668 | TR20JE01K0 |
| A16R2534 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR20JE01K0 |
| A16R2535 | 313-1102-00 |  | RES, FXD, FILM:1K OHM, 5\%, 0.2W | 57668 | TR20JE01K0 |
| A16R2536 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01KO |
| Al6R2537 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| A16R2538 | 313-1102-00 |  | RES, FXD, FILM: IK OHM, 5\%,0.2W | 57668 | TR2OJEOIKO |
| A16R2539 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE01K0 |
| A16R2540 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJE01K0 |
| Al6R2541 | 313-1102-00 |  | RES, FXD, FILM $1 \mathrm{1K}$ OHM, 5\%, 0.2W | 57668 | TR2OJEO1K0 |
| Al6R2542 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| Al6R2546 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%,0.2W | 57668 | TR20JE22E |
| A16R2547 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE22E |
| A16R2548 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%,0.2W | 57668 | TR20JE22E |
| A16R2549 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%, 0.2W | 57668 | TR2OJE22E |
| Al6R2550 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%,0.2W | 57668 | TR20JE22E |
| Al6R2551 | 313-1220-00 |  | RES, FXD, FILM: 22 OHN, 5\%, 0.2W | 57668 | TR2OJE22E |
| A16R2552 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%, 0.2W | 57668 | TR2OJE22E |
| A16R2553 | 313-1220-00 |  | RES, FXD, FILM: 22 OHM, 5\%,0.2W | 57668 | TR2OJE22E |
| A16R2554 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJEOIKO |
| A16R2555 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR2OJE100E |
| A16R2560 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A16R2561 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2 W | 57668 | TR20JE100E |
| A16R2562 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR2OJE100E |
| A16R2563 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM,5\%,0.2W | 57668 | TR20JE100E |


| Component No. | Tektronix Part No. | Serial/Assembly Mo. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A16R2564 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE100E |
| Al6U2300 | 156-1646-00 |  | MICROCKT,DGTL:CMOS,OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2301 | 156-1646-00 |  | MICROCKT,DGTL:CMOS,OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2302 | 156-1589-00 |  | MICROCKT, LINEAR:D/A CONVERTER,HIGH SPEED | 06665 | DAC312FR |
| A16U2303 | 156-0513-00 |  | MICROCKT, DGTL:CMOS, 8-CHANNEL MUX | 04713 | MC14051BCL |
| A16U2304 | 156-1200-00 |  | MICROCKT,LINEAR:OPERATIONAL AMP,QUAD BI-FET | 01295 | TL074CN |
| A16U2305 | 156-1200-00 |  | MICROCKT, LINEAR:OPERATIONAL AMP, QUAD BI-FET | 01295 | TL074CN |
| A16U2306 | 156-1126-00 |  | MICROCKT,LINEAR:VOLTAGE COMPARATOR | 01295 | LM311P |
| A16U2307 | 156-1646-00 |  | MICROCKT,DGTL:CMOS,OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2308 | 156-0513-00 |  | MICROCKT, DGTL:CMOS,8-CHANNEL MUX | 04713 | MC14051BCL |
| A16U2309 | 156-0513-00 |  | MICROCKT, DGTL:CMOS, 8-CHANNEL MUX | 04713 | MC14051BCL |
| A16U2310 | 156-0515-00 |  | MICROCKT, DGTL: CMOS, TRIPLE 2-CHAN MLX | 02735 | CD4053BF |
| A16U2311 | 156-0515-00 |  | MICROCKT, DGTL:CMOS, TRIPLE 2-CHAN MLX | 02735 | CD4053BF |
| A16U2312 | 156-0515-00 |  | MICROCKT, DGTL:CMOS, TRIPLE 2-CHAN MLX | 02735 | CD4053BF |
| A16U2313 | 156-1646-00 |  | MICROCKT, DGTL:CMOS,OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2314 | 156-1149-00 |  | MICROCKT, LINEAR:OPERATIONAL AMP, JFET INPUT | 27014 | LF351N/GLEA134 |
| A16U2400 | 160-3493-00 |  | MICROCKT, DGTL: 8 BIT MICROCOMPUTER, MASKED | 80009 | 160-3493-00 |
| Al6U2401 | 156-1646-00 |  | MICROCKT, DGTL:CMOS, OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2402 | 156-1646-00 |  | MICROCKT, DGTL:CMOS, OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| Al6U2403 | 156-1646-00 |  | MICROCKT, DGTL :CMOS, OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2404 | 156-0412-00 |  | MICROCKT, DGTL:SYN 4-BIT UP/DN CNTR, DUAL CLK | 80009 | 156-0412-00 |
| A16U2405 | 156-0412-00 |  | MICROCKT, DGTL:SYN 4-BIT UP/DN CNTR,DUAL CLK | 80009 | 156-0412-00 |
| A16U2406 | 156-1594-00 |  | MICROCKT, DGTL:NMOS, $2048 \times 8$ SRAM | TK1015 | HM6116P-3(DP-24) |
| A16U2407 | 156-1172-00 |  | MICROCKT, DGTL:DUAL 4 BIT BIN CNTR | 01295 | SN74LS393N |
| A16U2408 | 160-5391-00 |  | MICROCKT, DGTL:NMOS, $4098 \times 8$ EPROM, PRGM | 80009 | 160-5391-00 |
| Al6U2409 | 156-1172-00 |  | MICROCKT, DGTL:DUAL 4 BIT BIN CNTR | 01295 | SN74LS393N |
| A16U2410 | 160-4085-00 |  | ,MICROCKT, OGTL:OCT 16 INP REG AND/OR | TK2051 | 156-0442-00 |
| Al6U2411 | 156-1646-00 |  | MICROCKT, DGTL:CMOS, OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2412 | 156-1255-00 |  | MICROCKT,LINEAR:D/A CONVERTER,8 BIT | 06665 | DAC08-1570 |
| A16U2413 | 156-1255-00 |  | MICROCKT,LINEAR:D/A CONVERTER, 8 BIT | 06665 | DAC08-1570 |
| A16U2414 | 156-0514-00 |  | MICROCKT, DGTL:CMOS, DIFF 4-CHANNEL MUX | 02735 | CD4052BF-98 |
| A16U2415 | 156-0514-00 |  | MICROCKT, DGTL: CMOS, DIFF 4-CHANNEL MUX | 02735 | CD4052BF-98 |
| A16U2416 | 156-1200-00 |  | MICROCKT,LINEAR:OPERATIONAL AMP,QUAD BI-FET | 01235 | TL074CN |
| Al6U2417 | 156-0382-00 |  | MICROCKT,DGTL:QUAD 2-INP NAND GATE | 01295 | SN74LSOO(N OR J) |
| A16U2501 | 156-2003-01 |  | MICROCKT, DGTL:MOS,MICROPRC, 8 BIT, 8 MHZ | 34649 | C80188PC |
| A16U2503 | 156-0479-00 |  | MICROCKT, DGTL:QUAD 2-INP OR GATE | 01295 | SN74LS32 (N OR J) |
| A16U2506 | 156-0382-00 |  | MICROCKT, DGTL : QUAD 2-INP NAND GATE | 01295 | SN74LSOO(N OR J) |
| A16U2512 | 156-1065-01 |  | MICROCKT, DGTL:OCTAL D TYPE TRANS LATCHES | 04713 | SN74LS373 ND/JD |
| A16U2513 | 156-1065-01 |  | MICROCKT, DGTL:OCTAL D TYPE TRANS LATCHES | 04713 | SN74LS373 ND/JD |
| A16U2514 | 156-1111-00 |  | MICROCKT, DGTL:OCTAL BUS TRANSCEIVERS | 01295 | SN74LS245N |
| A16U2515 | 156-1111-00 |  | MICROCKT, DGTL:OCTAL BUS TRANSCEIVERS | 01295 | SN74LS245N |
| A16U2517 | 156-0469-00 |  | MICROCKT, DGTL:3-LINE TO 8-LINE DECODER | 01295 | SN74LS138N |
| A16U2518 | 156-0469-00 |  | MICROCKT, DGTL:3-LINE TO 8-LINE DECOOER | 01295 | SN74LS138N |
| A16U2519 | 160-5063-00 |  | MICROCKT, DGTL:131072 X 8 BIT, UN-EPROM, 250NS | 80009 | 160-5063-00 |
| A16U2521 | 156-2473-00 |  | MICROCKT, DGTL: $8192 \times 8$ CMOS, SRAM | TK0961 | UPD4464C-20 |
| A16U2523 | 156-1646-00 |  | MICROCKT,DGTL:CMOS,OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2524 | 156-1646-00 |  | MICROCKT, DGTL:CMOS,OCTAL D-TYPE EDGE TRIG | TK0273 | MD74HCT374RE |
| A16U2525 | 156-1058-00 |  | MICROCKT, DGTL:STTL, OCTAL SCHMITT TRIGGER | 01295 | SN74S240] |
| A16W2303 | 174-1040-00 |  | CA ASSY, SP, ELEC:17 COND,5.1 L,RIBBON | 80009 | 174-1040-00 |
| A16XU2400 | 136-0755-00 |  | SKT,PL-IN ELEK:MICROCIRCUIT, 28 DIP | 09922 | DILB28P-108 |
| A16XU2501 | 136-0813-00 |  | SKT, PL-IN ELEK:CHIP CARRIER, 68 CONTACTS | 19613 | 268-5400-00-1102 |
| A16XU2519 | 136-0963-00 |  | SKT,PL-IN ELEK:MICROCKT, 32 PIN | 80009 | 136-0963-00 |
| A16Y2501 | 119-2936-00 |  | RESONATOR:1OMHZ,CER | 80009 | 119-2936-00 |


| Component No. | Tektronix Part 10. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part Mo. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A18 | 670-9398-03 |  | CIRCUIT BD ASSY:LV POWER SUPPLY,A18 | 80009 | 670-9398-03 |
| A18C2201 | 285-1177-01 |  | CAP, FXD, PLASTIC:1UF, $10 \%$, 450 V | 80009 | 285-1177-01 |
| A18C2202 | 290-1118-00 |  | CAP, FXD, ELCTLT:220UF,20\%,400V | TK1424 | CEFTW2G221B |
| A18C2203 | 290-0922-01 |  | CAP, FXD, ELCTLT : 1000UF, 4100\% -10\%, 50V | 56289 | 674D108H050JJ5A |
| A18C2204 | 290-1151-00 |  | CAP, FXD, ELCTLT: 100UF, $20 \%$, 63 V | 55680 | VEB1J101MRA |
| A18C2206 | 281-0775-01 |  | CAP, FXD, CER DI: $0.1 \mathrm{UF}, 20 \%, 50 \mathrm{~V}$ | 04222 | SA105E104MAA |
| A18C2207 | 281-0775-01 |  | CAP, FXD, CER DI:0.1UF,20\%,50V | 04222 | SA105E104MAA |
| A18C2208 | 290-1144-00 |  | CAP, FXD, ELCTLT:4.7UF, $20 \%$, 100V | 80009 | 290-1144-00 |
| A18C2209 | 281-0773-00 |  | CAP, FXD, CER DI: $0.01 \mathrm{UF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA201C103KAA |
| A18C2210 | 290-1144-00 |  | CAP, FXD, ELCTLT:4.7UF, $20 \%$, 100V | 80009 | 290-1144-00 |
| A18C2211 | 281-0773-00 |  | CAP, FXD, CER DI:0.01UF, $10 \%, 100 \mathrm{~V}$ | 04222 | MA201C103KAA |
| A18C2212 | 281-0761-00 |  | CAP, FXD,CER DI:27PF, 5\%,100V | 04222 | MA101A270JAA |
| A18C2213 | 285-1381-00 |  | CAP, FXD,MTLZD: $1500 \mathrm{PF}, 10 \%$, 250 V | TK0515 | PME271Y415 |
| A18C2214 | 285-1381-00 |  | CAP, FXD.MTLZD: 1500PF, 10\%, 250V | TK0515 | PME271 Y415 |
| A18C2215 | 285-1252-00 |  | CAP, FXD, PLASTIC: $0.15 \mathrm{JF}, 10 \%$, 250VAC | 05243 | F1772-415-2000 |
| A18C2216 | 285-1252-00 |  | CAP, FXD, PLASTIC:0.15UF, 10\%, 250VAC | 05243 | F1772-415-2000 |
| A18C2217 | 285-1381-00 |  | CAP, FXD, MTLZD:1500PF, $10 \%$, 250V | TK0515 | PME271Y415 |
| A18C2218 | 281-0813-00 |  | CAP, FXD, CER DI:0.047UF, $20 \%$, 50 V | 05397 | C412C473M5V2CA |
| A18C2219 | 281-0773-00 |  | CAP, FXD, CER DI: 0.01 UF, $10 \%, 100 \mathrm{~V}$ | 04222 | MA201C103KAA |
| A18C2221 | 290-1129-00 |  | CAP, FXD, ELCTLT:1000UF, +100\%-10\%, 12V | 56289 | ORDER BY DESCR |
| A18C2222 | 290-1129-00 |  | CAP, FXD, ELCTLT: 1000 UF, $+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2223 | 290-1129-00 |  | CAP, FXD, ELCTLT: 1000UF, $+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2224 | 290-1129-00 |  | CAP, FXD, ELCTLT: $10000 \mathrm{~F},+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2225 | 290-1129-00 |  | CAP, FXD, ELCTLT: $1000 \mathrm{UF},+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2226 | 290-1129-00 |  | CAP, FXD, ELCTLT: 1000 UF, $+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2227 | 290-1129-00 |  | CAP, FXD, ELCTLT: $1000 \mathrm{UF},+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2228 | 290-1129-00 |  | CAP, FXD, ELCTLT: 1000 UF, $+100 \%-10 \%, 12 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2229 | 290-1128-00 |  | CAP, FXD, ELCTLT: 470UF, $+100 \%$, 25V | 56289 | ORDER BY DESCR |
| A18C2230 | 290-1128-00 |  | CAP, FXD, ELCTLT: $470 \mathrm{UF},+100 \%$, 25V | 56289 | ORDER BY DESCR |
| A18C2232 | 290-1130-00 |  | CAP, FXD, ELCTLT : $39 \mathrm{UF},+100 \%-10 \%, 150 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2233 | 290-1130-00 |  | CAP, FXD, ELCTLT: 39 UF, $+100 \%-10 \%, 150 \mathrm{~V}$ | 56289 | ORDER BY DESCR |
| A18C2234 | 290-1128-00 |  | CAP, FXD, ELCTLT: 470 UF,+100\%, 25V | 56289 | ORDER BY DESCR |
| A18C2236 | 290-1128-00 |  | CAP, FXD, ELCTLT: 470 UF, $+100 \%$, 25 V | 56289 | ORDER BY DESCR |
| Al8C2238 | 290-1144-00 |  | CAP, FXD, ELCTLT:4.7UF, $20 \%$, 100V | 80009 | 290-1144-00 |
| A18C2239 | 281-0775-01 |  | CAP, FXD, CER DI:0.1UF, $20 \%$, 50 V | 04222 | SA105E104MAA |
| A18C2243 | 281-0770-00 |  | CAP, FXD, CER DI: $1000 \mathrm{PF}, 20 \%, 100 \mathrm{~V}$ | 04222 | MA101C102MAA |
| A18C2244 | 285-1184-01 |  | CAP, FXD,MTLZD:0.01UF, $20 \%$, 4KV | 56289 | 430P103×040 |
| A18C2245 | 285-1184-01 |  | CAP, FXD,MTLZD:0.01UF,20\%,4KV | 56289 | 430P103×040 |
| A18C2248 | 290-1151-00 |  | CAP, FXD, ELCTLT: $1000 \mathrm{UF}, 20 \%$, 23 V | 55680 | VEBIJ101MRA |
| A18C2249 | 281-0773-00 |  | CAP, FXD, CER DI: $0.01 \mathrm{UF}, 10 \%, 100 \mathrm{~V}$ | 04222 | MA201C103KAA |
| A18CR2201 | 152-0661-01 |  | SEMICOND DVC, DI:RECT, SI, 600V,3A | 04713 | S.R.3523-1RL |
| A18CR2202 | 152-0400-00 |  | SEMICOND DVC, DI :RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2204 | 152-0400-00 |  | SEMICOND DVC, DI: RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2205 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2206 | 152-0582-00 |  | SEMICOND DVC, DI: RECT, SI, 20V,3A | 80009 | 152-0582-00 |
| A18CR2207 | 152-0582-00 |  | SEMICOND DVC, DI:RECT, SI, 20V,3A | 80009 | 152-0582-00 |
| A18CR2208 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2209 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2210 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2211 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2212 | 152-0400-00 |  | SEMICOND DVC, DI: RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2213 | 152-0400-00 |  | SEMICOND DVC, DI :RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2214 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2215 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2216 | 152-0400-00 |  | SEMICOND DVC, DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2218 | 152-0400-00 |  | SEMICOND DVC, DI:RECT,SI, 400V,1A | 04713 | SR1977K |
| A18CR2219 | 152-0581-00 |  | SEMICOND DVC, DI:RECT,SI, 20V,1A,A59 | 04713 | 1N5817 |
| A18CR2220 | 152-0581-00 |  | SEMICOND DVC, DI:RECT,SI,20V,1A,A59 | 04713 | 1 N5817 |


| Component No. | Tektronix <br> Part No . | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part Mo. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A18CR2227 | 152-0400-00 |  | SEMICOND DVC,DI:RECT, SI, 400V,1A | 04713 | SR1977K |
| A18CR2228 | 152-0400-00 |  | SEMICOND DVC,DI:RECT,SI,400V,1A | 04713 | SR1977K |
| A18CR2231 | 152-0040-00 |  | SEMICOND DVC,DI:RECT,SI,600V,1A, D0-41 | 80009 | 152-0040-00 |
| A18CR2232 | -152-0040-00 |  | SEMICOND DVC, DI :RECT, SI, 600V, 1A, D0-41 | 80009 | 152-0040-00 |
| A18CR2233 | 152-0040-00 |  | SEMICOND DVC, DI :RECT, SI, 600V, 1A, D0-41 | 80009 | 152-0040-00 |
| A18CR2234 | 152-0040-00 |  | SEMICOND DVC,DI:RECT,SI,600V,1A,D0-41 | 80009 | 152-0040-00 |
| A18CR2235 | 152-0400-00 |  | SEMICOND DVC, DI :RECT, SI , 400V, 1 A | 04713 | SR1977K |
| A18CR2236 | 152-0400-00 |  | SEMICOND DVC, DI:RECT,SI, 400V,1A | 04713 | SR1977K |
| A18CR2237 | 152-0141-02 |  | SEMICOND DVC, DI:SW, SI, 30V,150MA, 30V, 00-35 | 03508 | DA2527 (1N4152) |
| A18DS2201 | 150-0035-00 |  | LAMP, GLOW:90V MAX, 0.3 MA, AID-T,WIRE LD | TK0213 | JH005/3011JA |
| Al8J2208 | 131-3645-00 |  | CONN, RCPT, ELEC:3 POSITION, 0.01 SPACING | 80009 | 131-3645-00 |
| A18J2225 | 131-3486-00 |  | CONN, RCPT, ELEC:HEADER,RTANG, 2 POS, 0.1 SP | 00779 | 640452-2 |
| A18L2201 | 108-1324-00 |  | COIL, RF: FXD, 33UH, POWER | 54583 | OL1338-330K5RO |
| A18L2202 | 108-1319-00 |  | INDUCTOR, FIXED:33UH, 10\%, 1.8A | 54583 | TSL1110-330K 1R8 |
| A18L2203 | 108-1319-00 |  | INDUCTOR, FIXED: $33 \mathrm{UH}, 10 \%, 1.8 \mathrm{~A}$ | 54583 | TSL1110-330K 1R8 |
| A18L2204 | 108-1319-00 |  | INDUCTOR, FIXED: $33 \mathrm{UH}, 10 \%, 1.8 \mathrm{~A}$ | 54583 | TSL1110-330K 1R8 |
| A18L2205 | 108-1319-00 |  | INDUCTOR, FIXED: $33 \mathrm{UH}, 10 \%, 1.8 \mathrm{~A}$ | 54583 | TSL1110-330K 1R8 |
| A18L2206 | 108-1396-00 |  | INDUCTOR, FIXED: 150UH, 0.82A | TK2058 | TSL1110-151KR82 |
| A18L2207 | 108-1357-00 |  | COIL, RF: FXD, POWER | TK1441 | 86-343-2 |
| A18L2208 | 108-1357-00 |  | COIL, RF: FXD, POWER | TK1441 | 86-343-2 |
| A18P2204 | 131-3637-00 |  | CONN,RCPT, ELEC:HEADER, 13 CIRCUIT, 0.156 SP | 80009 | 131-3637-00 |
| A18Q2201 | 151-1214-00 |  | TRANSISTOR:MOSFET, SI, TO-220 | 80009 | 151-1214-00 |
| A18Q2202 | 151-0190-00 |  | TRANSISTOR:NPN, SI, TO-92 | 80009 | 151-0190-00 |
| A18Q2203 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A18Q2204 | 151-0190-00 |  | TRANSISTOR: NPN, SI, T0-92 | 80009 | 151-0190-00 |
| A18Q2206 | 151-0565-00 |  | THYRISTOR, SCR: 8A, 200V, SENS GATE, T0-220 | 80009 | 151-0565-00 |
| A18Q2208 | 151-0190-00 |  | TRANSISTOR:NPN, SI, T0-92 | 80009 | 151-0190-00 |
| A18Q2209 | 151-0852-00 |  | TRANSISTOR: | 80009 | 151-0852-00 |
| A18Q2210 | 151-0852-00 |  | TRANSISTOR: | 80009 | 151-0852-00 |
| A18Q2211 | 151-0188-00 |  | TRANSISTOR: PNP, SI, T0-92 | 80009 | 151-0188-00 |
| A18Q2212 | 151-0276-01 |  | TRANSISTOR: PNP, SI , T0-92 | TK1016 | S1423-TPE2 |
| A18Q2213 | 151-0276-01 |  | TRANSISTOR:PNP, SI, T0-92 | TK1016 | S1423-TPE2 |
| A1802214 | 151-1197-00 |  | TRANSISTOR:FET, MOS PWR,N-CHAN,TO-220 | 04713 | IRF533WLEADFORM |
| Al8R2201 | 308-0678-00 |  | RES, FXD, WW:0.1 OHM , $5 \%, 2 \mathrm{~W}$ | 75042 | BWH-R1000] |
| Al8R2203 | 301-0184-00 |  | RES, FXD, FILM: 180K OHM, 5\%,0.5W | 57668 | TR50J-E180K |
| A18R2204 | 301-0184-00 |  | RES, FXD, FILM: 180K OHM, $5 \%, 0.5 \mathrm{~W}$ | 57668 | TR50J-E180K |
| A18R2205 | 313-1104-00 |  | RES, FXD, FILM: 100 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| A18R2206 | 313-1104-00 |  | RES, FXD, FILM: 100 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| Al8R2207 | 322-3164-00 |  | RES, FXD, FILM: 499 OHM, 1\%, 0.2W, TC= T0 | 57668 | CRB20 FXE 499E |
| A18R2208 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| Al8R2209 | 313-1104-00 |  | RES, FXD, FILM: 100 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| A18R2210 | 313-1513-00 |  | RES, FXD, CMPSN: 51 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 51K |
| A18R2211 | 313-1332-00 |  | RES, FXD, FILM:3.3K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR2OJE 03K3 |
| A18R2212 | 313-1822-00 |  | RES, FXD, FILM:8.2K, OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 08K2 |
| A18R2215 | 313-1272-00 |  | RES, FXD, FILM: 2.7 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 02K7 |
| A18R2216 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| A18R2218 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJE01K0 |
| A18R2219 | 313-1105-00 |  | RES, FXD, FILM: 1 M OHMM, 5\%,0.2W | 57668 | TR20JE1M |
| A18R2220 | 313-1105-00 |  | RES, FXD, FILM: 1 M OHM, 5\%, 0.2W | 57668 | TR2OJE1M |
| A18R2221 | 313-1203-00 |  | RES, FXD, FILM: 20 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE20K |
| A18R2222 | 313-1103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A18R2223 | 313-1105-00 |  | RES, FXD, FILM:1M OHM , 5\%,0.2W | 57668 | TR20JE1M |
| A18R2224 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100E |
| A18R2225 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, 5\%, 0.2W | 57668 | TR20JE100E |
| A18R2226 | 301-0274-00 |  | RES, FXD, FILM: 270 K OHM, $5 \%, 0.5 \mathrm{~W}$ | 19701 | 5053CX270K0J |
| A18R2227 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| A18R2228 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE01K0 |
| A18R2229 | 301-0823-00 |  | RES, FXD, FILM: 82 K OHM, $5 \%, 0.5 \mathrm{~W}$ | 19701 | 5053CX82K00J |


| Componerit No. | Tektronix <br> Part No. | Serial/Assenbly No. Effective Dscont | Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Al8R2230 | 301-0823-00 |  | RES, FXD, FILM: 82 K OHM, $5 \%, 0.5 \mathrm{~W}$ | 19701 | $5053 \mathrm{CX82K00J}$ |
| A18R2231 | 315-0101-03 |  | RES, FXD, CMPSN: 100 OHM, 5\%, 0.25W | 01121 | CB1015 |
| A18R2232 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0.2W | 57668 | TR2OJEOIKO |
| Al8R2233 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A18R2236 | 313-1104-00 |  | RES, FXD, FILM: $100 \mathrm{~K} 0 H \mathrm{M}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100K |
| A18R2237 | 313-1105-00 |  | RES, FXD, FILM: 1 M OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JEIM |
| Al8R2238 | 313-1753-00 |  | RES, FXD, FILM: 75 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 75K |
| Al8R2239 | 313-1103-00 |  | RES, FXD, FILM: 10K OHM,5\%,0.2W | 57668 | TR20JE10K0 |
| A18R2240 | 313-1204-00 |  | RES,FXD, FILM:200K, 5\%, 0.2 W | 57668 | TR20JE 200K |
| Al8R2241 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR20JE10K0 |
| Al8R2242 | 313-1027-00 |  | RES, FXD, FILM:2.7 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 02E7 |
| A18R2243 | 313-1027-00 |  | RES, FXD, FILM:2.7 OHM, 5\%, 0.2W | 57668 | TR20JE 02E7 |
| A18R2245 | 313-1103-00 |  | RES, FXD, FILM, 10K OHM, 5\%, 0.2W | 57668 | TR2OJE10K0 |
| Al8R2246 | 313-1513-00 |  | RES, FXD, CMPSN: 51 K OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 51K |
| Al8R2247 | 322-3289-00 |  | RES, FXD, FILM: $10 \mathrm{~K} 0 \mathrm{HM}, 1 \%, 0.2 \mathrm{~W}, \mathrm{TC}=$ TO | 57668 | CRB20 FXE 10K0 |
| Al8R2248 | 313-1513-00 |  | RES, FXD, CMPSN:51K OHM, 5\%, 0.2 W | 57668 | TR20JE 51K |
| Al8R2250 | 301-0106-00 |  | RES, FXD, FILM: 10 M OHM, $5 \%, 0.50 \mathrm{~W}$ | 01121 | EB1065 |
| A18R2252 | 311-2270-00 |  | RES, VAR, NONWW: TRMR, 10K OHM, 20\%, 0.5W | TK1450 | GFO6VT 10 K OHM |
| Al8R2253 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE100E |
| Al8R2254 | 313-1051-00 |  | RES, FXD, FILM: 5.1 OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JT68 05E1 |
| Al8R2255 | 313-1051-00 |  | RES, FXD, FILM:5.1 OHM, 5\%, 0.2W | 57668 | TR20JT68 05E1 |
| Al8R2256 | 301-0274-00 |  | RES, FXD, FILM:270K OHM, $5 \%, 0.5 \mathrm{~W}$ | 19701 | 5053CX270K0J |
| Al8R2257 | 301-0200-00 |  | RES, FXD, FILM: 20 OHM, 5\%, 0.5W | 19701 | 5053CX20R00J |
| Al8R2259 | 315-0472-03 |  | RES, FXD, CMPSN: 4.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 01121 | CB4725 |
| A18R2260 | 301-0560-00 |  | RES, FXD, FILM: 56 OHM, 5\%, 0.5W | 19701 | 5053CX56R00J |
| Al8R2265 | 313-1101-00 |  | RES, FXD, FILM: 100 OHM,5\%,0.2W | 57668 | TR20JE100E |
| Al8R2666 | 315-0472-03 |  | RES, FXD, CMPSN: 4.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 01121 | CB4725 |
| A18R2267 | 307-0113-00 |  | RES, FXD, CMPSN:5.1 OHM,5\%,0.25W | 01121 | CB51G5 |
| A18R2268 | 313-1103-00 |  | RES, FXD, FILM: $10 \mathrm{~K} 0 \mathrm{MM}, 5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE10K0 |
| A18R2270 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR20JE10K0 |
| Al8R2271 | 313-1512-00 |  | RES, FXD, FILM 5.1 IK OHM, $5 \%, 0.2 \mathrm{~W}$ | 57668 | TR20JE 5K1 |
| Al8R2272 | 313-1051-00 |  | RES, FXD, FILM:5.1 OHM, 5\%, 0.2W | 57668 | TR20JT68 05E1 |
| A18R2273 | 313-1051-00 |  | RES, FXD, FILM:5.1 OHM, 5\%,0.2W | 57668 | TR20.JT68 05E1 |
| A18R2274 | 313-1103-00 |  | RES, FXD, FILM:10K OHM, 5\%, 0.2W | 57668 | TR20JE10K0 |
| A18R2275 | 301-0432-00 |  | RES, FXD, FILM: 4.3 K OHM, $5 \%, 0.5 \mathrm{~W}$ | 19701 | 5053CX4K300J |
| A18R2276 | 313-1102-00 |  | RES, FXD, FILM: 1 K OHM, 5\%, 0. 2 W | 57668 | TR2OJE01K0 |
| A18RT2201 | 307-0863-00 |  | RES, THERMAL: 10 O-M, 10\%, NTC | 15454 | SG-13S |
| A18S2201 | 260-2309-00 |  | SWITCH, PUSH:DPST, 4A, 250VAC | 31918 | NE15CT112A |
| A18S2202 | 260-2318-00 |  | SWITCH, THRMSTC: MC, 105 DEG C OP, 80 DEG CL | 80009 | 260-2318-00 |
| A18T2203 | 120-1686-00 |  | TRANSFORMER,RF:COUPLED INDUCTOR | 80009 | 120-1686-00 |
| A18T2204 | 120-1685-00 |  | XFMR, PUR, STU:HIGH VOLTAGE | 80009 | 120-1685-00 |
| A18T2205 | 120-1347-00 |  | TRANSFORMER,RF:DRIVER SATURATING | 54583 | BDT-001 |
| A18T2206 | 120-1401-00 |  | XFMR, TRIGGER:LINE, 1:1 TURNS RATIO | 54937 | DMI 500-2044 |
| Al8U2201 | 156-2395-00 |  | MICROCKT,LINEAR:BIPOLAR, PWM PWR SPLY,CONT | 01295 | MC34060N |
| A18U2230 | 152-0926-00 |  | SEMICOND DVC, DI: | 80009 | 152-0926-00 |
| Al8VR2201 | 152-0255-00 |  | SEMICOND DVC, DI :ZEN, SI, 51V,5\%,0.4W, D0-7 | 04713 | SZG35009K7 |
| A18VR2202 | 152-0166-00 |  | SEMICOND DVC, DI :ZEN, SI, 6. $2 \mathrm{~V}, 5 \%, 400 \mathrm{MN}$, D0-7 | 04713 | SZ11738RL |
| Al8VR2203 | 152-0304-00 |  | SEMICOND DVC, DI:ZEN, SI, 20V, 5\%,0.4W, D0-7 | 15238 | Z5411 |
| Al8VR2204 | 307-0456-00 |  | RES,V SENSITIVE:250VAC, 20W,METAL OXIDE | 03508 | MOV-V250LA15A |
| A18VR2205 | 152-0166-00 |  | SEMICOND DVC, DI :ZEN, SI , 6. $2 \mathrm{~V}, 5 \%, 400 \mathrm{MN}$, D0-7 | 04713 | SZ11738RL |
| Al8VR2206 | 152-0282-00 |  | SEMICOND DVC, DI :ZEN, SI, 30V, $2 \%, 400 \mathrm{MW}$ | 04713 | SZG35009K13 |
| Al8VR2207 | 152-0304-00 |  | SEMICOND DVC, DI :ZEN,SI, 20V, 5\%,0,4W, D0-7 | 15238 | 25411 |
| A18W28 | 196-3093-00 |  | LEAD, ELECTRICAL: 18 AWG, 3.3 L, 8-9 | 80009 | 196-3093-00 |
| A18W29 | 196-3092-00 |  | LEAD, ELECTRICAL:18 AWG,3.3 L, 8-0 | 80009 | 196-3092-00 |
| A18W31 | 196-3094-00 |  | LEAD, ELECTRICAL:26 AWG, $2.6 \mathrm{~L}, 9-\mathrm{N}$ | 80009 | 196-3094-00 |
| A18W32 | 196-3094-00 |  | LEAD, ELECTRICAL:26 AWG, $2.6 \mathrm{~L}, 9-\mathrm{N}$ | 80009 | 196-3094-00 |
| Al8W2201 | 131-0566-00 |  | BUS, CONDUCTOR:OLMMY RES, $0.09400 \times 0.225 \mathrm{~L}$ | 24546 | OMA 07 |


| Companent No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| B25 | 119-2063-00 |  | FAN, TUBEAXIAL:12V,130MA,19.4 CFM | 61529 | A1F891003 |
| DL21 | 119-2118-01 |  | DELAY LINE, ELEC: | 80009 | 119-2118-01 |
| F2201 | 159-0023-00 |  | FUSE, CARTRIDGE:3AG,2A, 250V,SLOW BLOW | 71400 | MDX2 |
| FL2201 | 119-2055-00 |  | FILTER,RFI:3A, 115-230V,48-440HZ | 05245 | 3EF1F |
| J16 | 131-0955-00 |  | CONN, RCPT, ELEC: BNC, FEMALE | 13511 | 31-279 |
| V1 | 154-0905-00 |  | ELECTRON TUBE:CRT | 80009 | 154-0905-00 |
| W30 | 195-3990-00 |  | LEAD, ELECTRICAL:18 AWG,4.5 L, 5-4 | 80009 | 195-3990-00 |

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# DIAGRAMS AND CIRCUIT BOARD ILLUSTRATIONS 

## Symbols

Graphic symbols and class designation letters are based on ANSI Standard Y32.2-1975.

Logic symbology is based on ANSI/IEEE 91-1984. Logic symbols depict the logic function performed and may differ from the manufacturer's data.

The overline on a signal name indicates that the signal performs its intended function when it is in the LO state.

Abbreviations are based on ANSI Y1.1-1972.

Other ANSI standards that are used in the preparation of diagrams by Tektronix, Inc., are:

Y14.15-1966
Y14.2M-1979 ANSIIEEE 280 Line Conventions and Lettering Letter Symbols for Quantities Used in Electrical Science and Electrical Engineering.

American National Standards Institute 1430 Broadway New York, New York 10018

## Component Values

Electrical components shown on the diagrams are in the following units unless noted otherwise:

| Capacitors | Values one or greater are in picofarads $(\mathrm{pF})$. <br>  <br> Resistors |
| :--- | :--- |
| Values less than one are in microfarads $(\mu \mathrm{F})$. |  |
| Ohms $(\Omega)$. |  |

## The information and special symbols below may appear in this manual.

## Assembly Numbers and Grid Coordinates

Each assembly in the instrument is assigned an assembly number (e.g., A20). The assembly number appears on the circuit board outline on the diagram, in the title for the circuit board component location illustration, and in the lookup table for the schematic diagram and corresponding component locator illustration. The Replaceable Electrical Parts list is arranged by assemblies in numerical sequence; the components are listed by component number *(see following illustration for constructing a component number).

The schematic diagram and circuit board component location illustration have grids. A lookup table with the grid coordinates is provided for ease of locating the component. Only the components illustrated on the facing diagram are listed in the lookup table. When more than one schematic diagram is used to illustrate the circuitry on a circuit board, the circuit board illustration may only appear opposite the first diagram on which it was illustrated; the lookup table will list the diagram number of other diagrams that the circuitry of the circuit board appears on.


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| COLOR | SIGNIFICANT FIGURES | RESISTORS |  |
| :---: | :---: | :---: | :---: |
|  |  | MULTIPLIER | tolerance |
| BLACK | 0 | 1 | --- |
| BROWN | 1 | 10 | $\pm 1 \%$ |
| RED | 2 | $10^{2}$ or 100 | $\pm 2 \%$ |
| Orange | 3 | $10^{3}$ or 1 K | $\pm 3 \%$ |
| Yellow | 4 | $10^{4}$ or 10 K | $\pm 4 \%$ |
| Green | 5 | $10^{5}$ or 100 K | $\pm 1 / 2 \%$ |
| blue | 6 | $10^{6}$ or 1 M | 112\% |
| VIolet | 7 | --- | $\pm 1 / 10 \%$ |
| GRAY | 8 | --- | --- |
| WHITE | 9 | --- | ---- |
| GOLD | - | $10^{-1}$ or 0.1 | $\pm 5 \%$ |
| SILVER | - | $10^{-2}$ or 0.01 | $\pm 10 \%$ |
| NONE | - | --- | $\pm 20 \%$ |






Figure 9-4b. Detailed block diagram-part 2.

Table 9-1
SIGNAL LINE LOCATIONS

| SIGNAL NAME | ORIGINATES ${ }^{\text {a }}$ <br> DIAG/CIR\#(VIA) | GOES TO <br> DIAG/CIR\#(VIA) |
| :---: | :---: | :---: |
| A Gate | 4/U603-11 | 5/VR302 |
| A GATE | 4/U603-14 | 5/VR301 |
| $\overline{\text { A GATE T }}$ | 4/Q604 | 9/U2410-9 |
| A INTEN | 11/U2312-14(R2357) | 7/U1001-12 |
| A INTEN GATE | 4/U602-17 | 7/Q1001 |
| A RAMP | 5/Q312,Q328 | 6/U802-3 |
| A SLOPE | 4/U600-30 | 3/U421-8(R493) |
| A SWP END | 5/U316-15(R378) | 4/U602-8 |
| A TRIG | 3/U421-10(R411) | 4/U602-7 |
| A TRIG LVL | 11/U2304-8 | 3/U421-24(R448) |
| AD COMP | 11/U2306-7 | 8/U2515-12(R2511) |
| ADDRO | 8/U2512-15(R2560) | 4/U501-1, U602-38(R619), U600-4 |
| ADDR1 | 8/U2512-6(R2561) | 4/U501-2,U602-39(R618) , U600-5 |
| ADDR2 | 8/U2512-16(R2562) | 4/U501-3, U600-6 |
| ADDR3 | 8/U2512-5(R2563) | 4/U502-10,U600-7 |
| ATS 0 | 4/U600-31 | 3/U421-13(R490) |
| ATS 1 | 4/U600-32 | 3/U421-12(R491) |
| ATS 2 | 4/U600-33 | 3/U421-9 (R492) |
| AUX DATA | 5/U303-9 | 3/U1103-2(R1162) |
| B DELTA TRIG LVL | 11/U2305-1 | 3/U1106-5 |
| B GATE | 4/U603-9 | 5/VR304 |
| B GATE | 4/U603-15 | 5/VR303 |
| B INTEN | 11/U2312-4(R2356) | 7/U1001-5 |
| B INTEN GATE | 4/U602-18 | 7/Q1004 |
| B RAMP | 5/Q325, Q329 | 6/U802-5 |
| B REF TRIG LVL | 11/U2304-7 | 3/U1106-3 |
| B SLOPE | 4/U600-26 | 3/U431-8(R497) |
| B SWP END | 5/U316-2 (R380) | 4/U602-37 |
| B TRIG | 3/U431-10(R415) | 4/U602-34(DL22+) |
| $\overline{\text { B TRIG }}$ | 3/U431-11 (R416) | 4/DL22- |
| BEAM FIND | 4/U503-7 | 7/Q2706(R2705);2/U701-21;6/U802-14 |
| BTS 0 | 4/U600-27 | 3/U431-13 (R494) |
| BTS 1 | 4/U600-28 | 3/U431-12(R495) |
| BTS 2 | 4/U600-29 | 3/U431-9(R496) |
| BW LIMIT | 3/U1103-11 | 4/U502-4;2/U701-22;3/U441-11, U441-13 |
| CH 1 EN | 4/U600-39 | 2/U210-11(R213) |
| CH 1 POS | 11/U2310-14(R2354) | 2/U203-3 |
| CH 1 PRB | 1/R105 | 7/U506-15 |
| CH 1 PREAMP 0 | 1/U172-4 | 2/U210-1 (CR201) |
| CH 1 PREAMP 1 | 1/U171-11 | 2/U210-2 (CR202) |
| CH 1 PREAMP $\mathrm{IN}^{+}$ | 1/U112-8 | 2/U210-7 |
| CH 1 TR + | 2/U210-20 | 3/U421-7,U431-7 |
| CH 1 VAR | 11/U2309-13(R2350) | 2/U210-10(R225) |
| CH 2 EN | 4/U600-38 | 2/U220-11 (R223) |
| CH 2 INVERT | 1/U173-6 | 2/U220-12 |
| CH 2 POS | 11/U2310-4(R2353) | 2/U203-5 |

Table 9-1 (cont)

| SIGNAL NAME | ORIGINATES ${ }^{\text {a }}$ DIAG/CIR\#(VIA) | GOES TO <br> DIAG/CIR\#(VIA) |
| :---: | :---: | :---: |
| CH 2 PRB | 1/R106, C121 | 7/U506-12 |
| CH 2 PREAMP 0 | 1/U173-5 | 2/U220-1 |
| CH 2 PREAMP 1 | 1/U173-4 | 2/U220-2 |
| CH 2 PREAMP $\mathrm{IN}^{+}$ | 1/U122-8 | 2/U220-7 |
| CH 2 TR + | 2/U220-20 | 3/U421-5,U431-5 |
| CH 2 VAR | 11/U2309-5 (R2351) | 2/U220-10(R227) |
| CH 3 EN | 4/U600-37 | 2/U230-11(R233) |
| CH 3 POS | 11/U2311-4(R2327) | 2/U203-10 |
| CH 3 PRB | 1/R107,C131 | 7/U506-1 |
| CH 3 PREAMP 1 | 1/U173-7 | 2/U230-2 |
| CH 3 PREAMP $\mathrm{IN}^{+}$ | 1/Q131A(R139), Q131B(R139) | 2/U230-7 |
| CH 3 TR + | 2/U230-20 | 3/U421-3, U431-3 |
| CH 4 EN | 4/U600-36 | 2/U240-11(R243) |
| CH 4 POS | 11/U2310-15(R2326) | 2/U203-12 |
| CH 4 PRB | 1/R108,C151 | 7/U506-5 |
| CH 4 PREAMP 1 | 1/U173-14 | 2/U240-2 |
| CH 4 PREAMP IN + | 1/Q151A(R159),Q151B(R159) | 2/U240-7 |
| CH 4 TR + | 2/U240-20 | 3/U421-1, U431-1 |
| CLK 1K | 7/U930-7(R933,R934) | 4/U600-2 |
| CLK 4M | 9/U2417-3 | 11/J2601-16 |
| CLK 8M | 8/U2501-56 | 9/U2409-1 |
| DAC INTR | 11/R2310 | 8/U2515-16(R2554) |
| $\overline{\text { DAC LSB CLK }}$ | 8/U2517-15 | 11/U2301-11 |
| $\overline{\text { DAC MSB CLK }}$ | 8/U2517-14 | 11/U2300-11 |
| DATA BUS | 8/U2514 | 9/U2401,U2402;10/U2523, U2524; <br> 11/U2300, U2301, U2307, U2313 |
| DELTA CURSOR | 11/U2304-1 | 9/U2414-2,U2415-2 |
| DELTA DELAY | 11/U2305-7 | 5/U301-12(R330), U313-6(R330) |
| DIG HORIZ POS | 11/U2305-14 | 6/U301-3(R369) ;2/U702-3(R722) |
| DLY END 0 | 5/U315-15(R388) | 4/U602-36 |
| DLY END 1 | 5/U315-2 (R387) | 4/U602-35 |
| DLY SEL | 4/U600-25 | 5/U301-11;3/U1106-9 |
| FLIC WR | 8/U2518-11 | 4/U602-40(R647) |
| HDO | 4/U600-24 | 6/U802-8 |
| HD1 | 4/U600-23 | 6/U802-11 |
| HOLDOFF | 11/U2308-5(R2343) | 4/Q600(R636) |
| + HORIZONTAL OUTPUT | 5/Q805(R819), Q806(R819) | 7/V1-R |
| - HORIZONTAL OUTPUT | 5/Q801 (R802), Q802 (R802) | 7/V1-L |
| IZ INTEN GATE | 4/U602-19 | 7/Q1003 |
| LED ANODE CLK | 8/U2501-27 | 10/U2523-11 (R2528) |
| LED CATH CLK | 8/U2501-25 | 10/U2524-11(R2529) |
| LINE TRIG | 12/T2206 | 3/U1106-2 |
| MAG | 3/U1103-6 | 6/U802-6 |
| MAIN BD MUX | 7/U506-3(R503) | 11/U2309-12 (R2352) |
| MB CNTL WR | 8/U2518-15(R2564) | 4/U501-4 |
| MB DATA | 8/U2515-11 (R2555) | 4/U600-9,U602-12,U502-2 |
| MB RETURN | 4/U502-12 | 8/U2515-14(R2509) |
| POT5 | 11/U2313-5 | 7/U506-11(R508) |
| POT6 | 11/U2313-19 | 7/U506-10(R510) |
| POT7 | 11/U2313-2 | 7/U506-9(R512) |


| SIGNAL NAME | ORIGINATES ${ }^{\text {a }}$ <br> DIAG/CIR\#(VIA) | GOES TO DIAG/CIR\#(VIA) |
| :---: | :---: | :---: |
| CH 2 PRB | 1/R106,C121 | 7/U506-12 |
| CH 2 PREAMP 0 | 1/U173-5 | 2/U220-1 |
| CH 2 PREAMP 1 | 1/U173-4 | 2/U220-2 |
| CH 2 PREAMP $\mathbb{N}+$ | 1/U122-8 | 2/U220-7 |
| CH 2 TR + | 2/U220-20 | 3/U421-5,U431-5 |
| CH 2 VAR | 11/U2309-5 (R2351) | 2/U220-10(R227) |
| CH 3 EN | 4/U600-37 | 2/U230-11(R233) |
| CH 3 POS | 11/U2311-4(R2327) | 2/U203-10 |
| CH 3 PRB | 1/R107,C131 | 7/U506-1 |
| CH 3 PREAMP 1 | 1/U173-7 | 2/U230-2 |
| CH 3 PREAMP $\mathrm{IN}^{+}$ | 1/Q131A(R139), Q131B(R139) | 2/U230-7 |
| CH 3 TR + | 2/U230-20 | 3/U421-3, U431-3 |
| CH 4 EN | 4/U600-36 | 2/U240-11(R243) |
| CH 4 POS | 11/U2310-15(R2326) | 2/U203-12 |
| CH 4 PRB | 1/R108,C151 | 7/U506-5 |
| CH 4 PREAMP 1 | 1/U173-14 | 2 U240-2 |
| CH 4 PREAMP IN + | 1/Q151A(R159), Q151B(R159) | 2/U240-7 |
| CH 4 TR + | 2/U240-20 | 3/U421-1, U431-1 |
| CLK 1K | 7/U930-7(R933,R934) | 4/U600-2 |
| CLK 4M | 9/U2417-3 | 11/J2601-16 |
| CLK 8M | 8/U2501-56 | 9/U2409-1 |
| DAC INTR | 11/R2310 | 8/U2515-16(R2554) |
| $\overline{\text { DAC LSB CLK }}$ | 8/U2517-15 | 11/U2301-11 |
| $\overline{\text { DAC MSB CLK }}$ | 8/U2517-14 | 11/U2300-11 |
| DATA BUS | 8/U2514 | 9/U2401,U2402; 10/U2523,U2524; <br> 11/U2300, U2301, U2307, U2313 |
| DELTA CURSOR | 11/U2304-1 | 9/U2414-2,U2415-2 |
| DELTA DELAY | 11/U2305-7 | 5/U301-12(R330), U313-6(R330) |
| DIG HORIZ POS | 11/U2305-14 | 6/U301-3 (R369);2/U702-3 (R722) |
| DLY END 0 | 5/U315-15(R388) | 4/U602-36 |
| DLY END 1 | 5/U315-2 (R387) | 4/U602-35 |
| DLY SEL | 4/U600-25 | 5/U301-11;3/U1106-9 |
| FLIC WR | 8/U2518-11 | 4/U602-40 (R647) |
| HDO | 4/U600-24 | 6/U802-8 |
| HD1 | 4/U600-23 | 6/U802-11 |
| HOLDOFF | 11/U2308-5 (R2343) | 4/Q600 (R636) |
| + HORIZONTAL OUTPUT | 5/Q805(R819), Q806(R819) | 7/V1-R |
| - HORIZONTAL OUTPUT | 5/Q801 (R802), Q802 (R802) | 7/V1-L |
| Z INTEN GATE | 4/U602-19 | 7/Q1003 |
| LED ANODE CLK | 8/U2501-27 | 10/U2523-11 (R2528) |
| LED CATH CLK | 8/U2501-25 | 10/U2524-11 (R2529) |
| LINE TRIG | 12/T2206 | 3/U1106-2 |
| MAG | 3/U1103-6 | 6/U802-6 |
| MAIN BD MUX | 7/U506-3(R503) | 11/U2309-12 (R2352) |
| MB CNTL WR | 8/U2518-15(R2564) | 4/U501-4 |
| MB DATA | 8/U2515-11(R2555) | 4/U600-9, U602-12,U502-2 |
| MB RETURN | 4/U502-12 | 8/U2515-14(R2509) |
| POT5 | 11/U2313-5 | 7/U506-11(R508) |
| POT6 | 11/U2313-19 | 7/U506-10(R510) |
| POT7 | 11/U2313-2 | 7/U506-9(R512) |


| SIGNAL NAME | ORIGINATES ${ }^{\text {a }}$ <br> DIAG/CIR\# (VIA) | GOES TO DIAG/CIR\#(VIA) |
| :---: | :---: | :---: |
| POT MUX CLK | 8/U2517-13 | 11/U2313-11 |
| REF CURSOR | 11/U2304-14 | 9/U2414-5,U2415-5 |
| REF DELAY | 11/U2305-8 | 5/U301-13(R329) |
| RO BLANK | 9/U2410-16(R2419) | 4/U600-12 |
| RO BUF RD | 8/U2501-29(R2515) | 9/U2402-1 |
| RO BUF WR | 8/U2501-28(R2516) | 9/U2417-9,U2401-11 |
| RO CH 1 POS EN | 9/U2403-19 | 2/U202-10 |
| ROCH2 POS EN | 9/U2403-2 | 2/U202-11 |
| RO CH 3 POS EN | 9/U2403-5 | 2/U201-9 |
| RO CH 4 POS EN | 9/U2403-6 | 2/U201-10 |
| RO FREEZE | 1/U173-11 | 4/U502-5,U503-3 |
| RO HORIZ | 9/U2416-8 | 6/U802-1 |
| RO INTEN | 11/U2312-15(R2355) | 7/U1001-10 |
| RO INTEN GATE | 4/U602-20 | 7/Q1002 |
| RO INTR | 9/U2417-11 | 8/U2515-15(R2508) |
| RO REQ | 9/U2410-14(R2420) | 4/U503-2, U600-11 |
| RO TR SEP EN | 9/U2403-9 | 2/U201-11 |
| RO VERT | 9/U2416-14 | 2/U202-4(R207,R205) |
| RO VERT EN | 4/U503-4 | 2/U202-9(R215) |
| SLIC RD | 8/U2503-8 | 4/U600-8 |
| SLIC WR | 8/U2518-12 | 4/U600-3 |
| SNAP CLK | 8/U2517-12 | 11/U2307-11 |
| SRO CLK | 4/U606-12 | 1/U171-3,U172-3,Q171,U173-3(R176) |
| SR1 CLK | 4/U606-4 | 5/U302-3, U303-3 |
| SR1 CLK TTL | 4/U501-13 | 3/U1103-3 |
| SR DATA | 4/U606-6 | 1/Q171B,U171-2;5/U302-2 |
| SW BD DATA | 10/U2002-9 | 8/U2515-16(R2510) |
| SW BD SR LOAD | 8/U2518-14 | 10/U2001-1, U2002-1 |
| SW BD SR SHIFT | 8/U2518-13 | 10/U2001-2,U2002-2 |
| SYS RESET | 8/U2506-8 | 9/U2400-28 |
| TB CAL | 8/U2501-22 | 3/U1106-1 (R1170) |
| time Var | 11/U2308-12(R2344) | 5/U309-5(R309, CR301) |
| TRACE SEP | 11/U2311-15(R2323) | 2/U801-5 |
| TRACE SEP EN | 4/U600-22 | 2/U201-11(R209) |
| $\overline{\text { TRIG CLK }}$ | 4/U600-19 | 3/U421-2(R498) |
| VERT COMP | 2/U702-7 | 4/U502-6 |
| VERT COMP EN | 3/U1103-7 | 2/Q703 |
| + VERTICAL OUTPUT | 2/Q701 (R731) | 7/V1-TOP |
| - VERtical output | 2/Q702(R732) | 7/V1-BOT |
| VOLT CAL | 7/U931-3 | 1/R114,R124 |
| VOLT CAL 0 | 5/U303-11 | 7/U931-11(R924) |
| VOLT CAL 1 | 5/U303-12 | 7/U931-10(R923) |
| VOLT CAL 2 | 5/U303-13 | 7/U931-9 (R922) |
| $\overline{X Y}$ | 3/U1103-12 | 6/U301-9 |
| X AXIS | 3/U421-19 (R426,L426) | 6/U802-7 (R836,R827) |
| ZERO HYST | 1/U173-13 | 3/Q480(R484) |

[^10]


Figure 9-5. A10-Main board.

WAVEFORMS FOR DIAGRAM 1


Figure s-6. Hybric pin identafiers.






## WAVEFORMS FOR DIAGRAM 4




SET SEC/DIV TO $20 ;$ s. WAVEFORM VARIES WITH SETTING OF TRIGGER






HORIZ MODE ALT, A SEC/DI $2 \mu \mathrm{~s}$,







## 2245A Service



Figure 9-7. A8-CRT Control board.
(x) $\begin{gathered}\text { Static Sensitive Devices } \\ \text { See Manitenance Section }\end{gathered}$


|  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| A8-CRT CONTROL BOARD |  |  |  |  |  |  |




## WAVEFORMS FOR DIAGRAM 7




## 2245A Service







MORE $\quad$ ?


## Figure 9-9. A14-Switch board.



| A1s-SWITCH BOARD |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| cracur numers | SCHEM | cincut | scarem | Gincut Number | SCMEM |
| C2009 | 14 | DS2293 | : | 52045 | 10 |
| 0 CROOT | 10 | OS2034 | \% | \$22016 | 10 |
| CR2022 | 10 | ${ }^{252035}$ | :0 | S2018 | :0 |
| ${ }_{\substack{\text { CR2033 } \\ C R 2004}}$ | 10 | 532037 | 10 | \$2009 | 10 |
| ${ }_{\substack{\text { che } \\ C R 20025}}$ | 10 | - 5820388 | 10 | \$2020 | 10 |
| CR2006 | 10 | DS204: | :0 | \$2022 | 10 |
|  |  | ${ }^{\text {OS2042 }}$ | 10 | \$2224 | $: 0$ |
| Oss200\% | 0 | -052043 | 10 | \$2025 \$2288 | \% |
| -52003 | : 0 | Os2045 | 10 | \$2230 | $: 0$ |
| DS2004 | :0 | ${ }^{525046}$ | 10 | S2034 | :0 |
| OS2205 DS2006 | :0 |  | 10 | S2033 S2034 | :0 |
| ${ }^{\text {OSP2007 }}$ | : | 5S2048 |  | S2035 | $: 0$ |
| ${ }^{252008}$ | 0 | P250\% | 0 | \$2236 | 10 |
| OS52008 SS200 | :10 | P2509 | 14 | \$2037 $\$ 2038$ | 10 |
| DS201\% | : | R200\% | 10 | \$2039 | 10 |
| 052012 052013 | 0 | R2002 | 10 | S2040 s 204 | 10 |
| OS2014 | 10 | \$2001 | 10 | \$2042 | 10 |
| DS2005 | $:$ | 52002 S2030 | 10 | S2043 | 10 |
| - 5232020 | 4 | S2003 | 10 | S2045 S2046 | 10 |
| 0s2022 | 10 | \$2005 | 10 | S2064 | 10 |
| ${ }^{2528223}$ | $: 0$ | S2006 | 10 | 52043 | 10 |
| ${ }_{\text {DS32225 }}$ | 10 | \$22008 | \% | U200: | 10 |
| ${ }^{\text {os2227 }}$ | 10 | \$2009 | 10 | U2007 | 14 |
| OS2223 OS2228 | 10 | S2010 52041 | 10 | 4 | 10 |
| ${ }^{\text {OS2230 }}$ | 10 | S2042 | \% | 0202 |  |
| OS2233\% SS232 | 10 | S2013 52014 | \% | W2509 | 10 |
| 25232 | 10 | \$2004 | :0 | W2509 |  |





Figure 9-10. A12-Potentiometer board.
(3) ${ }^{\text {Static Sensitive Devices }}$



|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A12-POT BOARD |  |  |  |  |  |

## WAVEFORMS FOR DIAGRAM 11




Figure 9-11. A18—Power Supply board.


more $\$


## WAVEFORMS FOR DIAGRAM 12 (cont)







## VOLTAGE/WAVEFORM SETUP CONDITIONS

## WAVEFORMS

Test waveforms are shown on a page just before the schematic diagram to which they apply. Normal control settings for the test oscilloscope are given in the readouts shown in each waveform illustration. Unless otherwise indicated near the waveform, setup conditions for the oscilloscope under test are as follows:

1. Set up the 2245A front-panel controls as follows:

VERTICAL MODE

CH 1 COUPLING
CH 1 VOLTSIDIV
VERTICAL POSITION Controls
SCOPE BW
HORIZONTAL MODE
A/B SELECT
SEC/DIV
Trigger LEVEL
HOLDOFF
SLOPE
Trigger MODE
Trigger SOURCE
Trigger COUPLING
MEASUREMENTS
A INTEN
READOUT
FOCUS

SCALE ILLUM

CH 1 (other channels off) DC
0.1 V 12 o'clock
On
A
A
0.1 ms

12 o'clock
MIN (CCW)
-
AUTO LEVEL VERT
DC
OFF
10 o'clock
12 o'clock
For well defined display
Fully CCW
2. Connect the front-panel PROBE ADJUST output to the Channel 1 input connector.
3. For all waveforms, except those obtained from the Low-Voltage Power Supply, connect the test oscilloscope probe ground wire to the chassis. When obtaining waveforms from the power supply, first connect the power cord of the

2245A under test through an isolation transformer, then connect probe ground wire to ground " $P$ "' (rear side of R2256). See Figure $9-11$ to locate ground " $P$ ".


#### Abstract

WARNING

To avoid electric shock and instrument damage, always connect the power cord of the instrument under test through an isolation transformer when viewing waveforms or measuring voltages in the Low-Voltage Power Supply.


## DC VOLTAGES

Dc voltages shown on the schematic diagrams are typical of a normally operating instrument. Voltages are referenced to chassis ground, except in the isolated portion of the Low-Voltage Power Supply where they are referenced to ground ' $P$ "' (at R2256 as shown in Figure 9-11). Make sure that the DMM leads are floating (isolated from chassis ground) when measuring voltages in this section.

## TEST EQUIPMENT

The following test equipment is recommended for obtaining waveforms and voltages from the 2245A Oscilloscope. Other similar equipment types can also be used.

1. Test Oscilloscope with 10X probe(s)TEKTRONIX 2246A.
2. Digital Voltmeter-TEKTRONIX DM 501A.
3. Power-Line Isolation Transformer-Tektronix Part No. 006-5953-00.

## OTHER PARTS

| CIRCUIT NUMBER | SCHEM NUMBER | SCHEM <br> LOCATION | CIRCUIT <br> NUMBER | SCHEM <br> NUMBER | SCHEM <br> LOCATION | CIRCUIT NUMBER | SCHEM <br> NUMBER | SCHEM <br> LOCATION |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| B25 | 12 | 6 N | P25 | 12 | 6 N | \$2202 | 12 | 3E |
| FL201 | 12 | 2 A | P27 | 7 | ${ }_{2 L}^{1 L}$ | V1 | 7 | 1M |
| J16 | 7 | 7A |  |  |  |  |  |  |

VERTICAL INPUTS DIAGRAM 1

| ASSEMBLY A10 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | SCHEM LOCATION | BOARD <br> LOCATION | CIRCUIT <br> NUMBER | SCHEM LOCATION | BOARD LOCATION | CIRCUIT <br> NUMBER | SCHEM <br> LOCATION | BOARD <br> LOCATION |
| AT117 | 1 J | 6B | J11 | 1A | 6 A | R132 | 6 H | 2A |
| AT127 | 3H | 4B | J12 | 4A | 4A | R133 | 6 H | 2 A |
|  |  |  | $J 13$ | 7 A | 3A | R134 | 7H | 2A |
| C1 | 1 K | 6C | $J 14$ | 8A | 1 A | R135 | 7 J | 2B |
| C2 | 4K | 4C |  |  |  | R136 | 7K | 2C |
| C10 | 2 H | 68 | K100 | $1 F$ | 6A | R137 | 7K | 2 C |
| C11 | 2.1 | 6 B | K101 | 1G | 5A | R139 | 7L | 2C |
| C20 | 4H | 48 | K102 | 1G | 5B | R141 | 7 J | 2B |
| C21 | 5」 | 4B | K103 | 1H | 6B | R142 | 7 J | 2B |
| C101 | 1 B | 6 A | K104 | 2 L | 5D | R151 | 8A | 2A |
| $\mathrm{C102}$ | 3B | 4A | K105 | 2K | 5 D | R152 | 8 H | 1 A |
| C103 | 7 B | 3A | K107 | 4F | 4 A | R153 | 8 H | 1 A |
| C104 | 8B | 1 A | K108 | 4G | 4A | R154 | 8 H | 1 A |
| $\mathrm{C105}$ | 1F | 6A | K109 | 4G | 4B | R155 | 8 J | 1B |
| C106 | 2G | 5A | K110 | 4 H | 5B | R156 | 8K | 1 C |
| C 107 | 4F | 5A | K111 | 5L | 4D | R157 | 8K | 1 C |
| C108 | 5G | 4A | K112 | 5K | 4D | R159 | 8L | 1 C |
| C111 | 18 | 9 C |  |  |  | R161 | 8 J | 18 |
| C112 | 1 F | 6A | L130 | 7 L | 2 C | R162 | 8 J | 1 B |
| C113 | 1F | 5A | L140 | 8L | 1 C | R171 | 5B | 3B |
| C114 | 2 J | 5 C |  |  |  | R175 | 5B | 3B |
| C121 | 3B | 10 C | 0131A | 7K | 2B | R176 | 6C | 3C |
| C122 | 4 F | 4A | Q131B | 7. | 2B | R177 | 6 C | 2C |
| C123 | 4F | 3A | Q151A | 8K | 1 B | R178 | 6E | 2 C |
| C124 | 4.3 | 4 C | Q151B | 8 J | 1 B | R179 | 6E | 3C |
| C125 | 4B | 1 C | 0171 | 5 C | 2 B | R180 | 6 J | 2 B |
| C126 | 7 F | 10 |  |  |  | R181 | 8 J | 1B |
| C131 | 7 B | 10 B | R12 | 2K | 6C |  |  |  |
| C132 | 7H | 2 A | R13 | 2K | 6C | U112 | 1 L | 6C |
| C133 | 7J | 2A | R22 | 4K | 4 C | U122 | 4 L | 4 C |
| C134 | 75 | 2B | R23 | 4K | 4 C | U171 | 4 C | 3B |
| C137 | 71 | 2 C | R101 | 1 B | 6A | U172 | 5 D | 3B |
| C138 | 7K | 2 C | $\mathrm{R102}$ | 38 | 7 A | U173 | 6 E | 3 C |
| C151 | 8 B | 10 C | R103 | 7 B | 7A | U174 | 1E | 3A |
| C152 | 8 H | 1 A | R104 | 7 B | 7 A | - U175 | $4 E$ | 3C |
| C153 | 8 J | 1 A | R105 | 1 B | 7 A |  |  |  |
| C154 | 8.1 | 1 B | R106 | 38 | 7A | W11 | 1 B | 6 A |
| C157 | 8L | 1 C | R107 | 7 B | 7 B | W12 | 3A | 4A |
| C158 | 8K | 1 C | R108 | 8B | 78 | W13 | 7 A | 3 A |
| C173 | 5 C | 3 B | R111 | 1A | 6A | W14 | 7A | 1 A |
| C190 | 7 L | 2 C | R113 | 1G | 5A | W100 | 4F | 5 C |
| C191 | 8 L | 1 C | R114 | 1 F | 5 A | W101 | 5 G | 5 C |
|  |  |  | R121 | 3A | 4A | W102 | 5 G | 3B |
| CR131 | 6 H | 2 B | R123 | 3G | 3A |  |  |  |
| CR151 | 8 H | 1B | R124 | 3 F | 3A |  |  |  |
| CR171 | 5B | 3B | R131 | 7 A | 2 A |  |  |  |
| Partial A10 also shown on diagrams 2, 3, 4, 5, 6, 7 and 13. |  |  |  |  |  |  |  |  |

VERTICAL PREAMPS AND OUTPUT AMPLIFIER DIAGRAM 2

| ASSEMBLY A10 |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIACUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | $\begin{gathered} \text { SCHEM } \\ \text { LOCATION } \end{gathered}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT <br> NUMBER | SCHEM LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| C139 | 4 C | 2 C | 0251 | 4G | 4F | R250C | $5 E$ | 5 E | R711 | 3L | 9 J |
| C159 | 5C | 1 C | 0252 | 3.1 | $4 E$ | R2500 | 3 E | 5 E | R712 | 4L | 10.1 |
| C201 | 7 C | 4G | 0253 | 4. | 4F | R250E | 2E | 5 E | R715 | 1L | 10K |
| C202 | 7 C | 4G | 0284 | 6 F | $5 E$ | R250F | 1E | 5 E | R716 | 2L | 9K |
| C 203 | 7 C | 4 H | Q285 | 6 F | 5 E | R250G | 5 F | 5 E | R717 | 2M | 9 K |
| C204 | 8 C | 5 H | Q701 | 3M | 9 H | R251A | 4 H | 5 F | R718 | 1M | 9K |
| C210 | 1 C | 6 D | 0702 | 4M | 10 H | R251B | 5 H | 5 F | R719 | 3M | 9 H |
| C211 | 2 D | 5E | 0703 | 2M | 9 K | R251C | 5 E | 5 F | R720 | 4M | 10 H |
| C212 | 1E | 5 E | 0704 | 6K | 10 H | R251D | 4 E | 5 F | R721 | 1L | 9 K |
| C213 | 2E | 5 E |  |  |  | R251E | $2 E$ | 5 F | R722 | 2L | 9 K |
| C218 | 68 | 9G | R115 | 1 D | 50 | R251F | 1 E | 5 F | R724 | 4 K | 9K |
| C220 | 3 C | 4D | R125 | 2D | 4 D | R251G | 5 F | 5 F | R725 | 4 K | 9 K |
| C229 | 30 | 4E | R138 | 4 C | 2 C | R254 | 3G | 5 F | R726 | 6 K | 10J |
| C222 | 3E | 4E | R140 | 4D | 2 C | R255 | 3G | 5 F | R727 | 5 K | 10 J |
| C223 | 3 E | 4 E | R158 | 5 C | 1 C | R256 | 2G | 6 F | R728 | 5K | 10 H |
| C228 | 7 B | 10G | R160 | 50 | 1 C | R260 | 7G | 5 E | R729 | 5 K | 10 H |
| C232 | 4E | $2 E$ | R201 | 6 E | 5G | R261 | 7G | 5 E | R730 | 5K | 9 K |
| C233 | 5 E | 2 E | R202 | 7 E | 5G | R262 | 3 F | 5F | R731 | 3M | 9 H |
| C238 | 7B | 10 H | R203 | 8 E | 5 G | R263 | 4F | 5 F | R732 | 4M | 10 H |
| C242 | 5E | 1 E | R204 | 8 E | 5G | R264 | 3 F | $5 F$ |  |  |  |
| C243 | 6 E | $1 E$ | R205 | 70 | 5G | R265 | 4F | 5 F | U201 | 80 | 5 H |
| C248 | 8 B | 10 H | R206 | 8 E | 5G | R266 | 2G | 4F | U202 | 7 D | 5G |
| C258 | 8 C | 4 H | R207 | 7 C | 9 G | R267 | 2G | 4F | U203A | 6 B | 10G |
| C268 | 7 D | 9G | R209 | 7 C | 5 H | R268 | 4 J | 5 F | U203B | 78 | 10 G |
| C271 | 3 H | 3 F | R210 | 1E | 5E | R269 | 2 J | 5 F | U203C | 7 B | 10 G |
| C272 | 3 H | 4F | R211 | 15 | 5 E | R270 | 3 J | 4 F | U203D | 8 B | 10G |
| C 273 | 3 H | 4 F | R212 | 2 C | 3L | R271 | 4 H | $3 F$ | U210 | 10 | 5 D |
| C274 | 3 H | 4F | R213 | 2 C | 4 M | R272 | 3H | 4F | U220 | 2 D | 4 D |
| C275 | 4G | 4F | R214 | 2C | 5 H | R273 | 3 H | 4F | U230 | 30 | 3 E |
| C491 | 2E | 2 F | R215 | 7 C | 6M | R274 | 3 J | 3 E | U240 | 5D | 2 E |
| C492 | 3E | 2 F | R218 | 2 C | 5E | R275 | 3G | 4E | U260 | 2F | 5 F |
| C493 | 4 E | 2 F | R219 | 1 C | 5C | R276 | 4G | 4F | U280 | 8F | 5 F |
| C494 | 6 E | 2 F | R220 | 2E | 4 E | R277 | 3G | 3F | U701 | 2L | 9. |
| C706 | 3L | 10 H | R221 | 2 E | 4 E | R278 | 3 J | 3 E | U702 | 1 M | 9 K |
| C 707 | 6L | 9 J | R222 | 3C | 3M | R279 | $4 J$ | 3F | U801B | 8B | 7H |
| C711 | 3L | 9 J | R223 | 3 C | 4 M | R280 | 3 J | $3 F$ |  |  |  |
| C712 | 4L | 10.5 | R224 | 3 C | 5 H | R281 | 4J | $3 F$ | W19 | 4M | 10 H |
| C811 | 8 B | 6.5 | R225 | 1 C | 8 C | R284 | 6 E | 6 E | W20 | 3M | 9 H |
|  |  |  | R227 | 2 C | 8 C | R285 | 6G | 5 E | W200 | 3 C | 5 G |
| CR201 | 2 C | 5 C | R228 | 3 C | 4 E | R286 | 7 F | 5G | W201 | 2 C | 5 G |
| CR202 | 1 C | 5 C | R229 | 1 C | 5D | R287 | 7 F | 5 F | W202 | 7 E | 4 G |
| CR260 | 3 J | 4 F | R230 | 4 E | 3E | R288 | 7G | 6 F | W203 | 70 | 5 H |
| CR261 | 4J | 4 F | R231 | 4 E | 3 E | R289 | 6G | 5 F | W205 | 78 | 5G |
|  |  |  | R232 | 5 C | 3 L | R290 | 7 F | 5 F | W206 | 68 | 5G |
| DL21 | 3 K | 3 F | R233 | 5 C | 4M | R291 | 7 F | 5 F | W207 | 7 B | 5G |
| DL21 | 3 K | 9 J | R234 | 4 C | 5 H | R292 | 8E | 5 F | W208 | 88 | 5G |
|  |  |  | R235 | 5 D | 3E | R293 | 8 F | 5 F | W209 | 8 C | 5G |
| L701 | 5L | 9 J | R238 | 5 C | 2D | R294 | 8G | 4F | W210 | 8 B | 10 G |
| L702 | 6L | 10. | R240 | 5 E | 2E | R295 | 8G | 5 F | W223 | 3 C | 4 D |
| L703 | 3M | 9 H | R241 | 5E | 2E | R296 | 7 F | 5 F | W231 | 4 E | 2 E |
| L704 | 4 M | 10 H | R242 | 6C | 3M | R702 | 5K | 9」 | W232 | 4E | 2 E |
|  |  |  | R243 | 6 C | 4L | R703 | 5K | 10 J | W415A | 1E | 4 E |
| P19 | 4 N | 10 H | R244 | 6 C | 5 H | R706 | 3 K | 9 K | W415B | 1 E | 2 F |
| P20 | 3 N | 9 H | R248 | 6 D | 2 E | R707 | 4K | 10K | W416A | 3 E | 3 E |
|  |  |  | R250A | 2 H | 5 E | R708 | 3M | 9 H | W416B | 3E | 2 E |
| 0250 | 3G | 4E | R250B | 3 H | 5 E | R710 | 1 L | 10 K | W815 | 8B | 8 G |
| Partial A10 also shown on diagrams 1, 3, 4, 5, 6, 7 and 13. |  |  |  |  |  |  |  |  |  |  |  |

A AND B TRIGGER SYSTEM DIAGRAM 3

| ASSEMBLY A10 |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | BOARD LOCATION | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | BOARD LOCATION | CIRCUIT <br> NUMBER | SCHEM <br> LOCATION | BOARD <br> LOCATION | CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | BOARD LOCATION |
| C421 | 1 H | 4G | 01102 | 4F | 1N | R475 | 7 L | 1G | R1154 | 6 F | 1M |
| C422 | 2 H | 4 H | Q1103 | 5 F | iN | R476 | 8M | 1 F | R1155 | 6G | 1M |
| C423 | 2 H | 4G | Q1104 | 3E | 2M | R477 | 8M | 2 H | R1162 | 5A | 1 K |
| C424 | 2 H | 4G | 01105 | 3F | 2N | R478 | 8 L | 2 H | R1163 | 5A | 2K |
| C425 | 2 J | 3G | Q1106 | 3 F | 2N | R483 | 3B | 1 G | R1170 | 3A | 1K |
| C426 | 2E | 2 H |  |  |  | R484 | 8 L | 1 F |  |  |  |
| C432 | 1 L | 3H | R410 | 1M | 3 F | R485 | 8 L | 1F | U421A | 10 | 3 G |
| C444 | 2 L | 3G | R411 | 1M | 4 F | R486 | 8L | 1 F | U421B | 1K | 3G |
| C447 | 3M | 3G | R412 | 2M | 4F | R487 | 8L | 1F | U421C | 1M | 3G |
| C451 | 6 H | 2G | R413 | 2M | 4G | R490 | 3B | 3J | U431A | 7 D | 2G |
| C452 | 7H | 2H | R414 | 6M | 2 F | R491 | 4 B | 3 J | U431B | 6 K | 2G |
| C453 | 8 H | 2G | R415 | 6M | 2G | R492 | 4B | 3 J | U431C | 6M | 2G |
| C454 | 7 H | 2G | R416 | 6M | 2 F | R493 | 4B | 3 J | U441A | 4K | 2 H |
| C455 | 6 J | 2G | R417 | 6M | 2 F | R494 | 7 B | 3J | U441B | 5K | 2 H |
| C462 | 6L | 1H | R420 | 2E | 4G | R495 | 7 B | 2 J | U441C | 7K | 2 H |
| C463 | 6L | 1 H | R421 | 1 H | 4H | R496 | 8B | $2 J$ | U441D | 4K | 2 H |
| C474 | 6L | 1G | R422 | 2 H | 4H | R497 | 8B | 2 J | U441E | 2K | 2 H |
| C477 | 8M | 1G | R423 | 2 H | 4G | R498 | 3B | 3 J | U441F | 1K | 2 H |
| C483 | 3B | 1F | R424 | 2 H | 4G | R607 | 2N | 3 J | U1101A | 2E | 2M |
| C484 | 4 B | 3 F | R425 | 2 H | 4 H | R1103 | 3D | 2M | U1101B | 6G | 2M |
| C485 | 8 B | 2 F | R426 | 2E | 4 H | R1104 | 3E | 2M | U1102A | 3G | 1L |
| C486 | 8 B | 2 F | R430 | 2K | 3 H | R1110 | 5E | 1 N | U1102B | 3H | 1L |
| C487 | 3B | 3 F | R431 | 1K | 3 H | R1111 | 4E | 1 N | U1103 | 5B | 2K |
| C488 | 8 B | 2 F | R432 | 2 L | 3 H | R1112 | 4 E | 1 N | U1 104A | 3 J | 2M |
| C489 | 4 B | 3 F | R440 | 1L | 3 H | R1113 | 4F | 1 N | U1104B | 4G | 2M |
| C611 | 2N | 3 J | R441 | 1L | 3 H | R1114 | 4 F | 1 N | U1104C | 4 J | 2M |
| C1103 | 3A | 3. | R442 | 1L | 3 H | R1115 | 4F | 1N | U1106A | 2B | 2 J |
| C1105 | 3E | 2N | R443 | 1L | 2 H | R1116 | 5 F | 1 N | U1106B | 8.5 | 2 J |
| C1106 | 3 H | 2 L | R444 | 2 L | 2 H | R1117 | 4F | 1N | U1106C | 6 H | 2J |
| $\mathrm{C1107}$ | 3 H | 2 L | R445 | 2 L | 3 H | R1118 | 5F | 1 N |  |  |  |
| C1110 | 3 E | 2M | R446 | 2M | 2G | R1120 | 3E | 2N | W401 | 2E | 2 H |
| C1111 | 3H | 1L | R447 | 3M | 3 H | R1121 | 4E | 2M | W403 | 6 J | 1 J |
| C1114 | 5E | 1 N | R448 | 3L | 3 H | R1122 | 3 E | 2 N | W404 | 6 F | 1 H |
| C1130 | 4G | 2 L | R449 | 2M | 3H | R1123 | 4 F | 2M | W405 | 8L | 1 J |
| C1154 | 6 F | 1 M | R450 | 6E | 2G | R1124 | 4F | 2N | W406 | 3 J | 2 H |
| C1155 | 6G | 2M | R451 | 7 H | 2 H | R1125 | $3 F$ | 2N | W407 | 3 J | 2 J |
|  |  |  | R452 | 7H | 2 H | R1126 | 3 F | 2N | W408 | 3J | 1 J |
| CR432 | 1L | 3 H | R453 | 8 H | 2G | R1127 | 4F | 2N | W410 | 3L | 3 J |
| CR462 | 6 K | 1H | R454 | 7 H | 2 F | R1128 | 3 F | 2N | W411 | 2E | 2.5 |
|  |  |  | R455 | 6 E | 2H | R1131 | 3G | 1L | W412 | 2E | 1 J |
| L426 | 2 E | 4H | R456 | 6 F | 2 H | R1132 | 3 H | 2L | W413 | 1M | 3J |
| L432 | 2 L | 3 H | R460 | 6K | 2 H | R1133 | 3H | 2 L | W414 | 2M | 3. |
| L462 | 6 K | 1 H | R461 | 6K | 2 H | R1134 | 3 J | 1M | W1 101 | 5 C | 2K |
|  |  |  | R462 | 6L | 1 H | R1135 | 4G | 2M | W1102 | 3K | 2K |
| Q440 | 1L | 3 H | R463 | 6L | 1 H | R1136 | 4G | 1 N | W1104 | 5A | 1K |
| Q444 | 2L | 3G | R470 | 6 L | 2 H | R1142 | 3 H | 1L | W1105 | 4 H | 1K |
| Q470 | 5L | $1 \mathrm{H}^{\text {d }}$ | R471 | 5L | 1H | R1143 | 4H | 1L | W1106 | 8 J | 2K |
| Q474 | 7 L | 1G | R472 | 5 L | 2 H | 81144 | 3J | 1M | W1107 | 4 H | 2K |
| Q480 | 8L | 1 F | R473 | 6K | 2 H | R1145 | 3 J | 1M | W1120 | 6 H | 2K |
| Q1 101 | 5E | 1M | R474 | 6 K | 1H | R1150 | 2D | 1M |  |  |  |
| Partial A1O also shown on diagrams 1, 2, 4, 5, 6, 7 and 13. |  |  |  |  |  |  |  |  |  |  |  |

DISPLAY AND TRIGGER LOGIC AND PROCESSOR INTERFACE DIAGRAM 4

| ASSEMBLY A10 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEM LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| C600 | 8 J | 4K | R616 | $6 F$ | 4K | R664 | 6 J | 2K |
| C601 | 8.J | 5K | R617 | 6 F | 4 K | R665 | 5 H | 3J |
| C602 | 1H | 3K | R618 | 6 F | 4K | R666 | 5 J | 3 J |
| C603 | 1 H | 2K | R619 | 6 F | 4L | R669 | 3H | 3M |
| C607 | 6. | 4L | R620 | 5 F | 4K | R670 | 4 J | 5M |
| C608 | 6 K | 4L | R621 | 5G | 4L | R671 | 6 K | 4L |
| C612 | 2G | 2K | R622 | 6G | 5K | R672 | 6 J | 4K |
|  |  |  | R623 | 6G | 5K |  |  |  |
| CR603 | 5. | 3.J | R624 | 4K | 5N | U501 | 3 C | 3N |
|  |  |  | R625 | 4K | 5N | U502 | 4D | 3 N |
| DL22 | 2F | 2L | R626 | 1 H | 3L | U503 | 3D | 5N |
| DL22 | 2 F | 2G | R627 | 1 H | 2 L | U600 | 3L | 4L |
|  |  |  | R628 | 4H | 4N | U601 | 8K | 5 K |
| P2502 | 2M | 1L | R630 | 6L | 5M | U602 | 1 G | 3K |
| P2502 | 4A | 1L | R631 | 4K | 6 N | U603A | 2 H | 3M |
|  |  |  | R636 | 8 H | 5K | U603B | 3 H | 3M |
| Q600 | 8 J | 5. | R637 | 8 H | 4 J | U603C | 1H | 3M |
| 0601 | 8 J | 5K | R638 | 8 J | 4.5 | U603D | 2 H | 3M |
| 0602 | 3K | 4M | R639 | 1 H | 3N | U604A | 4K | 5M |
| Q603 | 3K | 4M | R640 | 2 H | 3N | U604B | 7 F | 5M |
| 0604 | 2K | 4M | R641 | 5 H | 4. | U604C | 8 F | 5M |
| 0605 | 2K | 4M | R642 | 5 J | 4K | U606A | 5E | 5M |
| Q606 | 2K | 4M | R643 | 5 H | 3J | U606B | 3D | 5M |
| Q607 | 2K | 4M | R644 | $5 . J$ | 2K | U606C | 4E | 5M |
| 0608 | 6 K | 4 L | R645 | 6 H | 2K | U6060 | 2L | 5M |
|  |  |  | R646 | 4K | 5M | U606E | 2L | 5M |
| R501 | 6B | 3M | R647 | 5 F | 1K | U606F | 2D | 5M |
| R502 | 4 E | 5N | R648 | 5 F | 2 J |  |  |  |
| R601 | 7J | 4 J | R649 | 5G | 2 J | W505 | 4E | 5N |
| R602 | 8K | 5 L | R650 | 6 K | 4K | W510 | 4E | 6M |
| R603 | 7K | 5L | R651 | 2L | 5M | W603 | 1 H | 3M |
| R604 | 7K | 5L | R652 | 2L | 5M | W604 | 4J | 3L |
| $R 605$ | 8L | 5L | R653 | 3F | 4 N | W605 | 5G | 3K |
| R606 | 8J | 5K | R654 | 4G | 5 N | W610 | 3L | 4M |
| R609 | 3 K | 4M | R655 | 4 F | 5 N | W611 | 3L | 5M |
| R610 | 3K | 4M | R656 | 5 H | 4.J | W612 | 8 H | 5 K |
| R611 | 2K | 4M | R657 | 4J | 4 K | W2502 | 2M | 1L |
| R612 | 2K | 4M | R658 | 5 H | 4. | W2502 | 8A | 1L |
| R613 | 2K | 4M | R659 | 5 J | 3K |  |  |  |
| R614 | 3 K | 4M | R662 | 4K | 4M | Y600 | $6 K$ | 4L |
| R615 | 5F | 4K | R663 | 6H | 2K |  |  |  |
| Partial A10 also shown on diagrams 1, 2, 3, 5, 6, 7 and 13. |  |  |  |  |  |  |  |  |

## A AND B SWEEPS AND DELAY COMPARATORS DIAGRAM 5

| ASSEMBLY A10 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEM <br> LOCATION | BOARD <br> location | CIRCUIT NUMBER | SCHEM <br> LOCATION | BOARD location | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| C301 | 4D | 8 F | R309 | 3 C | 9 C | R363 | 7 C | 9 F |
| C302 | 7 D | 9 F | R310 | 3 C | 7 C | R364 | 8C | 9G |
| С303 | 3D | 7 C | R311 | 3D | 8C | R365 | 7H | 10E |
| C305 | 4B | 9 D | R313A | 4D | 7 C | R366 | 1A | 8 C |
| C306 | 4A | 7 C | R313B | 3 D | 7 C | R367 | 2A | 8 C |
| C307A | 5 J | 7 E | R313C | 3D | 7 C | R370 | 8 C | 9G |
| C307B | 5J | 7 E | R313D | 3 D | 7 C | R371 | 8 D | 9G |
| C307C | 7 J | 10F | R314 | 3 D | 7 C | R372 | 8D | 9 G |
| C308 | 4 H | 70 | R315 | 8 K | 10E | R373 | 8 C | 9 G |
| C310 | 4 | 7E | R316 | 5D | 7 F | R375 | 8K | 10 E |
| C311 | 5 C | 7 F | R317 | 4 B | 8 E | R376 | 7K | 9 E |
| C312 | 3 J | 9 E | R318 | 4 C | 8 E | R377 | 6L | 8G |
| C313 | 2 J | 9 E | R319 | 5B | 8 F | R378 | 5 M | 6 J |
| C314 | 5J | 7 F | R320 | 5 K | 8 E | R379 | 6 L | 7 G |
| C315 | 5 J | 7G | R321A | 6 F | 8D | R380 | 6M | 6. |
| C321 | 7 C | 9 F | R321B | 6 F | 8 D | R381 | 70 | 9 F |
| C326 | 7H | 10E | R321C | 6 F | 8 D | R382 | 6 L | 7G |
| C329 | 7 J | 10 F | R321D | 3 F | 8 D | R383 | 8 B | 9 G |
| C330 | 75 | 9G | R321E | 3 F | 8D | R384 | 5 E | 8D |
|  |  |  | R321F | 3 F | 8D | R385 | 1M | 8 F |
| CR301 | 3 C | 7 C | R322 | 5 L | 7 H | R386 | 1M | 9 F |
|  |  |  | R323 | 7L | 7G | R387 | 1M | 8 F |
| 0301 | 3D | 7 C | R325 | 4 H | 7 D | R388 | 3M | 8 F |
| Q302 | 4B | 8 E | R326 | 4 J | 70 | R391 | 5 E | 8D |
| 0303 | 4 C | 8 E | R327 | 7 C | 9 F | R393 | 4 H | 10 E |
| 0304 | 4D | 8 F | R328 | 3M | 8 E | R394 | 6 H | 10E |
| Q305 | 4 J | 7 E | R329 | 3 J | 9 E | R395 | 5 J | 7 E |
| O306 | 4. | 7D | R330 | 2 J | 9 E | R396 | $7 J$ | 9 E |
| 0307 | 3 H | 3 D | R331 | 3K | 8 E |  |  |  |
| 0308 | 5D | 7 F | R332 | 5 C | 7G | U301A | 1K | 8 D |
| 0309 | 5 C | 7 F | R333 | 50 | 7G | U301C | 2 K | 8D |
| Q310A | 5J | 7E | R334 | 5 B | 8G | U302 | 18 | 8 C |
| Q3108 | 5 J | 7E | R335 | 3L | 8 F | U303 | 2 C | 9 C |
| 0311 | 5 C | 8 F | R336 | 3 L | 8 F | U304A | 3 H | 8 D |
| Q312 | 5 K | 7E | R337 | 2M | 8 E | U3048 | 6 H | 8 D |
| Q313 | 8D | 9 F | R338 | 4L | 8 E | U307 | 2 F | 7 D |
| 0315 | 6 B | 9E | R340 | 6C | 7G | U308 | 2G | 70 |
| 0316 | 7 C | 9 E | R341 | 1L | 9 F | U309A | 4A | 7 C |
| 0317 | 7 D | 9 F | R342 | 2 L | 9 E | U309B | 30 | 7 C |
| 0318 | 7 J | 10 E | R343 | 1L | 9 F | U310 | 5 F | 9 D |
| 0320 | 6 H | 9D | R344 | 4K | 8 E | U311 | 5G | 9 D |
| Q321 | 70 | 9 F | R346 | 6K | 8D | U313 | 3M | 8 E |
| 0322 | 7 C | 9 F | R347 | 5 K | 8 E | U315A | 1 M | 8 F |
| 0323A | 7 J | 9 E | R348 | 5L | 8 H | U3158 | 4M | 8 F |
| O323B | 8 J | 9 E | R349 | 5L | 7G | U315C | 2M | 8 F |
| 0325 | 7K | 9 E | R350A | 6M | 7H | U316A | 6M | 7H |
| 0326 | 5D | 7 F | R350B | 7 M | 7 H | U316B | 6 L | 7 H |
| 0328 | 4K | 7 E | R350C | 6 L | 7H | U316C | 6L | 7H |
| Q329 | 6K | 9 E | R350E | 5L | 7H | U316D | 6M | 7 H |
| 0330 | 4 H | 7 E | R351 | 5E | 8 F |  |  |  |
| Q331 | 6 H | 9 E | R352 | 6 L | 7G | VR301 | 6 B | 6G |
| 0332 | 78 | 9 F | R354 | 6 B | $9 E$ | VR302 | 5B | 6G |
| 0333 | 5B | 8 F | R355 | 6C | 9 E | VR303 | 8B | 8G |
|  |  |  | R356 | 78 | 9 F | VR304 | 7B | 8G |
| R301 | 6 C | 9 E | R357B | 1 M | 8 F | VR308 | 7 C | 9 F |
| R302 | 4.1 | 7 E | R357C | 1M | 8 F | VR309 | 5 C | 6G |
| R303 | 4 C | 8 F | R3570 | 3M | 8 F | VR310 | 8C | 9G |
| R304 | 5 C | 8 F | R357E | 3M | 8 F | VR311 | 6K | 8 E |
| R305 | 5 C | 7G | R359 | 2M | 8 F | VR312 | 8K | 10E |
| R306 | 4 B | 7 C | R360 | 3M | 8 F |  |  |  |
| R307 | 4A | 7 C | R361 | 6D | 8G | W304 | 7K | 8G |
| R308 | 4A | 7 C | R362 | 4 C | 8 F | W802 | 5 K | 8G |

[^11]HORIZONTAL OUTPUT AMPLIFIER DIAGRAM 6

| ASSEMBLY A10 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | SCHEM LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| C319 | 6 B | 6 F | R369 | 6 B | 8D | R845 | 3 H | 7 J |
| C802 | 3K | 7 K | R801 | 2K | 7K | R846 | 4K | 7J |
| C803 | 3 J | 7J | R802 | 3L | 7K | R847 | 5G | 8J |
| $\mathrm{C804}$ | 3G | 8 J | R803 | 2.J | 7.1 | R848 | 5H | 8 K |
| C805 | 4 K | 8 J | R804 | 2. | 7 J | R849 | 5 H | 8K |
| C807 | 2 H | 7J | R805 | 4 H | 7 J | R850 | 5G | 8 J |
| C808 | 5B | 9G | R806 | 2 H | 7 J | R851 | 5 H | 8J |
| C809 | 5K | 8 K | R807 | 5B | 9G | R852 | 5 K | 8K |
| C810 | $5 . J$ | 8J | R808 | 4 D | 7H | R853 | 6 J | 8 J |
| C814 | 7 H | 8 J | R809 | 4D | 8 H | R854 | 5 E | 8 H |
| C817 | 6C | 6G | R810 | 5 E | 8 H | R855 | 4 E | 7 H |
| C819 | 7 L | 7 J | R811 | 7D | 7 H | R856 | 4 E | 8 H |
|  |  |  | R812 | 70 | 8 H | R857 | 4E | 8 H |
| CR801 | 4B | 9 H | R813 | 6K | 8K | R858 | 3K | 7 J |
| CR802 | 3L | 7K | R814 | 6.5 | 8 J |  |  |  |
| CR819 | 6L | 8 J | R815 | 6.5 | 8 J | U301B | 6B | 8 D |
|  |  |  | R816 | 7H | 8 J | U801A | 7 H | 7H |
| P17 | 3M | 7 K | R819 | 5L | 8K | U802 | 3C | 8H |
| P18 | 5M | 8K | R820 | 7L | 8 K |  |  |  |
|  |  |  | R821 | 7 L | 7K | VR801 | 4K | 8 J |
| 0801 | 2K | 7 J | R822 | 7L | 7 K | VR802 | 3G | 8 J |
| 0802 | 3 K | 7 J | R823 | 4C | 8G |  |  |  |
| 0803 | 3 H | 7 J | R825 | 7 C | 8 H | W17 | 3M | 7 K |
| Q804 | 3G | 7 J | R826 | 7 C | 7G | W18 | 5M | 8 K |
| Q805 | 5K | 8 J | R827 | 4 C | 8 H | W305 | 6B | 100 |
| Q806 | 6 K | 8 J | R828 | 3 K | 7K | W805 | 5B | 6 L |
| Q807 | 5 H | 8 J | R829 | 6K | 8K | W806 | 5 C | 6K |
| Q808 | 5 H | 8 J | R836 | 4C | 8H | W807 | 5B | 6L |
| 0809 | 5 E | 8 H | R840 | 2K | $7 J$ | W808 | 5 C | 6 K |
| 0810 | 3E | 7 H | R841 | 4F | 7 J | W810 | 4B | 5G |
|  |  |  | R842 | 3 F | 7 J | W811 | 4 B | 5 H |
| R353 | 6 B | 8D | R843 | $2 \mathrm{G}$ | $7 K$ |  |  |  |
| R358 | 6 B | 8D | R844 | 2G | 7K |  |  |  |
| Partial A10 also shown on diagrams 1, 2, 3, 4, 5, 7 and 13. |  |  |  |  |  |  |  |  |

Z-AXIS, CRT, PROBE ADJUST and CONTROL MUX DIAGRAM 7

| ASSEMBL | Y A8 |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | $\begin{array}{\|c\|} \text { SCHEM } \\ \text { LOCATION } \end{array}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | SCHEM LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT <br> NUMBER | $\begin{gathered} \text { SCHEM } \\ \text { LOCATION } \end{gathered}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| R901 R902 | $\begin{aligned} & 5 A \\ & 6 A \end{aligned}$ | 1 A 1 C | $\begin{aligned} & \mathrm{R} 903 \\ & \mathrm{R} 905 \end{aligned}$ | $\begin{aligned} & 6 A \\ & 4 A \end{aligned}$ | $\begin{aligned} & 1 \mathrm{~F} \\ & 1 \mathrm{H} \end{aligned}$ | W900 | 4A | 1 E |  |  |  |
| Partial A8 also shown on diagram 13. |  |  |  |  |  |  |  |  |  |  |  |
| ASSEMBLY A10 |  |  |  |  |  |  |  |  |  |  |  |
| C910 | 2 L | 10 B | DS2701 | 8L | 9 N | R924 | 2 H | 9C | R2727 | 5 E | 7 L |
| C935 | 2 H | 7A | DS2702 | 7L | 9M | R930 | 1 H | 8 A | R2728 | $5 E$ | 6L |
| C1001 | 5 C | 7L | DS2703 | 5 K | 9 M | R931 | 1 H | 7 A | R2729 | 6 E | 7L |
| C1002 | 6 C | 7M | DS2704 | 6 K | 9M | R932 | 1 H | 7 A | R2733 | 6 F | 9 L |
| C1003 | 6 C | 8M |  |  |  | R933 | 1 H | 7 B | R2734 | $6 F$ | 9 L |
| C1004 | 7 C | 7L | $J 15$ | 2K | 6 A | R934 | 2G | 7 B | R2735 | 5G | 9 L |
| C2703 | 7G | 6M | $J 927$ | 2 L | 10B | R935 | 2 H | 78 | R2736 | 5G | 10 L |
| C2704 | 6G | 7M |  |  |  | R936 | 1 J | 7A | R2737 | 5G | 10K |
| C2705 | 7G | 7 N | P8 | 8A | 10M | $R 937$ | 2 J | 7A | R2738 | 5G | 10L |
| C2706 | 7 H | 6 N | P9 | 3M | 8 N | $R 938$ | 1 G | 78 | R2739 | 4 H | 10L |
| C2707 | 7 H | 7M | P9 | 4M | 8 N | R939 | 2G | 78 | R2740 | 5 J | 10 L |
| C2708 | 6 H | 7N | P2302 | 1A | 10D | R940 | 2. | 7A | R2741 | 5 J | 8M |
| C2710 | 7 J | 7 N | P2304 | 3A | 10D | R1001 | 5 C | 3 K | R2742 | 6. | 8L |
| C2711 | 7K | 8M |  |  |  | R1002 | 6 C | 3K | R2743 | 6 H | 8L |
| C2712 | 7K | 8 N | Q905 | 4E | 10A | R1003 | 6 C | 3 L | R2745 | 7 J | 7 N |
| C2713 | 8K | 6 N | 0907 | 4 E | 10A | R1004 | 7 C | 3 K | R2750 | 6 J | 8M |
| C2715 | 6G | 10L | 0908 | 4F | 10A | R1005 | 5 C | 7 L | R2751 | 6 K | 9M |
| C2716 | 5 H | 10L | Q1001 | 5D | 3K | R1006 | 6 D | 7L | R2758 | 6 L | 9L |
| C2717 | 5 H | 10L | 01002 | 6 D | 3K | R1007 | 7 D | 8L | R2760 | 6 L | 10M |
| C2719 | 5 J | 10 M | 01003 | 6 D | 3L | R1008 | 70 | 7 L | R2765 | 7F | 7M |
| C2720 | $6 J$ | 8L | 01004 | 7 D | 3 K | R1009 | 8 C | 7 K | R2784 | 3L | 7N |
| C2721 | 6 J | 6K | 01005 | 8 D | 7 L | R1010 | 8 B | 7 K | R2785 | 3L | 8 N |
| C2723 | 6 E | 71 | 02701 | 7 H | 7 N | R1020 | 58 | 7 L | R2786 | 4L | 6 N |
| C2724 | 8K | 8M | Q2702 | 7 H | 7M | R1021 | 5B | 7L | R2787 | 5 L | 6 N |
| C2758 | 6K | 10 L | Q2703 | 7 H | 6M | R1022 | 6 B | 7 L | R2788 | 5 L | 6 N |
| C2759 | 7F | 7M | Q 2704 | 8 H | 6N | R1023 | 6 B | 7 L | R2789 | 5 L | 8 N |
| C2783 | 3L | 8 N | Q2705 | 7G | 6M | R1024 | 7 B | 7L | R2795 | 7E | 7L |
| C2784 | 5 L | 6N | 02706 | 8 F | 7M | R1025 | 7 B | 7 L | R2796 | 6 F | 6M |
| C2785 | 5L | 8 N | 02707 | 7 F | 6M | R1028 | 5D | 4K |  |  |  |
|  |  |  | 02708 | 5 E | 6L | R2701 | 7 E | 6 L | U506 | 2 E | 9 C |
| CR935 | 2. | 7 A | 02709 | 5 F | 6L | R2702 | 7 E | 6L | U930A | 1 H | 7 B |
| CR936 | 2. | 7A | 02711 | 5G | 10L | R2703 | 6 E | 7 L | U930B | 2 H | 7 B |
| CR1001 | 5 D | 4K | 02712 | 5 H | 10L | R2704 | 6 E | 7 L | U931 | 3 H | 9 B |
| CR1002 | 7 D | 4 K | 02713 | 5 H | 10L | R2705 | 7 F | 7 L | U1001B | 6 B | 7L |
| CR1003 | 8 C | 7 | 02715 | 7 F | 6M | R2706 | 7F | 7 M | U1001C | 6 B | 7 L |
| CR1004 | 7 C | 7 L |  |  |  | R2708 | 6G | 7 M | U10010 | 5B | 7 L |
| CR1005 | 5D | 5 M | $R 503$ | 2 B | 10C | R2709 | 6G | 7 M | U1101A | 7B | 2M |
| CR2701 | 7 K | 9 M | R505 | 5B | 9 C | R2710 | 8G | 6M |  |  |  |
| CR2702 | 8 K | 9M | R506 | 6 B | 9 C | R2711 | 7 G | 6 N | VR2701 | 7G | 6M |
| CR2703 | 7 K | 8 N | R507 | 6 B | 9 C | R2712 | 7G | 6M |  |  |  |
| CR2704 | 7K | 6 N | R508 | 2B | 10 C | R2713 | 7G | 7M | W9 | 3M | 8 N |
| CR2705 | 8G | 6M | R510 | 2B | 10C | R2714 | 7 G | 7 M | W9 | 8 A | 10 M |
| CR2707 | 7 F | 7 L | R512 | 3B | 10 C | R2715 | 7G | 7 M | W9 | 8M | 8 N |
| CR2713 | 6 H | 10L | R906 | 4E | 108 | R2716 | 6G | 7M | W16 | 8A | 7 K |
| CR2714 | 5 H | 10L | R907 | 4 E | 10A | R2717 | 6 H | 7M | W906 | 1H | 7A |
| CR2715 | 5 J | 9L | R908 | 4F | 10A | R2718 | 75 | 7M | W1000 | 5D | 3 L |
| CR2716 | 5 K | 8M | R909 | 5D | 8 B | R2719 | 7J | 7 N | W1010 | 7 D | 4K |
| CR2717 | 6 K | 9M | R910 | 2L | 10 B | R2720 | 7」 | 8 N | W1288 | 8 J | 6 J |
| CR2718 | 5」 | 8L | R911 | 2 L | 8A | R2721 | 7K | 9 N | W2302 | 3A | 10D |
|  |  |  | R920 | 3G | 8 B | R2722 | 7K | 6 L | W2304 | 4A | 100 |
| DS901 | 4E | 8A | R921 | 3G | 8 B | R2723 | 7K | 9M | W2701 | 7E | 5 K |
| DS902 | 4F | 9A | R922 | 3 H | 9 C | R2724 | 7K | 9M |  |  |  |
| DS903 | 4 F | 10A | R923 | 3 H | 9 C | R2726 | 5E | 6L |  |  |  |
| Partial A10 also shown on diagrams 1, 2, 3, 4, 5, 6 and 13. |  |  |  |  |  |  |  |  |  |  |  |
| CHASSIS MOUNTED PARTS |  |  |  |  |  |  |  |  |  |  |  |
| J16 | 7 A | CHASSIS | $\begin{aligned} & \mathrm{P} 26 \\ & \mathrm{P} 27 \end{aligned}$ | $\begin{aligned} & \text { 1L } \\ & \text { 2L } \end{aligned}$ | CHASSIS CHASSIS | V1 | 1 M | CHASSIS |  |  |  |

MEASUREMENT PROCESSOR DIAGRAM 8

ASSEMBLY A16

| CIRCUIT NUMBER | SCHEM LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | BOARD LOCATION | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BT02501 | 5K | 8D | $\begin{aligned} & \text { R2502 } \\ & \text { R2503 } \end{aligned}$ | 1D | 4 H | R2560 | 3 M | 4 F |
|  |  |  |  | 7E | 5 J | R2561 | 3M | 4F |
| C2514 | 6B | 6 H | R2504 | 6B | 5J | R2562 | 3M | 4F |
| C2515 | 6B | 6H | R2505 |  | 5F | R2563R2564 | $4 M$$5 M$ | 4 F |
| $\begin{aligned} & \mathrm{C} 2516 \\ & \mathrm{C} 2517 \end{aligned}$ | 5J | 8 J | R2506 | 8 D 5 K | 7 C |  |  | 4 J |
|  | 8A | 6. | $\begin{aligned} & \text { R2508 } \\ & \text { R2509 } \end{aligned}$ | 2B | 3D | R2564 | 5M |  |
| C2518 | 8A | 8. |  | 1B | 5J | $\mathrm{U} 2501$ | 1 C | 6G |
| C2551 | 4M | 4F | R2510 | 2B | 8 J |  | 7A | 6 J |
| C2552 | 4M | 4F | R2511 | 18 | 8C | U2502 | 2F | 4 H |
| $\begin{aligned} & \mathrm{C} 2553 \\ & \mathrm{C} 2554 \end{aligned}$ | 3M | $4 F$ | R2512 |  | 4H | U25038 | 2D | 4H |
|  | 3 M5 M | 4F | R2513 | $1 E$ 10 | 4G | U2503C | 8G | 4 H |
| C2555 |  |  | $\begin{aligned} & \text { R2514 } \\ & \text { R2515 } \end{aligned}$ | $\begin{aligned} & 3 D \\ & \text { 8D } \end{aligned}$ | 5 F | U2503D |  | 4H |
|  | 5M | 4J |  |  | $\begin{aligned} & \text { 6G } \\ & \text { 6G } \end{aligned}$ | U2506A | 7 D |  |
| CR2501 | 4J | 7J | R2516 | $\begin{aligned} & 8 D \\ & 70 \end{aligned}$ |  | U2506B | 70 | 5J |
| CR2502 | 4K | 7 J | R2517 | 8F | 6 J | U2506C | 7B | 53 |
| CR2504 | 8E | 6 J | R2518 |  |  | U25060 | 2 E | 5 J |
| CR2505 |  |  | $\begin{aligned} & R 2519 \\ & R 2520 \end{aligned}$ | $8 F$ $6 J$ | 6 J | U2512 | 3 J | 4 F |
|  | 7F |  |  | 6 J 5 H | 41 | U2513 |  | 41 |
| DS2501 | 8 E | 61 | $\begin{aligned} & \text { R2521 } \\ & \text { R2522 } \end{aligned}$ | 5 E3 H | 5161 | $\begin{aligned} & \text { U2514 } \\ & \text { U2515 } \end{aligned}$ | 2G | 5 H |
|  |  |  |  |  |  |  | 1 E | 4H |
|  | $\begin{aligned} & 1 \mathrm{~B} \\ & 3 \mathrm{M} \end{aligned}$ | $3 J$3 J | $\begin{aligned} & \text { R2523 } \\ & \text { R2524 } \\ & \text { R2526 } \end{aligned}$ | 7A | 6 J | U2517 | 4L | 5 F |
| J2502 |  |  |  | $\begin{aligned} & \text { 8B } \\ & 7 \mathrm{D} \end{aligned}$ | $\begin{aligned} & 6 \mathrm{~J} \\ & 6 \mathrm{~F} \end{aligned}$ | $\begin{aligned} & \text { U2518 } \\ & \text { U2519 } \end{aligned}$ | 5L6 L | 4J |
|  | 3M |  |  |  |  |  |  | 51 |
| 02507 | 7F | 7J | $\begin{aligned} & \text { R2527 } \\ & \text { R2554 } \end{aligned}$ | $7 D$$2 B$18 | $\begin{aligned} & 6 \mathrm{~F} \\ & 2 \mathrm{~A} \\ & 4 \mathrm{G} \end{aligned}$ | U2521 <br> Y2501 | $\begin{aligned} & 7 \mathrm{~J} \\ & 6 \mathrm{~B} \end{aligned}$ |  |
|  |  |  |  |  |  |  |  |  |
| R2501 | 2 D | 4G | R2555 |  |  |  |  | 6 H |

Partial 116 also shown on diagrams 9, 10, 11 and 14.

## READOUT SYSTEM DIAGRAM 9

| ASSEMBLY A16 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | $\begin{gathered} \text { SCHEM } \\ \text { LOCATION } \end{gathered}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | SCHEM <br> location | BOARD <br> LOCATION | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| C2411 | 6 J | 5 E | R2409 | 3 K | 6 C | U2407A | 4 F | 5 E |
| C2412 | 4J | 5 C | R2410 | 5M | 7 C | U24078 | 3 F | 5 E |
| C2416 | 2 H | 18 | R2411 | 3M | 7 C | U2408 | 4G | 5 C |
| C2417 | 2 J | 1 B | R2413 | 5J | 5 E | U2409A | 18 | 3 B |
| C2418 | 2 J | 1 B | R2414 | $6 J$ | 5 E | U2409B | 1 D | 3B |
| C2419 | 2 J | 18 | R2415 | 4 J | 50 | U2410 | 2E | 2B |
| C2420 | 2K | 18 | R2416 | 4 J | 5 C | U2411 | 7F | 4B |
|  |  |  | R2417 | 4M | 7 C | U2412 | 4J | 5 D |
| J2302 | 3M | 8 B | R2418 | 4 M | 7 C | U2413 | 3. | 5 C |
| J2502 | 1 A | 3 J | R2419 | 2M | 2 C | U2414 | 4L | 6 D |
| J2502 | 1M | 3 J | R2420 | 2M | 2 A | U2415 | 3 L | 6C |
|  |  |  | R2421 | 1A | 28 | U2416A | 5L | 7 D |
| R2400 | 2B | 2 A |  |  |  | U2416B | 3 L | 7 D |
| R2401 | 2M | 2A | U2400 | 2 C | 3 C | U2416C | 3M | 7 D |
| R2402 | 2 F | 2 B | U2401 | 4B | 5 F | U2416D | 5M | 7 D |
| R2404 | 16 | 10 | U2402 | 6 B | 5 F | U2417A | 1 B | 1A |
| R2405 | 4G | 5D | U2403 | 1 G | 1 C | U24178 | 1 C | 1A |
| R2406 | 5 K | 6 D | U2404 | 5 E | 4 B | U2417C | 2 B | 1A |
| R2407 | 5K | 6 E | U2405 | 6 F | 3 B | U2417D | 38 | 1A |
| R2408 | 3K | 6C | U2406 | 5G | 4 C |  |  |  |
| Partial A16 also shown on diagrams 8, 10, 11 and 14. |  |  |  |  |  |  |  |  |

SWITCH BOARD AND INTERFACE DIAGRAM 10

| ASSEMBLY A14 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | $\begin{gathered} \text { SCHEM } \\ \text { LOCATION } \end{gathered}$ | BOARD location | CIRCUIT NUMBER | SCHEM <br> LOCATION | BOARD LOCATION | CIRCUIT NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | BOARD LOCATION |
| CRO2001 | 3G | 3 F | DS2034 | 3 D | 2 F | S2015 | 3 J | 4F |
| CR2002 | 3G | 2 F | DS2035 | 4D | 2 F | S2016 | 3 J | 4 F |
| CR2003 | 3H | 4 E | DS2036 | 5D | 3 F | S2017 | 8 H | 1A |
| CR2004 | 3 J | 3D | DS2037 | 6 D | 3 F | \$2018 | 8 H | 2A |
| CR2005 | 3 J | 3 C | DS2038 | 6 D | 3 F | S2019 | 8 H | 3A |
| CR2006 | 3K | 3 A | DS2039 | 7 D | 3 F | S2020 | 7 H | 4A |
|  |  |  | DS2041 | 3 C | 2 F | S2021 | 7 H | 38 |
| DS2001 | 3 F | 2A | DS2042 | 3 C | 2 F | S2022 | 6 H | 1 B |
| DS2002 | 3 F | 2B | DS2043 | 4 C | 2 F | S2024 | 6 H | 3 C |
| DS2003 | 4 F | 2 B | DS2044 | 5 C | 3 F | \$2026 | 5 H | 1 C |
| DS2004 | 5 F | 2 C | DS2045 | 6 C | 3 F | S2028 | 4 H | 2 D |
| DS2005 | 6 F | 30 | DS2046 | 6 C | 3 F | \$2030 | 3H | 2E |
| DS2006 | 6 F | 3 D | DS2047 | 7 C | 3 F | S2031 | 3 H | 2 F |
| DS2007 | 7 F | 3D | DS2048 | 8 C | 4 F | S2033 | 8G | 1 B |
| DS2008 | 8 F | 3 D |  |  |  | \$2034 | 8G | 2A |
| DS2009 | 3 F | 4A | P2501 | 2 F | 18 | S2035 | 8G | 3A |
| DS2010 | 3 F | 48 | P2501 | 3 C | 18 | \$2036 | 7G | 4 B |
| DS2011 | 4 F | 48 |  |  |  | S2037 | 7G | 3 B |
| DS2012 | 5 F | 38 | R2001 | 7 L | 48 | S2038 | 6G | 1 C |
| DS2013 | 6 F | 4 C | R2002 | 4L | 3 E | S2039 | 6G | 4 C |
| DS2014 | 6 F | 4 C |  |  |  | S2040 | 6G | 3 C |
| DS2015 | 7 F | 4 C | S2001 | 8 J | 1 A | S2041 | 5 G | 4 C |
| DS2020 | 5 E | 2 C | S2002 | 8 J | 2A | \$2042 | 5G | 1D |
| DS2021 | 6 E | 2 C | S2003 | 8 J | 3A | S2043 | 5G | 3D |
| DS2022 | 6 E | 2 D | S2004 | 7 J | 4A | S2045 | 4G | 4 F |
| DS2023 | 7E | 2E | S2005 | 7 J | 3 A | S2046 | 3G | 3 F |
| DS2025 | 3 D | 2 F | S2006 | $6 J$ | 1 B | S2047 | 3G | 3 F |
| DS2026 | 3 D | 2 F | S2007 | 6 J | 4 B | S2048 | 3G | 3 F |
| DS2027 | 4 D | 2 F | S2008 | 6 J | 3 C |  |  |  |
| DS2028 | 5D | 3 F | S2009 | 53 | 4 C | U2001 | 2M | 2 B |
| DS2029 | 5D | 3 F | S2010 | 5 J | 1 C | U2002 | 5M | 4 B |
| DS2030 | 6 D | 3 F | S2011 | 4 J | 4D |  |  |  |
| DS2031 | 70 | 3 F | S2012 | 4 J | 1 D | W2501 | 2 N | 18 |
| DS2032 | 8 E | 4 E | S2013 | 4J | 4 E | W2501 | 8 C | 18 |
| DS2033 | 30 | 2 F | S2014 | 3 J | 4F |  |  |  |
| Partial A14 also shown on diagram 14. |  |  |  |  |  |  |  |  |
| ASSEMBLY A16 |  |  |  |  |  |  |  |  |
| C2521 | $2 F$ | 71 | 02501 | 2G | 71 | R2539 | 10 | 7H |
| C2522 | 1G | 71 | 02502 | 2 H | 71 | R2540 | 1 J | 7H |
| C2523 | 1H | 7 H | 02503 | 1H | 7H | R2541 | 1 E | 7G |
| C2524 | 1 J | 7 H | Q2504 | 1 J | 7 H | R2542 | 1 K | 7G |
| C2525 | $1 . J$ | 7H | 02505 | 1 K | 7H | R2546 | 3 B | 71 |
| C2526 | 1 K | 7 H | Q2506 | 1 K | 7H | R2547 | 4 C | 71 |
| C2543 | 3 C | 71 |  |  |  | R2548 | 4 C | 71 |
| C2544 | 4 C | 71 | R2528 | 2A | 6 H | R2549 | 58 | $7 J$ |
| C2545 | 4 C | 71 | R2529 | 4A | 6 H | R2550 | 6 B | 7 J |
| C2546 | 5 B | 71 | R2531 | 1 C | 71 | R2551 | 78 | 7 J |
| C2547 | 6 B | $7 J$ | R2532 | 2 F | 71 | R2552 | 78 | 7 J |
| C2548 | 78 | $7 J$ | R2533 | 1 C | 7 H | R2553 | 8 B | 8 |
| C2549 | 78 | 7. | R2534 | 1 G | 7H |  |  |  |
| C2550 | 8 B | 81 | R2535 | 1 D | 7 H | U2523 | 1A | 7H |
|  |  |  | R2536 | 1 H | 7H | U2524 | 3A | 61 |
| J2501 | 2 F | 81 | R2537 | 1 D | 7 H | U2525 | 3B | 71 |
| J2501 | 3 C | 81 | R2538 | 1 J | 7H |  |  |  |
| Partial A16 also shown on diagrams 8, 9, 11 and 14. |  |  |  |  |  |  |  |  |

ADC, DAC SYSTEM DIAGRAM 11

| ASSEMBLY A12 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | SCHEM <br> LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | BOARD LOCATION | CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| J2105 <br> R2101 R2102 R2103 R2104 | 4B <br> 6A <br> 8A <br> 7A <br> 6A | $1 B$ $3 A$ $2 A$ $3 B$ $2 B$ | $\begin{aligned} & \text { R2105 } \\ & \text { R2 } 106 \\ & \text { R2 } 107 \\ & \text { R2108 } \\ & \text { R2 } 109 \\ & \text { R2 } 110 \end{aligned}$ | $\begin{aligned} & 7 A \\ & 3 A \\ & 4 A \\ & 8 A \\ & 6 A \\ & 5 A \end{aligned}$ | 4C <br> 1D <br> 3D <br> 4D <br> $4 F$ <br> 1E | $\begin{aligned} & \text { R2111A } \\ & \text { R2111B } \\ & \text { R2112 } \\ & \text { R2113A } \\ & \text { R2113B } \end{aligned}$ | $\begin{aligned} & 3 A \\ & 3 B \\ & 5 A \\ & 4 B \\ & 4 A \end{aligned}$ | $\begin{aligned} & 2 C \\ & 2 D \\ & 1 F \\ & 2 D \\ & 2 E \end{aligned}$ |
| Partial A12 also shown on diagram 14. |  |  |  |  |  |  |  |  |
| ASSEMBLY A16 |  |  |  |  |  |  |  |  |
| C2300 C 2301 C 2302 C 2303 C 2305 C 2306 C 2307 C 2308 C 2309 C 2310 C 2318 C 2320 C 2322 C 2323 C 2324 J 2302 J 2304 J 2601 J 2601 P2105 R2301 $R 2302$ $R 2303$ $R 2304$ $R 2305$ $R 2306$ $R 2307$ $R 2308$ $R 2310$ $R 2311$ $R 2312$ $R 2313$ | 3 H <br> 3L <br> 4L <br> 3L <br> 2 L <br> 2M <br> 3L <br> 3M <br> 4L <br> 4 M <br> 6K <br> 5M <br> 5M <br> 5L <br> 5M <br> 2M <br> 6M <br> 1C <br> 1 M <br> 4B <br> 3 H <br> 3H <br> 2J <br> 3L <br> 4L <br> 6 K <br> 5K <br> 5K <br> 2C <br> 6F <br> 6F <br> 7E | 7B <br> 7 C <br> 7B <br> $7 B$ <br> 7B <br> 7B <br> 7A <br> 7A <br> 7A <br> 7B <br> 7 C <br> 70 <br> 70 <br> 70 <br> 7A <br> 8B <br> 8 E <br> 2A <br> 2A <br> 8G <br> 7 A <br> 7A <br> 6 C <br> 7 A <br> 7B <br> 7C <br> $7 C$ <br> 7 C <br> 2A <br> 7F <br> 7E <br> 7E | R2314 $R 2315$ $R 2316$ $R 2317$ $R 2318$ $R 2319$ $R 2320$ $R 2321$ $R 2322$ $R 2323$ $R 2324$ $R 2325$ $R 2326$ $R 2327$ $R 2328$ $R 2329$ $R 2330$ R2331 R2332 R2333 R2334 R2335 R2336 R2337 R2338 R2339 R2340 R2341 R2342 R2343 R2344 R2345 R2346 R2347 R2348 | 7E <br> 7F <br> 7F <br> 7E <br> 7E <br> 1 K <br> 1 J <br> 1 J <br> 1.」 <br> 6K <br> 1C <br> 4E <br> $7 K$ <br> 7K <br> 2F <br> 2F <br> 2G <br> 2G <br> 2H <br> 2G <br> 2 F <br> 2F <br> 2K <br> 4F <br> 4F <br> 4F <br> 4F <br> 4F <br> $4 F$ <br> 5 H <br> 4 H <br> 5E <br> 5E <br> 5E <br> 5E | 7E <br> 7E <br> $7 E$ <br> 7E <br> 7E <br> 4A <br> 3A <br> 5A <br> 5A <br> 7E <br> 5B <br> 8G <br> 7E <br> 7E <br> 6A <br> 6A <br> 6A <br> 6A <br> 5A <br> 5A <br> 5A <br> 5A <br> 7B <br> 7G <br> 7G <br> 7G <br> 7G <br> 7G <br> 7G <br> 7G <br> 7G <br> 7F <br> 7F <br> 7F <br> 7F | R2349 <br> R2350 <br> R2351 <br> R2352 <br> R2353 <br> R2354 <br> R2355 <br> R2356 <br> R2357 <br> U2300 <br> U2301 <br> U2302 <br> U2303 <br> U2304A <br> U2304B <br> U2304C <br> U2304D <br> U2305A <br> U2305B <br> U2305C <br> U2305D <br> U2306 <br> U2307 <br> U2308 <br> U2309 <br> U2310 <br> U2311 <br> U2312 <br> U2313 <br> U2314 <br> W2105 | 5E <br> 5 H <br> 5 H <br> 6L <br> 7L <br> 7L <br> 8L <br> 8L <br> 8L <br> 2D <br> 1E <br> 3. <br> 1 K <br> 4L <br> 2M <br> 3L <br> 3L <br> 5M <br> 4 M <br> 3M <br> 2L <br> 5K <br> 5D <br> 5. <br> 6J <br> 6G <br> 5G <br> 7G <br> 3G <br> 2J <br> 5B | 7F <br> $7 F$ <br> $7 F$ <br> 70 <br> 7E <br> $7 E$ <br> $7 D$ <br> 70 <br> $7 D$ <br> 5B <br> $5 B$ <br> 6B <br> 7A <br> $7 B$ <br> $7 B$ <br> 7B <br> $7 B$ <br> 78 <br> 78 <br> $7 B$ <br> 7B <br> 7 C <br> $6 E$ <br> 7G <br> 7G <br> $7 F$ <br> 7F <br> 7E <br> 6 E <br> $7 B$ <br> 8G |
| Partial A16 | /so shown | diagrams 8 | 10 and 14 |  |  |  |  |  |

POWER SUPPLY DIAGRAM 12

| ASSEMBLY A18 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT <br> NUMBER | $\begin{aligned} & \text { SCHEM } \\ & \text { LOCATION } \end{aligned}$ | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | SCHEM LOCATION | BOARD LOCATION |
| C2201 | 3H | 5D | CR2234 | 2 C | 3B | R2231 | 7M | 1 J |
| C2202 | 2D | 3D | CR2235 | 4 L | 4 H | R2232 | 6.5 | 1 F |
| C2203 | 5H | 2E | CR2236 | 6. | 1G | R2233 | 6G | $\dagger \mathrm{E}$ |
| C2204 | 3D | 2D | CR2237 | 4G | 3 E | R2236 | 8G | 2 F |
| C2206 | 4G | 4 E |  |  |  | R2237 | 6 E | 1D |
| C2207 | 3E | 3 D | DS2201 | 8M | 2K | R2238 | 6 H | 1E |
| C2208 | $3 E$ | 3D |  |  |  | R2239 | 5 H | 1 E |
| C2209 | 4E | 2E | F2201 | 2A | 2 A | R2240 | $6 E$ | 2D |
| C2210 | 6K | 1G |  |  |  | R2241 | 5H | 1E |
| C2211 | 4E | 2 D | J2208 | 7M | 2K | R2242 | 7 J | 1 G |
| C2212 | 4G | 3 E | J2225 | 6M | 5 H | R2243 | 7K | 1 G |
| C2213 | 2B | 53 | J2726 | 6M | 4K | R2245 | 4F | 3 E |
| C2214 | 1 B | 5A |  |  |  | R2246 | 6E | 20 |
| C2215 | 2B | 4B | L2201 | 2M | 3G | R2247 | 5D | 35 |
| C2216 | 2 B | 1 B | L2202 | 3M | 5 G | R2248 | 3E | 3 D |
| C2217 | 2C | 3 B | 12203 | 5M | 5 H | R2250 | 1 A | 1 C |
| C2218 | 8 H | 2 F | L2204 | 4M | 5 H | R2252 | 6 H | 1 E |
| C2219 | 6. | $1 E$ | L2205 | 4M | 5G | R2253 | 4G | 4 E |
| C2221 | 2 M | 3 F | L2206 | 6 K | 1 J | R2254 | 7 J | 1 G |
| C2222 | 2M | 4G | L2207 | 1 B | 4B | R2255 | 6K | 1 G |
| C2223 | 3M | 3 F | L2208 | 2B | 3B | R2256 | 2D | 2C |
| C2224 | 3M | 4G |  |  |  | R2257 | 6M | 5G |
| C2225 | 5M | 5 F | P2204 | 1M | 4F | R2259 | 8M | 3 K |
| C2226 | 5M | 4 H |  |  |  | R2260 | 1 B | 4A |
| C2227 | 5M | 4 G | 02201 | 4H | 4E | R2265 | 2 D | 2 C |
| C2228 | 5M | 4 H | 02202 | 3G | 3D | R2266 | 8M | 2K |
| C2229 | 4M | 4 F | Q2203 | 4G | 3E | R2267 | 8M | 2K |
| C2230 | 4M | 4 H | Q2204 | 3E | 1 D | R2268 | $6 \sqrt{ }$ | 1 F |
| C2232 | 3M | 4J | Q2206 | 6 F | 1D | R2270 | 8G | 2E |
| C2233 | 4M | $4 J$ | Q2208 | 6 E | 2D | R2271 | 4 F | 3 E |
| C2234 | 5L | 5G | Q2209 | 7J | 1F | R2272 | 7K | 1G |
| C2236 | 6M | 5G | 02210 | 7K | 1E | R2273 | 6 | 1 G |
| C2238 | 6 E | 2 D | 02211 | 2E | 10 | R2274 | 6G | 2 E |
| C2239 | 4 E | 2D | Q2212 | 6G | 2E | R2275 | 5 E | 10 |
| C2243 | 2E | 1 C | 02213 | 6 H | 2E | R2276 | 6. | 1G |
| C2244 | 7M | 1 J | 02214 | 8. | 2F |  |  |  |
| C2245 | 7L | 2 J |  |  |  | RT2,201 | 1 A | 18 |
| C2248 | 6 J | 2G | R2201 | 5 H | 3 E |  |  |  |
| C2249 | 4G | 4D | R2203 | 2D | 20 | S2201 | 1 C | 4B |
|  |  |  | R2204 | 2 D | 20 |  |  |  |
| CR2201 | 4 H | 4E | R2205 | 6 E | 2 D | T2203 | 2 H | 5 C |
| CR2202 | 2G | 2C | R2206 | 4D | 3 D | T2204 | 2K | 2 H |
| CR2204 | 6 J | 1 F | R2207 | 5D | 3 E | T2205 | 6 K | 1 H |
| CR2205 | 6 J | 1F | R2208 | 5 E | $3 E$ | T2206 | 1 C | 5E |
| CR2206 | 2L | 4G | R2209 | 5 E | 3D |  |  |  |
| CR2207 | 2L | 4 G | R2210 | 4 E | 3 D | U2201 | 5F | 3E |
| CR2208 | 6L | 3 H | R2211 | 4 E | 3D | U2230 | 7L | 3 K |
| CR2209 | 5 L | 3 H | R2212 | 4 D | 2E |  |  |  |
| CR2210 | 5 L | 3 H | R2215 | 4 E | 30 | VR2201 | 5 F | 10 |
| CR2211 | 5L | 3 H | R2216 | 4F | $3 E$ | VR2202 | 3 E | 1 C |
| CR2212 | 4L | 3 H | R2218 | 3 E | 20 | VR2203 | 4 H | 4 E |
| CR2213 | 4L | 3 H | R2219 | 3D | 1 C | VR2204 | 2A | 1 A |
| CR2214 | 4L | 3 J | R2220 | 3 E | 1 C | VR2205 | 5G | 1 E |
| CR2215 | 4 M | 3 H | R2221 | 2E | 1 C | VR2206 | 3D | 2 C |
| CR2216 | 4M | 3 J | R2222 | 2 E | 1 C | VR2207 | 8J | 2 F |
| CR2218 | 3M | 3 J | R2223 | 3D | 1 C |  |  |  |
| CR2219 | 3L | 3 H | R2224 | 6 F | 10 | W28 | 2 A | 2 C |
| CR2220 | 3L | 3G | R2225 | 6 F | 10 | W29 | 1A | 2 C |
| CR2227 | 7」 | 1 G | R2226 | 2A | 2 B | W31 | 2E | 3D |
| CR2228 | 7 K | 1 G | R2227 | 1 B | 4A | W32 | 3 E | 4 D |
| CR2231 | 2 C | 3B | R2228 | 2B | 2 B | W2201 | $7 J$ | 1 F |
| CR2232 | 1 C | 2B | R2229 | 1 C | 4 C |  |  |  |
| CR2233 | 1 C | 3B | R2230 | 1 C | 4 C |  |  |  |
| CHASSIS MOUNTED PARTS |  |  |  |  |  |  |  |  |
| B25 | 6N | CHASSIS | P25 | 6 N | CHASSIS |  |  |  |
| FL2201 | 2A | CHASSIS | S2202 | 3E | CHASSIS |  |  |  |

## MAIN BOARD POWER DISTRIBUTION DIAGRAM 13

| ASSEMBLY A8 |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | SCHEM LOCATION | BOARD LOCATION | CIRCUIT <br> NUMBER | SCHEM LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEM <br> LOCATION | BOARD LOCATION | CIRCUIT <br> NUMBER | SCHEM LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| W900 | 5M | 1 E |  |  |  |  |  |  |  |  |  |
| Partial 48 also shown on diagram 7. |  |  |  |  |  |  |  |  |  |  |  |
| ASSEMBLY A10 |  |  |  |  |  |  |  |  |  |  |  |
| C135 | 70 | 2B | C613 | 2 E | 4K | R390 | 1K | 8F | U602 | 1F | 3K |
| C136 | 8E | 2B | C701 | 3H | 10K | R392 | 8 F | 7 C | U603 | 1G | 3M |
| C140 | 8 D | 1 C | C702 | 3J | 9 J | R481 | 1 C | 2G | U604 | 2F | 5M |
| C155 | 7E | 1 B | C 703 | 3J | 10K | R504 | 1 M | 9C | U606 | 2F | 5M |
| C156 | 8E | 1B | C704 | 3 J | 9K | R701 | 3 H | 9 J | U701 | 3.1 | 9J |
| C171 | 5A | 2B | C 705 | 4A | 9G | R709 | 3 J | 9 H | U702 | 3 J | 9K |
| C172 | 1A | 3C | C708 | 3 H | 9 J | R723 | 5 H | 9 J | U801 | 5G | 7H |
| C180 | 8 D | 6D | C801 | 4A | 8K | R733 | 3 J | 10K | U802 | 6 J | 8 H |
| C181 | 7A | 6D | C806 | 5G | 8 H | R734 | 4B | 9G | U901A | 5 K | 9A |
| C205 | 3 H | 10 H | C815 | 6 J | 7H | R837 | 7 J | 8K | U901B | 5L | 9A |
| C206 | 3 H | 10 H | C816 | 7 J | 8 H | R915 | 5L | 9A | U901 | 5J | 9A |
| C214 | 7 B | 4D | C818 | 4B | 7 K | R916 | 5L | 9A | U930 | 5 J | 7B |
| C215 | 7 B | 5D | C901 | 5K | 9A | R1026 | 8F | 7M | U931 | 3L | 9B |
| C216 | 2 B | 5G | C902 | 5K | 7A | R1027 | 6 F | 8L | U932 | 5K | 7 A |
| C217 | 1B | 4H | C 903 | 5M | 8A | R1101 | 6G | 1 J | U1001 | 7F | 7 L |
| C219 | 7B | 5D | C904 | 5M | 9B | R1102 | 8G | 1 J | U1101 | 7 H | 2M |
| C224 | 7B | 3D | C1005 | 7F | 7M | R1158 | 1L | 2J | U1102 | 7 H | 1L |
| C 225 | 7 B | 3D | C1006 | 7F | 8L | R1159 | 3M | 2 J | U1103 | 1L | 2K |
| C229 | 7B | 3D | C1101 | 6G | 1M | R2783 | 4D | 7N | U1104 | 2L | 2M |
| C234 | 7 C | 2D | C1102 | 8G | 2M |  |  |  | U1106 | 2M | 2 J |
| C235 | 7 C | 2D | C1158 | 1L | 2K | U112 | 7 D | 6 C |  |  |  |
| C239 | 7 C | 2D | C1159 | 3M | 2 J | U122 | 7 D | 4 C | W103 | 6 A | 6D |
| C244 | 7D | 1D | C2701 | 5 H | 7L | U171 | 5A | 3B | W235 | 7E | 5D |
| C245 | 7 C | 1 D | C2702 | 8G | 6 L | U172 | 6 A | 3B | W900 | 5M | 9B |
| C249 | 7D | 1 D | C2709 | 4E | 7M | U173 | 1 A | 3 C | W1103 | 2L. | 1 K |
| C265 | 5B | 5 F |  |  |  | U201 | 1B | 5 H | W1200 | 1 H | 6 F |
| C282 | 3B | 4F | J1204 | 1A | 5 J | U202 | 1 B | 5G | W1201 | 3 L | 8 C |
| C283 | 6 B | 6 F |  |  |  | U203 | 3H | 10G | W1 202 | 2 H | 9 H |
| C297 | 3C | 5 F | L101 | 5A | 2C | U210 | 7 B | 5D | W1204 | 1 H | 7G |
| C 298 | 3B | 3 F | L102 | 8D | 2 C | U220 | 7B | 4D | W1205 | 2 E | 4 N |
| C304 | 50 | 70 | L201 | 6A | 6E | U230 | 7 C | 3E | W1209 | 1E | 2 J |
| C309 | 2H | 6 H | L216 | 2B | 4 H | U240 | 7 C | 2E | W1210 | 1 E | 4K |
| C316 | 5C | 8 E | L217 | 1B | 5 H | U260 | 5B | 5 F | W1216 | 3L | 8 C |
| C317 | 1K | 8 E | L445 | 1 C | 3 H | U301 | 1K | 8 D | W1217 | 3G | 6 H |
| C318 | 8. | 9 E | L446 | 2 C | 4H | U302 | 5 E | 8 C | W1218 | 3G | 5 H |
| C320 | 1H | 8 F | L475 | 1 C | 1 J | U303 | 5E | 9 C | W1221 | 3B | 4 H |
| C337 | 5D | 9E | L476 | 2 D | 2 H | U304 | 5 F | 8D | W1222 | 8B | 6D |
| C338 | 8A | 8G |  |  |  | U307 | 5E | 7 D | W1223 | 3K | 6D |
| C339 | 8B | 9G | P2302 | 8M | 10 D | U308 | 5E | 7 D | W1231 | $6 F$ | 8K |
| C351 | 5 F | 7 C | P2502 | 1 N | 1L | U309 | 5 F | 7 C | W1237 | 8 F | 6 K |
| C445 | 1 C | 3G |  |  |  | U310 | 5E | 9 D | W1247 | 5C | 6D |
| C475 | 1 C | 1G | R182 | 8D | 6 D | U311 | 5E | 9 D | W1248 | 5G | 6 H |
| C481 | 2 C | 3G | R208 | 3H | 10 H | U315 | 1 H | 8F | W1249 | 5G | 5 H |
| C482 | 2 D | 2G | R226 | 78 | 6 E | U316 | 2 H | 7 H | W1250 | 5 H | 7 K |
| C501 | 1 E | 2N | R245 | 7 C | 3D | U421 | 2 C | 3G | W1251 | 8 A | 6H |
| C502 | 1 E | 2N | R282 | 3B | 3F | U431 | 2 C | 2G | W1252 | 8A | 5 H |
| C503 | 3 E | 5 N | R283 | 6B | 6 F | U441 | 1D | 2 H | W1255 | 5B | 6 F |
| C505 | 2M | 9 C | R297 | 3C | 6 F | U501 | 1E | 3N | W1277 | 4D | 8 K |
| C604 | 2 F | 5M | R298 | 3B | 3 F | U502 | 2E | 3N | W2302 | 8M | 10D |
| C605 | 1 F | 4L | R312 | 5D | 7 C | U503 | 3E | 5 N | W2502 | 1M | 1 L |
| C606 | 1F | 2 J | R339 | 8. | BE | U506 | 2M | 9 C |  |  |  |
| C609 | 1G | 3M | R345 | 5C | 8E | U600 | 1E | 4L |  |  |  |
| C610 | 2 F | 5N | R374 | 5D | 10E | U601 | 2E | 5 K |  |  |  |

[^12]PROCESSOR BOARD POWER DISTRIBUTION DIAGRAM 14


## A10-MAIN BOARD

| CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AT117 | 1 | C235 | 13 | C493 | 2 | C2708 | 7 | K108 | 1 | Q600 | 4 |
| AT127 | 1 | C238 | 2 | C494 | 2 | C2709 | 13 | K109 | 1 | Q601 | 4 |
|  |  | C239 | 13 | C501 | 13 | C2710 | 7 | K110 | 1 | Q602 | 4 |
| C1 | 1 | C242 | 2 | C502 | 13 | C2711 | 7 | K111 | 1 | Q603 | 4 |
| C2 | 1 | C243 | 2 | C503 | 13 | C2712 | 7 | K112 | 1 | Q604 | 4 |
| C10 | 1 | C244 | 13 | C505 | 13 | C2713 | 7 |  |  | Q605 | 4 |
| C11 | 1 | C245 | 13 | C600 | 4 | C2715 | 7 | L101 | 13 | Q606 | 4 |
| C20 | 1 | C248 | 2 | C601 | 4 | C2716 | 7 | L102 | 13 | Q607 | 4 |
| C21 | 1 | C249 | 13 | C602 | 4 | C2717 | 7 | L130 | 1 | Q608 | 4 |
| C101 | 1 | C258 | 2 | C603 | 4 | C2719 | 7 | L140 | 1 | Q701 | 2 |
| C102 | 1 | C265 | 13 | C604 | 13 | C2720 | 7 | L201 | 13 | Q702 | 2 |
| C103 | 1 | C268 | 2 | C605 | 13 | C2721 | 7 | L216 | 13 | Q703 | 2 |
| C104 | 1 | C271 | 2 | C606 | 13 | C2723 | 7 | L217 | 13 | Q704 | 2 |
| C105 | 1 | C272 | 2 | C607 | 4 | C2724 | 7 | L426 | 3 | Q801 | 6 |
| C106 | 1 | C273 | 2 | C608 | 4 | C2758 | 7 | $\llcorner 432$ | 3 | Q802 | 6 |
| C107 | 1 | C274 | 2 | C609 | 13 | C2759 | 7 | L445 | 13 | Q803 | 6 |
| C108 | 1 | C275 | 2 | C610 | 13 | C2783 | 7 | L446 | 13 | Q804 | 6 |
| C111 | 1 | C282 | 13 | C611 | 3 | C2784 | 7 | $\llcorner 462$ | 3 | Q805 | 6 |
| C112 | 1 | C283 | 13 | C612 | 4 | C2785 | 7 | L475 | 13 | Q806 | 6 |
| C113 | 1 | C297 | 13 | C613 | 13 |  |  | $\llcorner 476$ | 13 | Q807 | 6 |
| C114 | 1 | C298 | 13 | C701 | 13 | CR131 | 1 | L701 | 2 | Q808 | 6 |
| C121 | 1 | C301 | 5 | C702 | 13 | CR151 | 1 | L702 | 2 | Q809 | 6 |
| C122 | 1 | C302 | 5 | C703 | 13 | CR171 | 1 | $L 703$ | 2 | Q810 | 6 |
| C123 | 1 | C303 | 5 | C704 | 13 | CR201 | 2 | L. 704 | 2 | Q905 | 7 |
| C124 | 1 | C304 | 13 | C705 | 13 | CR202 | 2 |  |  | Q907 | 7 |
| C125 | 1 | C305 | 5 | C706 | 2 | CR260 | 2 | P8 | 7 | Q908 | 7 |
| C126 | 1 | С306 | 5 | 'C707 | 2 | CR261 | 2 | P9 | 7 | Q1001 | 7 |
| C131 | 1 | C307 | 5 | C708 | 13 | CR301 | 5 | P17 | 6 | Q1002 | 7 |
| C132 | 1 | C308 | 5 | C711 | 2 | CR432 | 3 | P18 | 6 | Q1003 | 7 |
| C133 | 1 | C309 | 13 | C712 | 2 | CR462 | 3 | P19 | 2 | Q1004 | 7 |
| C134 | 1 | C310 | 5 | C801 | 13 | CR603 | 4 | P20 | 2 | Q1005 | 7 |
| C135 | 13 | C311 | 5 | C802 | 6 | CR801 | 6 | P2302 | 7 | Q1101 | 3 |
| C136 | 13 | C312 | 5 | C803 | 6 | CR802 | 6 | P2302 | 13 | Q1102 | 3 |
| C137 | 1 | C313 | 5 | C804 | 6 | CR819 | 6 | P2304 | 7 | Q1103 | 3 |
| C138 | 1 | C314 | 5 | C805 | 6 | CR935 | 7 | P2502 | 4 | Q1104 | 3 |
| C139 | 2 | C315 | 5 | C806 | 13 | CR936 | 7 | P2502 | 13 | Q1105 | 3 |
| C140 | 13 | C316 | 13 | C807 | 6 | CR1001 | 7 |  |  | Q1106 | 3 |
| C151 | 1 | C317 | 13 | C808 | 6 | CR1002 | 7 | Q131 | 1 | Q2701 | 7 |
| C152 | 1 | C318 | 13 | C809 | 6 | CR1003 | 7 | Q151 | 1 | Q2702 | 7 |
| C153 | 1 | C319 | 6 | C810 | 6 | CR1004 | 7 | Q171 | 1 | Q2703 | 7 |
| C154 | 1 | C320 | 13 | C811 | 2 | CR1005 | 7 | Q250 | 2 | Q2704 | 7 |
| C155 | 13 | C321 | 5 | C814 | 6 | CR2701 | 7 | Q251 | 2 | Q2705 | 7 |
| C156 | 13 | C326 | 5 | C815 | 13 | CR2702 | 7 | Q252 | 2 | Q2706 | 7 |
| C157 | 1 | C329 | 5 | C816 | 13 | CR2703 | 7 | Q253 | 2 | Q2707 | 7 |
| C158 | 1 | С330 | 5 | C817 | 6 | CR2704 | 7 | Q284 | 2 | Q2708 | 7 |
| C159 | 2 | C337 | 13 | C818 | 13 | CR2705 | 7 | Q285 | 2 | Q2709 | 7 |
| C171 | 13 | C338 | 13 | C819 | 6 | CR2707 | 7 | Q301 | 5 | Q2711 | 7 |
| C172 | 13 | C339 | 13 | C901 | 13 | CR2713 | 7 | Q302 | 5 | Q2712 | 7 |
| C173 | 1 | C351 | 13 | C902 | 13 | CR2714 | 7 | Q303 | 5 | Q2713 | 7 |
| C180 | 13 | C421 | 3 | C903 | 13 | CR2715 | 7 | Q304 | 5 | Q2715 | 7 |
| C181 | 13 | C422 | 3 | C904 | 13 | CR2716 | 7 | Q305 | 5 |  |  |
| C190 | 1 | C423 | 3 | C910 | 7 | CR2717 | 7 | Q306 | 5 | R12 | 1 |
| C191 | 1 | C424 | 3 | C935 | 7 | CR2718 | 7 | Q307 | 5 | R13 | 1 |
| C201 | 2 | C425 | 3 | C1001 | 7 |  |  | Q308 | 5 | R22 | 1 |
| C202 | 2 | C426 | 3 | C1002 | 7 | DL21 | 2 | Q309 | 5 | R23 | 1 |
| C203 | 2 | C432 | 3 | C1003 | 7 | DL22 | 4 | Q310 | 5 | R101 | 1 |
| C204 | 2 | C444 | 3 | C1004 | 7 |  |  | Q311 | 5 | R102 | 1 |
| C205 | 13 | C445 | 13 | C1005 | 13 | DS901 | 7 | Q312 | 5 | R103 | 1 |
| C206 | 13 | C447 | 3 | C1006 | 13 | DS902 | 7 | Q313 | 5 | R104 | 1 |
| C210 | 2 | C451 | 3 | C1101 | 13 | DS903 | 7 | Q315 | 5 | R105 | 1 |
| C211 | 2 | C452 | 3 | C1102 | 13 | DS2701 | 7 | Q316 | 5 | R106 | 1 |
| C212 | 2 | C453 | 3 | C1103 | 3 | DS2702 | 7 | Q317 | 5 | R107 | 1 |
| C213 | 2 | C454 | 3 | C1105 | 3 | DS2703 | 7 | Q318 | 5 | R108 | 1 |
| C214 | 13 | C455 | 3 | C1106 | 3 | DS2704 | 7 | Q320 | 5 | R111 | 1 |
| C215 | 13 | C462 | 3 | C1107 | 3 |  |  | Q321 | 5 | R113 | 1 |
| C216 | 13 | C463 | 3 | C1110 | 3 | J11 | 1 | Q322 | 5 | R114 | 1 |
| C217 | 13 | C474 | 3 | C1111 | 3 | J12 | 1 | Q323 | 5 | R115 | 2 |
| C218 | 2 | C475 | 13 | C1114 | 3 | J13 | 1 | Q325 | 5 | R121 | 1 |
| C219 | 13 | C477 | 3 | C1130 | 3 | J14 | 1 | Q326 | 5 | R123 | 1 |
| C220 | 2 | C481 | 13 | C1154 | 3 | J15 | 7 | Q328 | 5 | R124 | 1 |
| C221 | 2 | C482 | 13 | C1155 | 3 | J927 | 7 | Q329 | 5 | R125 | 2 |
| C222 | 2 | C483 | 3 | C1158 | 13 | J1204 | 13 | Q330 | 5 | R131 | 1 |
| C223 | 2 | C484 | 3 | C1159 | 13 |  |  | Q331 | 5 | R132 | 1 |
| C224 | 13 | C485 | 3 | C2701 | 13 | K100 | 1 | Q332 | 5 | R133 | 1 |
| C225 | 13 | C486 | 3 | C2702 | 13 | K101 | 1 | Q333 | 5 | R134 | 1 |
| C228 | 2 | C487 | 3 | C2703 | 7 | K102 | 1 | Q440 | 3 | R135 | 1 |
| C229 | 13 | C488 | 3 | C2704 | 7 | K103 | 1 | Q444 | 3 | R136 | 1 |
| C232 | 2 | C489 | 3 | C2705 | 7 | K104 | 1 | Q470 | 3 | R137 | 1 |
| C 233 | 2 | C491 | 2 | C2706 | 7 | K105 | 1 | Q474 | 3 | R138 | 2 |
| C234 | 13 | C492 | 2 | C2707 | 7 | K107 | 1 | Q480 | 3 | R139 | 1 |


| CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R140 | 2 | R270 | 2 | R353 | 6 | R463 | 3 | R652 | 4 | R845 | 6 |
| R141 | 1 | R271 | 2 | R354 | 5 | R470 | 3 | R653 | 4 | R846 | 6 |
| R142 | 1 | R272 | 2 | R355 | 5 | R471 | 3 | R654 | 4 | R847 | 6 |
| R151 | 1 | R273 | 2 | R356 | 5 | R472 | 3 | R655 | 4 | R848 | 6 |
| R152 | 1 | R274 | 2 | R357 | 5 | R473 | 3 | R656 | 4 | R849 | 6 |
| R153 | 1 | R275 | 2 | R358 | 6 | R474 | 3 | R657 | 4 | R850 | 6 |
| R154 | 1 | R276 | 2 | R359 | 5 | R475 | 3 | R658 | 4 | R851 | 6 |
| R155 | 1 | R277 | 2 | R360 | 5 | R476 | 3 | R659 | 4 | R852 | 6 |
| R156 | 1 | R278 | 2 | R361 | 5 | R477 | 3 | R662 | 4 | R853 | 6 |
| R157 | 1 | R279 | 2 | R362 | 5 | R478 | 3 | R663 | 4 | R854 | 6 |
| R158 | 2 | R280 | 2 | R363 | 5 | R481 | 13 | R664 | 4 | R855 | 6 |
| R159 | 1 | R281 | 2 | R364 | 5 | R483 | 3 | R665 | 4 | R856 | 6 |
| R160 | 2 | R282 | 13 | R365 | 5 | R484 | 3 | R666 | 4 | R857 | 6 |
| R161 | 1 | R283 | 13 | R366 | 5 | R485 | 3 | R669 | 4 | R858 | 6 |
| R162 | 1 | R284 | 2 | R367 | 5 | R486 | 3 | R670 | 4 | R906 | 7 |
| R171 | 1 | R285 | 2 | R369 | 6 | R487 | 3 | R671 | 4 | R907 | 7 |
| R175 | 1 | R286 | 2 | R370 | 5 | R490 | 3 | R672 | 4 | R908 | 7 |
| R176 | 1 | R287 | 2 | R371 | 5 | R491 | 3 | R701 | 13 | R909 | 7 |
| R177 | 1 | R288 | 2 | R372 | 5 | R492 | 3 | R702 | 2 | R910 | 7 |
| R178 | 1 | R289 | 2 | R373 | 5 | R493 | 3 | R703 | 2 | R911 | 7 |
| R179 | 1 | R290 | 2 | R374 | 13 | R494 | 3 | R706 | 2 | R915 | 13 |
| R180 | 1 | R291 | 2 | R375 | 5 | R495 | 3 | R707 | 2 | R916 | 13 |
| R181 | 1 | R292 | 2 | R376 | 5 | R496 | 3 | R708 | 2 | R920 | 7 |
| R182 | 13 | R293 | 2 | R377 | 5 | R497 | 3 | R709 | 13 | R921 | 7 |
| R201 | 2 | R294 | 2 | R378 | 5 | R498 | 3 | R710 | 2 | R922 | 7 |
| R202 | 2 | R295 | 2 | R379 | 5 | R501 | 4 | R711 | 2 | R923 | 7 |
| R203 | 2 | R296 | 2 | R380 | 5 | R502 | 4 | R712 | 2 | R924 | 7 |
| R204 | 2 | R297 | 13 | R381 | 5 | R503 | 7 | R715 | 2 | R930 | 7 |
| R205 | 2 | R298 | 13 | R382 | 5 | R504 | 13 | R716 | 2 | R931 | 7 |
| R206 | 2 | R301 | 5 | R383 | 5 | R505 | 7 | R717 | 2 | R932 | 7 |
| R207 | 2 | R302 | 5 | R384 | 5 | R506 | 7 | R718 | 2 | R933 | 7 |
| R208 | 13 | R303 | 5 | R385 | 5 | R507 | 7 | R719 | 2 | R934 | 7 |
| R209 | 2 | R304 | 5 | R386 | 5 | R508 | 7 | R720 | 2 | R935 | 7 |
| R210 | 2 | R305 | 5 | R387 | 5 | R510 | 7 | R721 | 2 | R936 | 7 |
| R211 | 2 | R306 | 5 | R388 | 5 | R512 | 7 | R722 | 2 | R937 | 7 |
| R212 | 2 | R307 | 5 | R390 | 13 | R601 | 4 | R723 | 13 | R938 | 7 |
| R213 | 2 | R308 | 5 | R391 | 5 | R602 | 4 | R724 | 2 | R939 | 7 |
| R214 | 2 | R309 | 5 | R392 | 13 | R603 | 4 | R725 | 2 | R940 | 7 |
| R215 | 2 | R310 | 5 | R393 | 5 | R604 | 4 | R726 | 2 | R1001 | 7 |
| R218 | 2 | R311 | 5 | R394 | 5 | R605 | 4 | R727 | 2 | R1002 | 7 |
| R219 | 2 | R312 | 13 | R395 | 5 | R606 | 4 | R728 | 2 | R1003 | 7 |
| R220 | 2 | R313 | 5 | R396 | 5 | R607 | 3 | R729 | 2 | R1004 | 7 |
| R221 | 2 | R314 | 5 | R410 | 3 | R609 | 4 | R730 | 2 | R1005 | 7 |
| R222 | 2 | R315 | 5 | R411 | 3 | R610 | 4 | R731 | 2 | R1006 | 7 |
| R223 | 2 | R316 | 5 | R412 | 3 | R611 | 4 | R732 | 2 | R1007 | 7 |
| R224 | 2 | R317 | 5 | R413 | 3 | R612 | 4 | R733 | 13 | R1008 | 7 |
| R225 | 2 | R318 | 5 | R414 | 3 | R613 | 4 | R734 | 13 | R1009 | 7 |
| R226 | 13 | R319 | 5 | R415 | 3 | R614 | 4 | R801 | 6 | R1010 | 7 |
| R227 | 2 | R320 | 5 | R416 | 3 | R615 | 4 | R802 | 6 | R1020 | 7 |
| R228 | 2 | R321 | 5 | R417 | 3 | R616 | 4 | R803 | 6 | R 1021 | 7 |
| R229 | 2 | R322 | 5 | R420 | 3 | R617 | 4 | R804 | 6 | R1022 | 7 |
| R230 | 2 | R323 | 5 | R 421 | 3 | R618 | 4 | R805 | 6 | R1023 | 7 |
| R231 | 2 | R325 | 5 | R422 | 3 | R619 | 4 | R806 | 6 | R1024 | 7 |
| R232 | 2 | R326 | 5 | R423 | 3 | R620 | 4 | R807 | 6 | R1025 | 7 |
| R233 | 2 | R327 | 5 | R424 | 3 | R621 | 4 | R808 | 6 | R1026 | 13 |
| R234 | 2 | R328 | 5 | R425 | 3 | R622 | 4 | R809 | 6 | R1027 | 13 |
| R235 | 2 | R329 | 5 | R426 | 3 | R623 | 4 | R810 | 6 | R1028 | 7 |
| R238 | 2 | R330 | 5 | R430 | 3 | R624 | 4 | R811 | 6 | R1101 | 13 |
| R240 | 2 | R331 | 5 | R431 | 3 | R625 | 4 | R812 | 6 | R1102 | 13 |
| R241 | 2 | R332 | 5 | R432 | 3 | R626 | 4 | R813 | 6 | R1103 | 3 |
| R242 | 2 | R333 | 5 | R440 | 3 | R627 | 4 | R814 | 6 | R1104 | 3 |
| R243 | 2 | R334 | 5 | R441 | 3 | R628 | 4 | R815 | 6 | R1110 | 3 |
| R244 | 2 | R335 | 5 | R442 | 3 | R630 | 4 | R816 | 6 | R1111 | 3 |
| R245 | 13 | R336 | 5 | R443 | 3 | R631 | 4 | R819 | 6 | R1112 | 3 |
| R248 | 2 | R337 | 5 | R444 | 3 | R636 | 4 | R820 | 6 | R1113 | 3 |
| R250 | 2 | R338 | 5 | $R 445$ | 3 | R637 | 4 | R821 | 6 | R1114 | 3 |
| R251 | 2 | R339 | 13 | R446 | 3 | R638 | 4 | R822 | 6 | R1115 | 3 |
| R254 | 2 | R340 | 5 | R447 | 3 | R639 | 4 | R823 | 6 | R1116 | 3 |
| R255 | 2 | R341 | 5 | R448 | 3 | R640 | 4 | R825 | 6 | R1117 | 3 |
| R256 | 2 | R342 | 5 | R449 | 3 | R641 | 4 | R826 | 6 | R1118 | 3 |
| R260 | 2 | R343 | 5 | R450 | 3 | R642 | 4 | R827 | 6 | R1120 | 3 |
| R261 | 2 | R344 | 5 | R451 | 3 | R643 | 4 | R828 | 6 | R1121 | 3 |
| R262 | 2 | R345 | 13 | R452 | 3 | R644 | 4 | R829 | 6 | R1122 | 3 |
| R263 | 2 | R346 | 5 | R453 | 3 | R645 | 4 | R836 | 6 | R1123 | 3 |
| R264 | 2 | R347 | 5 | R454 | 3 | R646 | 4 | R837 | 13 | R1124 | 3 |
| R265 | 2 | R348 | 5 | R455 | 3 | R647 | 4 | R840 | 6 | R1125 | 3 |
| R266 | 2 | R349 | 5 | R456 | 3 | R648 | 4 | R841 | 6 | R1126 | 3 |
| R267 | 2 | R350 | 5 | R460 | 3 | R649 | 4 | $\mathrm{R842}$ | 6 | R1127 | 3 |
| R268 | 2 | R351 | 5 | R461 | 3 | R650 | 4 | R843 | 6 | R1128 | 3 |
| R269 | 2 | R352 | 5 | R462 | 3 | R651 | 4 | R844 | 6 | R1131 | 3 |


| A10-MAIN BOARD (cont) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEM <br> NUMBER | CIRCUIT NUMBER | SCHEM <br> NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER |
| R1132 | 3 | R2739 | 7 | U301 | 5 | U701 | 2 | W19 | 2 | W811 | 6 |
| R1133 | 3 | R2740 | 7 | U301 | 6 | U701 | 13 | W20 | 2 | W815 | 2 |
| R1134 | 3 | R2741 | 7 | U301 | 13 | U702 | 2 | W100 | 1 | W900 | 13 |
| R1135 | 3 | R2742 | 7 | U302 | 5 | U702 | 13 | W101 | 1 | W906 | 7 |
| R1136 | 3 | R2743 | 7 | U302 | 13 | U801 | 2 | W102 | 1 | W1000 | 7 |
| R1142 | 3 | R2745 | 7 | U303 | 5 | U801 | 6 | W103 | 13 | W1010 | 7 |
| R1143 | 3 | R2750 | 7 | U303 | 13 | U801 | 13 | W200 | 2 | W1101 | 3 |
| R1144 | 3 | R2751 | 7 | U304 | 5 | U802 | 6 | W201 | 2 | W1102 | 3 |
| R1145 | 3 | R2758 | 7 | U304 | 13 | U802 | 13 | W202 | 2 | W1103 | 13 |
| R1150 | 3 | R2760 | 7 | U307 | 5 | U901 | 13 | W203 | 2 | W1104 | 3 |
| R1154 | 3 | R2765 | 7 | U307 | 13 | U930 | 7 | W205 | 2 | W1105 | 3 |
| R1155 | 3 | R2783 | 13 | U308 | 5 | U930 | 13 | W206 | 2 | W1106 | 3 |
| R1158 | 13 | R2784 | 7 | U308 | 13 | U931 | 7 | W207 | 2 | W1107 | 3 |
| R1159 | 13 | R2785 | 7 | U309 | 5 | U931 | 13 | W208 | 2 | W1120 | 3 |
| R1162 | 3 | R2786 | 7 | U309 | 13 | U932 | 13 | W209 | - 2 | W1200 | 13 |
| R1163 | 3 | R2787 | 7 | U310 | 5 | U1001 | 7 | W210 | $\cdots 2$ | W1201 | 13 |
| R1170 | 3 | R2788 | 7 | U310 | 13 | U1001 | 13 | W223 | 2 | W1202 | 13 |
| R2701 | 7 | R2789 | 7 | U311 | 5 | U1101 | 3 | W231 | 2 | W1204 | 13 |
| R2702 | 7 | R2795 | 7 | U311 | 13 | U1101 | 7 | W232 | 2 | W1205 | 13 |
| R2703 | 7 | R2796 | 7 | U313 | 5 | U1101 | 13 | W235 | 13 | W1209 | 13 |
| R2704 | 7 |  |  | U315 | 5 | U1102 | 3 | W304 | 5 | W1210 | 13 |
| R2705 | 7 | U112 | 1 | U315 | 13 | U1102 | 13 | W305 | 6 | W1216 | 13 |
| R2706 | 7 | U112 | 13 | U316 | 5 | U1103 | 3 | W401 | 3 | W1217 | 13 |
| -R2708 | 7 | U122 | 1 | U316 | 13 | U1103 | 13 | W403 | 3 | W1218 | 13 |
| R2709 | 7 | U122 | 13 | U421 | 3 | U1104 | 3 | W404 | 3 | W1221 | 13 |
| R2710 | 7 | U171 | 1 | U 421 | 13 | U1104 | 13 | W405 | 3 | W1222 | 13 |
| R2711 | 7 | U171 | 13 | U431 | 3 | U1106 | 3 | W406 | 3 | W1223 | 13 |
| R2712 | 7 | U172 | 1 | U431 | 13 | U1106 | 13 | W407 | 3 | W1231 | 13 |
| R2713 | 7 | U172 | 13 | U441 | 3 |  |  | W408 | 3 | W1237 | 13 |
| R2714 | 7 | U173 | 1 | U441 | 13 | VR301 | 5 | W410 | 3 | W1247 | 13 |
| R2715 | 7 | U173 | 13 | U501 | 4 | VR302 | 5 | W411 | 3 | W1248 | 13 |
| R2716 | 7 | U174 | 1 | U501 | 13 | VR303 | 5 | W412 | 3 | W1249 | 13 |
| R2717 | 7 | U175 | 1 | 4502 | 4 | VR304 | 5 | W413 | 3 | W1250 | 13 |
| R2718 | 7 | U201 | 2 | U502 | 13 | VR308 | 5 | W414 | 3 | W1251 | 13 |
| R2719 | 7 | U201 | 13 | $\cup 503$ | 4 | VR309 | 5 | W415 | 2 | W1252 | 13 |
| R2720 | 7 | U202 | 2 | $\cup 503$ | 13 | VR310 | 5 | W416 | 2 | W1255 | 13 |
| R2721 | 7 | U202 | 13 | U506 | 7 | VR311 | 5 | W505 | 4 | W1277 | 13 |
| R2722 | 7 | U203 | 2 | U506 | 13 | VR312 | 5 | W510 | 4 | W1288 | 7 |
| R2723 | 7 | U203 | 13 | U600 | 4 | VR801 | 6 | W603 | 4 | W2302 | 7 |
| R2724 | 7 | U210 | 2 | U600 | 13 | VR802 | 6 | W604 | 4 | W2302 | 13 |
| R2726 | 7 | U210 | 13 | U601 | 4 | VR2701 | 7 | W605 | 4 | W2304 | 7 |
| R2727 | 7 | U220 | 2 | U601 | 13 |  |  | W610 | 4 | W2502 | 4 |
| R2728 | 7 | U220 | 13 | U602 | 4 | W9 | 7 | W611 | 4 | W2502 | 13 |
| R2729 | 7 | U230 | 2 | U602 | 13 | W11 | 1 | W612 | 4 | W2701 | 7 |
| R2733 | 7 | U230 | 13 | U603 | 4 | W12 | 1 | W802 | 5 |  |  |
| R2734 | 7 | U240 | 2 | U603 | 13 | W13 | 1 | W805 | 6 | Y600 | 4 |
| R2735 | 7 | U240 | 13 | U604 | 4 | W14 | 1 | W806 | 6 |  |  |
| R2736 | 7 | U260 | 2 | U604 | 13 | W16 | 7 | W807 | 6 |  |  |
| R2737 | 7 | U260 | 13 | U606 | 4 | W17 | 6 | W808 | 6 |  |  |
| R2738 | 7 | U280 | 2 | U606 | 13 | W18 | 6 | W810 | 6 |  |  |


| A12-POT BOARD |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUTT Number | SCHEM NUMBER | CIRCUT Number | SCHEM Number | CIRCUIT numben | SCHEM NUMBER |
| J2105 | 11 | R2104 | 11 | R2110 | 11 |
| J2105 | 14 | R2105 | 11 | R2111 | 11 |
|  |  | R2106 | 11 | R2112 | 11 |
| R2101 | 11 | R2107 | 11 | R2113 | 11 |
| R2102 | 11 | R2108 R2109 | 11 |  |  |
| R2103 | 11 | R2109 | 11 |  |  |



| A14-SWITCH BOARD |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| chevt <br> NUWEER | SCHEM NUKBER | CIRCUT <br> Numben | SCHEM <br> numaer | CIRCUT NUMEX | SCNEM <br> NUNEER |
| C200\% | 14 | 0\$2033 | 10 | \$2015 | 10 |
|  |  | 082034 | 10 | \$20:6 | \% 0 |
| CR200\% | 10 | DS2035 | 10 | \$2077 | 10 |
| CR2002 | \% | 0S2006 | 10 | \$20:3 | 10 |
| CR2003 | 10 | 0S2037 | 10 | \$2019 | \% |
| $\mathrm{C}_{2} 2004$ | 10 | 0\$2038 | 10 | \$2020 | :0 |
| CR2005 | 10 | 052039 | 10 | \$202\% | 10 |
| CR2006 | 10 | 052041 | 10 | \$2022 | \$0 |
|  |  | 052042 | 10 | \$2024 | 10 |
| 0s200\% | 10 | 0S2043 | 10 | \$2026 | 10 |
| 052002 | 10 | DS2044 | 10 | \$2028 | 10 |
| OS2003 | 10 | DS2045 | 10 | 52030 | 10 |
| OS2004 | 10 | DS2046 | 10 | \$203\% | 10 |
| 0\$2005 | 10 | 052047 | 10 | \$2033 | :0 |
| 052005 | 10 | DS2048 | 10 | S2034 | 10 |
| 7S2007 | 10 |  |  | S2035 | 10 |
| 052008 | 10 | P2501 | 10 | S2036 | 10 |
| 052009 | 10 | P250\% | 14 | 52037 | 10 |
| OS2000 | 10 |  |  | \$2038 | 10 |
| DS201\% | 10 | R200\% | 10 | \$2039 | 10 |
| 052012 | 10 | R2002 | 10 | 52040 | 10 |
| 0s2013 | 10 |  |  | S204: | 10 |
| OS2014 | 10 | \$200\% | 10 | \$2042 | 10 |
| 052045 | 10 | S2002 | 10 | \$2043 | 10 |
| 052020 | \% | \$2003 | to | \$2045 | 10 |
| 0 S 2021 | 10 | \$2004 | 10 | \$2046 | 10 |
| 052022 | *0 | \$2005 | 10 | S2047 | 10 |
| 052023 | 10 | \$2006 | 10 | \$2048 | 10 |
| 052025 | 10 | \$2007 | 10 |  |  |
| 0\$2020 | 10 | \$2008 | 10 | U200\% | 10 |
| 0\$2027 | 80 | \$2009 | 10 | veout | 14 |
| 052028 | 10 | \$2010 | 10 | 62002 | 10 |
| 0S2029 | 10 | S201\% | *0 | 42002 | 14 |
| 052030 | 10 | \$2012 | \% 0 |  |  |
| - 52037 | 60 | S20:3 | \% 0 | W250 | 10 |
| จS2032 | \% 0 | \$2014 | 10 | W250: | 44 |


| A16-PROCESSOR BOARD |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM <br> NUMBER | CIRCUIT NUMBER | SCHEM <br> NUMBER | CIRCUIT NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM NUMBER |
| BT2501 | 8 | C 2516 | 8 | R2302 | 11 | R2402 | 9 | R2546 | 10 | U2406 | 9 |
|  |  | C2517 | 8 | R2303 | 11 | R2404 | 9 | R2547 | 10 | U2406 | 14 |
| C2300 | 11 | C2518 | 8 | R2304 | 11 | R2405 | 9 | R2548 | 10 | U2407 | 9 |
| C2301 | 11 | C2521 | 10 | R2305 | 11 | R2406 | 9 | R2549 | 10 | U2407 | 14 |
| C2302 | 11 | C2522 | 10 | R2306 | 11 | R2407 | 9 | R2550 | 10 | U2408 | 9 |
| C 2303 | 11 | C2523 | 10 | R2307 | 11 | R2408 | 9 | R2551 | 10 | U2408 | 14 |
| C2304 | 14 | C2524 | 10 | R2308 | 11 | R2409 | 9 | R2552 | 10 | U2409 | 9 |
| C2305 | 11 | C2525 | 10 | R2309 | 14 | R2410 | 9 | R2553 | 10 | U2409 | 14 |
| C2306 | 11 | C2526 | 10 | R2310 | 11 | R2411 | 9 | R2554 | 8 | U2410 | 9 |
| C2307 | 11 | C2530 | 14 | R2311 | 11 | R2412 | 14 | R2555 | 8 | U2410 | 14 |
| C2308 | 11 | C2531 | 14 | R2312 | 11 | R2413 | 9 | R2560 | 8 | U2411 | 9 |
| C2309 | 11 | C2532 | 14 | R2313 | 11 | R2414 | 9 | R2561 | 8 | U2411 | 14 |
| C2310 | 11 | C2541 | 14 | R2314 | 11 | R2415 | 9 | R2562 | 8 | U2412 | 9 |
| C2311 | 14 | C2543 | 10 | R2315 | 11 | R2416 | 9 | R2563 | 8 | U2412 | 14 |
| C2312 | 14 | C2544 | 10 | R2316 | 11 | R2417 | 9 | R2564 | 8 | U2413 | 9 |
| C2313 | 14 | C2545 | 10 | R2317 | 11 | R2418 | 9 |  |  | U2413 | 14 |
| C2314 | 14 | C2546 | 10 | R2318 | 11 | R2419 | 9 | U2300 | 11 | U2414 | 9 |
| C 2315 | 14 | C 2547 | 10 | R2319 | 11 | R2420 | 9 | U2300 | 14 | U2414 | 14 |
| C2316 | 14 | C2548 | 10 | R2320 | 11 | R2421 | 9 | U2301 | 11 | U2415 | 9 |
| C2317 | 14 | C2549 | 10 | R2321 | 11 | R2501 | 8 | U2301 | 14 | U2415 | 14 |
| C2318 | 11 | C 2550 | 10 | R2322 | 11 | R2502 | 8 | U2302 | 11 | U2416 | 9 |
| C2319 | 14 | C2551 | 8 | R2323 | 11 | R2503 | 8 | U2302 | 14 | U2416 | 14 |
| C2320 | 11 | C 2552 | 8 | R2324 | 11 | R2504 | 8 | U2303 | 11 | U2417 | 9 |
| C2321 | 14 | C2553 | 8 | R2325 | 11 | R2505 | 8 | U2303 | 14 | U2417 | 14 |
| C2322 | 11 | C2554 | 8 | R2326 | 11 | R2506 | 8 | U2304 | 11 | U2501 | 8 |
| C2323 | 11 | C2555 | 8 | R2327 | 11 | R2508 | 8 | U2304 | 14 | U2501 | 14 |
| C2324 | 11 |  |  | R2328 | 11 | R2509 | 8 | U2305 | 11 | U2502 | 8 |
| C2401 | 14 | CR2501 | 8 | R2329 | 11 | R2510 | 8 | U2305 | 14 | U2502 | 14 |
| C2402 | 14 | CR2502 | 8 | R2330 | 11 | R2511 | 8 | U2306 | 11 | U2503 | 8 |
| C 2403 | 14 | CR2504 | 8 | R2331 | 11 | R2512 | 8 | U2306 | 14 | U2503 | 14 |
| C2404 | 14 | CR2505 | 8 | R2332 | 11 | R2513 | 8 | U2307 | 11 | U2506 | 8 |
| C2405 | 14 |  |  | R2333 | 11 | R2514 | 8 | U2307 | 14 | U2506 | 14 |
| C2406 | 14 | DS2501 | 8 | R2334 | 11 | R2515 | 8 | U2308 | 11 | U2512 | 8 |
| C2407 | 14 |  |  | R2335 | 11 | R2516 | 8 | U2308 | 14 | U2512 | 14 |
| C2408 | 14 | J2302 | 9 | R2336 | 11 | R2517 | 8 | U2309 | 11 | U2513 | 8 |
| C2409 | 14 | J2302 | 11 | R2337 | $t 1$ | R2518 | 8 | U2309 | 14 | $\cup 2513$ | 14 |
| 02410 | 14 | J2302 | 14 | R2338 | 11 | R2519 | 8 | U2310 | 11 | U2514 | 8 |
| 02411 | 9 | J2304 | 11 | R2339 | 11 | R2520 | 8 | U2310 | 14 | U2514 | 14 |
| C2412 | 9 | J2501 | 10 | R2340 | 11 | R2521 | 8 | U2311 | 11 | U2515 | 8 |
| C2415 | 14 | J2501 | 14 | R234 1 | 11 | R2522 | 8 | U2311 | 14 | U2515 | 14 |
| C2416 | 9 | J2502 | 8 | 82342 | 11 | R2523 | 8 | U2312 | 11 | U2517 | 8 |
| C2417 | 9 | J2502 | 9 | R2343 | 11 | R2524 | 8 | U2312 | 14 | U2517 | 14 |
| C2418 | 9 | J2502 | 14 | R2344 | 11 | R2526 | 8 | U2313 | 11 | U2518 | 8 |
| C2419 | 9 | J2601 | 11 | R2345 | 11 | R2527 | 8 | U2313 | 14 | U2518 | 14 |
| C2420 | 9 | J2601 | 14 | R2346 | 11 | R2528 | 10 | U2314 | 11 | U2519 | 8 |
| C2501 | 14 |  |  | R2347 | 11 | R2529 | 10 | U2314 | 14 | U2519 | 14 |
| C 2502 | 14 | P2105 | 11 | R2348 | 11 | R2531 | 10 | U2400 | 9 | U2521 | 8 |
| C 2503 | 14 | P2105 | 14 | R2349 | 11 | R2532 | 10 | U2400 | 14 | U2523 | 10 |
| C2504 | 14 |  |  | R2350 | 11 | R2533 | 10 | U2401 | 9 | 42523 | 14 |
| C2505 | 14 | Q2501 | 10 | R2351 | 11 | R2534 | 10 | U2401 | 14 | U2524 | 10 |
| C2506 | 14 | Q2502 | 10 | R2352 | 11 | R2535 | 10 | U2402 | 9 | U2524 | 14 |
| C2507 | 14 | Q2503 | 10 | R2353 | 11 | R2536 | 10 | U2402 | 14 | U2525 | 10 |
| C2508 | 14 | Q2504 | 10 | R2354 | 11 | R2537 | 10 | U2403 | 9 | U2525 | 14 |
| C2509 | 14 | Q2505 | 10 | R2355 | 11 | R2538 | 10 | U2403 | 14 |  |  |
| C2510 | 14 | Q2506 | 10 | R2356 | 11 | R2539 | 10 | U2404 | 9 | W2105 | 11 |
| C2511 | 14 | Q2507 | 8 | R2357 | 11 | R2540 | 10 | U2404 | 14 | W2105 | 14 |
| C2514 | 8 |  |  | R2400 | 9 | R2541 | 10 | U2405 | 9 |  |  |
| C2515 | 8 | R2301 | 11 | 72401 | 9 | R2542 | 10 | U2405 | 14 | Y2501 | 8 |


| A18-POWER SUPPLY BOARD |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | SCHEM <br> NUMBER | CIRCUIT <br> NUMBER | SCHEM <br> NUMBER | CIRCUIT <br> NUMBER | SCHEM <br> NUMBER | CIRCUIT NUMBER | SCHEM <br> NUMBER | CIRCUIT <br> NUMBER | SCHEM NUMBER | CIRCUIT NUMBER | SCHEM <br> NUMBER |
| C2201 | 12 | C2238 | 12 | CR2235 | 12 | Q2212 | 12 | R2233 | 12 | R2276 | 12 |
| C2202 | 12 | C2239 | 12 | CR2236 | 12 | 02213 | 12 | R2236 | 12 |  |  |
| C2203 | 12 | C2243 | 12 | CR2237 | 12 | Q2214 | 12 | R2237 | 12 | RT2201 | 12 |
| C2204 | 12 | C2244 | 12 |  |  |  |  | R2238 | 12 |  |  |
| C2206 | 12 | C2245 | 12 | DS2201 | 12 | R2201 | 12 | R2239 | 12 | S2201 | 12 |
| C 2207 | 12 | C2248 | 12 |  |  | R2203 | 12 | R2240 | 12 |  |  |
| C2208 | 12 | C2249 | 12 | F2201 | 12 | R2204 | 12 | R2241 | 12 | T2203 | 12 |
| C2209 | 12 |  |  |  |  | R2205 | 12 | R2242 | 12 | T2204 | 12 |
| C2210 | 12 | CR2201 | 12 | J2208 | 12 | R2206 | 12 | R2243 | 12 | T2205 | 12 |
| C2211 | 12 | CR2202 | 12 | J2225 | 12 | R2207 | 12 | R2245 | 12 | T2206 | 12 |
| C 2212 | 12 | CR2204 | 12 | J2726 | 12 | R2208 | 12 | R2246 | 12 |  |  |
| C2213 | 12 | CR2205 | 12 |  |  | R2209 | 12 | R2247 | 12 | U2201 | 12 |
| C2214 | 12 | CR2206 | 12 | $L 2201$ | 12 | R2210 | 12 | R2248 | 12 | U2230 | 12 |
| C2215 | 12 | CR2207 | 12 | 12202 | 12 | R2211 | 12 | R2250 | 12 |  |  |
| C2216 | 12 | CR2208 | 12 | $\underline{L 203}$ | 12 | R2212 | 12 | R2252 | 12 | VR2201 | 12 |
| C2217 | 12 | CR2209 | 12 | L2204 | 12 | R2215 | 12 | R2253 | 12 | VR2202 | 12 |
| C2218 | 12 | CR2210 | 12 | 1.2205 | 12 | R2216 | 12 | R2254 | 12 | VR2203 | 12 |
| C2219 | 12 | CR2211 | 12 | L2206 | 12 | R2218 | 12 | R2255 | 12 | VR2204 | 12 |
| C2221 | 12 | CR2212 | 12 | L2207 | 12 | R2219 | 12 | R2256 | 12 | VR2205 | 12 |
| C2222 | 12 | CR2213 | 12 | L2208 | 12 | R2220 | 12 | R2257 | 12 | VR2206 | 12 |
| C 2223 | 12 | CR2214 | 12 |  |  | R2221 | 12 | R2259 | 12 | VR2207 | 12 |
| C 2224 | 12 | CR2215 | 12 | P2204 | 12 | R2222 | 12 | R2260 | 12 |  |  |
| C2225 | 12 | CR2216 | 12 |  |  | R2223 | 12 | R2265 | 12 | W28 | 12 |
| C2226 | 12 | CR2218 | 12 | Q2201 | 12 | R2224 | 12 | R2266 | 12 | W29 | 12 |
| C2227 | 12 | CR2219 | 12 | Q2202 | 12 | R2225 | 12 | R2267 | 12 | W31 | 12 |
| C2228 | 12 | CR2220 | 12 | Q2203 | 12 | R2226 | 12 | R2268 | 12 | W32 | 12 |
| C2229 | 12 | CR2227 | 12 | Q2204 | 12 | R2227 | 12 | R2270 | 12 | W2201 | 12 |
| C2230 | 12 | CR2228 | 12 | Q2206 | 12 | R2228 | 12 | R2271 | 12 |  |  |
| C2232 | 12 | CR2231 | 12 | Q2208 | 12 | R2229 | 12 | R2272 | 12 |  |  |
| C2233 | 12 | CR2232 | 12 | Q2209 | 12 | R2230 | 12 | R2273 | 12 |  |  |
| C2234 | 12 | CR2233 | 12 | Q2210 | 12 | R2231 | 12 | R2274 | 12 |  |  |
| C2236 | 12 | CR2234 | 12 | Q2211 | 12 | R2232 | 12 | R2275 | 12 |  |  |

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## REPLACEABLE MECHANICAL PARTS

## PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

## ITEM NAME

In the Parts List, an item Name is separated from the description by a colon(:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

FIGURE AND INDEX NUMBERS
Items in this section are referenced by figure and index numbers to the illustrations.

## INDENTATION SYSTEM

This mechanical parts list is indented to indicate item relationships. Following is an example of the indentation system used in the description column.
$12345 \quad$ Name \& Description
Assembly and/or Component
Attaching parts for Assembly and/or Component
END ATTACHING PARTS
Detail Part of Assembly and/or Component
Attaching parts for Detail Part
END ATTACHING PARTS
Parts of Detail Part
Attaching parts for Parts of Detail Part
END ATTACHING PARTS

Attaching Parts always appear in the same indentation as the item it mounts, while the detail parts are indented to the right. Indented items are part of, and included with, the next higher indentation.

Attaching parts must be purchased separately, unless otherwise specified.

## ABBREVIATIONS

Abbreviations conform to American National Standards Institute YI.I

## CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 06383 | PANDUIT CORP | 17301 RIDGELAND | TINLEY PARK IL 07094-2917 |
| 06915 | RICHCO PLASTIC CO | 5825 N TRIPP AVE | CHICAGO IL 60646-6013 |
| 07418 | NELSON NAME PLATE CO | 3191 CASITAS | LOS ANGELES CA 90039-2410 |
| 12327 | FREEWAY CORP | 9301 ALLEN DR | CLEVELAND OH 44125-4632 |
| 13103 | THERMALLOY CO INC | 2021 W VALLEY VIEW LN PO BOX 810839 | DALLAS TX 75381 |
| 22670 | G M NaMEPLATE INC | 2040 15TH AVE WEST | SEATTLE WA 98119-2728 |
| 23740 | AMUNEAL MFG CORP | 4737 DARRAH | PHILADELPHIA PA 19124-2705 |
| 24931 | SPECIALTY CONNECTOR CO INC | 2100 EARL HWOOD DR PO BOX 547 | FRANKLIN IN 46131 |
| 28520 | HEYCO MOLDED PRODUCTS | $\begin{aligned} & 750 \text { BOULEVARD } \\ & \text { PO BOX } 160 \end{aligned}$ | KENILWORTH NJ 07033-1721 |
| 52676 | S. K. F. INDUSTRIES, INC. | P 0 B0X 6731 | PHILADELPHIA, PA 19132 |
| 70903 | COOPER BELDEN ELECTRONICS WIRE AND C SUB OF COOPER INDUSTRIES INC | 2000 S batavia ave | GENEVA IL 60134-3325 |
| 71400 | BUSSMANN <br> DIV OF COOPER INDUSTRIES INC | 114 OLD STATE RD PO BOX 14460 | ST LOUIS MO 63178 |
| 75915 | LITTELFUSE TRACTOR INC sUB TRACTOR INC | 800 E NORTHWEST HWY | des PLAINES IL 60016-3049 |
| 77900 | SHAKEPROOF <br> DIV OF ILLINOIS TOOL WORKS | SAINT CHARLES RD | ELGIN IL 60120 |
| 78189 | ILLINOIS TOOL WORKS INC SHAKEPROOF DIV | ST CHARLES ROAD | ELGIN IL 60120 |
| 80009 | TEKTRONIX INC | 14150 SW KARL BRaUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 83014 | HARTWELL CORP | 900 S RICHFIELD RD | PLACENTIA CA 92670-6732 |
| 83385 | MICRODOT MFG INC GREER-CENTRAL DIV | 3221 W BIG BEAVER RD | TROY MI 48098 |
| 86113 | MICRODOT MFG INC CENTRAL SCREW-KEENE DIV | 149 EMERALD ST | KEENE NH 03431-3628 |
| 93907 | TEXTRON INC CAMCAR DIV | 600 18TH AVE | ROCKFORD IL 61101 |
| S3109 | FELLER ASA ADOLF AG C/O PANEL COMPONENTS CORP | 355 TESCONI CIRCLE | SANTA ROSA CA 95401 |
| S3629 | SCHURTER AG H C/O PANEL COMPONENTS CORP | 2015 SECOND STREET | BERKELEY CA 94170 |
| TK0174 | BADGLEY MFG CO | 1620 NE ARGYLE | PORTLAND OR 97211 |
| TK0858 | STAUFFER SUPPLY CO | 105 SE TAYLOR | PORTLAND OR 97214 |
| TK1319 | MORELLIS Q \& D PLASTICS | 1812 16-TH AVE | FOREST GROVE OR 97116 |
| TK1373 | PATELEC-CEM (ITALY) | 10156 TORINO | VAICENTALLO 62/455 ITALY |
| TK1808 | FASTEX | 195 ALGONQUIN RD | DES PLAINES IL 60016 |
| TK1938 | GALGON INDUSTRIES | 37399 CENTRAL MONT PLACE | FREMONT CA 94536 |
| TK2165 | TRI-QUEST CORP | 3000 LEWIS AND CLARK HAY | VANCOUVR WA 98661-2999 |


| Fig. \& Index Ho. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Qty | 12345 Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1-1 | 334-7078-00 |  | 1 | MARKER, IDENT:MARKED 2245A, HANDLE | 80009 | 334-7078-00 |
| -2 | 367-0289-00 |  | 1 | HANDLE, CARRYING: 13.855 ,SST ATTACHING PARTS | 80009 | 367-0289-00 |
| -3 | 212-0144-00 |  | 2 | SCREW,TPG,TF:8-16 X 0.562,PLASTITE,SPCL HD END ATTACHING PARTS | 93907 | 225-38131-012 |
| -4 | 200-3233-01 |  | 1 | COVER,REAR: POLYCARBONATE, SMOKE TAN ATTACHING PARTS | 80009 | 200-3233-01 |
| -5 | 211-0691-00 |  | 4 | SCREW, MACHINE: $6-32 \times 0.625$, PNH,STL END ATTACHING PARTS | 93907 | ORDER BY DESCR |
| -6 | 334-6707-00 |  | 1 | MARKER, IDENT M M D Caution | 80009 | 334-6707-00 |
| -7 | 334-6708-00 |  | 1 | MARKER, IDENT:MKD REAR PANEL Z-AXIS | 80009 | 334-6708-00 |
| -8 | 348-0919-00 |  | 2 | FOOT, CABINET: BLACK POLYURETHANE | 80009 | 348-0919-00 |
| -9 | 390-0980-00 |  | 1 | CABINET,OSC:GPSB | 80009 | 390-0980-00 |
| -10 | 213-0882-00 |  | 1 | SCREW, TPG,TR:6-32 $\times 0.437$ TAPTITE, PNH,STL | 83385 | ORDER BY DESCR |
| -11 | 348-0659-00 |  | 2 | FOOT, CABINET:BLACK POLYURETHANE | 80009 | 348-0659-00 |

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Fig. 8

| Index No. | Tektronix Part No. | Serial/Assenbly No. Effective Dscont | Oty | 12345 Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2-1 | 334-7079-00* |  | 1 | MARKER, IDENT:MARKED 2245A,BEZEL | 80009 | 334-7079-00 |
| -2 | 426-1765-02 |  | 1 | FRAME,CRT: POLYCARBONATE,GRAY ATTACHING PARTS | 80009 | 426-1765-02 |
| -3 | 211-0690-01 |  | 2 | SCREN,MACHINE: 6-32 $\times 0.875$ PNH, SST END ATTACHING PARTS | 86113 | ORDER BY DESCR |
| -4 | 337-2775-00 |  | 1 | SHLD, IMPLOSION:FILTER, BLUE | 80009 | 337-2775-00 |
| -5 | 333-3290-00 |  | 1 | PANEL, FRONT: | 80009 | 333-3290-00 |
| -6 | 351-0752-00 |  | 1 | GUIDE,LIGHT:ACRYLIC GRATICULE | 80009 | 351-0752-00 |
| -7 | 348-0660-00 |  | 4 | CUSHION, CRT: POLYURETHANE | 80009 | 348-0660-00 |
| -8 | 366-2089-00 |  | 5 | KNOB:GRAY, PUSH ON, $0.185 \times 0.392 \times 0.495$ | 80009 | 366-2089-00 |
| -9 | 366-2093-00 |  | 2 | KNOB:DOVE GRAY, 0.235 ID X 0.36 OD $\times 0.495 \mathrm{H}$ | 80009 | 366-2093-00 |
| -10 | 366-1510-00 |  | 3 | KNOB:DOVE GRAY, VAR, $0.127 \times 0.392 \times 0.466$ | 80009 | 366-1510-00 |
| -11 | 366-2090-00 |  | 3 | KNOB:GRAY, VAR, 0.2 ID X 0.546 OD X 0.69 H | 80009 | 366-2090-00 |
| -12 | 366-2089-00 |  | 8 | KNOB:GRAY, PUSH ON, $0.185 \times 0.392 \times 0.495$ | 80009 | 366-2089-00 |
| -13 | 333-3557-00 |  | 1 | PANEL, FRONT: | 80009 | 333-3557-00 |
| -14 | 386-3339-00 |  | 1 | SUBPANEL, FRONT: ATTACHING PARTS | 80009 | 386-3339-00 |
| -15 | 213-0882-00 |  | 2 | SCREW,TPG,TR:6-32 $\times 0.437$ TAPTITE, PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -16 | - |  | 1 | FILTER,RFI: (SEE FL2201 REPL) ATTACHING PARTS |  |  |
| -17 | 213-0882-00 |  | 2 | SCREW,TPG,TR:6-32 $\times 0.437$ TAPTITE, PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -18 | ---------- |  | 1 | CONN,RCPT, ELEC:BNC (SEE J16 REPL) |  |  |
| -19 | 441-1721-00 |  | 1 | CHASSIS, REAR:GPSB ATTACHING PARTS | 80009 | 441-1721-00 |
| -20 | 213-0882-00 |  | 10 | SCREW,TPG,TR:6-32 $\times 0.437$ TAPTITE,PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -21 | 343-1240-00 |  | 2 | CLAMP, CABLE: 0.25 ID, NYLON | TK1808 | 220-340802-00 |
| -22 | ---------- |  | 1 | LEAD, ELECTRICAL: (SEE W30 REPL) ATTACHING PARTS |  |  |
| -23 | 210-0457-00 |  | 1 | NUT, PL, ASSEM WA:6-32 $\times 0.312, S T L$ CD PL | 78189 | 511-061800-00 |
|  | 210-0006-00 |  | 1 | WASHER, LOCK:\#6 INTL, 0.018 THK, STL END ATTACHING PARTS | 77900 | 1206-00-00-0541C |
| -24 | 214-1061-06 |  | 1 | SPRING,GROUND:CRT SHIELD | 80009 | 214-1061-06 |
| -25 | 200-2519-00 |  | 1 | CAP,CRT SOCKET:NATURAL LEXAN | 80009 | 200-2519-00 |
| -26 | 426-1766-00 |  | 1 | MOUNT, RESILIENT:CRT,REAR | 80009 | 426-1766-00 |
| -27 | ---------- |  | 1 | WIRE SET, ELEC:SOCKET ASSY CRT (SEE A1OW9) |  |  |
| -28 | 337-2774-00 |  | 1 | SHIELD, ELEC:CRT, STEEL | 23740 | C-2059 |
| -29 | 386-4443-00 |  | 1 | SUPPORT, SHIELD:CRT,FRONT, PLASTIC | 80009 | 386-4443-00 |
| -30 | 334-1951-00 |  | 1 | MARKER, IDENT:MKD WARNING, CRT VOLTAGES | 22670 | ORDER BY DESCR |
| -31 | 334-1379-00 |  | 1 | MARKER, IDENT:MKD HI VACUM | 07416 | ORDER BY DESCR |
| -32 | ---------- |  | 1 | DELAY LINE, ELEC: (SEE DL21 REPL) |  |  |
| -33 | 343-0549-00 |  | 3 | STRAP, TIEDOWN, E: 0.091 W X 4.0 L,ZYTEL | 06383 | PLTIM |
| -34 | 441-1720-00 |  | 1 | CHAS, PWR SUPPLY:GPSB | 80009 | 441-1720-00 |
| -35 | ----- ----- |  | 1 | FAN, TUBEAXIAL: (SEE B25 REPL) ATTACHING PARTS |  |  |
| -36 | 213-0991-00 |  | 4 | SCREW, TPG,TC:6-32 X 1.25 L,TYPE T,PNH,STL END ATTACHING PARTS | TK0858 | ORDER BY DESCR |
| -37 | 343-1305-00 |  | 1 | CLP, WIRE SADDLE:0.437 ID,NYLON | 06915 | WS-1N |
| -38 | 348-0532-00 |  | 2 | GROMMET, PLASTIC:BLACK,ROUND,0.625 ID | 28520 | SB-750-10 |
| -39 | 344-0347-00 |  | 1 | CLIP, ELECTRICAL:ANODE, 0.72 OD,NYLON | TK2165 | ORDER BY DESCR |
| -40 | 441-1719-00 |  | 1 | CHASSIS,MAIN:GPSB <br> ATTACHING PARTS | 80009 | 441-1719-00 |
| -41 | 213-0882-00 |  | 6 | SCREW, TPG,TR:6-32 $\times 0.437$ TAPTITE, PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -42 | 378-0295-00 |  | 1 | GRILLE,AIR DUCT:ALLMINUM | 80009 | 378-0295-00 |
| -43 | 214-3835-00 |  | 1 | ARM, PIVOT:POWER SWITCH | 80009 | 214-3835-00 |
| -44 | 384-1697-00 |  | 1 | EXTENSION SHAFT:6.25 $\times$ X 0.285 OD, NYLON | 80009 | 384-1697-00 |
| -45 | 384-1696-00 |  | 1 | EXTENSION SHAFT:12.2 L X 0.285 OD, NYLON | 80009 | 384-1696-00 |
|  | 361-1427-00 |  | 2 | SPACER,CABLE:SILICONE | 80009 | 361-1427-00 |


| Fig. \& Index No . | Tektronix <br> Part No. | Serial/Assembly No. Effective Dscont | Qty | 12345 Name \& Description | Mfr. <br> Code | Mfr. Part Mo. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3-1 | ---------- |  | 1 | CIRCUIT BD ASSY:POTENTIOMETER (SEE A12) ATTACHING PARTS |  |  |
| -2 | 214-3826-00 |  | 7 | LATCH, PLUNGER: BLACK | 80009 | 214-3826-00 |
|  | 348-0904-00 |  | 7 | GROMMET,FSTNR:0. 187 DIA, BLACK END ATTACHING PARTS | 83014 | HN3G-32-1 |
| -3 | 376-0130-00 |  | 3 | COUPLER, SHAFT:2.260 L X 0.132 ID, POLYCARB | 80009 | 376-0130-00 |
| -4 | ----- ------ |  | , | CIRCUIT BD ASSY:SWITCH (SEE A14 REPL) |  |  |
| -5 | 260-2271-00 |  | 1 | SWITCH, PUSH:42 BUTTON, 2 POLE | 80009 | 260-2271-00 |
| -6 | 366-2088-00 |  | 14 | PUSH BUTTON:GRAY, 0.172 SQ X 0.3 H | 80009 | 366-2088-00 |
| -7 | 105-0997-00 |  | 3 | ACTUATOR, CAM SW:CHRONOMATIC CONTACT | 80009 | 105-0997-00 |
| -8 | 214-1126-01 |  | 3 | SPRING,FLAT: $0.7 \times 0.125, C U$ BE GRN CLR | 80009 | 214-1126-01 |
| -9 | 214-0274-00 |  | 3 | BALL, BEARING:0.125 DIA, SST,GRADE 100 | 52876 | ORDER BY DESCR |
| -10 | 366-2091-00 |  | 17 | PUSH BUTTON:CLEAR, 0.312 DIA $\times 0.3 \mathrm{H}$ | 80009 | 366-2091-00 |
| -11 | 380-0767-00 |  | 1 | HOUSING, SWITCH: POL YCARBONATE | 80009 | 380-0767-00 |
| -12 | --------- |  | 1 | CIRCUIT BD ASSY:PROCESSOR (SEE A16 REPL) ATTACHING PARTS |  |  |
| -13 | 213-0882-00 |  | 12 | SCREW, TPG, TR: $6-32 \times 0.437$ TAPTITE, PNH,STL | 83385 | ORDER BY DESCR |
| -14 | 211-0691-00 |  | 2 | SCREW,MACHINE: $6-32 \times 0.625$, PNH,STL END ATTACHING PARTS | 93907 | ORDER BY DESCR |
| -15 | 131-1428-00 |  | 1 | CONTACT,ELEC:GROUNDING,CU BE CD PL ATTACHING PARTS | 80009 | 131-1428-00 |
| -16 | 213-0882-00 |  | 1 | SCREW,TPG,TR:6-32 $\times 0.437$ TAPTITE, PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -17 | 337-3290-01 |  | 1 | SHIELD, ELEC:TOP,W/CAUTION LABEL | 80009 | 337-3290-01 |
| -18 | 334-4251-00 |  | 1 | MARKER, IDENT:MKD CAUTION | 07416 | ORDER BY DESCR |
| -19 -20 | ----- ----- |  | 1 | CIRCUIT BD ASSY:LVPS (SEE A18 REPL) <br> ATTACHING PARTS |  |  |
| -20 | 213-0882-00 |  | 6 | SCREW,TPG,TR:6-32 $\times 0.437$ TAPTITE, PNH,STL END ATTACHING PARTS <br> LVPS BOARD INCLUDES: | 83385 | ORDER BY DESCR |
| -21 | 204-0906-00 |  | 1 | . BODY, FUSEHOLDER:3AG \& $5 \times 2$ 2MM FUSES | \$3629 | TYPEFAU031. 3573 |
| -22 | 200-2264-00 |  | 1 | .CAP, FUSEHOLDER:3AG FUSES | S3629 | FEK 0311666 |
| -23 | 214-3821-00 |  | 2 | .HEAT SK, XSTR:PWR SPLY,GOLD W/CHROMATE PL | 80009 | 214-3821-00 |
| -24 | - - |  | 1 | .SWITCH, THRMSTC: (SEE A18S2202 REPL) ATTACHING PARTS |  |  |
| -25 | 213-0882-00 |  | 2 | .SCREW,TPG, TR: 6-32 $\times 0.437$ TAPTITE, PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -26 | --- ----- |  | 1 | .TRANSISTOR: (SEE A18Q2201 REPL) ATTACHING PARTS |  |  |
| -27 | 213-0882-00 |  | 1 | .SCREW,TPG, TR: 6-32 $\times 0.437$ TAPTITE,PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -28 | ---------- |  | 1 | .TRANSISTOR: (SEE A18Q2214 REPL) ATTACHING PARTS |  |  |
| -29 | 213-0882-00 |  | 1 | .SCREW,TPG,TR:6-32 $\times 0.437$ TAPTITE,PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -30 | 344-0410-00 |  | 1 | .CLIP, COIL SPRT: $1 \times 1.46$, POLYCARBONATE | TK1319 | ORDER BY DESCR |
| -31 | 342-0781-00 |  | 1 | INSUL, PWR SPLY: POLYCARBONATE | 80009 | 342-0781-00 |
| -32 | ----- |  | 1 | CIRCUIT BD ASSY:MAIN (SEE A10 REPL) |  |  |
|  | 342-0324-00 |  | 6 | . INSULATOR, DISK:TRANSISTOR, NYLON | 13103 | 7717-5N-BLUE |
| -33 | 337-3342-02 |  | 2 | . SHIELD, ELEC:HIGH VOLTAGE, 2246 | 80009 | 337-3342-02 |
| -34 | 337-3358-01 |  | 1 | .SHIELD, ATTEN: FRONT,MAIN BD ATTACHING PARTS | 80009 | 337-3358-01 |
| -35 | 211-0690-01 |  | 2 | .SCREW,MACHINE:6-32 $\times 0.875$ PNH,SST END ATTACHING PARTS | 86113 | ORDER BY DESCR |
| -36 | 337-3279-00 |  | 1 | .SHIELD,ATTEN:ALLMINUM ATTACHING PARTS | TK1938 | ORDER BY DESCR |
| -37 | 213-0882-00 |  | 10 | .SCREW,TPG, TR:6-32 X 0.437 TAPIITE,PNH,STL END ATTACHING PARTS | 83385 | ORDER BY DESCR |
| -38 | 344-0286-00 |  | 5 | .CLIP, ELECTRICAL: FUSE, SPR BRS | 75915 | 102074 |
| -39 | 343-0003-00 |  | 1 | .CLAMP,LOOP:0. 25 ID.PLASTIC ATTACHING PARTS | 06915 | E4 CLLEAR ROUND |
| -40 | 213-0882-00 |  | 1 | .SCREW, TPG, TR: 6-32 $\times 0.437$ TAPTITE, PNH, STL | 83385 | ORDER BY DESCR |
| -41 | 210-0949-00 |  | 1 | .WASHER, FLAT: 0.141 ID $\times 0.500 \times 0.062$, BRS END ATTACHING PARTS | 12327 | ORDER BY DESCR |
| -42 | 407-3416-00 |  | 1 | . BRACKET, ATTEN:BRASS | 80009 | 407-3416-00 |
| -43 | ---------- |  | 4 | .CONN,RCPT,ELEC:BNC,MALE <br> (SEE A10111,J12,J13,J14) ATTACHING PARTS |  |  |

Fig. \&

| Index <br> No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Oty | 12345 Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3-44 | 220-0497-00* |  | 4 | .NUT,PLAIN, HEX:0.5-28 X 0.562 HEX, BRS CD PL | 80009 | 220-0497-00 |
| -45 | 210-1039-00 |  | 4 | .WASHER, LOCK: $0.521 \mathrm{ID}, \mathrm{INT}, 0.025$ THK, SST END ATTACHING PARTS | 24931 | ORDER BY DESCR |
| -46 | 214-3136-00 |  | 2 | .HEAT SINK, XSTR:TO-5,ALLMINUM | 13103 | 22288 |
|  | 358-0715-00 |  | 2 | .BUSHING, SNAP: $0.25 \times 0.234, N Y L, 0.375$ | 28520 | 2810 |
| -47 | 384-1702-00 |  | 1 | .EXTENSION SHAFT:9.97 $\mathcal{X}$ X 0.25, POLYMIDE | 80009 | 384-1702-00 |
| -48 | ----- ----- |  | 1 | .CIRCUIT BD ASSY:CRT CONTROL (SEE A8 REPL) |  |  |
| -49 | 358-0715-00 |  | 1 | ..BUSHING,SNAP:0.25 X 0.234,NYL, 0.375 | 28520 | 2810 |
|  | 384-1713-00 |  | 4 | ..EXTENSION SHAFT:0.918 L X 0.218 OD,PLASTIC | 80009 | 384-1713-00 |

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Fig. 8

| Index | Tektronix | Serial/Assembly No. |  |  | Mfr. |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| No. | Part No. | Effective Dscont | Oty 12345 | Name \& Description | Mfr. Part No. |  |

4-
-1 161-0230-01
-2 343-1213-00
020-0859-00
343-0170-00
-3 161-0104-06
020-0860-00
343-0170-00
$-4$

020-0861-0
$-5 \quad 161-0104-05$
020-0862-00
343-0170-00
$-6$
161-0104-08
020-0863-00
343-0170-00
-7 161-0167-00

070-6558-0
070-6718-00
159-0023-00
337-2775-01

016-0180-00
016-0359-01 016-0592-00 016-0848-00 016-0857-00 070-6557-00 200-3232-00 346-0199-00

STANDARD ACCESSORIES

| CABLE ASSY, PWR, 3 , 18 AWG,92.0 L | 80009 | 161-0230-01 |
| :---: | :---: | :---: |
| CLAMP, PWR CORD:POLYMIDE | 80009 | 343-1213-00 |
| COMPONENT KIT: EUROPEAN | 80009 | 020-0859-00 |
| .RTNR,CA TO CA:U/W 0.25 OD CABLES | 80009 | 343-0170-00 |
| .CABLE ASSY, PWR, $3 \times 0.75 \mathrm{MM} \mathrm{SQ,220V,98.0} \mathrm{~L}$ | S3109 | ORDER BY DESCR |
| . (OPTION AI - EUROPEAN) |  |  |
| COMPONENT KIT:UNITED KINGDOM | 80009 | 020-0860-00 |
| .RTNR,CA TO CA: U/W 0.25 OD CABLES | 80009 | 343-0170-00 |
| .CABLE ASSY, PWR, $3 \times 0.751 \mathrm{M}$ SQ, $240 \mathrm{~V}, 98.0 \mathrm{~L}$ | TK1373 | A25UK-RA |
| ( (OPTION A2 - UNITED KINGDOM) |  |  |
| COMPONENT KIT:AUSTRALIAN | 80009 | 020-0861-00 |
| .RTNR,CA TO CA:U/W 0.25 OD CABLES | 80009 | 343-0170-00 |
| .CABLE ASSY, PWR, 3,18 AWG,240V,98.0 L | S3109 | ORDER BY DESCR |
| . (OPTION A3 - AUSTRALIAN) |  |  |
| COMPONENT KIT:NORTH AMERICAN | 80009 | 020-0862-00 |
| .RTNR,CA TO CA:U/W 0.25 OD CABLES | 80009 | 343-0170-00 |
| .CABLE ASSY, PWR, 3 ,18 AWG,240V,98.0 L | 70903 | ORDER BY DESCR |
| . (OPTION A4 - NORTH AMERICAN) |  |  |
| COMPONENT KIT:SWISS | 80009 | 020-0863-00 |
| .RTNR,CA TO CA:U/W 0.2500 CABLES | 80009 | 343-0170-00 |
| .CABLE ASSY, PWR, $3.0 \times 0.75,6 \mathrm{~A}, 240 \mathrm{~V}, 2.5 \mathrm{ML}$ | S3109 | OROER BY DESCR |
| . (OPTION A5 - SWISS) |  |  |
| ACCESSORY PKG:2,P6109 OPT 01 W/ACCESSORIES |  |  |
| MANUAL, TECH:OPERATORS, 2245A | 80009 | 070-6558-00 |
| CARD, INFO:REFERENCE, 2245A | 80009 | 070-6718-00 |
| FUSE, CARTRIDGE:3AG,2A, 250V, SLOW BLOW | 71400 | MDX2 |
| SHLD, IMPLOSION: | 80009 | 337-2775-01 |

## OPTIONAL ACCESSORIES

VISOR,CRT:FOLDING
ADAPTER HOOD:
VISOR,CRT:
COVER,PROT:WATERPROOF VINYL
ACCESSORY POUCH:W/PLATE,2246
MANUAL, TECH: SERVICE, 2245A
COVER,FRONT:
STRAP, CARRYING:MKD TEKTRONIX

Code Mfr. Part No

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## MANUAL CHANGE INFORMATION

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Sometimes, due to printing and shipping requirements, we can't get these changes immediately into printed manuals. Hence, your manual may contain new change information on following pages.

A single change may affect several sections. Since the change information sheets are carried in the manual until all changes are permanently entered, some duplication may occur. If no such change pages appear following this page, your manual is correct as printed.

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Product: 2245A SERVICE

## MANUAL CHANGE INFORMATION

Date: 11-28-88
Change Reference: $\qquad$
Manual Part Number: 070-6557-00

EFFECTIVE SERIAL NUMBER: BO13034

## REPLACEABLE ELECTRICAL PARTS LIST CHANGES

CHANGE TO:

| A10AT117 | $307-2135-01$ | RES NTWK, FXD, FI: ATTENUATOR DIP PKG |
| :--- | :--- | :--- |
| A10AT127 | $307-2135-01$ | RES NTWK, FXD, FI: ATTENUATOR DIP PKG |
| A10U112 | $165-2232-01$ | MICROCKT, LINEAR: BUFFER AMPLIFIER |
| A10U122 | $165-2232-01$ | MICROCKT, LINEAR: BUFFER AMPLIFIER |

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Product: $\qquad$ Date: 11-28-88 Change Reference: $\qquad$

## DIAGRAM CHANGES

## DIAGRAM 8 MEASUREMENT PROCESSOR

Change the value of resistor R2510 (location 2B) to $510 \Omega$.

## DIAGRAM

The following changes are illustrated with a partial schematic of Diagram 10 contained in this insert.
Remove the following list of $1 \mathrm{~K} \Omega$ resistors from the output of U 2523 . Locations are 1 C through 1 E .
R2531 R2533 R2535 R2537 R2539 R2541
Add connector J2503 and resistor R2525 (620 $\Omega$ ).

DIAGRAM
 ADC AND DAC SYSTEM

Change the value of resistor R2312 (location 6F) to $4.12 \mathrm{~K} \Omega$.
Change the value of resistor R2313 (location 7E) to $4.12 \mathrm{~K} \Omega$.


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[^0]:    ${ }^{\text {a }}$ Performance Requirement not checked in manual.

[^1]:    $\mathbf{a}_{\text {Performance Requirement not checked in manual. }}$

[^2]:    ${ }^{\text {a }}$ Performance Requirement not checked in manual.

[^3]:    ${ }^{\text {a }}$ Performance Requirement not checked in manual.

[^4]:    ${ }^{\text {a }}$ Performance Requirement not checked in manual.

[^5]:    VERT COMP EN: Turns on the Vertical Comparator (U702, Diagram 2) during voltage self characterization.

    TB CAL: Switches the time-base calibration signal into the $B$ trigger system during horizontal self characterization (U1106A).

    BW FULL B: Switches between full and limited B Trigger bandwidth.

[^6]:    a C GATE not used externally.

[^7]:    ${ }^{\text {a }}$ Requires a TM500-series power module.

[^8]:    \{CAUTION
    Before using any test equipment to make measurements on static-sensitive, currentsensitive, or voltage-sensitive components or assemblies, ensure that any voltage or current supplied by the test equipment does not exceed the limits of the component to be tested.

[^9]:    ${ }^{\text {a }}$ At rated load.

[^10]:    Signals that begin and end on the same diagram are not listed in this table.

[^11]:    Partial A10 also shown on diagrams $1,2,3,4,6,7$ and 13

[^12]:    Partial A10 also shown on diagrams 1, 2, 3, 4, 5, 6 and 7

