Instruction Manual

## Tektronix

DC 504A
Counter/Timer
070-4291-00

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#### Abstract

Warning The servicing instructions are for use by qualified personnel only. To avoid personal injury, do not perform any servicing unless you are qualified to do so. Refer to the Safety Summary prior to performing service.


Please check for change information at the rear of this manual.

First Edition: January 1983
Last Revised: June 1988

## WARRANTY

Tektronix warrants that this product will be free from defects in materials and workmanship for a period of one (1) year from the date of shipment. If any such product proves defective during this warranty period, Tektronix, at its option, either will repair the defective product without charge for parts and labor, or will provide a replacement in exchange for the defective product.

In order to obtain service under this warranty, Customer must notify Tektronix of the defect before the expiration of the warranty period and make suitable arrangements for the performance of service. Customer shall be responsible for packaging and shipping the defective product to the service center designated by Tektronix, with shipping charges prepaid. Tektronix shall pay for the return of the product to Customer if the shipment is to a location within the country in which the Tektronix service center is located. Customer shall be responsible for paying all shipping charges, duties, taxes, and any other charges for products returned to any other locations.

This warranty shall not apply to any defect, failure or damage caused by improper use or improper or inadequate maintenance and care. Tektronix shall not be obligated to furnish service under this warranty a) to repair damage resulting from attempts by personnel other than Tektronix representatives to install, repair or service the product; b) to repair damage resulting from improper use or connection to incompatible equipment; or c) to service a product that has been modified or integrated with other products when the effect of such modification or integration increases the time or difficulty of servicing the product.

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## TABLE OF CONTENTS

Page
List of Illustrations ..... iii
List of Tables ..... iii
Operators Safety Summary ..... iv
Servicing Safety Summary ..... $v$
Section 1 SPECIFICATION
Instrument Description ..... 1-1
Standard Accessories ..... 1-1
Performance Conditions ..... 1-1
Electrical Characteristics ..... 1-2
Environmental ..... 1-6
Physical Characteristics ..... $1-7$
Section 2 OPERATING INSTRUCTIONS
Introduction ..... 2-1
Preparation For Use ..... 2-1
First Time Inspection ..... 2-1
Operating And Non-Operating Environments ..... 2-1
Rear Interface Considerations ..... 2-1
Installation And Removal ..... 2-1
Controls And Connectors ..... 2-2
Operating Considerations ..... $2-5$
Input Connections ..... $2-5$
Maximum Safe Input Voltage Limits ..... 2-5
Connecting External Signal Sources ..... $2-5$
Input Coupling, Noise,
And Attenuation ..... 2-5
Triggering ..... 2-6
Input Coupling Switch ..... 2-6
Trigger Level ..... 2.6
Reducing Measurement Errors ..... 2-6
Frequency Measurements ..... 2-6
Measurement Intervals ..... 2-6
Overflow ..... 2-6
Frequencies Lower Than 10 MHz ..... 2-7
Frequencies Higher Than 10 MHz ..... 2-7
Period Measurements ..... 2-8
Low Frequencies ..... 2-8
Period Averaging ..... 2-8
Width Measurements ..... 2-8
Width Averaging ..... 2.8
Totalizing ..... 2-9
Starting The Count ..... 2-9
Repackaging For Shipment ..... 2-9

## WARMING

the following servicing instructions ARE FOR USE BY QUALIFIED PERSONNEL ONLY. TO AVOID PERSONAL INJURY, DO NOT PERFORM ANY SERVICING OTHER THAN THAT CONTAINED IN OPERATING INSTRUCTIONS UNLESS YOU ARE QUALIFIED TO DO SO. REFER TO OPERATORS SAFETY SUMMARY AND SERVICE SAFETY SUMMARY PRIOR TO PERFORMING ANY SERVICE.
Page
Section 3 THEORY OF OPERATION
Introduction ..... 3-1
Block Diagram ..... 3-1
Input Conditioning ..... 3-1
Signal Routing ..... 3-1
Direct ..... 3-1
Prescaler ..... 3-1
$\times 100$ Multiplier ..... 3-1
Counter ..... 3-2
Function, Aange, And Decimal Select ..... 3-4
Function Select ..... 3-4
Range Select ..... 3-4
Decimal Point Logic ..... 3-4
Autorange ..... 3-5
Display ..... 3-6
Power Supplies ..... 3-6
Section 4 CHECKS AND ADJUSTMENTS
Performance Check Procedure ..... 4-1
Introduction ..... 4-1
Adjustment interval ..... 4-1
Services Available ..... 4-1
Test Equipment Required ..... 4-1
Adjustment Procedure ..... 4-7
Introduction ..... 4-7
Test Equipment Required ..... 4-7
Preparation ..... 4-7

## TABLE OF CONTENTS (cont)

Section 5 MAINTENANCE
Static Sensitive Components ..... 5-1
Test Equipment ..... 5-1
Cleaning instructions ..... 5-2
Exterior ..... 5-2
Interior ..... 5-2
Obtaining Replacement Parts ..... 5-2
Ordering Parts ..... 5-2
Soldering Techniques ..... 5-2
Interconnecting Pins ..... 5-3
Square Pin Assemblies ..... 5-3
Multipin Connectors ..... 5-3
Semiconductors ..... 5-3
Release Latch Removal ..... 5-4
Main Circuit Board (A12) Removal ..... 5-4
Display Circuit Board (A10) Removal ..... 5-4
Internal Jumpers ..... 5-5
Test Fixture Connectors ..... 5-5
Rear Interface Connector ..... 5-5
Functions Available ..... 5-5
Page
Section 6 OPTIONS
Section 7 REPLACEABLE ELECTRICAL PARTS
Section 8 DIAGRAMS AND ILLUSTRATIONS
Adjustment Locations
Block Diagram
Schematic Diagrams
Parts Location Grid
Section 9 REPLACE
Change Information

## LIST OF ILLUSTRATIONS

## Fig.

No. Page2-12-22-3
Plug-in Installation And Removal
Controls and Connectors . . . . ..... 2-2 ..... $2-3$
Advantages In Signal Attenuation ..... 2-5
Frequency Measurement ..... 2-7
Period Measurement ..... 2-8
Width Measurement ..... 2-9
Relationship of display update and counter reset signals ..... 3-3
Typical Square Pin Assembly ..... 5-3
Orientation And Disassembly of Multipin Connectors ..... 5-3
Rear Interface Connector Assignments ..... 5-6

## NOTE

The following illustrations appear in the Diagrams and Illustrations foldout section.

8-1 Adjustments And Test Points (Display Board)

## LIST OF TABLES

## Table

> Adjustments And Test Points (Main Board)

Parts Location Grids
No.
Page
1-1 Electrical Characteristics ..... 1-2
1-2 Environmental ..... 1-6
$1-3$2-1
3-1Physical Characteristics
1.7
Gate Time vs Measurement Resolution ..... 2-7
Counter Input, Function/Range Select, And Time Slot Relationships ..... 3-43-2
4-1
Time Slot to Decimal Point Relationship ..... 3-5
5-1
List of Test Equipment Requirements ..... 4-2
Relative Susceptability To Static Discharge Damage ..... 5-1
note

The following tables appear in the Diagrams and Illustrations foldout section.

## OPERATORS SAFETY SUMMARY

This general safety information is for both operating and servicing personnel. Specific warnings and cautions will be found throughout the manual where they apply, but may not appear in this summary.

## TERMS

## In This Manual

CAUTION statements identify conditions or practices that can result in damage to the equipment or other property.

WARNING statements identify conditions or practices that can result in personal injury or loss of life.

## As Marked on Equipment

CAUTION indicates a personal injury hazard not immediately accessible as one reads the marking, or a hazard to property including the equipment itself.

DANGER indicates a personal injury hazard immediately accessible as one reads the marking.

## SYMBOLS

## In This Manual

$\triangle$
This symbol indicates where applicable cautionary or other information is to be found.

## As Marked on Equipment



DANGER — High voltage.
Protective ground (earth) terminal.
ATTENTION - refer to manual.
(I) Refer to manual

## Power Source

This product is designed to operate from a power module connected to a power source that does not apply more than 250 volts rms between the supply conductors or between either supply conductor and ground. A protective ground connection by way of the grounding conductor in the power cord is essential for safe operation.

## Grounding The Product

This product is grounded through the grounding conductor of the power module power cord. To avoid electrical shock, plug the power cord into a properly wired receptacle before connecting to the product input or output terminals. A protective ground connection by way of the grounding conductor in the power cord is essential for safe operation.

## Danger Arising From Loss of Ground

Upon loss of the protective-ground connection, all accessible conductive parts (including knobs and controls that may appear to be insulating) can render an electric shock.

## Use The Proper Fuse

To avoid fire hazard, use only the fuse specified in the parts list for your product, and which is identical in type, voltage rating and current rating.

Refer fuse replacement to qualified service personnel.

## Do Not Operate in Explosive Atmospheres

To avoid explosion, do not operate this product in an atmosphere of explosive gases unless it has been specifically certified for such operation.

## Do Not Operate Plug-In Unit Without Covers

To avoid personal injury, do not operate this product without covers or panels installed. Do not apply power to the plug-in via a plug-in extender.

# SERVICING SAFETY SUMMARY 

## FOR QUALIFIED SERVICE PERSONNEL ONLY

Refer also to the preceding Operators Safety Summary

## Do Not Service Alone

Do not perform internal service or adjustment of this product unless another person capable of rendering first aid and resuscitation is present.

## Use Care When Servicing With Power On

Dangerous voltages may exist at several points in this product. To avoid personal injury, do not touch exposed connections and components while power is on.

Disconnect power before removing protective panels, soldering, or replacing components.

## Do Not Wear Jewelry

Remove jewelry before servicing this instrument. Rings, necklaces, and other metalic objects could come into contact with dangerous voltages and currents.

## Power Source

This product is intended to operate from a power module connected to a power source that will not apply more than 250 volts rms between the supply conductors or betwen either supply conductor and ground. A protective ground connection by way of the grounding conductor in the power cord is essential for safe operation.


## SPECIFICATION

## Instrument Description

The TEKTRONIX DC 504A is a multi-function counter/timer designed to operate in one compartment of any TM 500 or TM 5000-Series power module.

Frequency measurements to 100 MHz are within the capability of the DC 504A. Frequencies above 10 MHz are internally prescaled. Measurement of pulse widths and periods at rates up to 2.5 MHz is possible. Width and Period averaging of up to 1000 events is possible. An autorange feature allows the counter to automatically select the gate time (up to one second) or number of averages (up to 100). $A \times 100$ phase-locked loop multiplier automatically increases display resolution by a factor of 100 in the 10 Hz to 25 kHz frequency range. The 10 MHz internal time base provides a singleshot resolution of 100 ns . Input signals can be ac or dc coupled and attenuated by a factor of five. All measurement results are displayed in a six digit LED readout.

No options to the standard DC 504A are available.

## Standard Accessories

1 Instruction Manual

## NOTE

Refer to the tabbed Accessories page at the rear of this manual for more information.

## Performance Conditions

The limits stated in the Performance Requirements column of the following tables are valid only if the DC 504A has been adjusted at an ambient temperature between $+20^{\circ} \mathrm{C}$ and $+30^{\circ} \mathrm{C}$ and is operating at an ambient temperature between $0^{\circ} \mathrm{C}$ and $+50^{\circ} \mathrm{C}$ unless otherwise stated.

Information given in the Supplemental information and Description columns of the following tables is provided for user information only and should not be interpreted as performance check requirements.

The DC 504A must be operated or stored in an environment whose limits are described under Environmental Characteristics.

Allow at least 30 minutes warm up time for operation to specified accuracy; 60 minutes after storage in a high humidity environment.

Table 1-1
ELECTRICAL CHARACTERISTICS

| Characteristics | Performance Requirements | Supplemental information |
| :---: | :---: | :---: |
| InPuts |  |  |
| Input Frequency Range <br> Front Panel <br> Rear interface | Dc coupled, 0 to 100 MHz <br> Ac coupled, 10 Hz to 100 MHz <br> Dc coupled, 0 to 50 MHz <br> Ac coupled, 10 Hz to 50 MHz |  |
| Input Sensitivity $\times 1$ Attenuation $\times 5$ Attenuation Accuracy | 30 mV ms sinewave ( $85 \mathrm{mV} \mathrm{p}-\mathrm{p}$ ) to 100 <br> MHz <br> 85 mV p-p pulse at a minimum width of 5 ns | Within 2\% at dc |
| Input Dynamic Range X1 X5 |  | $2.0 \mathrm{Vp-p}$ signal within a $\pm 2.0 \mathrm{Vdc}$ window <br> 10.0 V p-p signal within a $\pm 10.0 \mathrm{Vdc}$ window |
| Trigger Level Range |  | Typically greater than $\pm 2 \mathrm{~V} \times$ attenuator setting. |
| Maximum Saie Input Voltage <br> Front Panel $\times 1$ $\times 5$ <br> Rear Interface |  | 200 V pk; 400 V p-p from dc to 50 kHz . derate to 15 V p-p from 1.33 MHz to 100 MHz <br> $200 \mathrm{~V} \mathrm{pk} ; 400 \mathrm{~V}$ p-p from dc to 5 MHz , derate to 20 V p-p at 100 MHz <br> $\leqslant 4 \mathrm{~V} k$ |
| Input impedance <br> Front Panel $\times 1, \times 5$ <br> Rear Interface $\times 1, \times 5$ |  | 1 M , paralleled by approximately 25 pF <br> 50 ohms $\pm 10 \%$ at dc |

Table 1-1 (cont.)

| Characteristics | Performance Requirements | Supplemental Information |
| :---: | :---: | :---: |
| FUNCTIONS |  |  |
| Frequency to 10 MHz <br> Range <br> Accuracy <br> Gate Time <br> Resolution <br> Non-phase-locked <br> Phase Locked <br> Lock Range <br> Multiplication <br> Lock Time | Dc coupled, 0 Hz to 10 MHz Ac coupled, 10 Hz to 10 MHz $\begin{aligned} & 10 \mathrm{~Hz} \leqslant \text { Freq } \leqslant 25 \mathrm{kHz} \\ & \times 100 \\ & \leqslant 5 \text { seconds } \end{aligned}$ | $\pm 1$ count $\pm$ time base error $\times$ freq <br> 10 ms to 10 sec , selectable in decade steps, or autoranging ( 10 ms to 1 sec only) <br> 100 Hz to 0.1 Hz , selectable in decade steps, or autoranging ( 100 Hz to 1 Hz only) <br> 1 Hz to 0.001 Hz , selectable in decade steps, or autoranging ( 1 Hz to 0.01 Hz only) <br> Phase Lock Loop automatically increases resolution whenever loop locks. PLL defeat can be accomplished by an internal jumper. |
| Frequency to 100 MHz <br> Range <br> Prescale Factor <br> Accuracy <br> Gate Time (Resolution) | Dc coupled, 0 Hz to 100 MHz Ac coupled, 10 Hz to 100 MHz $\div 10$ | $\pm 1$ count $\pm$ time base error $\times$ freq <br> 10 ms to $10 \mathrm{sec}(1 \mathrm{kHz}$ to 1 Hz ). Selectable in decade steps, or autoranging ( 10 ms to 1 sec only). |
| Period AVG <br> Freq Range <br> Number of Averages ( N ) <br> Resolution <br> Accuracy | Dc coupled, 0 Hz to 2.5 MHz Ac coupled, 10 Hz to 2.5 MHz | Overflows above $99999.9 \mu \mathrm{~s}$ ( 100 ms ) <br> $10^{\circ}$ to $10^{3}$, selectable in decade steps, or autoranging ( $10^{\circ}$ to $10^{2}$ only). <br> 100 ns to 100 ps , selectable in decade steps or autoranging ( 100 ns to 1 ns only). $\begin{aligned} & \pm \frac{100 \mathrm{~ns}}{\mathrm{~N}} \pm \text { time base error } \times \text { period } \\ & \pm 1.4 \times\left(\frac{\text { trigger jitter error }}{\mathrm{N}}\right) \end{aligned}$ |

Table 1-1 (cont.)


Table 1-1 (cont.)

| Characteristics | Performance Requirements | Supplemental Information |
| :---: | :---: | :--- |
| Totalize | Dc coupled, 0 Hz to 10 MHz |  |
| Freq Range | Ac coupled, 10 Hz to 10 MHz | Overflows above 999999. Display update <br> run/hold will hold display while counter contin- <br> ues to advance. Releasing run/hold will update <br> display to new value. |

## NOTES:

Trigger Jitter Error (in $\mu \mathrm{s} \mathrm{rms}$ ) $=$
$\sqrt{\left(e_{n^{\prime}}\right)^{2}+\left(e_{n^{2}}\right)^{2}(V)}$
Input slew rate at trigger point ( $\mathrm{V} / \mu \mathrm{s}$ )
where $e_{n^{\prime}}=150 \mu \mathrm{~V}$ rms typical internal noise
$e_{n^{2}}=r m s$ noise of the signal input at the trigger point for a 100
MHz bandwidth.

Trigger slew rate error in $\mu \mathrm{s}=$
$\frac{\text { input hysteresis }}{2}(V)$
$\overline{\text { | Input slew rate | at trigger point }(\mathrm{V} / \mu \mathrm{S})}$
where input hysteresis $=30 \mathrm{mV}$ p-p typical.
$N=$ Number of periods averaged in PERIOD AVG, or the number of widths averaged in WIDTH AVG $\Omega$ or WIDTH AVG ㄷ.

Time base error is the sum of all errors specified for the time base.

## TIME BASE

| Time Base |  |  |
| :---: | :---: | :---: |
| Frequency (at calibration | $10 \mathrm{MHz} \pm 1 \times 10^{-7}$ |  |
| Adjustment Resolution | $\pm 5 \times 10^{-8}$ |  |
| Temperature Stability $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right)$ | $\pm 5 \times 10^{-6}( \pm 5 \mathrm{ppm})$ |  |
| Aging | $\leqslant 1 \times 10^{-6 / y r}(\leqslant 1 \mathrm{ppm} / \mathrm{yr})$ |  |
| External Timebase Input | 10 MHz | Must Drive one HC Logic family load plus 100 K |
|  |  | $\mathrm{V}_{\mathrm{IH}}=3.7 \mathrm{~V} / 40 \mu \mathrm{~A}$ minimum |
|  |  | $\mathrm{V}_{\mathrm{IL}}=0.95 \mathrm{~V} / 10 \mu \mathrm{~A}$ maximum |

Table 1-2
ENVIRONMENTAL*

| Characteristics | Description |  |
| :---: | :---: | :---: |
| Temperature |  | Meets MIL-T-28800B, class 5. |
| Operating | $0^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$ |  |
| Nonoperating | $-55^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ |  |
| Humidity | $\begin{aligned} & 95 \% \text { RH, } 0^{\circ} \mathrm{C} \text { to } 30^{\circ} \mathrm{C} \\ & 75 \% \text { RH, to } 40^{\circ} \mathrm{C} \\ & 45 \% \text { RH, to } 50^{\circ} \mathrm{C} \end{aligned}$ | Meets MIL-T-28800B, class 5. |
| Altitude |  | Meets MIL-T-28800B, class 5. |
| Operating | $4.6 \mathrm{~km}(15,000 \mathrm{ft})$ |  |
| Nonoperating | $15 \mathrm{~km}(50,000 \mathrm{ft})$ |  |
| Vibration | $0.38 \mathrm{~mm}\left(0.015^{\prime \prime}\right)$ peak to peak, 5 Hz to 55 $\mathrm{Hz}, 75$ minutes. | Meets MIL-T-28800B, class 5, when installed in qualified power modules. ${ }^{\text {D }}$ |
| Shock | 30 g 's ( $1 / 2$ sine), 11 ms duration, 3 shocks in each direction along 3 major axes, 18 total shocks. | Meets MIL-T-28800B, class 5, when installed in qualified power modules. ${ }^{\text {D }}$ |
| Bench Handling | 12 drops from $45^{\circ}, 4^{\prime \prime}$ or equilibrium, whichever occurs first. | Meets MIL-T-28800B, class 5 when installed in qualified power modules. ${ }^{\text {D }}$ |
| Packaged Product Vibration and Shock ${ }^{\text {c }}$ | Qualified under National Safe Transit Association Preshipment Test Procedures 1A-B-1 and 1A-B-2. |  |
| Electrostatic Immunity | 20 KV maximum charge applied to instrument case. |  |
| Electromagnetic Compatibility ${ }^{\text {d }}$ | Within limits of F.C.C. Regulations, Part 15, Subpart J. Class A; VDE 0871; and MIL461A tests RE01, CE01, CE03, RS01, RS03, CS01, and CS02.e |  |

## ENVIRONMENTAL EXCEPTIONS

| Temperature | During low temperature test 4.5 .5 .1 .3 (b) for class 5, steps 4 and 5 shall be performed before <br> step 2. Also, the instrument shall not be operating during step 6, paragraph 4.5.5.1.3 (e), class 5. <br> While operating, condensed moisture shall not be present on class 5 instruments. Drying of the <br> instrument for this class may be performed in a suitable chamber, if necessary. |
| :--- | :--- |

${ }^{-}$With power module.
${ }^{\text {thefer to }}$ TM 500/5000 power module specifications.
${ }^{\text {'Without power module. }}$
${ }^{\text {a }}$ System performance subject to exceptions of power module or other individual plug-ins.

- Within 4 dB of REO2 spec at 140 MHz and 150 MHz .

Table 1-3
PHYSICAL CHARACTERISTICS

| Characteristics | Description |
| :--- | :--- |
| Finish | Polycarbonate |
| Front Panel | Chromate conversion coated aluminum |
| Chassis | $794 \mathrm{~g} \mathrm{(13/4} \mathrm{lbs)}$. |
| Net Weight (nominal) |  |
| Physical Dimensions (nominal) | $126.0 \mathrm{~mm}(4.96$ inches) |
| Height | $65 \mathrm{~mm} \mathrm{(2.5} \mathrm{inches)}$ |
| Width | $278.8 \mathrm{~mm}(10.98$ inches) |
| Length |  |

# OPERATING INSTRUCTIONS 

## Introduction

This section of the manual provides operating information required to obtain the most effective performance from the DC 504A. Included is a functional description of the front panel controls and connectors, operating considerations. and basic measurement techniques. Also included are installation instructions and repackaging information.

## PREPARATION FOR USE

## First Time Inspection

Inspect the instrument for visible damage (dents, scratches, etc.). Keep the original shipping container and packing material for future use. If the instrument is damaged, notify the carrier and the nearest Tektronix Service Center or representative.

## Operating and Non-Operating Environments

The instrument can be operated, stored, or shipped within the environmental limits stated in the Specification section of this manual. However, the counter should be protected at all times from temperature extremes which can cause condensation within the instrument.

## Rear Interface Considerations

A slot between pins 21 and 22 on the rear connector identifies this instrument as a member of the TM 500 counter family. If the counter is used to build a system, insert a family barrier key (Tektronix Part No. 214-1593-02) in the corresponding position of the selected power module jack to prevent plug-ins belonging to a different family from being used in that compartment of the power module.

## WARMING

To avoid electric shock, disconnect the power module power cord before inserting the family barrier key in the power module jack. Refer the barrier key insertion to qualified service personnel.

## NOTE

Rear interface information is found in the Maintenance section of this manual. Refer the interface connections to qualified service personnel.

## INSTALLATION AND REMOVAL

## NOTE

Refer to the Operator's Safety Summary in the front of this manual before installing this instrument in the power module.

Refer to the power module instruction manual and make sure that the line selector block is positioned correctly for the line voltage in use. Check the counter and the power module for the proper fuses. Be certain that the power plug for the power module has the proper grounding conductor.


To prevent damage to the instrument, turn the power module off before installation or removal from the power module. Do not use excessive force to install or remove the instrument from the power module.

Check to see that the plastic barrier keys on the interconnecting jack of the selected power module compartment match the cutouts in the rear interface connector for the counter. If they do not match, do not insert the counter until the reason is investigated.

If the cutouts and barrier keys match, align the chassis of the counter with the upper and lower guides of the selected compartment. See Fig. 2-1. Insert the counter into the compartment and press firmly to seat the rear interface connector. Apply power by operating the POWER switch on the power module.


Fig. 2-1. Plug-in installation and removal.

To remove the counter from the power module, turn off the POWER switch, pull the release latch knob (located in the lower left front comer) until the interconnecting jack disengages. Pull the counter straight out of the power module compartment.

## CONTROLS AND CONNECTORS

Although the DC 504A is fully calibrated and ready to use, the location and function of the controls and connectors should be reviewed before attempting to operate it. Following is a brief description of the front panel controls and connectors. Refer to Fig. 2-2.

READOUT DISPLAY-six digit LED readout with automatically positioned decimal point and leading zero suppression. Display reads in KILOHERTZ or MICROSECONDS.

GATE-indicates the status of the main gate. When illuminated, the gate is open; the instrument is in the process of making a measurement. When extinguished, the gate is closed:

OVERFLOW-when illuminated, indicates register overflow.

MULTIPLIER LOCK-illuminated when the Multiplier (Phase Lock Loop) circuit is active. The Multiplier is automatically activated when measuring frequencies between 10 Hz and 25 kHz . This circuit multiplies the measured frequency by 100 , providing two additional digits of display resolution.

FUNCTION-selects the following measurement or counting modes for the instrument.

FREQ TO 10 MHz -measures directly and displays the frequency of input signals up to 10 MHz .

FREQ TO 100 MHz -internally prescales and displays the frequency of input signals up to 100 MHz .

PERIOD-measures and displays the period of the input signal.


Fig. 2-2. Controls and Connectors.

WIDTH $\Omega$-measures and displays the time interval between the triggering point on the positive leading edge to the corresponding point on the trailing edge of a pulse applied to the input.

WIDTH 工 - measures and displays the time interval between the triggering point on the negative leading edge to the corresponding point on the trailing edge of a puise applied to the input.

TOTALIZE-pulses applied to the input will be displayed in a running total until the counter is manually reset or register overflow occurs.

TIME/AVGS-depending on the position of the FUNCTION switch, selects the gate time or the number of measurements to be averaged. In AUTO, a gate time that will display six digits is automatically selected.

RESET-resets the count to zero when operating in the TOTALIZE mode. Acts as a master reset ensuring that the readout has been cleared before the next measurement. Also provides a check of all display LED's; when pressed and held, a row of 8 's is displayed.

DISPLAY UPDATE-when the button is in the RUN (out) position, the DC 504A counts or makes measurements continuousiy.

When the button is in the HOLD (in) position and the instrument is in a measurement mode, the last measurement is displayed and no more made until the button is released.

When the instrument is counting (TOTALIZE), moving the button to the HOLD position stops the display only; the count continues to accumulate in the registers. When the button is released, the display is automatically updated to the current count accumulation and continues to run.

TRIGGER LEVEL-selects the amplitude point on the positive or negative slope of the input signal at which the triggering window is placed.
(10) ATTEN-selects the attenuation factor for the input signal. When the button is in the $\times 1$ (out) position the input signal is not attenuated. The input signal is attenuated by a factor of five when the button is in the $\times 5$ (in) position.

COUPL-selects the method of coupling the input signal to the counter. When the button is in the DC (out) position, the signal is applied directly. The input signal is capacitively coupled to the input when the button is in the AC (in) position.
(12) Input Connector to the counter. Input impedance is 1 $\mathrm{M} \Omega$ shunted by approximately 25 pF .


Maximum input amplitude is limited to 200 V peak.

Release Latch-disengages the instrument for removal from the power module.

Provisions have been incorporated in the DC 504A to modify the following operating conditions.

Multiplier (PLL)-the instrument is shipped with the multiplier circuit in the enabled condition. This circuit can be disabled if desired.

Time Base-the instrument is shipped with the internal time base connected. This can be disconnected to permit application of an external clock signal via the rear interface.

Signal Input-the instrument is shipped with the front panel input connected. Disconnecting this input allows signal measurements to be made via the rear interface.

## WARNING

Refer qualified service personnel to the Maintenance Section to make changes to the above operating conditions.

## OPERATING CONSIDERATIONS

## INPUT CONNECTIONS

## Maximum Safe Input Voltage Limits

To avoid instrument damage, make certain that the input voltages to the front panel connectors or rear interface inputs do not exceed their specified limits. See Specification section.

Be careful with high-frequency, high-amplitude signals. The front panel maximum safe input voltage ( $\times 1$ attenuation) is cerated linearity from 400 V pp at 50 kHz to 15 V pp at 1.33 MHz and higher. Refer to the Specification section.

## Connecting External Signal Sources

If a high impedance signal probe is to be used between the front panel bic connector and the measurement source, use a probe capable of compensating for the input capacitance of the counter (less than 30 pF ). A high impedance probe such as the TEKTRONIX P6125, is recommended for all digital logic applications.

## Input Coupling, Noise, and Attenuation

You can use either the ac coupling (AC COUPL) or dc conping (DC COUPL) mode to couple the input signal to the input amplifier. If the signal to be measured is riding on a dc level, its amplitude limits may not fall within the triggering level range. The AC COUPL mode should be used for repetitive signals having a fixed frequency and a constant duty cycle when they are riding on a large dc level.

If the signal duty cycle changes during a measurement, the triggering point will shift, possibly causing erroneous results. Use the DC COUPL mode for low frequency ac signals without large dc offset, signals with a low duty cycle, and during width measurements.

Noise may be coupled to the input amplifier along with the signal to be measured. Noise may originate from the operating environment, the signal source, or be caused by improper connections. If the noise is of sufficient amplitude, it can result in inaccurate measurements due to false triggering. Using an external attenuator may solve the problem. See Fig. 2-3.

The input dynamic range specification describes the largest amplitude signal with a risetime or fallime less than about 5 ns that will not cause ringing and distortion internal to the counter. Ringing may cause mistriggering near the positive or negative peaks of the signal.

(3464-04A)4291-03A

Fig. 2-3. Advantages in signal attenuation.

## Operating Instructions-DC 504A

The minimum signal amplitudes are defined by the input sensitivity requirements for the AC COUPL and DC COUPL modes (see Specification section). Proper use of the ATTEN (attenuation) control will ensure operation within the maximum limits; $\pm 2 \mathrm{~V}$ for $\times 1$ ATTEN. $\pm 10 \mathrm{~V}$ for $\times 5$ ATTEN.

## Triggering

The TRIGGER LEVEL and COUPL controls affect the counter's ability to make a measurement. In general, the trigger controls are similar to oscilloscope controls, except that the end result is not a stable waveform graphic display, but a stable digital frequency display.

Input Coupling Switch. The Input Coupling switch selects ac (capacitive) or dc (direct) coupling for the input signal. Ac coupling is convenient for most frequency measurements to avoid readjusting the TRIGGER LEVEL control for changing dc levels. It does, however, reduce sensitivity to signals below 10 Hz . Thus, for period measurements longer than 0.1 sec , dc coupling shoutd be used.

Trigger Level. The TRIGGER LEVEL control must be properly adjusted for a stable reading. It is not difficult to adjust unless the signal amplitude or frequency is ciose to (or beyond) the specified limits.

A signal that looks stable on an oscilloscope may still show jitter when measured with a digital counter. If the count varies from reading to reading, it is probably due to jitter in the signal source. If the count changes dramatically, the DC 504A is not being triggered properly, either because the controls are not set right or the signal is beyond the counter's capabilities (too small in amplitude or too high in frequency).

The TRIGGER LEVEL control allows the operator to move the hysteresis window of the trigger circuit to an optimum level on the input signal to ensure stable triggering. The TRIGGER LEVEL control adjusts over a nominal $\pm 2.0 \mathrm{~V}$ range of the input signal. If a wider range is desirable, use the $\times 5$ input attenuator for $\pm 10 \mathrm{~V}$ range.

## Reducing Measurement Errors

As an aid in reducing measurement errors, keep in mind the following factors:

Use the proper ATTEN control and high impedance attenuator type probes when measuring signals from high impedance circuits.

- Consider trigger errors caused by input signals with slow rise or falltimes.
- Average the measurement over a larger number of cycles of the input signal (greater number of AVERAGES).
- Maintain the counter environment at a constant temperature.
- Apply a 10 MHz external time reference standard to the rear interface inputs.
- Perform internal adjustments, if necessary.


## FREQUENCY MEASUREMENTS

Use ac coupling for most frequency measurements to avoid readjusting the LEVEL control because of changing do levels. Signals less than 4 volts peak-to-peak need not be attenuated; larger signals should be attenuated to within the range of 85 mV to 4 volts peak-to-peak.

Set the FUNCTION switch to FREQ TO 10 MHz and, with the TIME/AVGS switch, select one of the shorter gate times. Connect the signal to be measured to the input and adjust the TRIGGER LEVEL control for a stable display. The level control setting is not critical uniess the signal amplitude and frequency are close to specified limits. Fig. 2-4 shows waveform timing during frequency measurement.

## Measurement Intervals

To adjust the trigger control, choose a short gate time such as 0.1 or .01 seconds. This gives rapid feedback via the display as to whether or not the counter is being triggered. Final selection of gate time depends upon the frequency being measured, desired resolution, and the time required to make a measurement. A 10 second gate time requires 10 seconds for a measurement to be made and displayed. This gives 0.1 Hz resolution. See Table 2-1.

## Overtiow

Through intentional use of overflow displays, it is possible to increase the resolution of the counter. Select a gate time that displays the most significant digit as far to the left as possible without overflow. Note the numbers displayed to the right of the decimal. Move the decimal to the left, by selecting longer gate times, until the desired resolution is


Fig. 2-4. Frequency Measurement.
achieved. The OVERFLOW indicator will light when the most significant digit has overfowed the last storage register. The relationship between gate time and resolution is shown in Table 2-1.

Table 2-1
GATE TIME VS. MEASUREMENT RESOLUTION

| Gate <br> Time | FREQ TO <br> 10 MHz | FREQ TO 10 MHz <br> Multiplier Locked | FREQ TO <br> 100 MHz |
| :---: | :---: | :---: | :---: |
| .01 sec | 100 Hz | 1 Hz | 1 kHz |
| 0.1 sec | 10 Hz | 0.1 Hz | 100 Hz |
| 1.0 sec | 1 Hz | .01 Hz | 10 Hz |
| 10 sec | 0.1 Hz | .001 Hz | 1 Hz |

## Frequencies Lower Than 10 MHz

Frequencies 10 MHz and below are measured with the FUNCTION switch in the FREO TO 10 MHz position: Frequencies within the range 10 Hz to 25 kHz are automatically multiplied internally by 100 to increase display resolution. This is accomplished by routing the incoming signal through a phase-locked loop multiplier circuit before it is counted. If, for example, a 5 kHz signal is to be measured with a conventional counter, the display would read 5.000 kHz with one second of gate tirne. The same signal measured with
the DC 504A, because it is multiplied by 100 (the counter is actually measuring 500 kHz ), would display 5.00000 kHz with one second of gate time.

Since any frequency within the range of the multiplier will be multiplied, provision has been incorporated to lock out this feature if so desired. Refer qualified service personnel to the Maintenance Section. A front panel LED indicates when the multiplier is locked. The multiplier circuit is only active when the DC 504A is in this mode.

## nOTE

When the multiplier is locked and a gate time of 10 Sec is selected, no decimal point appears. The decimal point is implied to the left of the sixth digit (MSD).

## Frequencies Higher Than $10 \mathbf{~ M H z}$

Frequencies between 10 MHz and 100 MHz are measured with the FUNCTION switch in the FREQ TO 100 MHz position. Input frequencies in this range are internally prescaled (divided) by a factor of 10. If, for example, a frequency of 95 MHz is to be measured, the prescaler divides it down so the counter is actually measuring only 9.5 MHz . This, however, also reduces the display resolution by a factor of 10. Resolution can be increased, if desired, by selecting a longer gate time.

## PERIOD MEASUREMENTS

The PERIOD mode reverses the functions of signal and clock as compared to the frequency mode. In frequency mode, signal events are counted for some number of clock pulses, then displayed. In PERIOD, clock pulses are counted for some number of signal events then displayed. Refer to Fig. 2-5.

## Low Frequencies

Period measurements of signals below 10 Hz , and particularly in the lowest decade from 0.1 Hz to 1.0 Hz , are sensitive to wave shape and amplitude. Since it is desirable for the signal to pass through the trigger hysteresis abruptly, square-wave inputs are preferred. Sine and triangle waves can be measured accurately at the very low end if the input amplitude is kept somewhat above minimum specification so that the trigger input is driven hard.

## Period Averaging

The best single shot resolution attainable in a period measurement is a direct function of the speed (frequency) of the time base clock being counted. The DC 504A has a 10 MHz time base; a single period of this time base is 100 ns (period $=1$ /frequency). Therefore, the resolution of a single period measurement is 100 ns .

Resolution can be increased by utilizing the capability of the DC 504A to average period measurements. Period averag-
ing up to 1000 is attainable, which results in a directly proportional increase in resolution. If, for example, the resolution of a single period measurement is 100 ns , averaging 1000 events results in a 1000 times increase in resolution, or 100 ps .

To illustrate the display readout, assume an input signal with a $1.0032 \mu \mathrm{~s}$ period. A single period measurement would display $1.0 \mu \mathrm{~s}$ (100 ns LSD). Averaging 10 periods of this same signal would display $1.00 \mu \mathrm{~s}$ ( 10 ns LSD) and 100 periods would display $1.003 \mu \mathrm{~s}$ ( $1 \mu \mathrm{~s}$ LSD). With a 1000 period average the display will read $1.0032 \mu \mathrm{~s}$ ( 100 ps LSD).

In the AUTO mode, the counter always attempts to fill the display ( 6 digits) while averaging up to 100 events. Note that periods longer than 100 ms will overflow the display.

## WIDTH MEASUREMENTS

The width modes measure the time between two points on a waveform. These two points are selected with the TRIGGER LEVEL control such that the main gate turns on at the selected level and turns off at the same level but the opposite slope. Refer to Fig. 2-6.

## Width Averaging

Averaging can be used to increase the accuracy and resolution of repetitive signal measurements. The basic reason for


Fig. 2-5. Period Measurement.


Fig. 2-6. Width Measurement
averaging is the statistical reduction of the $\pm 1$ count error. If the $\pm 1$ count error is truly random, then as more intervals are averaged, the measurement will tend to approach the true value of the time interval. For time interval averaging to work, the time interval being measured must be repetitive and have a repetition frequency that is nonsynchronous to the counter clock rate.

The DC 504A has the capability of width averaging up to 1000 events. This single input measurement is much easier than typically associated with Universal Time Interval Counters.

## nOtE

Width $\Omega$ and Width Lrequire an arming pulse before a measurement begins. In the case where a stream of pulses is being measured, this presents no problem as the first pulse will arm the measurement, and the next ' $N$ " pulses will be measured. If a single pulse is to be measured, the counter can be put into the armed mode by rotating the trigger level completeIy clockwise, then counter-clockwise until the GATE indicator just turns on (it may require two rotations). The counter is then armed and will measure the next pulse it sees.

## TOTALIZING

In the Totalize mode, signal events applied to the INPUT are counted and the accumulated total is displayed until the re-
set button is pushed or the FUNCTION switch is changed to another position. This mode is a manual analog of the frequency mode. Its main application is to accumulate a count of relatively slow and irregular events.

## Starting the Count

Apply the signal to the input connector and set the trigger controls the same as for frequency measurement. Adjust the TRIGGER LEVEL controf until the displayed total begins to increment. The accumulated count is displayed in whole numbers. In the Totalize mode, only the TRIGGER LEVEL control, the RESET button and the DISPLAY UPDATE button affect the display.

## NOTE

In the TOTALIZE mode, moving the DISPLAY UPDATE button to the HOLD position stops the display only; the count continues to accumulate in the registers. Releasing the button to the RUN position updates the display to the current register accumulation and the count display continues from there.

## REPACKAGING FOR SHIPMENT

Should it become necessary to return the instrument to a Tektronix Service Center for service or repair, attach a tag to the instrument showing the owner (with address) and the name of the individual to be contacted, complete instrument serial number, option number, and a description of the service required.

If the original container and packaging material is unfit for use or not available, repackage the instrument as follows:

1. Obtain a carton of corrugated cardboard having inside dimensions no less than six inches more than the instrument dimensions; this will allow for cushioning. The shipping carton test strength for the DC 504A is 200 pounds.
2. Surround the instrument with polyethylene sheeting to protect the finish.
3. Custion the instrument on all sides by tightly packing dunnage or urethane foam between carton and instrument, allowing three inches on all sides.
4. Seal the carton with shipping tape or industrial staples.
5. Mark the shipping carton "FRAGILE INSTRUMENT" to indicate special handling.

## Warning

The following servicing instructions are for use only by qualified personnel. To avoid personnel injury, do not perform any servicing other than that contained in the operating instructions unless you are qualified to do so. Refer to General Safety Summary and Service Safety Summary prior to performing any service.

## THEORY OF OPERATION

## Introduction

This section of the manual contains a description of the electrical circuits of the DC 504A. Refer to the block diagram and schematic diagrams on the foldout pages in the rear of the manual to aid in understanding this description. Diamond enclosed numbers appearing throughout this section refer to the schematic diagram on which the circuit being discussed is located. The schematic diagrams are divided with gray-tint blocks according to circuit function. The titles correspond to those shown on the block diagram.

## Block Diagram

The block diagram shows the stages and basic interconnections of each major circuit in the instrument. Each circuit is described in detail. Use the block diagram and detailed circuit diagrams for reference.

## Input Conditioning

Input signals are applied to front panel connector J4015, or through connections at the rear interface. The position of Input selector jumper P4014 selects either front panel or rear interface input. Input to the rear interface is terminated in $50 \Omega$ (R4015) to allow connections using standard $50 \Omega$ coaxial cable. Input signals pass through DC/AC coupling switch S4024 into a frequency compensated attenuator network. Attenuator switch S 4025 is normally in the $\times 1$ position, which allows the signal to pass directly through. Five times attenuation is provided by R4023 and R4024. C4021 and C4025 provide frequency compensation. R4028 is the 1 M $\Omega$ input termination. R4032, R4036, and C4036 serve to limit current to and compensate for capacitance around the gate of Q4022. Overvoltage protection is provided by CR4032 and CR4037. These diodes clamp the signal at approximately $\pm 5.5 \mathrm{~V}$.

A matched pair of FET's, Q4022 and Q4023, form a high impedance differential comparator. Constant current to this amplifier is supplied by Q4021 with associated circuitry. The voltage at the gate of Q4023 is set by the TRIGGER LEVEL control (R4037). This voltage is divided across R4033 and R4034 to approximately $\pm 2.2 \mathrm{~V}$.

The output of the comparator drives a three stage line receiver, the inputs of which are pins 9 and 10 of U3022B. The
first stage matches the impedance of the comparator to the second stage amplifier. U3022A is a voltage amplifier with a gain of approximately three. The third stage, U3022C, is configured as a Schmitt trigger circuit. High frequency peaking is accomplished by C3021. This stage serves to shape the inputs into fast edge outputs which feed to the counter.

## Signal Routing

Output from the Schmitt trigger is routed through one of three paths to the counter circuit. Depending on the function or frequency range selected, signals pass directly, through a $\div 10$ prescaler, or through a $\times 100$ resolution multiplier (phase-locked loop) to the counter.

DIRECT. This routing to the counter is through a switching circuit composed of U1063A, Q1066, and Q1068. For all signals, except frequencies to be multiplied or divided, or negative pulse measurements, Q1068 tums off and the signal path is through Q1066. When the instrument is set to measure negative pulse width, Q1066 turns off and the signal path is through Q1068. When measuring frequencies higher than 10 MHz, Q1066 and Q1068 are both turned off and the path is through the $\div 10$ Prescaler, U2067.

The output of the switching circuit is fed to pin 9 of U1063B. The differential outputs of U1063B drive an ECL to TTL converter, Q1062 and Q1064. The converter outputs are inverted through U1048A and U1048B and applied directly to the A and B inputs of the counter, U2047 (Diagram 3).

PRESCALER. Inputs at frequencies from 10 MHz to 100 MHz are routed through a $\div 10$ prescaler. In this mode, both transistor switches (Q1066 and Q1068) are off and the signal is applied to the input (pin 7) of U2067. This integrated circuit is a $\div 10$ counter; the output frequency is one-tenth the input frequency. The prescaler output (pin 15) connects to pin 10 of U1063B. The signal then routes through the ECL to TTL converter to the counter circuits. The prescaler is enabled when pin 9 is pulled low through S2061A in the FREQ TO 100 MHz position.
$\times 100$ MULTIPLIER. With the FUNCTION switch in the FREQUENCY TO 10 MHz position, inputs ranging between 10 Hz and 25 kHz route to a $\times 100$ Resolution Multiplier
(phase-locked loop) circuit. This is an automatic function unless the loop is disabled by moving jumper P1040 (PLL Defeat) to the ground position.

Transistor Q1056 serves as an ECL to TTL converter. The input signal is buffered and inverted by U1052D and fed to pin 14 of U2054. (The output signal from U1052D is +5 V to -5 V . This integrated circuit consists of a phase comparator and voltage controlled oscillator. Only the phase comparator is utilized. The phase of the signal at pin 14 is compared to the phase of the signal at pin 3. The output at pin 13 determines the oscillator frequency. The voltage controlled oscillator (VCO) consists of U1044A, B, C, Q1053 and Q1054.

To understand the operation of the oscillator circuitry, assume that the emitter of Q1054 is at about +5 V . Current flows through U1044A and R1046 charging capacitor C1052. Pin 10 of U1044C is at about +5 V and pin 12 at about -5 V . Q1054 is tumed off, with its base at about +5 $V$. The drain of U1044A goes negative at a rate determined by the current flow through it. When the voltage at the drain of U1044A drops to about 0 V , pin 12 of U1044C switches to about +5 V and pin 8 of U1044B goes low turning Q1054 on. As current flows through Q1054, the voltage drop across R1046 increases turning. on Q1053. Current flow through Q1053 is much greater than through U1044A and pin 10 of U1044C rises rapidly until U1044C and U1044B change state. This turns off Q1054 and repeats the cycle. The output waveform at the collector of Q1054 is a fast spike from about -5 V to about 0 V . The frequency of the circuit varies from about 500 Hz to about 3.5 MHz . This is accomplished by varying the current through U1044A and consequently the charge time of C1052.

The positive going ( -5 V to 0 V ) spike, at varying frequencies, feeds to U1052A, is buffered, inverted and applied to the input of U1032 (pin 4). This integrated circuit (U1032A and B) divides the output frequency by 100 . The output of U1032 (pin 13) feeds through Q1043, a TTL to MOS converter, to the second input of the phase comparator (U2054 pin 3).

If the frequency of the waveform at the collector of Q1054 goes higher than exactly 100 times the input (pin 14 U2054), the output voltage at pin 13 of U2054 goes more negative, reducing the oscillator frequency until both frequencies are in lock. The oscillator output at pin 3 U1052A feeds through U1052B and U1063C, is converted to ECL levels and applied to the third input, pin 11, of U1063B.

When the circuit is out of lock, pin 1 of U2054 goes low turning Q1057 on and Q1052 off. This results in a high at the output (pin 8) of U1052C. This high is applied to pin 9 of U1031B (Diagram 5) causing its output to go low. This low
at pin 13 of U1048E causes its output to go high extinguishing the MULTIPLIER LOCK indicator (Diagram 4). When the loop is locked, the output of U1052C goes low and the indicator is on.

## Counter

The counting circuitry for the DC 504A is contained almost entirely in one integrated circuit package U2047. With the exception of R2051, C2051, C2052, C2053, and a 10 MHz crystal (Y2054), the time base circuit is internal to the package. Range, function detection, switching circuitry, time slot, and display segment decoders and drivers are contained in the package.

The external oscillator input to the counter at pin 33 is connected to the buffered internal time base output, pin 38. Counter timing can also be from a clock signal external to the instrument by moving P2042 to the Ext position. This signal is taken from pin 14A on the rear interface and buffered by U2027C.

Variable capacitor C2051 serves to compensate for variations in the 10 MHz crystal and will vary the oscillator frequency several hundred Hertz.

The counter has two inputs for measured events; input $A$ (pin 40) and input B (pin 2). All signals to these inputs come through the ECL to TTL converter circuit (Diagram 2). All events to be counted, except width, are applied to input A. In the width mode, the counter measures the time interval between an event on $A$ input and an event on $B$ input. For example: in the width positive mode, the rising edge of the pulse triggers input A starting the count, and the falling edge triggers input B stopping the count. There are four other inputs that set the counter to measure and display signals applied to inputs A and B. These inputs are: Range (pin 21), Function (pin 4), Control (pin 1), and Ext Decimal Point (pin 20). The counter digit drive (time slot) outputs, through the range and function select circuitry, provide the control signals. This is discussed in more detail under the heading Range and Function Selection.

The Run/Hold function is controlled by front panel pushbutton switch S3032. When the switch is in the RUN (out) position, pin 39 of U2047 is low through Q3031. When the switch is moved to the HOLD (in) position, pin 39 is at +5 V stopping the counter. The last complete measurement made is displayed. When operating in the TOTALIZE mode, activating HOLD stops only the display; the counter continues to accumulate information. Returning to RUN updates the display to the data in the accumulator and the count continues.

The Reset Input, pin 19, is high when the counter is running. Moving S3012A (RESET) to the reset position resets the counter to zero and clears the display. With S3012A in this position, pin 12 of U1031C (Diagram 5) is also pulled low enabling the gate and allowing TS8 to pass through the gate. TS8 is inverted through U1031A and applied to the counter Control Input, pin 1. During TS8, the counter Display Test function is activated and all segments and decimal points in the display are illuminated.

The BCD outputs, pins 6, 7, 17, and 18 are used to detect display zeros. The BCD information is applied to U1037A which triggers the autorange circuitry. Additional details are contained in the discussion on Autoranging.

The Measurement In Progress output at pin 3 is used to drive the front panel GATE indicator. The level at this pin is
low when the gate is open and the counter is making a measurement. This output is buffered and inverted through U1048D. The high output from U1048D turns the pulse stretcher circuit on, Q2023 and Q2027 (Diagram 4), which illuminates the GATE indicator. This circuit lengthens short gate pulses (to approximately 50 ms ) so that the GATE indicator is on long enough to be visible.

The STORE (pin 5) and $\overline{\text { RESET }}$ (pin 32) outputs latch and reset the autorange circuit. See Autorange. Refer to Fig. 3-1 for the Gate, Store, and Reset relationship.

The digit select and segment drive outputs drive the display elements directly. However, because these outputs are neither TTL nor CMOS compatible, they are routed through level shift circuitry to drive the Range and Function Select components. The level shift circuit consists of a pair of


Fig. 3-1. Relationship of display update and counter reset signals.
quad-comparators U2043 and U2045. The reference voltage (minus input) of each unit is set at +2.5 V through divider R2034 and R2035. The open collector output of each device is pulled up to +5 V through $10 \mathrm{k} \Omega$ resistors, R1043B through I. The outputs of these comparators drive Multiplexer U1012 and the Function Select circuitry (Diagram 5).

## Function, Range, \& Decimal Point Select

Function and range selection in the DC 504A is accomplished through a combination of switch closures and counter time slot routing. Table 3-1 shows the relationship between function, range, time slot output, and counter input.

Function Select. Time slot switching logic for function selection is provided by U1036. One input of each of the gates is controlled by front panel FUNCTION switch S2061A. The other input of each gate is controlled by time slot output from the counter, U2047. FUNCTION switch closures are grounded through Q2031 and the time slot signals are active low.

To understand the switching action of the function select circuit, assume the FUNCTION switch is in the PERIOD position. In this position, pin 2 of U1036A is pulled low. This allows TS8 (Time Slot 8) to pass through the gate to pin 10 of U1037B. The output of U1037B drives pin 4 of the counter, U2047 (Diagram 3), setting it to the Period mode.

In like manner each of the other functions is selected and routed to the counter Function Input.

Range Select. Range selection is accomplished by routing the time slots through multiplexer U1012. Manual range selection is via the front panel TIME/AVGS switch, S2061B, which controls the $A$ and $B$ select line inputs to the multiplexer. All time slot switching is internal to U1012. The $x$ output, pin 13, goes directly to the counter Range input, pin 21, U2047.

Decimal Point Logic. The display decimal point is placed automatically by the counter (U2047) for all measurement functions applied directly to the counter inputs. For those functions that are multiplied or divided prior to measurement, decimal point positioning is accomplished through selected time slot application to the counter Ext D.P. Input, pin 20. This input is enabled during TS3 at the counter Control Input, pin 1. TS3 is controlled and gated through U1034C and D. During TOTALIZE and measurement of PERIOD, WIDTH, and FREQ TO 10 MHz (with the multiplier off), pin 8 of U1034C is held low preventing TS3 from enabling the counter Control Input. During these measurements, circuitry internal to the counter sets the decimal point.

When measuring frequencies within the range of the Multiplier circuit, the display decimal point must be shifted left two digits. Pins 8 and 9 of U1031B are pulled low setting the output, pin 10, high. Pin 8 of U1025C is driven high, disabling the gate. The high output of U1031B is also inverted

Table 3-1
COUNTER INPUT, FUNCTION/RANGE SELECT, AND TIME SLOT RELATIONSHIPS

| COUNTER INPUT PIN \# | FUNCTION/RANGE | TIME SLOT (DIGIT) |
| :--- | :--- | :--- |
| FUNCTION INPUT | FREQUENCY | TS1 (D0) |
| PIN 4 | PERIOD | TS8 (D7) |
|  | WIDTH | TS5 (D4) |
|  | TOTALIZE | TS4 (D3) |
| RANGE INPUT | (TIME/AVGS) |  |
| PIN 21 | 01 SEC/1 | TS1 (D0) |
|  | 0.1 SEC/10 | TS2 (D1) |
|  | 1 SEC/100 | TS3 (D2) |
| CONTROL INPUT | EXT OSEC/1000 | TS4 (D3) |
| PIN 1 | EXT D.P. ENABLE | TS1 (D0) |
|  | DISPLAY TEST | TS3 (D2) |
|  |  | TS8 (D7) |

through U1048E driving pin 5 of U1025B low to enable the gate. The low output of U1048E also drives pin 4 of U1026A low switching its output high. The high now at pin 8 of U1034C enables the gate and TS3 passes to pin 1 of the counter. This enables the Ext D.P. Input. Depending on the range (gate time) selected, TS4, 5, 6, or 7 gates through U1025B to U1025D. The time slot now at U1025D (pin 11) is applied to the Ext D.P. Input (pin 20) of the counter.

Since frequencies above 10 MHz are divided by ten prior to counting, the display decimal point must be shifted one digit to the right. During this condition, pin 5 of U2026A is pulled low through S2061A forcing the output high. This sets pin 8 of U1034C high to gate TS3 through to the counter Control input, pin 1. This enables the Ext D.P. Input. Pin 8 of U1031B is high during these measurements, and the output remains low. The low output from U1031B sets pin 8 of U1025C low enabling this gate. The low output from U1031B is inverted through U1048E and applied to pin 5 of U1025B disabling this gate. The low output from U1025B enables U1025D and, depending on the range (gate time) selected. gates TS1, 2, 3, or 4 through to the Ext D.P. Input (pin 20) of the counter. Refer to Table 3-2 for Time Slot (TS) to decimal point relationships.

## Autorange

In the Auto mode, the front panel TIMEIAVGS switch (S2061B) is disconnected from the multiplexer (U1012) control inputs. In this mode, the output of the autorange circuit controls the inputs to the multiplexer. Setting S2061B to the AUTO position pulls pin 2 of U2027A low through Q2032. This switches the output high enabling the autorange circuit.

Output from pin 1 of U2027A drives pin 2 of U1034A high switching the output low, removing the resets on U1011A and U1011B. The reset caused the $\overline{\mathrm{Q}}$ outputs, pin 2 and pin 14, to be high. With pin 10 of U2026B and pin 12 of U2026C high (enabled) by U2027A, the high levels at pins 9 and 13 switch the output of these gates low. The low outputs from U2026B and U2026C drive the control inputs of U1012 low. This causes time slot one (TS1) to appear at the x output, pin 13. With TS1 applied to the Range Input, pin 21 of U2047, the counter selects the shortest range, .01 sec . A measurement is made and the result displayed. If the displayed result does not fill digit six (MSD), U1037A (Diagram 3) detects all lows on its inputs, during TS6, causing the output to go high (display zero). The high at pin 1 of U1037A is applied to the Data input, pin 9, of U1024B. The leading edge of TS6 triggers the input of a one shot multivibrator, pin 5 of U1023A. About halfway through TS6 (approximately $125 \mu \mathrm{~s}$ ) the $\overline{\mathrm{Q}}$ output, pin 7, of U1023A goes high. This high is applied to the Clock input, pin 11 of U1024B, which latches the high present on the Data input. Since U1024B is in a set state, latching a high on the Data causes no change in state and the $\bar{Q}$ output, pin 12, remains low. This low is inverted through U2027B driving the $J$ and $K$ inputs of U1011A high and putting the flip-flop in the toggle state. The Store pulse from pin 5 of the counter, U2047, is applied to the CLOCK input, pin 3, causing U1011A to change state. U1011A $\bar{Q}$, pin 2, switches from high to low driving pin 13 of U2026C low. The output of U2026C switches from low to high driving the A input, pin 10, of the multiplexer high. This change in the control input causes TS2 to appear at the output, pin 13, which is applied to the Range input of the counter. The counter selects the next longer gate time, 0.1 sec , and another measurement is made and displayed. If the second gate time selected is still too short to fill the sixth digit (MSD), the events are repeated and TS3 selects the next longer gate time, 1 sec.

Table 3-2
time slot to decimal point relationship

| TIME/AVGS | FUNCTION |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | FREQ TO 10 MHz PERIOD WIDTH |  | FREQ TO 10 MHz ( $\times 100$ MULTIPLIER) |  | FREQ TO 100 MHz ( -10 PRESCALE) |  | totalize |  |
|  | TIME SLOT | DISPLAY DECIMAL | TIME SLOT | DISPLAY DECIMAL | $\begin{aligned} & \text { TIME } \\ & \text { SLOT } \end{aligned}$ | DISPLAY DECIMAL | $\begin{aligned} & \text { TIME } \\ & \text { SLOT } \end{aligned}$ | DISPLAY DECIMAL |
| . 01 SEC/1 | TS2 | 0.0 | TS4 | 0.000 | TS1 | 0. | TS1 | 0. |
| 0.1 SEC/10 | TS3 | 0.00 | TS5 | 0.0000 | TS2 | 0.0 | TS1 | 0. |
| 1.0 SEC/100 | TS4 | 0.000 | TS6 | 0.00000 | TS3 | 0.00 | TS1 | 0. |
| 10 SEC/1000 | TS5 | 0.0000 | TS7 | ${ }^{2} 000000$ | TS4 | 0.000 | TS1 | 0. |
| EXT D.P. ACTIVE | NO |  | YES |  | YES |  | NO |  |

[^1]When the counter selects a gate time that results in the display of digit six at least one of the BCD lines driving U1037A (Diagram 3) will be high and the output, pin 1, is low driving the Data input, pin 9, of U1024B low. TS6 triggers the input of U1023A causing the $\bar{Q}$ output to go high. This high is applied to the Clock input of U1024B. The high Clock input latches the low on the Data input causing a change in state. The $\bar{Q}$ output switches from low to high. This high at pin 5 of U2027B causes the output to go low driving the $J$ and $K$ inputs of U1011A low. With the $J$ and $K$ inputs held low, the Store pulse from the counter cannot toggle the device. No change at the input of U1012 results in no change in time slot output. Measurements will continue using the last gate time selected.

The Autorange circuit prevents the counter advancing to the 10 sec gate time. If the 1 sec gate time is too short to fill digit six, measurements continue in this gate time, displaying as many digits as time allows. Conditions at the output of U1011B when the 1 sec gate time was selected, prevent advancement to the 10 sec time. When the 1 sec gate time is selected, the Q output, pin 15, of U1011B switches high. This high is inverted through U2027B, driving the J and K inputs of U1011A low, disabling the device. With the $J$ and $K$ inputs low, the Store pulse from the counter does not cause a change in state. The $\bar{Q}$ output remains high, U2026C output remains low, no new time slot information is sent from U1012, and the counter continues measuring in the 1 sec range.

Overflow conditions (when the counter tries to display digit seven) are detected during TS7. When an overflow condition occurs. the Data input. pin 5, of U1024A goes low through Q1025 (Diagram 3). TS7 triggers the input to U1023B causing the $\overline{\mathrm{Q}}$ output to go low for approximately $125 \mu \mathrm{~s}$, then returns to the high state. This high at the Clock input, pin 3 of U1024A, latches the low on the Data line and toggles the device causing the Q1 output to go low. This low at pin 1 of U1034A causes the output to go high. This high resets U1011A and U1011B, causing their $\overline{\mathbf{Q}}$ outputs to go high. These highs are inverted through U2026B and U2026C. The output from these gates drives the multiplexers (U1012) control inputs low causing TS1 to appear at the output, pin 13. TS1 at the Range input, pin 21, sets the counter to the shortest $(.01 \mathrm{sec})$ gate time. The counter progresses through the succeeding longer ranges as previously described.

## Display

The display consists of six common cathode seven segment LED's. Digit select time slot pulses (TS1 through TS8) are
generated within counter U2047 (Diagram 3). Individual segment drive (a through $f$ and dp) is also generated within the counter. The OVERFLOW indicator, DS2011, connects to the seventh digit position. Whenever time slot 7 (TS7) and either segment line $b$ or $f$ are active this LED illuminates indicating a display overflow condition. Capacitor C2031, one section of which is connected to each time slot line, serves to suppress any noise spikes that might result in erroneous displays.

## Power Supplies

The DC 504A receives power from the power module via interface connections on the rear edge of the main circuit board. The voltages supplied depend on the power module being used. Typical nominal voltages are: +26 Vdc TM 5000 Series ( +33.5 Vdc TM 500 Series), -26 Vdc TM 5000 Series ( -33.5 Vdc TM 500 Series) and +8 Vdc TM 5000 Series ( +11.5 Vdc TM 500 Series). The regulated +5 V and -5 V supplies for the DC 504A are developed from these voltages.

The +5 V supply, except for a series pass transistor located in the power module, is contained almost entirely within regulator package U2013. This regulator package contains a reference, operational amplifier, and current limiting elements. The regulator is powered by the fused $+26 \mathrm{~V} /+33.5$ $V$ supply from the power module. The regulated $+5 . \mathrm{V}$ is developed from fused $+8 \mathrm{~V} /+11.5 \mathrm{~V}$ furnished by the power module.

The output of U2013 drives the series pass transistor. The regulator reference voltage, +7.15 V (nominal), is divided to +5.00 V by R3012 and R3015 and connected to pin $5\left(\mathrm{~V}_{\text {ret }}\right.$ In). Frequency compensation for the regulator is provided by R3014 and C3013. The $0.3 \Omega$ resistor, R2016 in the emitter circuit of the series pass transistor, is the external current sensing element. Should the current flow through R2016 reach approximately 2 A , the sensing and drive circuitry within the regulator reduce base drive to the series pass transistor. This results in reduced supply output and shutdown if current demand rises sufficiently.

The entire -5 V supply, except filter capacitors C2014 and C3014, is contained within regulator package U2014. This regulator receives supply voltage from the fused power module $-26 \mathrm{~V} /-33.5 \mathrm{~V}$ supply and is completely self contained.

## PERFORMANCE CHECK PROCEDURE

## Introduction

This procedure checks the electrical performance requirements as listed in the Specification section in this manual. Perform the Adjustment procedure if the instrument fails to meet these checks. In some cases, readjustment may not correct the discrepancy; circuit troubleshooting is then indicated. Also, use this procedure to determine acceptability of performance in an incoming inspection facility.

## Adjustment Interval

To ensure instrument accuracy, check the performance every 2000 hours of operation or at a minimum of every 12 months if used infrequently. Allow 30 minutes warm up time prior to performing any checks.

## Services Available

Tektronix, inc. provides complete instrument repair, adjustment, and performance verification at local field service centers and at the factory service center. Contact your local Tektronix field office or representative for further information.

## Test Equipment Required

The test equipment (or equivalent) listed in Table 4-1 is suggested to perform the Performance Check and Adjustment Procedures.

Table 4-1
LIST OF TEST EQUIPMENT REQUIREMENTS

| Description | Performance Requirements | Perf. <br> Check | Adj. <br> Proc. | Example |
| :---: | :---: | :---: | :---: | :---: |
| Power Module |  | X | X | TEKTRONIX TM 506 or TM 5006 |
| Oscilloscope Mainframe <br> Vertical Plug-In <br> Horizontal Plug-in | Dc to 250 MHz bandwidth Bandwidth, dc to 200 MHz <br> Fastest sweep rate 10 ns | $\begin{aligned} & x \\ & x \\ & x \end{aligned}$ |  | TEKTRONIX 7704A <br> TEKTRONIX 7A16A <br> TEKTRONIX 7B80 |
| Leveled Sinewave Generator | Calibrated amplitude > 135 MHz | X |  | TEKTRONIX SG 503 |
| Pulse Generator | Risetime <1 ns | X |  | TEKTRONIX PG 502 |
| Function Generator | Range, Sinewave 10 Hz to 1 MHz ; Offset $+7.5 \vee$ level | X |  | TEKTRONIX FG 501A |
| Digital Multimeter | $4 \frac{1}{2}$ digits, $0.5 \%$ | $X$ |  | TEKTRONIX DM 501A |
| WWVB ( 60 kHz ) <br> Receiver/Frequency Standard | $1 \mathrm{MHz} \pm 1 \times 10^{-9}$ output | X | X | SPECTRACOM CORP Type $8161$ |
| $50 \Omega$ Feedthrough Termination | Bnc connectors | $x$ | x | Tektronix Part No. 011-0049-01 |
| Coaxial cable, $50 \Omega$ Precision 36 inch | Bnc connectors | X | X | Tektronix Part No. 012-0482-00 |
| Adapter. Bnc Female to Dual Banana |  | $x$ |  | Tektronix Part No. 103-0090-00 |
| $50 \Omega, 10 \times$ Attenuator | Bnc connectors | X |  | Tektronix Part No. 011-0059-02 |
| $50 \Omega, 5 \times$ Attenuator | Bnc connectors | X |  | Tektronix Part No. 011-0060-02 |
| Flexible Extender |  |  | x | Tektronix Part No. 067-0645-01 |

## 1. Check Display

Test Equipment Required:
Function Generator
$50 \Omega$ Termination
$\times 10$ Attenuator
a. Set the DC 504A controls as follows:

| FUNCTION | TOTALIZE |
| :--- | :--- |
| TIME/AVGS | AUTO |
| COUPL | DC |
| ATTEN | $\times 1$ |

b. Set the function generator to produce a 2 Hz sine wave with an amplitude of approximately 5 volts and zero offset (into $50 \Omega$ ).
c. Connect the function generator output, through a $\times 10$ attenuator and $50 \Omega$ termination, to the DC 504A input.
d. Reset the DC 504 A by pushing the RESET button.
e. CHECK - that the least significant digit (far right) in the DC 504A display counts from 0 to 9 and carries to the next digit.
f. Set the function generator to 20 Hz .
g. CHECK_that the second digit in the DC 504A display counts from 0 to 9 and carries to the third digit.
h. Increase the function generator frequency in decade steps until all six digits in the display have been checked.
i. CHECK-that the OVERFLOW light on the DC 504A comes on after the most significant digit (far left) has counted to 9 .
j. Set the DC 504A DISPLAY UPDATE switch to the HOLD position.
k. CHECK—that the DC 504A display remains stable.

1. Set the DC 504A DISPLAY UPDATE switch to the RUN position.
m. CHECK-that the DC 504A display indicates a new number and continues counting from there.
n. Set the function generator frequency to 200 kHz .
o. Set the DC 504A FUNCTION switch to FREQ TO 10 MHz and the TIME/AVGS switch to the .01 SEC/ $/ 1$ position.
p. CHECK—that the DC 504A display reads approximately 200.0 kHz.
q. Rotate the DC 504A TIME/AVGS switch clockwise through each position.
r. CHECK-that the DC 504A display indicates one additional digit of resolution for each succeeding switch position. In the 10 SEC/1000 position the OVERFLOW light will be on.
s. CHECK_that the DC 504A display reads approximately 200.000 kHz with the TIME/AVGS switch in the AUTO position.

NOTE
Stability of the display will depend on stability of the signal source used.
t. Push the RESET button and check that the display shows all 8's with all decimal points illuminated.
u. Remove all connections for the next step.

## 2. Check Time Base Oscillator Frequency

Test Equipment Required:
1 MHz Frequency Standard
$50 \Omega$ Termination
a. Set the DC 504A controls as follows:

| FUNCTION | FREQ TO 10 MHz |
| :--- | :--- |
| TIMEIAVGS | $1.0 \mathrm{SEC} / 100$ |
| COUPL | DC |
| ATTEN | $\times 1$ |
| TRIGGER LEVEL | midrange |

b. Connect a coaxial cable and $50 \Omega$ termination from the 1 MHz frequency standard to the DC 504A input connector.
c. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
d. CHECK-that the DC 504A display reads between 999.994 and 000.006 ( $\pm 5 \mathrm{ppm} \pm 1$ count). The OVERFLOW light will be on if the count is greater than 999.999.
e. Remove this connection for the next step.

## 3. Check Input Impedance

Test Equipment Required:
Digital Multimeter
$50 \Omega$ Termination
a. Set the DC 504A controls as follows:

| FUNCTION | FREQ TO 10 MHz |
| :--- | :--- |
| TIME/AVGS | $0.1 \mathrm{SEC} / 10$ |
| COUPL | DC |
| ATTEN | $\times 1$ |

b. Connect the BNC Female to Dual Banana adaptor to the Digital Multimeter with the adaptors GND connected to the HI input of the meter. Connect the DC 504A to the meter. Set the Digital Multimeter to read $1 \mathrm{M} \Omega$.
c. CHECK-that the digital multimeter display reads between . $990 \mathrm{M} \Omega$ and $1.010 \mathrm{M} \Omega$.
d. Set the DC 504A ATTEN switch to the $\times 5$ position.
e. CHECK_that the digital multimeter display reads between $.990 \mathrm{M} \Omega$ and $1.010 \mathrm{M} \Omega$.
f. Return the DC 504A ATTEN switch to the $\times 1$ position.
g. Remove all connections for the next step.

## 4. Check Attenuator

Test Equipment Required:
Pulse Generator
Digital Multimeter
$\times 5$ Attenuator
$50 \Omega$ Termination
a. Set the DC 504A controls as follows:

| FUNCTION | PERIOD |
| :--- | :--- |
| TIME/AVGS | AUTO |
| COUPL | DC |
| ATTEN | $\times 1$ |
| TRIGGER LEVEL | fully clockwise |

b. Set the pulse generator for manually triggered output.
c. Connect the pulse generator, through a $50 \Omega$ termination and $5 \times$ attenuator, to the digital multimeter.
d. Adjust the pulse generator output for approximately 1 volt reading on the multimeter. Note the reading. (The Pulse Generator is used as a voltage source in this case.)
e. Move the connection from the multimeter to the DC 504A input.
f. Press the DC 504A RESET button.
g. Adjust the DC 504A TRIGGER LEVEL control counterclockwise until the GATE light just comes on.
h. Repeat steps $4 f$ and $4 g$ several times to arrive as close as possible to the point where the GATE light just turns on.
i. Set the DC 504A ATTEN switch to the $\times 5$ position.
j. Remove the $\times 5$ attenuator from the test set up and reconnect the cable.
k. Press the DC 504A RESET button.
I. Adjust the pulse generator output control clockwise until the DC 504A GATE light just comes on.
m . Repeat steps 4 k and 41 several times to arrive as close as possible to the point where the GATE light just comes on.
n. Move the connection from the DC 504A to the multimeter.
o. Note the multimeter reading.
p. Divide the reading obtained in step 40 by the reading obtained in step 4d.
q. CHECK-that the result obtained in step $4 p$ is between 4.90 and 5.10 .
r. Remove these connections for the next step.

## 5. Check Low Frequency Stability

Test Equipment Required:
Function Generator
$50 \Omega$ Termination
a. Set the DC 504A controls as follows:

| FUNCTION | FREQ TO 10 MHz |
| :--- | :--- |
| TIME/AVGS | AUTO |
| COUPL | DC |
| ATTEN | $\times 1$ |
| TRIGGER LEVEL | midrange |

b. Set the function generator controls to produce a 25 kHz sine wave with an amplitude of 60 mV centered around 0 volts. Attenuate the output if necessary.
c. Connect the function generator output, through a $50 \Omega$ coaxial cable and $50 \Omega$ termination, to the DC 504A INPUT connector.
d. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
e. CHECK-that the DC 504A display reads approximately 25.0000 kHz and the MULTIPLIER LOCK light is on. The display must be stable within 100 counts.
f. Readjust the function generator controls to produce a 10 Hz sine wave.
g. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
h. CHECK_that the DC 504A display reads approximately .01000 kHz and the MULTIPLIER LOCK light is on. The display must be stable within 10 counts.
i. Set the function generator dc offset to a level at least 0.5 volts negative.
j. CHECK-that the DC 504A display reads .000 kHz and the MULTIPLIER LOCK light is off.
k. Set the DC 504A COUPL switch to AC.
I. CHECK-that the DC 504A display is stable at approximately .01000 kHz and the MULTIPLIER LOCK light is on.
m . Remove these connections for the next step.

## 6. Check High Frequency Stability

Test Equipment Required:
Sine Wave Generator
$50 \Omega$ Termination
a. Set the DC 504A controls as follows:

| FUNCTION | FREQ TO 100 MHz |
| :--- | :--- |
| TIME/AVGS | AUTO |
| COUPL | DC |
| ATTEN | $\times 1$ |

b. Set the sine wave generator to produce a 100 MHz signal with a peak-to-peak amplitude of 70 mV centered around 0 Volts.
c. Adjust the DC 504A TRIGGER LEVEL for a stable display.
d. CHECK-that the DC 504A display reads approximately 100000 kHz and is stable within one count.
e. Set the sine wave generator amplitude to 4.0 V .
f. CHECK -that the DC 504A display reads approximately 100000 kHz and is stable within one count.
g. Set the sine wave generator frequency to 10 MHz and the DC 504A FUNCTION switch to FREQUENCY TO 10 MHz.
h. CHECK-that the DC 504A display reads approximately 10000.0 kHz and is stable within one count.
i. Set the sine wave generator amplitude to 70 mV .
j. CHECK—that the DC 504A dispiay reads approximately 10000.0 kHz and is stable within one count.
k. Set the DC 504A FUNCTION switch to TOTALIZE.

1. CHECK-that the DC 504A display is advancing (digits will appear blurred and dim).
m . Leave these connections for the next step.

## 7. Check Period and Width

Test Equipment Required:
Pulse Generator
$50 \Omega$ Termination
X10 Attenuator
a. Set the DC 504A controls as follows:

| FUNCTION | PERIOD |
| :--- | :--- |
| TIME/AVGS | AUTO |
| COUPL | DC |
| ATTEN | $\times 1$ |

b. Set the pulse generator to produce a 2.55 MHz square wave with an amplitude of 60 mV p-p.
c. CHECK—that the DC 504A display reads approximately $.392 \mu \mathrm{~s}$ and is stable within one count. Note the reading.
d. Set the DC 504A FUNCTION switch to WIDTH $\Omega$.
e. CHECK-that the DC 504A display reads approximately $.200 \mu \mathrm{~S}$ and is stable within $\pm 15$ counts. Note the reading.
$h$. The sum of the readings obtained in steps 8 e and 8 g should be equal to the reading obtained in step 8c $\pm .040 \mu \mathrm{~s}$.

This completes the performance check procedure for the DC 504A; remove all connections.
f. Set the DC 504A FUNCTION switch to WIDTH $\qquad$
g. CHECK - that the DC 504A display reads approximately $.200 \mu \mathrm{~s}$ and is stable within $\pm 15$ counts. Note the reading.

## ADJUSTMENT PROCEDURE

## Introduction

Use this Adjustment Procedure to restore the DC 504A to original performance requirements. This Adjustment Procedure need not be performed uniess the instrument fails to meet the Performance Requirements of the electrical characteristics listed in the Specification section, or if the Performance Check procedure cannot be completed satisfactorily. If the instrument has undergone repairs, the Adjustment Procedure is recommended. Allow thirty minutes warmup time for operation to specified accuracy (sixty minutes after storage in a high humidity environment).

Satisfactory completion of all adjustment steps in this procedure assures that instrument performance will meet the Performance Requirements.

## Test Equipment Required

The test equipment (or equivalent) listed in Table 4-1 is required for adjustment of the DC 504A. Specifications given for the test equipment are the minimum necessary for accurate adjustment. All test equipment is assumed to be correctly calibrated and operating within specifications.

If other test equipment is substituted, the adjustment setup may need to be altered to meet the requirements of the equipment used.

## Preparation

Access to the internal adjustments is achieved most easily when the DC 504A is connected to the power module with a fiexible plug-in extender. Remove the left side cover of the DC 504A to reach the adjustments on the main board. Refer to the Adjustment Locations in the pullout pages at the rear of this manual.

NOTE
Make adjustments at an ambient temperature between $+20^{\circ} \mathrm{C}$ and $+30^{\circ} \mathrm{C}$.

## 1. Adjust Time Base Frequency-C2051

Test Equipment Required:
1 MHz Frequency Standard
$50 \Omega$ Termination
a. Set the DC 504A controls as follows:

| FUNCTION | FREQ TO 10 MHz |
| :--- | :--- |
| TIME/AVGS | $10 \mathrm{SEC} / 1000$ |
| COUPL | DC |
| ATTEN | $\times 1$ |
| TRIGGER LEVEL. | midrange |

b. Connect a coaxial cable and $50 \Omega$ termination from the 1 MHz frequency standard to the DC 504A input connector.
c. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
d. ADJUST-C2051 (located on the main board) until the DC 504A display reads between 99.9998 and 00.0002 ( $\pm 0.1 \mathrm{ppm} \pm 1$ count). The OVERFLOW light will be on.

This completes the adjustment procedure; remove all connections.

## MAINTENANCE

## Static-Sensitive Components



Static discharge may damage semiconductor components in this instrument.

This instrument contains electrical components that are susceptible to damage from static discharge. See Table 5-1 for relative susceptibility of various classes of semiconductors. Static voltages of 1 kV to 30 kV are common in unprotected environments.

Observe the following precautions to avoid damage:

1. Minimize handling of static-sensitive components.
2. Transport and store static-sensitive components or assemblies in their original containers, on a metal rail, or on conductive foam. Label any package that contains staticsensitive assemblies or components.
3. Discharge the static voltage from your body by wearing a grounded wrist strap while handling these components. Servicing static-sensitive assemblies or components should be performed only at a static-free work station by qualified service personnel.
4. Nothing capable of generating or holding a static charge should be aliowed on the work station surface.
5. Keep the component leads shorted together whenever possible.
6. Pick up components by the body, never by the leads.
7. Do not slide the components over any surface.
8. Avoid handling components in areas that have a floor or work surface covering capable of generating a static charge.
9. Use a soldering iron that is connected to earth ground.
10. Use only special antistatic suction type or wick type desoldering tools.

## Test Equipment

Before using any test equipment to make measurements on static-sensitive components or assemblies, be certain that any voltage or current supplied by the test equipment does not exceed the limits of the component to be tested.

Table 5-1
RELATIVE SUSCEPTIBILITY TO STATIC DISCHARGE DAMAGE

| Semiconductor Classes | Relative Susceptibility Levels* |
| :---: | :---: |
| MOS or CMOS microcircuits or discretes, or linear microcircuits with MOS inputs. <br> (Most Sensitive) | 1 |
| $\overline{\text { ECL }}$ | 2 |
| Schottky signal diodes | 3 |
| Schottky TTL | 4 |
| High-frequency bipolar transistors | 5 |
| JFETs | 6 |
| Linear microcircuits | 7 |
| Low-power Schottky TTL | 8 |
| TTL (Least Sensitive) | 9 |
| ${ }^{\text {- Voltage equivalent for levels: }}$ |  |
| $1=100$ to $500 \mathrm{~V} \quad 4=500 \mathrm{~V}$ | $7=400$ to 1000 (est.) |
| $2=200$ to $500 \mathrm{~V} \quad 5=400$ to 600 V | $8=900 \mathrm{~V}$ |
| $3=250 \mathrm{~V} \quad 6=600$ to 800 V | $9=1200 V$ |

(Voltage discharged from a 100 pF capacitor through a resistance of 100 a.)

## Cleaning Instructions

This instrument should be cleaned as often as operating conditions require. Accumulation of dirt on components acts as an insulating blanket and prevents efficient heat dissipation that can cause overheating and component breakdown.


Avoid the use of chemical cleaning agents that might leave a film or damage the plastic material used in this instrument. Use a nonresidue type of cleaner, preferably, isopropyl alcohol or totally denatured ethyl alcohol. Before using any other type of cleaner, consult your Tektronix Service Center or representative.

Exterior. Loose dust accumulated on the front panel can be removed with a soft cloth or a small brush. Dirt that remains can be removed with a soft cloth dampened with a mild detergent and water solution. Abrasive cleaners should not be used.

Interior. Dust in the interior of the instrument should be removed occasionally, due to its electrical conductivity under high humidity conditions. The best way to clean the interior is to blow off the accumulated dust with dry, low pressure air, then use a soft brush. If further cleaning is required, use a mild detergent and water solution, flushing well with clean water.


Do not clean the circuit board with any solvent, unless the pushbutton switches and FUNCTION and TIME/AVGS switch are removed first. Any solvent forced or carried under the switches can remove the lubricants and cause intermittent operation. Circuit boards and components must be dry before applying power to prevent damage from electrical arcing.

Drying can be accomplished with dry, low-pressure air or by placing in an oven at $40^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$ for approximately four hours.

After making minor board repairs, cleaning is best accomplished by carefully flaking or chipping the solder flux from the repaired area.

Isopropyl alcohol can be used to clean major repairs to the circuit board; however, flush the board well with clean, isopropyl alcohol. Make certain that resin or dirt is carefully
removed from the board. Avoid contact with switches (see CAUTION above).

## Obtaining Replacement Parts

Electrical and mechanical parts can be obtained through your local Tektronix Field Office or representative. However, many of the standard electronic components can be obtained from a local commercial source. Before purchasing or ordering parts from a source other than Tektronix, Inc., check the Replaceable Electrical Parts list for the proper value, rating, tolerance, and description.

## Ordering Parts

When ordering replacement parts from Tektronix, Inc., it is important to include all of the following information.

1. Instrument type (include modification or option numbers).
2. Instrument serial number.
3. A description of the part (if electrical, include the component number).
4. Tektronix part number.

## Soldering Techniques

## WARMING

To avoid electric shock hazard, disconnect the instru-
ment from the power source before soldering.

The reliability and accuracy of this instrument can be maintained only if proper soldering techniques are used when repairing or replacing parts. General soldering techniques which apply to maintenance of any precision electronic equipment should be used when working on this instrument. Use only 60/40 rosin-core, electronic grade solder. The choice of soldering iron is determined by the repair to be made.

When soldering on circuit boards or small wiring, use only a 15 watt, pencil type soldering iron. A higher wattage soldering iron can cause the etched circuit wiring to separate from the board base material and melt the insulation from small wiring. Always keep the soldering iron tip properly tinned to
ensure the best heat transfer to the solder joint. Apply only enough heat to remove the component or to make a good solder joint. To protect heat sensitive components, hold the component lead with a pair of long-nose pliers between the component body and the solder joint. Use a solder removing wick to remove excess solder from connections or to clean circuit board pads.

## Interconnecting Pins

Several methods of interconnection are used to electrically connect the circuit boards with the other boards and components.

Several types of mating connectors are used for these interconnecting pins. If the mating connector is mounted on a plug-on circuit board, special sockets are soldered into the board. If the mating connector is on the end of a lead, an end-lead pin connector is used. This connector mates with the interconnecting pin. The following information provides the removal and replacement procedure for the various interconnecting methods.

## Square Pin Assemblies

See Fig. 5-1. These pins are of various lengths. They are attached to each other with a plastic strip. To remove them simply unsolder from the circuit board.

## Multipin Connectors

The pin connectors used to connect the wires to the interconnecting pins are clamped to the ends of the wires. To replace damaged multipin connectors, remove the old pin connector from the holder. Do this by inserting a scribe between the connector and the holder and prying the connector from the holder. Clamp the replacement connector to the wire. Reinstall the connector in the holder.

It the individual end lead pin connectors are removed from the plastic holder, note the order of the individual wires for correct replacement in the holder. For proper replacement see Fig. 5-2.

## Semiconductors

To remove the in-line integrated circuits installed in sockets, use an extracting tool. This tool is available from Tektronix, inc.; order Tektronix Part Number 003-0619-00. If an extracting tool is not available, use care to avoid damaging the pins. Pull slowly and evenly on both ends of the integrated
circuit. Try to avoid disengaging one end before the other. IC's that are soldered in should be carefully unsoldered, using commercially available de-soldering tools, and gently removed. Care should be taken not to lift runs or pads from the etched circuit board. If de-soldering tools are not available, the pins of the IC may be clipped with diagonal cutters, and the pins then individually removed from the board.


Fig. 5-1. Typical square pin assembly.


Fig. 5-2. Orientation and disassembly of multipin connectors.

## Release Latch Removal

All plastic parts of the latch assembly and the return spring are individually replaceable. However, should the latch tension spring become damaged, the entire bottom frame rail assembly must be replaced.

1. Pull the latch pull bar out approximately $1 / 8$ inch and hold the latch out.
2. Push the pull bar inward and downward until the retaining pins clear the slot in the latch.
3. Release the latch and remove the pull bar.
4. Remove the screw securing the lower edge of the main circuit board to the bottom frame rail.
5. Remove the two screws from the bottom of the front frame assembly and the two guide pins at the lower edge of the rear frame.
6. The bottom frame rail can now be removed and the latch disassembled.
7. Re-assemble in the reverse order.
8. Push the pull bar through the front panel as far as it will go and hold it. Push the latch forward until the pull bar retaining pins engage the slot in the latch.

## Main Circuit Board (A12) Removal

1. Remove the side covers. A tab on the front frame assembly and a quarter-turn fastener at the rear secure the covers.
2. Remove the TIME/AVGS and FUNCTION switch knobs.
3. Disconnect the input cable at J 4012 .
4. Remove the screw securing U2014 (heat sink) to the rear frame.
5. Remove the two screws and two guide pins that secure the rear frame to the top and bottom frame rails and remove the rear frame.
6. Remove the three screws that secure the circuit board to the top (2) and bottom (1) frame rails.
7. Puil the circuit board straight toward the rear of the instrument to disengage the connection to the display circuit board.
8. Re-assemble in the reverse order. Take care that the pins on the display board are properly aligned with the mating connector on the main board.

## Display Circuit Board (A10) Removal

1. Remove the side covers. $A$ tab on the front frame assembly and a quarter-turn fastener at the rear secure the covers.
2. Remove the release latch pull bar as previously outlined under Release Latch Removal.
3. Remove the TIME/AVGS and FUNCTION switch and TRIGGER LEVEL knobs.
4. Remove the nut from the INPUT connector. A special wrench to remove this nut is available from Tektronix, Inc.; order Tektronix Part Number 003-0306-00. If this tool is not available, exercise care to prevent damage to the front panel.
5. Disconnect the input cable from the display circuit board at J4012.
6. Remove four screws that secure the top (2) and bottom (2) frame rails to the front frame assembly.
7. Pull the front frame assembly carefully straight out to avoid damaging the interconnecting pins to the main circuit board.
8. Remove the two screws on the back of the circuit board and separate the assembly.
9. Re-assemble in the reverse order taking care that interconnecting pins, LEDs, etc. are properly aligned.

## NOTE

Display and indicator LED lead length is critical. If the leads of the replacement part are cut shorter than the original, that digit or indicator may not be clearly visible when viewed from an angle.

## Internal Jumpers

Refer to the Adjustments and Test Points illustrations in the pull out pages for the locations of the following internal jumpers.

PLL DISABLE (P1040) located on the main board (A12)-disables the Phase Lock Loop circuitry.

INT/EXT CLOCK (P2042) located on the main board (A12)-selects the internal ( 10 MHz ) time base, or permits application of an external time base via the rear interface.

INT/EXT INPUT (P4014) located on the display board (A10)-permits signal measurements via the front panel INPUT connector (EXT) or the rear interface (INT). P4012 at the rear edge of the Main board (A12) must also be moved to pins 1 and 2 of $J 4012$ for INT.

## Test Fixture Connectors

The two connectors identified on the schematic diagrams as J1032 and J2032 are test points used during the manufacturing process.

# REAR INTERFACE CONNECTOR 

Refer to Fig. 5-3 for the following.

A slot between pins 21 and 22 on the rear connector identifies this instrument as a member of the TM 500 counter family. Insert a barrier in the corresponding position of the power module jack to prevent noncompatible plug-ins being used in that compartment. Consult the power module manual for further information.

## Functions Available

Pin 14A External Clock Input-This connection allows an external 10 MHz frequency standard to be used in
place of the internal time base. The input is one LSTTL load.

Pin 15A External Clock Ground-This is the common connection for the clock input and output signals.

Pin 16A input-This is the signal input when the INT/EXT jumper is in the INT position. This connection is terminated into $50 \Omega$ with a maximum input of 4 volts peak.

Pin 17A Input Ground-This is the common connection for the rear interface signal input.

| INPUT OR OUTPUT | PIN |  | PIN | INPUT OR OUTPUT |
| :---: | :---: | :---: | :---: | :---: |
|  | 28 | FAMILY <br> BARRIER <br> SLOT | 28 |  |
|  |  |  |  |  |
|  | 22 |  | 22 |  |
|  | 21 | TMS50 BARRIER SLOT | 21 |  |
|  |  |  | 17 | INPUT GND |
|  |  |  | 16 | INPUT |
|  |  |  | 15 | EXT CLOCK GNO |
|  |  |  | 14 | EXT CLOCK IN |
| * +26 Vdc | 12 |  | 12 | * +26 Vde |
| GROUND | 9 |  | 9 | GROUND |
| * -28 vode | 8 |  | 8 | * -26 Vodc |
| NPN SERIES PASS COLLECTOR | 7 |  | 7 | MPN SERIES PASS EMITTER |
|  | 6 |  | 6 | NPN SERIES PASS base |
| Ground | 4 | $\begin{gathered} \text { REAR } \\ \text { VIEW } \\ \text { OF } \\ \text { PLUG-IN } \end{gathered}$ | 4 | GROUND |
| GROUND | 3 |  | 3 | ground |
| - +8 Vdc | 2 |  | 2 | * +8 Vdc |
|  | 1 |  | 1 |  |
|  |  |  |  |  |

* Nomlnal Voliage - May be higher depending on power module type.

Fig. 5-3. Rear interface connector assignments.

## OPTIONS

There are no options for the DC 504A.

# REPLACEABLE ELECTRICAL PARTS 

## PARTS ORDERING INFORMATION

Replacement parts are available from or ihrough your local Tektronix, Inc. Field Office or representative

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important. when ordering parts. to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix. Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

## LIST OF ASSEMBLIES

A list of assemblies can be found at the beginning of the Electrical Parts List. The assemblies are listed in numerical order. When the complete component number of a part is known, this list will identify the assembly in which the part is lacated.

## CROSS INDEX-MFR. CODE NUMBER TO MANUFACTURER

The Mfr. Code Number to Manufacturer index for the Electrical Parts List is located immediately after this page. The Cross Index provides codes names and add;esses of manufacturers of components listed in the Electrical Parts List

## ABBREVIATIONS

Abbreviations conform to American National Standard $\mathrm{V}_{1} 1$

## COMPONENT NUMBER (column one of the Electrical Parts List)

A numbering method has been used to identify assemblies, subassemblies and parts. Examples of this numbering method and typical expansions are illustrated by the following:


Read: Resistor 1234 of Assembly 23


Read: Resistor 1234 of Subassembly 2 of Assembly 23

Only the circuit number will appear on the diagrams and circuit board illustrations. Each diagram and circuit board illustration is clearly marked with the assembly number. Assembly numbers are also marked on the mechanical exploded views located in the Mechanical Parts List. The component number is obtained by adding the assembly number prefix to the circuit number.

The Electrical Parts List is divided and arranged by assemblies in numerical sequence (e.g., assembly A1 with its subassemblies and parts, precedes assembly A2 with its subassemblies and parts).

Chassis-mounted parts have no assembly number prefix and are located at the end of the Electrical Parts List.

## TEKTRONIX PART NO. (column two of the Electrical Parts List)

Indicates part number to be used when ordering replacement part from Tektronix

## SERIAL/MODEL NO. (columns three and four of the Electrical Parts List)

Column three (3) indicates the serial number at which the part was first used Column four (4) indicates the serial number at which the part was removed. No serial number entered indicates part is good for all serial numbers.

## NAME \& DESCRIPTION (column five of the Electrical Parts List)

In the Parts List, an Item Name is separated from the description by a colon (). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S Federal Cataloging Handbook H6-1 can be utilized where possible.

## MFR. CODE (column six of the Electrical Parts List)

Indicates the code number of the actual manufacturer of the part. (Code to name and address cross reference can be found immediately after this page.)

## MFR. PART NUMBER (column seven of the Electrical Parts List)

Indicates actual manufacturers part number

## CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 00136 | MCCOY ELECTRONICS CO | 100 WATTS ST P0 B0X B | MT HOLLY SPRINGS PA 17065-1821 |
| 00213 | NYTRONICS COMPONENTS GROUP INC SUBSIDIARY OF NYTRONICS INC | ORANGE ST | DARLINGTON SC 29532 |
| 00853 | SANGAMO WESTON INC COMPONENTS DIV | SANGAMO RD <br> PO BOX 128 | PICKENS SC 29671-9716 |
| 01121 | ALLEN-BRADLEY CO | 1201 SOUTH 2ND ST | MILWALKEE WI 53204-2410 |
| 01295 | TEXAS INSTRUMENTS INC | 13500 N CENTRAL EXP | DALLAS TX 75265 |
|  | SEMICONDUCTOR GROUP | PO BOX 655012 |  |
| 02735 | RCA CORP <br> SOLID STATE DIVISION | ROUTE 202 | SOMERVILLE NJ 08876 |
| 03508 | GENERAL ELECTRIC CO SEMI-CONDUCTOR PRODUCTS DEPT | W GENESEE ST | AUBURN NY 13021 |
| 04222 | AVX CERAMICS DIV OF AVX CORP | 19TH AVE SOUTH P O BOX 867 | MYRTLE BEACH SC 29577 |
| 04713 | MOTOROLA INC <br> SEMICONDICTOR PRODUCTS SECTOR | 5005 E MCOOWELL RD | PHOENIX AZ 85008-4229 |
| 05828 | GENERAL INSTRUMENT CORP <br> GOVERNMENT SYSTEMS DIV | 600 W JOHM ST | HICKSVILLE NY 11802 |
| 07263 | FAIRCHILD SEMICONDUCTOR CORP NORTH AMERICAN SALES <br> SUB OF SCHL MBERGER LTD MS 118 | 10400 RIDGEVIEW CT | CUPERTINO CAW CA 95014 |
| 07716 | TRW INC <br> TRW IRC FIXED RESISTORS/BURLINGTON | 2850 MT PLEASANT AVE | BURLINGTON IA 52601 |
| 11236 | CTS CORP <br> BERNE DIV <br> THICK FILM PRODUCTS GROUP | 406 PARR ROAD | BERNE IN 46711-9506 |
| 18324 | SIGNETICS CORP <br> MILITARY PRODUCTS DIV | 4130 S MARKET COURT | SACRAMENTO CA 95834-1222 |
| 19701 | MEPCO/CENTRALAB <br> A NORTH AMERICAN PHILIPS CO | P O BOX 760 | MINERAL WELLS TX 76067-0760 |
| 22526 | DU PONT E I DE NEMOLRS AND CO INC DU PONT CONNECTOR SYSTEMS DIV MILITARY PRODUCTS GROUP | 515 FISHING CREEK RD | NEW CUMBERLAND PA 17070-3007 |
| 24931 | SPECIALTY CONNECTOR CO INC | 2100 EARLYWOOD DR P0 B0X 547 | FRANKLIN IN 46131 |
| 27014 | NATIONAL SEMICONDUCTOR CORP | 2900 SEMICONDUCTOR OR | SANTA CLARA CA 95051-0606 |
| 29604 | STACKPOLE COMPONENTS CO SUB OF THE STACKPOLE CORP | PO BOX 14466 | RALEIGH NC 27610 |
| 32293 | INTERSIL INC SUB OF GENERAL ELECTRIC CO | 10600 RIDGEVIEW COURT | CUPERTINO CA 95014-0704 |
| 32997 | BOURNS INC <br> TRIMPOT DIV | 1200 COLUMBIA AVE | RIVERSIDE CA 92507-2114 |
| 54473 | MATSUSHITA ELECTRIC CORP OF AMERICA | ONE PANASONIC WAY PO BOX 1501 | SECAUCUS NJ 07094-2917 |
| 55680 | NICHICON /AMERICA/ CORP | 927 E STATE PKY | SCHAUMBURG IL. 60195-4526 |
| 56289 | SPRAGUE ELECTRIC CO WORLD HEADOUARTERS | 92 HAYDEN AVE | LEXINGTON MA 02173-7929 |
| 57668 | R-OHM CORP | 16931 MILLIKEN AVE | IRVINE CA 92713 |
| 58361 | GENERAL INSTRUMENT CORP OPTOELECTRONICS DIV | 3400 HILLVIEW AVE | PALO ALTO CA 94304-1319 |
| 59660 | TUSONIX INC | 7741 N BUSINESS PARK DR PO BOX 37144 | TUCSON AZ 85740-7144 |
| 71400 | BUSSMANN <br> DIV OF COOPER INDUSTRIES INC | 114 OLD STATE RD PO BOX 14460 | ST LOUIS MO 63178 |
| 71590 | MEPCO/CENTRALAB INC A NORTH AMERICAN PHILIPS CO | HWY 20 W PO BOX 858 | FORT DODGE IA 50501 |
| 76493 | BELL INDUSTRIES INC. JW MILLER DIV | 19070 REYES AVE PO BOX 5825 | COMPTON CA 90224-5825 |
| 80009 | TEKTRONIX INC | 14150 SW KARL BRAUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 80031 | MEPCO/ELECTRA INC | 22 COLLMBIA RD | MORRISTOWN NJ 07960 |
| 96733 TK1483 | SFE TECHNOLOGIES <br> TEKA PRODUCTS IMC | 1501 FIRST ST <br> 45 SALEM ST | SAN FERNANDO CA 91340-2707 PROVIDENCE RI 02907 |
| TK1483 | TEKA PRODUCTS INC | 45 SALEM ST | PROVIDENCE R1 02907 |


| Component No. | Tektronix Part Mo. | Serial/Ass Effective | mbly No. Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AlO | 670-7597-00 | B010100 | B011129 | CIRCUIT BD ASSY:DISPLAY | 80009 | 670-7597-00 |
| A10 | 670-7597-01 | B011130 |  | CIRCUIT BD ASSY:DISPLAY | 80009 | 670-7597-01 |
| A12 | 670-7598-00 | 8010100 | B011129 | CIRCUIT BD ASSY:MAIN | 80009 | 670-7598-00 |
| A12 | 670-7598-01 | B011130 | B011469 | CIRCUIT BD ASSY:MAIN | 80009 | 670-7598-01 |
| A12 | 670-7598-02 | B011470 | B012375 | CIRCUIT BD ASSY:MAIN | 80009 | 670-7598-02 |
| A12 | 670-7598-03 | B012376 |  | CIRCUIT BD ASSY:MAIN | 80009 | 670-7598-03 |
| A10 | 670-7597-00 | B010100 | 8011129 | CIRCUIT BD ASSY: DISPLAY | 80009 | 670-7597-00 |
| AlO | 670-7597-01 | B011130 |  | CIRCUIT BD ASSY:DISPLAY | 80009 | 670-7597-01 |
| A10C2011 | 281-0775-00 |  |  | CAP, FXD, CER DI :0.1UF, 20\%, 50V | 04222 | MA205E104MAA |
| A10C2012 | 290-0920-00 |  |  | CAP, FXD, ELCTLT: $33 \mathrm{UF},+50-20 \%, 35 \mathrm{WVDC}$ | 55680 | UVX1H33CMPA |
| A10C2014 | 281-0775-00 |  |  | CAF, FXD, CER DI : $0.14 \mathrm{~F}, 20 \%$, 50 V | 04222 | MA205E104MAA |
| A10C2031 | 283-0487-00 |  |  | CAP NTWK,CER, DI: (7) $330 \mathrm{PF}, 20 \%, 50 \mathrm{~V}$ | 56289 | 470C7C06331M5DG |
| A10C2033 | 290-0920-00 |  |  | CAP, FXD, ELCTLT:33UF, +50-20\%,35WVOC | 55680 | UVXIH330MPA |
| A10C3021 | 281-0785-00 |  |  | CAP. FXD, CER DI: 68PF, $10 \%$, 100 V | 04222 | MA101A680KAA |
| A10C3034 | 281-0775-00 |  |  | CAP, FXD, CER DI: $0.14 \mathrm{~F}, 20 \%$, 50 V | 04222 | MA205E104MAA |
| A10C4013 | 281-0775-00 |  |  | CAP, FXD, CER DI: $0.1 \mathrm{UF}, 20 \%$, 50 V | 04222 | MA205E104MAA |
| A10C4014 | 283-0057-00 | B010100 | 8011129 | CAP, FXD, CER DI: $0.1 \mathrm{UF},+80-20 \%, 200 \mathrm{~V}$ | 04222 | SR306E104ZAA |
| A10C4014 | 281-0907-00 | B011130 |  | CAP,FXD,CER DI: $0.068 \mathrm{UF}, 10 \%, 200 \mathrm{~V}$ | 96733 | RH06BX683K |
| Al0C4021 | 281-0797-00 |  |  | CAP, FXD, CER DI: 15PF. $10 \%$, 100V | 04222 | MA106A150KAA |
| Al0C4025 | 281-0798-00 |  |  | CAP, FXD, CER DI:51PF, $1 \%$, 100 V | 04222 | MA101A510GAA |
| A10C4035 | 281-0775-00 |  |  | CAP, FXD, CER DI: $0.1 \mathrm{UF}, 20 \%$, 50 V | 04222 | MA205E104MAA |
| A10C4036 | 283-0067-00 |  |  | CAP, FXD, CER DI $: 0.001 \mathrm{UF}, 10 \%, 200 \mathrm{~V}$ | 59660 | 835-515-YSE0102K |
| A10C4038 | 281-0775-00 |  |  | CAP, FXD, CER DI: $0.14 \mathrm{~F}, 20 \%$, 50 V | 04222 | MA205E104MAA |
| A10CR2012 | 152-0141-02 |  |  | SEMICOND DVC, DI:SW,SI, 30V,150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR2013 | 152-0141-02 |  |  | SEMICOND DVC, DI:SW, SI, 30V, 150MA, 30V, 00-35 | 03508 | DA2527 (1N4152) |
| A10CR2023 | 152-0141-02 |  |  | SEMICOND DVC, DI :SW, SI, 30V, 150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| AlOCR3034 | 152-0141-02 |  |  | SEMICOND DVC, DI: SW, SI, 30V, 150MA, 30V, D0-35 | 03508 | DA2527 (1N4152) |
| A10CR4032 | 152-0141-02 |  |  | SEMICOND DVC. DI :SW, SI, 30V, 150MA, 30V, 00-35 | 03508 | DA2527 (1N4152) |
| AlOCR4037 | 152-0141-02 |  |  | SEMICOND DVC,DI:SW, SI, 30V,150MA, 30V,00-35 | 03508 | DA2527 (1N4152) |
| A100S1011 | 150-1048-00 |  |  | LAMP, LED RDOUT:ORANGE, 7 SEG, 1 DIGIT | 58361 | Q3383/MAN4640A |
| Al00S1012 | 150-1048-00 |  |  | LAMP, LED RDOUT:ORANGE, 7 SEG, 1 digit | 58361 | Q3383/MAN4640A |
| A10DS1023 | 150-1048-00 |  |  | LAMP, LED RDOUT: ORANGE, 7 SEG, 1 DIGIT | 58361 | Q3383/MAN4640A |
| A10DS1024 | 150-1048-00 |  |  | LAMP, LED RDOUT:ORANGE, 7 SEG, 1 digit | 58361 | Q3383/MAN4640A |
| A10DS1035 | 150-1048-00 |  |  | LAMP, LED RDOUT: ORANGE, 7 SEG, 1 digit | 58361 | Q3383/MAN4640A |
| A10DS1036 | 150-1048-00 |  |  | LaMP, LED RDOUT: ORANGE, 7 SEG, 1 digit | 58361 | Q3383/MAN4640A |
| A100S2011 | 150-1036-00 |  |  | LT EMITTING DIO:RED, 650Mm, 40MA MAX | 58361 | Q6878/MV5074C |
| A100S2022 | 150-1036-00 |  |  | LT EMITIING DIO:RED, 650NM, 40MA MAX | 58361 | Q6878/MV5074C |
| A10DS2034 | 150-1036-00 |  |  | LT EMITTING DIO:RED, 650NM, 40MA MAX | 58361 | Q6878/MV5074C |
| Al0J2062 | 131-2651-01 |  |  | CONN, RCPT, ELEC: HEADER, $1 \times 36,0.1$ CTR, 0.025 PIN | TK1483 | 082-3643-SS05 |
| A1034012 | 131-1857-00 |  |  | TERM SET, PIN:36/0.025 SQ PIN,ON 0.1 CTRS | TK1483 | 082-3643-SS10 |
| A10J4014 | 131-1857-00 |  |  | TEPM SET, PIN:36/0.025 SQ PIN,ON 0.1 CTRS | TK1483 | 082-3643-SS10 |
| A10,34015 | 131-2833-00 |  |  | CONN, RCPT, ELEC : BNC, FEMALE | 24931 | 28JR175-4 |
| A10L2013 | 108-0245-00 |  |  | CHOKE, RF:FIXED, 3.9 ${ }^{\text {U }}$ | 76493 | B6310-1 |
| A1002023 | 151-0341-00 |  |  | TRANS ISTOR:NPN,SI, TO-106 | 04713 | SPS6919 |
| A1002027 | 151-0342-00 |  |  | TRANSISTOR: PNP, SI, T0-92 | 07263 | S035928 |
| A10Q3011 | 151-0190-00 |  |  | TRANSISTOR:NPN, SI, TO-92 | 80009 | 151-0190-00 |
| A10Q3031 | 151-0190-00 |  |  | TRANSISTOR:NPN, SI, $70-92$ | 80009 | 151-0190-00 |
| A1004021 | 151-0427-00 |  |  | TRANSISTOR:NPN, SI, T0-92 | 07263 | S39287 |
| A1004022 | 151-1042-00 |  |  | SEMICOND DVC SE:FET,SI,T0-92 | 04713 | SPF627M2 |
| A10Q4023 | 151-1042-00 |  |  | SEMICOND DVC SE:FET,SI, T0-92 | 04713 | SPF627M2 |
| A10R2011 | 315-0103-00 |  |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043C×10K00J |
| A10R2012 | 315-0512-00 |  |  | RES, FXD, FILM: $5.1 \mathrm{~K} 0 \mathrm{HM}, 5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E05K1 |
| A10R2022 | 315-0561-00 |  |  | RES, FXD, FILM: 560 OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX560R0J |
| A10R2023 | 315-0103-00 |  |  | RES, FXD, FILM:10K OHM, 5\%,0.25W | 19701 | $5043 C \times 10 \mathrm{K00} 3$ |
| Al0R2025 | 315-0472-00 |  |  | RES, FXD, FILM 4.7 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E04K7 |
| AlOR2026 | 315-0472-00 |  |  | RES, FXD, FILM:4.7K OHM, 5\%,0.25W | 57668 | NTR25J-E04K7 |



| Componert Mo． | Tektronix Port No． | Serial／Asenbly Mo． Effective Dscom | Mone 8 Description | Mfr Code | Mfr．Part Mo． |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A12C3014 | 290－0952－00 |  | CAP，FXC，ELCTLT 4.7 UF＋／－20\％．63V | 55880 | ULBijarims |
| A12CRid20 | 152－0141－02 |  | SEMICONO DVC．DI SW．S1，30V．150M．30V，00－35 | 03508 | D42527（1N4：52） |
| A12CRi021 | 152－0141－02 |  | SEMICOND DVC，DI ：SW． $51,30 \mathrm{~V}, 150 \mathrm{MA}$ ．30V，00－35 | 03508 | D42527（1M452） |
| A12CR1025 | 152－0141－02 |  | SEMICOND DVC．DI ．SW．S1．30V，1504K．30V，00－35 | 03508 | DA2527（1me：53） |
| A12CR1026 | 152－0141－02 |  | SEMICOND DVC．DI Sw．SI，30V．1504，，30V，D0－35 | 03508 | Da2527（1N4：52： |
| A．2CR1062 | 152－0141－02 |  | SEMICONE DVE．Di．Swi．Sl．30V．150\％，30V，D0－35 | 03508 | Daz527（inci52； |
| AizCRIOG3 | 152－0141－02 |  | SEMICOND DVC，DI：SW，SI，30V．1504，30V． $00-35$ | 03508 | 042527（NE：52） |
| A．2CR2014 | 152－0056－00 |  | SEMICONC DVC．DI：RECT．SI．400V，1A．D0－41 | 05828 | GPIDG－02： |
| Ai2CR2018 | 152－0066－0？ |  | SEM：CONO CVC．DI：RECT，S1．400V．14．D0－41 | 05828 | GPix－02： |
| A）2CR2022 | 152－0141－02 |  | SEMICONE DVC．DI ：Sw，SI，30V，150w，30V，00－35 | 03508 | DA25z？（INC：52） |
| A：2CR2023 | 152－0141－02 |  | SEMICONE DV．O1 SW，SI，30V， 150 W ，30V． $00-35$ | 03508 | DA2527（ $14 \mathrm{C}: 52$ ） |
| A：2CR2034 | 152－0141－02 |  | SEMICOND DV：．DI：SW，51，30V，150M4，30V，00－35 | 03508 | DA2527（144252） |
| A：2CR2035 | 152－0141－02 |  | SEMICONC DVC．DI SW．ST，30V，150M4，30V．00－35 | 03508 | 042527（1．4：52） |
| A：2CR2036 | 152－0141－02 |  | SEMICOND DVC．DI ： $5 \mathrm{~W}, 51,30 \mathrm{~V}, 150 \mathrm{WK}, 30 \mathrm{~V} .00-35$ | 03508 | DAZ527（ $1: 4052$ |
| A：2CR2037 | 152－014i－02 |  | SEMICOND DVC．DI ：SW，SI．30V．150KK．30V，D0－35 | 03508 | 022527 （1，4：52） |
| AiCC22038 | 152－0141－0？ |  | SEMICONE OVC．DI：SW，SI，30V．150\％，30V，D0－35 | 03508 | 022527 （114：52） |
| A：2F20：0 | 159－0222－00 |  | FUSE，WIRE LEAD 0.2504 .125 V ．FAST | 71400 |  |
| Ai2F30：2 | 159－0220－00 |  | FUSE．WIRE LEAD：34．125V．FAST | 71400 | TRA ${ }^{\text {a }}$ |
| A12F30：3 | 159－0114－00 |  | FUSE．CARTRIDEE：1A，125A，AXIAL LEASS | 71400 | GFA： |
| A：201032 | 131－2132－01 |  | CONN，RCPT，ELEC：IEADER． $1 \times 35,0.16$ Th | TK1483 | 08\％－364べ－Sここさ |
| Aicul040 | 131－1857－00 |  | TERN SET．PIA 36／0． 025 SQ PIN，ON 0．1 CTRS | TK14E： | 082－364こ－5：2 |
| A1232032 | 131－2132－01 |  | CONN．RCPT，ELEC ：IEADER， $1 \times 3 \mathrm{E}, 0.1 \mathrm{CTF}$ | TK148： | 082－364－55こ |
| A 1232042 | 131－1857－00 |  | TEAM SET，PIN：35／0．025 SC PIN．ON 0．1 CTRS | TK1483 | 082－3643－5i10 |
| Al2jaix 2 | 131－1957－00 |  | TEAN SET．PIN：36／0．025 SC PIN，ON 0．1 CTRS | TK1483 | 08¢－364－5：10 |
| A1202062 | 131－2858－0C |  | CONA，REPT，ELEC：OK BC． $2 \times 13$. HORIZONIAL | 22525 | 65000－0： |
| 41201025 | 151－0：90－00 |  | TRANSISTOR：NPN，S1，T0－92 | 8000 C | 151－0：90－6 |
| A1201042 | 151－0190－00 |  | TRANSISTOR：NDN，S1，T0－92 | 80009 | 151－0：90－0 |
| A1201043 | 151－م190－00 |  | TRANS！STOR MPN，51，T0－92 | 80009 | 151－0190－0： |
| A．201052 | ：51－318E－0C |  | TRANSISTOR PRF．S1．T0－92 | 80009 | 151－0：38－0 |
| Ai201053 | 151－0164－00 |  | TRANS 15TOR：PNP，S1，T0－92 | 04713 | 2N29074 |
| A1201054 | 111－5164－20 |  | TRANSISTOR PNP，S1．T0－92 | 04713 | 2N2957\％ |
| A120105E | － 5 －C＇35－0c |  | TRANSISTOR PNF．S1．T0－92 | 80009 | 151－0188－2t |
| A1201057 | 151－2216－00 |  | TRANSISTOR PRP，SI，T0－92 | 04713 | SPS88： |
| A120：062 | 151－0220－00 |  | TRANS ISTOR PPNF ．SI，T0－92 | 80009 | 151－0220－95 |
| A12C1064 | 151－0720－0 |  | TRANSISTOR：PNP，S1，TO－92 | 80009 | 151－022j－0i |
| A1201066 | 151－0188－00 |  | TRANSISTOR：PNP，S1，TO－92 | 86009 | 151－0188－00 |
| A1201068 | ！51－0188－00 |  | TRANSISTOR：PWP，S1，T0－92 | 80009 | 151－0188－02 |
| A1202031 | 151－0190－00 |  | TRANSISTOR：NPN，SI，TO－92 | 80009 | 151－0190－00 |
| A1202032 | 151－0190－00 |  | TRANSISTOR MPN，SI，T0－92 | 80009 | 151－0190－00 |
| A12R201 | 315－0104－00 | B011470 | RES，FXD，FIMM： 100 K O＋1．5\％，0．251 | 57668 | NTR251－E100k |
| AL2RJ013 | 307－0445－00 |  | RES NTWK，FXD，FI： 4.7 K O＋4，20\％，（9）RES | 32997 | 4310R－101－472 |
| Ai2R1022 | 315－0101－00 |  | RES．FXD，FILM： $100 \mathrm{Om}, 5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25－E 10t： |
| A12R1024 | 315－0222－00 |  | RES，FXD，FILM： $2.2 \mathrm{X} 0+\mathrm{m}, 5 \%, 0.25 w$ | 57568 | NTR251－E02K |
| A12R1025 | 315－0103－00 |  | RES，FXD，FILM $10 \mathrm{~K} 0 \mathrm{OH}, 5 \%, 0.25 \mathrm{~W}$ | 19701 | $50438 \times 10 \mathrm{Kcol}$ |
| A12R1025 | 315－0223－00 |  | RES，FXD，FILM： $22 \mathrm{~K} \mathrm{OH+}, 5 \%, 0.25 \mathrm{~W}$ | 19701 | $50435 \times 22 \mathrm{K0013} 2 \mathrm{U}$ |
| A12R1031 | 315－0272－00 |  | RES，FXD，FILM 2.7 KO OM，5\％， 0.25 | 57658 | NTR25－E020 |
| A12R1032 | 315－0103－00 |  | RES，FXD，FILM 10 K OHM，5\％，0．25\％ | 19701 | 5043010\％00 |
| A12R1039 | 315－0472－00 |  | RES，FXD，FILM： $4.7 \mathrm{KOH}, 5 \%$ ， 0.25 N | 57658 | NTR25－E04\％ |
| A12R1040 | 315－0151－00 |  | RES，FXD，FILM： $1500 \mathrm{OHM}, 5 \%, 0.25 \mathrm{~N}$ | 57668 | WTR25J－E150E |
| AIzRIOA1 | 315－0102－0 |  | RES，FXD，FILM：IK OM，5\％，0．251 | 57668 | NTR25JEOIKO |
| A12R1042 | 315－0103－00 |  | RES．FXD．FILM：10 $0 \times 4,5 \%, 0.254$ | 19701 | $5043 \times 10 \times 001$ |
| A12R1043 | 307－0446－00 |  | RES NTK．FXD，FI： 10 K OM，20\％．（9）RES | 11236 | 750－101－210 |
| AL2R1044 | 315－0152－0 |  | RES，FXD，FILM： 1.5 K OM，5x， 0.251 | 57668 | WTR25－E01K5 |
| A2RLOM5 | 315－0561－00 |  | RES，FXP FILM：56C OMM，5\％， 0.25 W | 19701 | $50430 \times 560 \mathrm{Ba}$ |
| A12RIO46 | 315－0101－00 |  | RES．FXD，FIMM： 100 OF4，5x，0．251 | 57688 | MTR25J－E $100 E$ |
| A12R1047 | 315－0107－00 |  | RES，FXD，FILM：100 O＋M，5\％．0．25 | 01121 | CB1075 |
| A12R1050 | 315－0102－00 |  | RES，FXD，FILM： 1 K OM， $5 \mathrm{5x}, 0.25 \mathrm{~N}$ | 57668 | NTR25JE01K0 |
| AL2R1052 | 315－0331－00 |  | RES，FXD，FILM： $330 \mathrm{Om}, 5 \pm, 0.251$ | 57668 | NTR25J－E330E |


| Component No. | Tektronix <br> Part No. | Serial/Assenbly No. Effective Dscont | Name \& Description | Mfr. Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A12R1052 | 315-0331-00 |  | RES, FXD, FILM: 330 OHM , $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E330E |
| A12R1053 | 315-0162-00 |  | RES, FXD, FILM:1.6K OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX1K600J |
| A12R1054 | 315-0561-00 |  | RES, FXD, FILM: 560 OHM, 5\%, 0.25W | 19701 | 5043CX560R0J |
| A12R1055 | 315-0102-00 |  | RES, FXD, FILM: 1 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25JE01K0 |
| A12R1056 | 315-0201-00 |  | RES, FXD, FILM: 200 OHM, 5\%, 0.25W | 57668 | NTR25J-E200E |
| A12R1057 | 315-0270-00 |  | RES, FXD, FILM: 27 OHM, 5\%,0.25W | 19701 | 5043CX27R00J |
| Al2R1058 | 315-0473-00 |  | RES, FXD,FILM: 47 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E47K0 |
| A12R1059 | 315-0103-00 |  | RES, FXD, FILM 10 KK OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX10K00J |
| Al2R1060 | 315-0103-00 |  | RES, FXD, FILM: 10 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX10K00J |
| A12R1062 | 315-0511-00 |  | RES, FXD, FILM: 510 OHM, 5\%, 0.25W | 19701 | 5043CX510R0J |
| A12R1063 | 315-0270-00 |  | RES, FXD, FILM: 27 OHM, 5\%, 0.25 W | 19701 | 5043CX27R00J |
| A12R1064 | 315-0101-00 |  | RES, FXD, FILM 100 OHM, 5\%, 0.25W | 57668 | NTR25J-E 100E |
| A12R1065 | 315-0101-00 |  | RES, FXD, FILM 100 OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E 100E |
| A12R1066 | 315-0182-00 |  | RES.FXD,FILM: 1.8 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25j-E1K8 |
| A12R1067 | 315-0182-00 |  | RES, FXD, FILM: 1.8 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25j-E1K8 |
| A12R1068 | 315-0181-00 |  | RES, FXD, FILM 180 OHM, 5\%, 0.25W | 57668 | NTR25J-E180E |
| A12R1069 | 315-0751-00 |  | RES, FXD, FILM 750 OHM, 5\%, 0.25W | 57668 | NTR25J-E750E |
| A12R2014 | 315-0104-00 | B011470 | RES, FXD, FILM: 100 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E100K |
| A12R2015 | 315-0102-00 |  | RES, FXD, FILM: $1 \mathrm{~K} \mathrm{OHM}, 5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25JE01K0 |
| A12R2016 | 308-0244-00 |  | RES, FXD, WW: 0.3 OHM, 10\%, 2W | 00213 | 310s 0.3-10 |
| A12R2031 | 307-0445-00 |  | RES NTWK, FXD, FI:4.7K OHM, 20\%, (9)RES | 32997 | 4310R-101-472 |
| A12R2032 | 307-0445-00 |  | RES NTWK, FXD, FI:4.7K OHM, 20\%, (9)RES | 32997 | 4310R-101-472 |
| A12R2034 | 315-0472-00 |  | RES.FXD,FILM:4.7K OHM, 5\%,0.25W | 57668 | NTR25J-E04K7 |
| A12R2035 | 315-0472-00 |  | RES,FXD,FILM:4.7K OHM,5\%,0.25W | 57668 | NTR25J-E04K7 |
| A12R2038 | 315-0103-00 |  | RES, FXD, FILM 10 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX10K00J |
| A12R2039 | 315-0103-00 |  | RES, FXD, FILM $10 \mathrm{~K} 0 \mathrm{HM}, 5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX10K003 |
| A12R2046 | 315-0472-00 |  | RES, FXD,FILM:4.7K OHM,5\%,0.25W | 57668 | NTR25J-E04K7 |
| A12R2047 | 315-0561-00 | B010100 B011129 | RES, FXD, FILM: 560 OHM, 5\%,0.25W | 19701 | 5043CX560R0J |
| A12R2048 | 315-0561-00 | 8010100 B011129 | RES, FXD, FILM $5600 \mathrm{HM}, 5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX560R0J |
| A12R2051 | 315-0106-00 |  | RES, FXD, FILM 10 M OHM, 5\%, 0.25W | 01121 | CB1065 |
| A12R2052 | 315-0682-00 |  | RES, FXD, FILM: 6.8 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 57668 | NTR25J-E06K8 |
| A12R2053 | 315-0154-00 |  | RES, FXD, FILM: 150 K OHM, $5 \%$, 0.25 W | 57668 | NTR25J-E150K |
| A12R2063 | 307-0598-00 |  | RES NTWK, FXD, F1:7,330 OHM, 2\%, 1.0W | 11236 | 750-81-R330 |
| A12R3012 | 321-0260-00 |  | RES, FXD,FILM: $4.99 \mathrm{~K} \mathrm{OHM}, 1 \%, 0.125 \mathrm{~W}, \mathrm{TC}=$ T0 | 19701 | 5033ED4K990F |
| A12R3014 | 315-0162-00 |  | RES, FXD, FILM 11.6 K OHM, $5 \%, 0.25 \mathrm{~W}$ | 19701 | 5043CX1K600J |
| A12R3015 | 321-0225-00 |  | RES, FXD, FILM: 2.15 K OMM, $1 \%, 0.125 \mathrm{~W}, \mathrm{TC}=$ TO | 19701 | 5033ED2K15F |
| A12R3016 | 321-0105-00 |  | RES, FXD, FILM: 121 OHM $1 \%, 0.125 \mathrm{~W}, \mathrm{TC}=10$ | 07716 | CEADI21ROF |
| A12R3017 | 321-0151-00 |  | RES, FXD, FILM: 365 OHM, 1\%, 0.125W, TC=T0 | 07716 | CEAD365ROF |
| A12S2061 | 260-2123-00 |  | SWITCH,ROTARY: DUAL CONCENTRIC | 29604 | 73-8501 |
| A12TP1063 | 214-0579-00 |  | TERM.TEST POINT:BRS CD PL | 80009 | 214-0579-00 |
| A12TP2012 | 214-0579-00 |  | TERM, TEST POINT:BRS CD PL | 80009 | 214-0579-00 |
| A12TP2014 | 214-0579-00 |  | TERM, TEST POINT:BRS CD PL | 80009 | 214-0579-00 |
| A12TP3012 | 214-0579-00 |  | TERM, TEST POINT:BRS CD PL | 80009 | 214-0579-00 |
| A12U1011 | 156-0525-03 |  | MICROCKT, DGTL:DUAL J-K MASTER SLAVE FF,SEL | 04713 | MC14027BCLD |
| A12U1012 | 156-0514-01 |  | MICROCKT,DGTL:DIFF 4-CHANNEL MUX,SEL | 80009 | 156-0514-01 |
| Al2U1023 | 156-1152-01 |  | MICROCKT, DGTL:PRCN RETRIGGERABLE,SCRN | 04713 | MC14538BCLDS |
| A12U1024 | 156-0366-02 |  | MICROCKT, DGTL:DUAL D FLIP-FLOP, SCREENED | 02735 | CD4013BFX |
| A12U1025 | 156-0349-06 |  | MICROCKT. DGTL:QUAD 2 INP NOR GATE | 02735 | CD4001BFX |
| A12U1031 | 156-0383-02 |  | MICROCKT, DGTL :QUAD 2-INP NOR GATE, SCRN, | 18324 | N74LSO2NB |
| A12U1032 | 156-0910-02 |  | MICROCKT, DGTL:DUAL DECADE COUNTER, SCRN | 01295 | SN74LS390N3 |
| Al2U1034 | 156-0350-05 |  | MICROCKT, DGTL:QUAD 2 INPUT NAND GATE | 02735 | CD4011BFX |
| Al2U1036 | 156-0349-06 |  | MICROCKT,DGTL:QUAD 2 INP NOR GATE | 02735 | CD4001BFX |
| A12U1037 | 156-0754-02 |  | MICROCKT, DGTL:DUAL 4 -INPUT NOR GATE, SCRN | 02735 | CD4002BFX-98 |
| Al2U1044 | 156-0352-00 |  | MICROCKT, DGTL:CMOS, DUAL CMPLM PAIR + INVT | 02735 | CD4007A(E OR F) |
| Al2U1048 | 156-0385-02 | B010100 B011129 | MICROCKT, DGTL:HEX INVERTER,SCRN | 07263 | 74LSO4PCQR |
| Al2U1048 | 156-2027-00 | B011130 | MICROCKT,DGTL:CMOS,HEX INVERTER | 27014 | MM74HCO4N |
| Al2U1052 | 156-0970-03 |  | MICROCKT,DGTL:QUAD HV NAND GATE W/OC OUT | 01295 | SN74LS26NP3 |
| A12U1063 | 156-0182-02 |  | MICROCKT, DGTL:TRIPLE 2-3-2 INP GATE, SCRN | 04713 | MC10105PD/LD |


| Component Mo. | Tektronix Part Mo. | Serial/Asse Effective | bly No. Dscont | Nane \& Description | Mfr. Code | Mfr. Part Mo. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A12U2013 | 156-0071-02 |  |  | MICROCKT, LINEAR:VOLTAGE REGULATOR, CHECKED | 04713 | MC1723CLDS |
| Al2U2014 | 156-1451-00 |  |  | MICROCKT, LINEAR:3-TERM NEG VOLTAGE RGLTR | 27014 | LM337T |
| A12U2026 | 156-0384-02 |  |  | MICROCKT. DGTL.:QUAD 2-INP NAND GATE, SCRN | 07263 | 741403PCOR |
| A12U2027 | 156-0383-02 | B010100 | B011129 | MICROCKT. DGTL:QUAD 2-INP NOR GATE, SCRN, | 18324 | N74LSO2NB |
| A12U2027 | 156-2026-00 | B011130 |  | MICROCKT, DGTL:CMOS,QUAD 2 INPUT NOR GATE | 04713 | MC74HCO2(N OR J) |
| A12U2043 | 156-0411-02 |  |  | MICROCKT, LINEAR:QUAD COMPARATOR, SCREENED | 04713 | LM339JDS |
| A12U2045 | 156-0411-02 |  |  | MICROCKT, LINEAR:QUAD COMPARATOR, SCREENED | 04713 | LM339J0S |
| A12U2047 | 156-1655-00 |  |  | MICROCKT, DGTL: IDL, 1OMHZ UNIVERSAL COUNTER | 32293 | ICM72268IPL |
| A12U2054 | 156-0704-00 |  |  | MICROCKT, LINEAR:CMOS, PHASE LOCK LOOP | 04713 | MC14046CP |
| A12U2067 | 156-0642-01 |  |  | MICROCKT, DGTL: BI QUINARY CNTR, SCREENED | 04713 | MC10138PD/LD |
| A12Y2054 | 158-0129-00 |  |  | XTAL UNIT, QTZ:10WHZ 0.001\%, PARALLEL | 00136 | 20-9-1 |

## 2 <br> Digitally signed by http://www.aa4df.com

## DIAGRAMS AND CIRCUIT BOARD ILLUSTRATIONS

## Symbols

Graphic symbols and class designation letters are based on ANSI Standard Y32.2-1975.

Logic symbology is based on ANSI Y32.14-1973 in terms of positive logic. Logic symbols depict the logic function performed and may differ from the manufacturer's data.

The overline on a signal name indicates that the signal performs its intended function when it is in the low state.

Abbreviations are based on ANSI Y1.1-1972.

Other ANSI standards that are used in the preparation of diagrams by Tektronix, Inc. are:

Y14.15, 1966 Drafting Practices.
Y14.2, 1973 Line Conventions and Lettering.
Y10.5, 1968 Letter Symbols for Quantities Used in Electrical Science and Electrical Engineering.

American National Standard Institute 1430 Broadway
New York, New York 10018

## Component Values

Electrical components shown on the diagrams are in the following units unless noted otherwise:
Capacitors = Values one or greater are in picofarads (pF). Values less than one are in microtarads $(\mu \mathrm{F})$.
Resistors $=$ Ohms $(\Omega)$.

## The information and special symbols below may appear in this manual.

## Assembly Numbers and Grld Coordinates

Each assembly in the instrument is assigned an assembly number (e.g., A20). The assembly number appears on the circuit board outline on the diagram, in the title for the circuit board component location illustration, and in the lookup table for the schematic diagram and corresponding component locator illustration. The Replaceable Electrical Parts list is arranged by assemblies in numerical sequence; the components are listed by component number "(see following illustration for constructing a component number).

The schematic diagram and circuit board component location illustration have grids. A lookup table with the grid coordinates is provided for ease of locating the component. Only the components illustrated on the facing diagram are listed in the lookup table. When more than one schematic diagram is used to illustrate the circuitry on a circuit board, the circuit board illustration may only appear opposite the first diagram on which it was illustrated; the lookup table will list the diagram number of other diagrams that the circuitry of the circuit board appears on.



Fig. 8-1. Display Board.

## ADJUSTMENTS AND TEST POINTS




Fig. B-2. Main Board.


DC 504A


4291-55
BLOCK DIAGRAM
ig. 8-3. Block Diagram.

# Table 8-1 COMPONENT REFERENCE CHART 

| P/O A10 ASSY |  |  |  | FRONT PANEL BOARD |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION |
| C2012 E2 A3 P3012 K3 |  |  |  |  |  |
| C2014 | D2 | B4 | R3014 | K3 | B4 |
| C2033 | D3 | C3 | R3018 | 16 | B5 |
| C3021 | L4 | B4 | R3024 | 13 | 84 |
| C3034 | 12 | C4 | R3025 | K4 | 84 |
| C4013 | H6 | B5 | R3026 | K3 | B4 |
| C4014 | E5 | B5 | R3027 | H2 | C4 |
| C4021 | F5 | B5 | R3032 | M3 | C4 |
| C4025 | F6 | C5 | R3035 | J4 | C4 |
| C4035 | 15 | D5 | R3036 | 12 | C4 |
| C4036 C4038 | G4 | C6 C6 | R3037 | ${ }^{\text {J2 }}$ | C4 |
| C4038 |  |  | R4014 | H6 | A5 |
| CR3034 | 12 | C4 | R4015 | D7 | A5 |
| CR4032 | H4 | C5 | R4023 | E6 | C5 |
| CR4037 | H5 | C4 | R4024 | E5 | B5 |
|  |  |  | R4027 | E5 | B6 |
| J4012 | C6 | A5 | R4028 | G5 | C6 |
| J4015 | C5 | A5 | R4033 | J5 | D5 |
|  |  |  | R4034 | J4 | D5 |
| L2013 | D2 | $B 4$ | R4036 | G5 | C5 |
| P4012 |  |  | R4037 | K5 | C5 |
| P4014 | D4 | A5 | S4024 | ${ }^{6} 6$ | B5 |
|  |  |  | S4025 | J6 | C5 |
| $\begin{aligned} & \text { Q4021 } \\ & \text { Q4022 } \\ & \text { O4023 } \end{aligned}$ | $\stackrel{16}{16}$ | B5 | U3022 | K3 | B4 |
|  |  |  |  |  |  |
|  |  |  | W500 | B6 | Chassis |
| P/O A10 ASSY also shown on |  |  |  |  |  |
| P/O A12 ASSY |  |  |  | MAIN BOARD |  |
| J4012 | B6 | E2 | P2010 P4012 | $\begin{aligned} & 86 \\ & B 6 \end{aligned}$ | $\begin{aligned} & \text { E3 } \\ & \text { E2 } \end{aligned}$ |
| P/O A12 ASSY also shown on$\langle 2\rangle\langle 3\rangle$ |  |  |  |  |  |

## PARTS LOCATION GRID



(3)Static Sensitive Devices See Mantenance Section

Fig. 8-4. Display Board (A10 Assy), and partial of Main Board (A12 Assy).

## COMPONENT NUMBER EXAMPLE


Chassis- molumed components have no Assembly Num
prefir - see end of Replaceabie Electrical Parts List


DC 5D4A


## rION GRID



## PARTS LOCATION



Fig. 8-5. Main Board (A12 As

## Table 8-2 <br> COMPONENT REFERENCE CHART

| P/O A12 ASSY |  |  |  | MAIN BOARD <2> |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT <br> NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION |
| C1051 | L7 | $J 1$ | R1046 | J5 | H1 |
| C1052 | G6 | J2 | R1047 | G6 | H1 |
| C1057 | H5 | J2 | R1050 | C5 | K1 |
| C2055 | G7 | J3 | R1052 | $J 4$ | J2 |
| C2067 | E5 | K3 | R1053 | 16 | J2 |
| C2068 | C3 | L3 | R1054 | 16 | J2 |
|  |  |  | R1055 | C5 | K1 |
| CR1020 | L5 | D1 | R1056 | 16 | K1 |
| CR1021 | L5 | D1 | R1057 | G5 | K2 |
| CR1062 | ${ }^{\text {J6 }}$ | L1 | R1058 | G4 | K2 |
| CR1063 | C4 | L1 | R1059 | D5 | K2 |
| J1040 | 19 | H1 | R1062 | B4 | K2 |
|  |  |  | R1063 | G2 | L1 |
| P1040 | J9 | H1 | R1064 | H4 | L1 |
|  |  |  | R1065 | G4 | L2 |
| 01042 | H7 | H1 | R1066 | D1 | M1 |
| 01043 | F8 | H1 | R1067 | D2 | M1 |
| Q1052 | J4 | J1 | R1068 | L6 | M1 |
| 01053 | G5 | J2 | R1069 | L6 | M1 |
| Q1054 | ${ }^{\text {J65 }}$ | K2 | R2046 | ${ }_{13}{ }^{17}$ | H2 H3 |
| $Q 1057$ | J4 | K2 | R2048* | J3 | H3 |
| $Q 1062$ | G2 | K1 | R2052 | F6 | J3 |
| Q1064 | H2 | L1 M2 | R2053 R2063 | F6 | J3 |
| Q1068 | D1 | M2 | R2063 | E3 | L2 |
|  |  |  | TP1063 | B2 | L2 |
| R1032 | ${ }_{L 5}$ | F1 | U1032 | 18 | F1 |
| R1039 | H7 | G1 | U1044 | G6 | H2 |
| R1040 | G7 | G1 | U1048 | H3 | H2 |
| R1041 | G8 | G1 | U1052 $\mathbf{U 1 0 6 3}$ | ${ }^{\text {J6 }}$ | J1 |
| R1044 | K6 | H1 | U2054 | F5 | K3 |
| R1045 | 15 | H1 | U2067 | D4 | L3 |
| P/O A12 ASSY also shown on |  |  |  |  |  |

-See Parts List for
serial number ranges.



## CATION GRIDS



Fig. 8-7. Main Board (A12 Assy).

PARTS LOCA


Fig. 8.6. Display Board (A10 Assy).

# Table 8-3 <br> COMPONENT REFERENCE CHART 

| P/O A12 AS |  |  |  | MAIN B | ARD 3 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT <br> NUMBER | SCHEMATIC LOCATION | BOARD LOCATION |
| C2012 | $K 8$ |  | R1013 | F4 | B2 |
| C2014 | G10 | ${ }^{\text {C3 }}$ | R1024 | C2 | D2 |
| C2038 | L8 | F3 | R1025 | C2 | D2 |
| C2045 | L9 | A2 | R1026 | C2 | D2 |
| C2051 | C4 | J3 | R1043 | K1 | G2 |
| C2052* | D4 | J3 | R2014** | B3 | C3 |
| C2053 | C4 | J3 | R2015 | 18 | B3 |
| C3013 | 19 | C4 | R2016 | ${ }^{18}$ | B3 |
| C3014 | F10 |  | R2034 | A6 H 1 | F3 |
| CR2014 | K8 | B3 | R2051 | D4 | J3 |
| CR2018 | H10 | C3 | R3012 | H9 | B5 |
|  |  |  | R3014 | 19 | C4 |
| F2010 | E8 | B4 | R3015 | H9 G10 | 85 |
| F3012 | ${ }_{\text {E8 }}^{\text {E }} 10$ | 85 $C 5$ | R3016t R3017 | G10 F10 | B6 86 |
|  |  |  | TP2012 | H10 | C3 |
| $\begin{aligned} & \mathrm{J} 1032 \\ & \mathrm{~J} 2032 \\ & \mathrm{~J} 2042 \end{aligned}$ | $\begin{aligned} & 83 \\ & \text { D7 } \\ & \text { D3 } \end{aligned}$ | $\begin{aligned} & \text { G2 } \\ & \text { E4 } \\ & \text { H3 } \end{aligned}$ | TP2014 | $\stackrel{L 8}{\square 8}$ | C4 |
|  |  |  | U1037 | G3 | F4 |
|  |  |  | U1048 | ${ }^{\text {c }}$ | H2 |
| P2010 P2042 P2062 | $\begin{aligned} & \text { D10 } \\ & \text { D3 } \\ & 15 \end{aligned}$ | $\begin{aligned} & \text { A3 } \\ & \text { H3 } \\ & \text { M3 } \end{aligned}$ | U2013 | K8 | B4 |
|  |  |  | U2014 | ${ }^{\text {F10 }}$ | B4 |
|  |  |  | $\mathrm{U}_{\mathbf{U} 2027}$ | C3 | - C 4 |
| 01025 | C2 | D2 | U2045 | J2 | U2 |
|  |  |  | U2047 | F4 | G3 |
|  |  |  | Y2054 | D4 | J3 |
| P/O A12 ASSY also shown on < 1$\rangle\langle 2\rangle$ 考 |  |  |  |  |  |
| P/O A10 ASSY |  |  |  | DISPLAY BOARD |  |
| $\begin{aligned} & \text { Q3011 } \\ & \text { Q3031 } \end{aligned}$ | 86 86 | A4 | R2035 $\mathbf{R 2 0 3 6}$ | B6 $\mathrm{C6}$ | D3 D3 |
| $\begin{aligned} & \text { R2011 } \\ & \text { R2012 } \end{aligned}$ | $\begin{aligned} & \mathrm{B7} \\ & \mathrm{C} 6 \end{aligned}$ | $\begin{aligned} & \text { B3 } \\ & \text { A3 } \end{aligned}$ | $\begin{aligned} & \mathbf{S 3 0 1 2} \\ & \mathbf{S} 3032 \end{aligned}$ | $\begin{aligned} & \text { B6 } \\ & \text { B6 } \end{aligned}$ | $\begin{aligned} & \text { A4 } \\ & \text { D4 } \end{aligned}$ |
| P/O A10 ASSY also shown on <1> 4 |  |  |  |  |  |

tMay be located on back of board.
*See Parts List for
serial number ranges.



SEE PARTS LIST FOR EARLIER VALUES AND SERIAL NUMBER RANGES OF PARTS OUTLINED OR DEPICTED IN GREY

Static sensitive devices See haintenance section

COMPONENT NUMBER EXAMPLE


CMASSIS-MOUNTED COMPONENTS MAVE MO ASSEHRLY MUPER PREFIX - SEE ENO OF REMLACEAQE


4291-52
REV FEB 1986

## PARTS LOCATION GRID



Fig. 8-8. Display Board (A10 Assy).

## (3) <br> Static Sensitive Devices

See Mantenance Section

COMPONENT HUMBER EXAMPLE


Chassis mounted components hove no As sembly Mumber
prelix-see end of Redaceable Electucal Parts list

Table 8-4
COMPONENT REFERENCE CHART

| P/O A10 AS |  |  |  | DISPLAY E | RD |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEMATIC LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ | CIRCUIT NUMBER | SCHEMATIC LOCATION | $\begin{aligned} & \text { BOARD } \\ & \text { LOCATION } \end{aligned}$ |
| C2011 | D6 | B3 | J2062 | B2 | C3 |
| C2031 | C | C3 | P2062 | A1 | C3 |
| CR2012 | C4 | B2 |  |  | 83 |
| $\begin{aligned} & \text { CR2013 } \\ & \text { CR2023 } \end{aligned}$ | B4 C 6 | B2 | $\begin{aligned} & \text { Q2023 } \\ & \text { Q2027 } \end{aligned}$ | C6 | 83 |
| DS1011 | D3 | A1 | R2022 | D6 | B2 |
| DS 1012 | E3 | 81 | R2023 | C7 | B3 |
| DS1023 | F3 | B1 | R2025 | D7 | C3 |
| DS1024 | G3 | C1 | R2026 | C7 | C3 |
| DS1035 | 13 | C1 | R2027 | D6 | B3 |
| DS1036 | J3 | D1 | R2031 | F6 | C3 |
| DS2011 | C3 | A2 |  |  |  |
| DS2022 | D6 | B2 |  |  |  |
| DS2034 | F6 | C2 |  |  |  |
| P/O A10 ASSY also shown on |  |  |  |  |  |




CHASSIS-MOUNTED COMPONENTS have no assembly NUMBER PREFIX - SEE END OF REPLACEABLE ELECTRICAL PARTS LIST

## GRID



## PARTS LOCATION GRID



Fig. 8-9. Main Board (A12 Assy)

# Table 8-5 COMPONENT REFERENCE CHART 

| P/O A12 AS |  |  |  | MAIN B | RD <5 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD <br> LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD OCATION |
| C1011 | J7 | B2 | R1013 | E10 | B2 |
| C1012 | K7 | C2 | R1022 ${ }^{\text {R1043A* }}$ | 18 | D1 |
| C1021 | G10 | D1 | ${ }_{\text {R2031 }}{ }^{\text {R1043 }}$ | ${ }^{56}$ | E3 |
| C2027 | K8 | C2 | R2032 | D1 | E4 |
|  |  |  | R2038 | B4 | E3 |
| CR1025 | 15 | 02 | R2039 | B4 | F3 |
| CR1026 | ${ }^{16}$ | D2 | S2061 | C3 | $K 3$ |
| CR2022 | B7 B7 | D3 E3 |  |  |  |
| CR2034 | E3 | E3 | U1011 | 17 | B2 |
| CR2035 | E3 | E3 | 41012 | E7 | C2 |
| CR2036 | E3 | E3 | ${ }^{1} 1023$ | H10 | D1 |
| CR2037 | E2 | E3 | U1024 | F9 15 | D2 |
| CR2038 | G5 | F3 | U1025 U 1031 | ${ }_{6}^{15}$ | E2 |
| J2032 | A1 | E4 | U1034 | H 11 | E2 |
|  |  |  | $\cup 1036$ | G3 | E2 |
| Q2031 $02032$ | C3 | F3 | U1037 U1048 | H4 G6 | F2 H 2 |
| 02032 | B4 | F4 | U1028 | H5 | D3 |
|  |  |  | U2027 | D8 | D4 |
| P/O A12 ASSY also shown on |  |  | $\rangle$ | $\langle 3$ |  |

*See Parts List for
serial number ranges.


F| G $|$| G | I | J | K | L |
| :--- | :--- | :--- | :--- | :--- | :--- |



# REPLACEABLE MECHANICAL PARTS 

## PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

SPECIAL NOTES AND SYMBOLS
X000 Part first added at this serial number
00x Part removed after this serial number

FIGURE AND INDEX NUMBERS
Items in this section are referenced by figure and index numbers to the illustrations.

## INDENTATION SYSTEM

This mechanical parts list is indented to indicate item relationships. Foliowing is an example of the indentation system used in the description column.

12345
Name \& Description
Assembly and/or Component
Attaching parts for Assembly and/or Component
.... - . -
Detail Part of Assembly and/or Component
Attaching parts for Detail Part
....*...
Parts of Detail Part
Attaching parts for Parts of Detail Part

Attaching Parts always appear in the same indentation as the item it mounts, while the detaif parts are indented to the right Indented items are part of, and included with, the next higher indentation. The separation symbol - . . .- - indicates the end of attaching parts

## Attaching parts must be purchased separately, unless otherwise

 specified.
## ITEM NAME

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

## ABBREVIATIONS

| " | INCH | ELCTRN | ELECTRON | IN | INCH | SE | SINGLE END |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| * | NUMBER SIZE | ELEC | ELECTRICAL | INCAND | INCANDESCENT | SECT | SECTION |
| ACTR | ACTUATOR | ELCTLT | ELECTROLYTIC | INSUL | INSULATOR | SEMICOND | SEMICONDUCTOR |
| ADPTR | ADAPTER | ELEM | ELEMENT | INTL | INTERNAL | SHLD | SHIELD |
| ALIGN | ALIGNMENT | EPL | ELECTRICAL PARTS LIST | LPHLDR | LAMPHOLDER | SHLDR | SHOULDERED |
| AL | ALUMINUM | EQPT | EQUIPMENT | MACH | MACHINE | SKT | SOCKET |
| ASSEM | ASSEMBLED | EXT | EXTERNAL | MECH | MECHANICAL | SL | SLIDE |
| ASSY | ASSEMBLY | FIL | FILLISTER HEAD | MTG | MOUNTING | SLFLKG | SELF-LOCKING |
| ATTEN | ATTENUATOR | FLEX | FLEXIBLE | NIP | NIPPLE | SLVG | SLEEVING |
| AWG | AMERICAN WIRE GAGE | FLH | FLAT HEAD | NON WIRE | NOT WIRE WOUND | SPR | SPRING |
| BD | BOARD | FLTR | FILTER | OBD | ORDER BY DESCRIPTION | SO | SQUARE |
| BRKT | BRACKET | FR | FRAME or FRONT | OD | OUTSIDE DIAMETER | SST | STAINLESS STEEL |
| BRS | BRASS | FSTNA | FASTENEA | OVH | OVAL HEAD | STL | STEEL |
| BRZ | BRONZE | FT | FOOT | PH BRZ | PHOSPHOA BRONZE | SW | SWITCH |
| BSHG | BUSHING | FXD | FIXED | PL | PLAIN or PLATE | $T$ | TUBE |
| CAB | CABINET | GSKT | GASKET | PLSTC | PLASTIC | TERM | TEAMINAL |
| CAP | CAPACITOA | HDL | HANDLE | PN | PART NUMBEA | THD | THREAD |
| CER | CERAMIC | HEX | HEXAGON | PNH | PAN HEAD | THK | THICK |
| CHAS | CHASSIS | HEX HD | HEXAGONAL HEAD | PWR | POWER | TNSN | TENSION |
| CKT | CIRCUIT | HEX SOC | HEXAGONAL SOCKET | RCPT | RECEPTACLE | TPG | TAPPING |
| COMP | COMPOSITION | HLCPS | HELICAL COMPRESSION | RES | RESISTOR | TRH | TRUSS HEAD |
| CONN | CONNECTOR | HLEXT | HELICAL EXTENSION | RGO | RIGID | $V$ | VOLTAGE |
| COV | COVER | HV | HIGH VOLTAGE | RLF | RELIEF | VAR | VAPIABLE |
| CPLG | COUPLING | IC | INTEGRATED CIRCUIT | ATNA | RETAINER | W/ | WITH |
| CRT | CATHODE RAY TUEE | 10 | INSIDE DIAMETEA | SCH | SOCKET HEAD | WSHR | WASHER |
| DEG | DEGREE | IOENT | IDENTIFICATION | SCOPE | OSCILLOSCOPE | XFMR | TRANSFORMER |
| DWR | DRAWER | IMPLR | IMPELLER | SCA | SCREW | XSTR | TRANSISTOR |

CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. Code | Manufacturer | Address | City, State, Zip Code |
| :---: | :---: | :---: | :---: |
| 00261 | GENERAL ELECTRIC 00 | 14TH AND ARNOLD STS | CHICAGO HEIGHTS IL 60411 |
|  | FOOD SERVICE EQUIPMENT BUSINESS DEPT |  |  |
| 09772 | WEST COAST LOCKWASHER CO INC | 16730 E JOHNSON DRIVE P O BOX 3588 | CITY OF INDUSTRY CA 91744 |
| 09922 | BURNOY CORP | RICHARDS AVE | NORWALK CT 06852 |
| 22526 | DU PONT E I DE NEMOURS AND CO INC DU PONT CONNECTOR SYSTEMS dIV MILITARY PRODUCTS GROUP | 515 FISHING CREEK RD | NEW CLMBERLAND PA 17070-3007 |
| 55285 | BERGQUIST CO INC THE | 5300 EDINA INDUSTRIAL BLVD | MINNEAPOLIS MN 55435-3707 |
| 71159 | BRISTOL SOCKET SCREW CO |  | WATERBURY CT |
| 73743 | FISCHER SPECIAL MFG CO | 111 INDUSTRIAL RD | COLD SPRING KY 41076-9749 |
| 78189 | ILLINOIS TOOL WORKS INC SHAKEPROOF DIV | ST CHARLES ROAD | ELGIN IL 60120 |
| 80009 | TEKTRONIX INC | 14150 SW KARL BRAUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 83385 | MICRODOT MFG INC GREER-CENTRAL DIV | 3221 W BIG BEAVER RD | TROY MI 48098 |
| 93907 | TEXTRON INC CAMCAR DIV | 60018 TH AVE | ROCKFORD IL 61101 BEAVERTON OR 97005-6448 |
| TK0392 <br> TK0435 | NORTHWEST FASTENER SALES INC LEWIS SCREW CO | 7923 SW CIRRUS DRIVE 4300 S RACINE AVE | BEAVERTON OR 97005-6448 CHICAGO IL 60609-3320 |
| TK0772 | RADAR ELECTRIC | 168 WESTERN AVE W | SEATHLE WA 98119-4212 |
| TK0858 | STAUFFER SUPPLY CO | 105 SE TAYLOR | PORTLAND OR 97214 |
| TK1326 | NORTHWEST FOLRSLIDE INC | 18224 SW 100TH CT | TUALATIN OR 97062 |

Fig. 8

| Index <br> No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Oty | 12345 Name \& Description | Mfr. <br> Code | Mfr. Part No. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1-1 | 337-3039-00 |  | 2 | SHIELD, ELEC:SIDE | 80009 | 337-3039-00 |
| -2 | 105-0932-00 |  | 2 | LATCH, PANEL:SIDE | 80009 | 105-0932-00 |
| -3 | 214-3364-00 |  | 2 | FASTENER, LATCH:ACETAL, SIL GRAY | 80009 | 214-3364-00 |
| -4 | 366-1023-13 |  | 1 | KNOB:GY, 0.127 ID X $0.39200 \times 0.531 \mathrm{H}$ | 80009 | 366-1023-13 |
|  | 213-0246-00 |  | 1 | .SETSCREW:5-40 X 0.094, STL | 71159 | ORDER BY DESCR |
| -5 | 366-2156-00 |  | 1 | KNOB:DOVE GRAY, 0.421 ID X $0.70600 \times 0.6 \mathrm{H}$ | 80009 | 366-2156-00 |
|  | 213-0153-00 |  | 2 | .SETSCREW:5-40 X 0.125, STL | TK0392 | ORDER BY DESCR |
| -6 | 358-0686-00 |  | 1 | BUSHING, SLEEVE: 0.197 ID $\times 0.43800 \times 0.375$ (ATTACHING PARTS) | 80009 | 358-0686-00 |
| -7 | 220-0495-00 |  | 1 | NUT, PLAIN, HEX: $0.375-32 \times 0.438$ HEX, BRS | 73743 | ORDER BY DESCR |
| -8 | 344-0195-01 |  | 1 | CLIP, ELECTRICAL:GRONNDING, PH BRZ ALBALOY PL | 80009 | 344-0195-01 |
| -9 | 210-0012-00 |  | 1 | WASHER, LOCK: 0.384 ID, INTL, 0.022 THK, STL (END ATTACHING PARTS) | 09772 | ORDER BY DESCR |
| -10 | 378-2030-05 |  | 1 | LENS,LED DSPL:RED W/MARKINGS | 80009 | 378-2030-05 |
|  | 334-4827-00 |  | 1 | MARKER, IDENT:MKD DC504A | 80009 | 334-4827-00 |
| -11 | 366-1851-01 |  | 1 | KNOB, LATCH: IVORY GY, $0.625 \times 0.25 \times 1.09$ | 80009 | 366-1851-01 |
| -12 | 105-0865-00 |  | 1 | BAR, LATCH RLSE: | 80009 | 105-0865-00 |
| -13 | 105-0866-00 |  | 1 | LATCH, RETAINING: SAFETY | 80009 | 105-0866-00 |
| -14 | 214-3143-00 |  | 1 | SPRING. HLEXT: $0.12500 \times 0.545 \mathrm{~L}, \times \mathrm{LOOP}$ | 80009 | 214-3143-00 |
| -15 | 366-0494-08 |  | 1 | KNOE:GY,NEW GEN, $0.12710 \times 0.5300 \times 0.5 \mathrm{H}$ | 80009 | 366-0494-08 |
|  | 213-0246-00 |  | 1 | .SETSCREW:5-40 X 0.094.STL | 71159 | ORDER BY DESCR |
| -16 | 333-3009-00 |  | 1 | FRONT PNL ASSY: | 80009 | $333-3009-00$ |
| -17 | 337-3044-00 |  | 1 | SHIELD, ELEC: FRONT SUBPANEL | 80009 | 337-3044-00 |
| -18 | 426-0725-24 |  | 1 | FR SECT, PLUG-IN:TOP (ATTACHING PARTS) | 80009 | 426-0725-24 |
| -19 | 211-0101-00 |  | 2 | SCREW,MACHINE:4-40 X 0.25,FLH, 100 DEG,STL (END ATTACHING PARTS) | TK0435 | ORDER BY DESCR |
| -20 | 214-3406-00 |  | 1 | SPRING, FLAT: $1.48 \mathrm{~L} \times 0.125$ W,CU BE | TK1326 | ORDER BY DESCR |
| -21 | - ---- |  | 1 | CKT BOARD ASSY:DISPLAY(SEE A10 REPL) (ATTACHING PARTS) |  |  |
| -22 | 211-0244-00 |  | 2 | SCR,ASSEM WSHR:4-40 $\times 0.312$.PNH STL (END ATTACHING PARTS) | TK0858 | 211-0244-00 |
|  |  |  |  | CKT BOARD ASSY INCLLDES: |  |  |
| -23 | 136-0494-00 |  | 6 | .SKT,PL-IN ELEK:MICROCIRCUIT. 14 DIP | 82526 | $75060-012$ |
| -24 | 136-0252-07 |  | 6 | . SOCKET, PIN CONN:W/O DIMPLE | 22526 | 75060-012 |
| -25 | ---------- |  | 1 | .CONN,RCPT, ELEC: (SEE A1OJ2062 REPL) .TERM SET,PIN: (SEE A10J4012,4014 REPL) |  |  |
| -27 | 131-0993-00 |  | 1 | .BUS , CONDUCTOR:SHUNT ASSEMBLY, BLACK | 22526 | 65474-005 |
| -28 | ---------- |  | 1 | .RES., VAR, NONWIR: (SEE A10R4037 REPL) |  |  |
| -29 | --- |  | , | .CONN,RCPT, ELEC: (SEE A10J4015 REPL) <br> (ATTACHING PARTS) |  |  |
| $-30$ | 210-0473-00 |  | 1 | .NUT, PLALN, DODEC: 0.469-32 $\times 0.638$,BRS NP . (END ATTACHING PARTS) | 73743 | ORDER BY DESCR |
| -31 | ---------- |  | 3 | .SWITCH, PUSH: (SEE A1OS3032,4024,425 REPL) |  |  |
| -32 | ----------- |  | 1 | .SWITCH, PUSH: (SEE A1OS3012 REPL) |  |  |
| -33 | 366-1559-09 |  | 4 | PUSH BUTTON: IVORY GRAY, 0.18 SQ X 0.43 H | 80009 | 366-1559-09 |
| -34 | ---------- |  | 1 | CKT BOARD ASSY:MAIN(SEE A12 REPL) (ATTACHING PARTS) |  |  |
| -35 | 213-0146-00 |  | 4 | SCREW,TPG,TF:6-20 X 0.312,TYPE B,PNH,STL (END ATTACHING PARTS) | 83385 | ORDER BY DESCR |
| -36 | ----------- |  | 1 | CKT BOARD ASSY INCLUDES: <br> .CONN,RCPT,ELEC: (SEE A12P2062 REPL) |  |  |
| -37 | 136-0729-00 |  | 1 | .SKT.PL-IN ELEK:MICROCKT, 16 CONTACT | 09922 | DILB16P-108T |
| -38 | 136-0757-00 |  | 1 | . SKT,PL-IN ELEK:MICROCIRCUIT, 40 DIP | 09922 | DILB40P-108 |
| -39 | ----.- ----- |  | 1 | . SWITCH, ROTARY: (SEE Al2S2061 REPL) |  |  |
| -40 | ----- ------ |  | 1 | .CONN, RCPT, ELEC: (SEE A12J1032,2032 REPL) |  |  |
| -41 | ------.--- |  | 9 | .TERMINAL PIN: (SEE A12J1040,2042,4012 REPL) |  |  |
| -42 | 131-0993-00 |  | 2 | .BUS, CONDUCTOR:SHUNT ASSEMBLY, BLACK | 22526 | 65474-005 |
| -43 | - |  | 4 | TERM,TEST POINT: (SEE A12TP1063,TP2012, TP2014,TP3012 REPL) |  |  |
| -44 | ---------- |  | 1 | .MICROCIRCUIT, LI: (SEE A12U2014 REPL) <br> . (ATTACHING PARTS) |  |  |
| -45 | 211-0292-00 |  | 1 | .SCR, ASSEM WSHR:4-40 X 0.29, PNH, BRS NI PL | 78189 | 51-040445-01 |
| -46 | 210-0406-00 |  | 1 | .NUT, PLAIN, HEX:4-40 ${ }^{\text {a }} 0.188$, BRS CD PL | 73743 | 12161-50 |
| -47 | 210-1171-00 |  | 1 | .WASHER, SHLDR:0.12 $10 \times 0.14300 \times 0.07 \mathrm{D}$ . (END ATTACHING PARTS) | 00261 | A7148516P2 |
| -48 | 136-0760-00 |  | 1 | .SKT,PL-IN ELEK:TRANSISTOR, 3 CONTACT | TK0772 | 10-18-2033 |
| -49 | 342-0354-00 |  | 1 | INSULATOR, PLATE:TRANSISTOR | 55285 | 7403-09FR-52 |


| Fig. 8 Index No. | Tektronix Part 1 Ho . | Serial/Assembly No. Effective Dscont | Oty | 12345 Mane \& Description | Mfr. Code | Mfr. Part Mo. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1-50 | 351-0612-00 |  | 1 | GUIDE,CKT BOARD:NYLON, 1.0 L | 80009 | 351-0612-00 |
| -51 | 426-0724-25 |  | 1 | FR SECT, PLUG-IN:BOTTOM (ATTACHING PARTS) | 80009 | 426-0724-25 |
| -52 | 211-0101-00 |  | 2 | SCREW,MACHINE:4-40 X 0.25, FLH, 100 DEG,STL (END ATTACHING PARTS) | TK0435 | ORDER BY DESCR |
| -53 | 386-4910-00 |  | 1 | SUPPORT, FRAME:REAR (ATtACHING PARTS) | 80009 | 386-4910-00 |
| -54 | 213-0868-00 |  | 2 | SCREW,TPG, TF: 6-32 $\times 0.375$ L,FILH,STL | 93907 | ORDER BY DESCR |
| -55 | 386-3657-01 |  | 2 | SUPPORT, PLUG-IN: <br> (END ATTACHING PARTS) | 93907 | ORDER BY DESCR |
|  | 175-2985-00 |  | 1 | WIRE ASSEMBLIES <br> CABLE ASSY,RF:50 OHM COAX,10.0 L,9-3 | 80009 | 175-2985-00 |
|  | 070-4291-00 |  | 1 | STANDARD ACCESSORIES MANLAL, TECH: INSTRUCTION, DC504A | 80009 | 070-4291-00 |




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[^1]:    -Decimal point implied to left of digit six.

